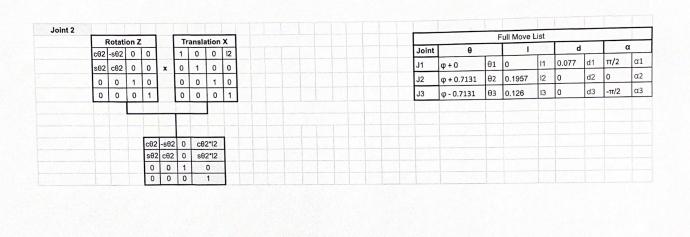


	Rotati	on Z			Tra	ansla	tion	Z			Rota	ion X							The state of the s	F	Full Move	List				1
с01	-sθ1	0	0		1	0	0	0		1	0	0	0					Joint	θ		- 1		d			α
s01	с01	0	0	x	0	1	0	0	x	0	ca1	-sa1	0					J1	φ+0	θ1	0	11	0.077	d1	π/2	α1
0	0	1	0		0	0	1	d1	. 0	0	sa1	ca1	0					J2	φ + 0.7131	θ2	0.1957	12	0	d2	0	α2
0	0	0	1		0	0	0	1		0	0	0	1					J3	φ - 0.7131	θ3	0.126	13	0	d3	-π/2	α3
					- 6	1		Val.			100	Redu	uce:	s(π/2	= 1											
					100					-	1			c(π/2	= 0											
				ce1	-sθ1	0	0		1	0	0	0		с01	0	sθ1	0									
		301		-	-	0	0	x	0	0	-1	-	=	sθ1	-	-cθ1	-									
				0	0	1	d1		0	1	0	0		0	1	0	d1									
				0	0	0	1	0	0	0	0	1		0	0	0	1									



C91 -S91 0 0 1 1 0 0 13 1 0 0 0 13	_	ation	_			Translation X					The party	Rota	ation)	X	1 99				Value of the	1 1/2	Full Move	List	Carriet Colored	100		1	
se1 ce1 ce1 ce1 ce1 center 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0	с01	-se	0 0		0		1	0	0	13		1	0	0	0				Joint	θ		_		1	1	T	α
0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 0 1 0	se1	сθ	1 0		0		0	1	0	0		0	ca1	-sa1	10				J1		101	-	1	-	1	1	_
0 0 0 1 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0	0	0	1		0	46	0	0	1	0					+	-			_		_	_	_	_	_		-
Reduce: s(-π/2) = -1 c(π/2) = 0 ce3 -se3 0 ce3*13 x 0 0 1 0 = se3 0 ce3 se3*13 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 1 0 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 0 1 0	0		_	-	\dashv		_	_				_	-	_	-	-				-	-	_			_	_	
c63 s63 0 c63*l3 x 0 0 1 0 = c63 0 c63*l3 s63 c63 0 s63*l3 x 0 0 1 0 = c63 0 c63*l3 0 0 1 0 0 0 1 0 0 0 1 0 -1 0 0 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1	-	-	1	-	-		-		-	34.5			0	-	1.	_		(- (0) - (13	φ - 0.7131	63	0.126	13	0	d3	-π/2	_
c03 -s03 0 c03*13 x 0 0 1 0 0 -s03 c03*13 s03 0 s03*13 x 0 0 1 0 0 -1 0 0 0 -1 0 0 0 0 0 0 1 0 0 0 0 1			-	1					100						-	Re	educe:	Constitution of the Alexander Special Assess in the		-							
893 C93 0 893*13 x 0 0 1 1 0 = 893 0 C93 893*13 0 0 -1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0					T			VE ST					12.00		-			$c(\pi/2) = 0$									
893 C93 0 893*13 x 0 0 1 1 0 = 893 0 C93 893*13 0 0 -1 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1 0 0 0 0			CE	3 -	803	0	cθ3	*13		1	0	0	0	1	CB	3 0	-sA3	CB3*I3									
			se	3 0	:03	0	s03	*13	x	_	-	_	-	=	_	_	-									1	
			(0	1	()		_	-	-	-		-	_	_			-	1						
The second of th			(0	0	1	400		0	0	0	1		_	_	_	ACCORDING TO LINE									
					The second																						
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45.65	17	Join	t 1				J	oint 2	2	100		4.50	J	oint 3		200			185,000		5	Full Move	List		State See	and the same	
	c01	0	s01	0		с02 -	se2	0	cθ2*	2		:03	0	-sθ3	c03*I3				Joint	θ	****	1		d	4000	-	α
	s01	42.00	-c 0 1	0	and and	IS ON A SECOND	cθ2	0	s02*		-	0000	500000		s03*l3				J1	φ+0	θ1	0	11	0.077	d1	π/2	a
-	0	1	Second	d1		0	0	1	0			0	-1	0	0				J2	φ + 0.7131	θ2	0.1957	12	0	d2	0	o
	0	0	0	1	200	0	0	0	1			0	0	0	1				J3	φ - 0.7131	θ3	0.126	13	0	d3	-π/2	C
	-	0000	-	1000	1000	-			part tyre	N. San		-								in the same of		1000	1	100	172	1 15	
			-			-	1,114	and the	- 1	989	-				-												
					(Manager)	с02	cθ3 -	sθ2s	683	0	-c02	2s03	- sθ:	2c03	θ2cθ3*	13 - 8	92	93*13 + c02*12									
					W. Low	s02	c03 +	- cθ2	s03	0	-sθ2	2sθ3	+ cθ	92c 0 3 s	θ2cθ3*	13 + 0	сθ2	s03*l3 + s02*l2									
			141		10,15	DI T	C)	24	-1	33		0	200			0			1							
							()		0	1000		0			e e	1		4			-					
	cθ1	0	sθ1			c(02-	-03)	0	-e/92	-B3)	13/0	(82)	2+03)) + c0		92*12				Podu	ced With Trig	cmo	θ - sφsθ =		с(ф	+ 0)		
	s01	0	-c01			s(θ2-		-			I3(s(θ2				_				Identi				θ + cφsθ =		+ 0)		
	0	1	0	d1	^	3(02	_	-1	0	_	10(3	(02)	0) 1 002	- 12	1			Continues		54.						
	0	0	0	1		0	_	0	0				1							-	1						
				1 34		Seller				- 6		12	10			01	-	arctan2(T[0,1], T	(1.11)	,	7,	,					
			-					1								3			cθ1) - (T[2,2] I3)) / I2				1				
		c01c(02+03) -s		-s81	-cθ1	s(02	+03)	сθ	1(13(c(θ2	+03	93)) + c02*			82		cθ2 = ((T[2,3] - d1) - T[2,0] 13) / 12										
				+03)			_		_				_	cθ2*12	1000			arctan2(s02, c0)									
			02+6	-	0	-	-sθ1s(θ2+θ3) c(θ2+θ3)							12 + d1		1	1-	arctan2(T[2,0],			7.						
		No. of	0		0	2000	0	-	5,161			1			Annua	03	5		- θ2								

 $\theta_{2} : \quad \text{Sin2} : \quad P_{2} = \mathcal{L}_{2} \times S(\Theta_{2} + \Theta_{3}) + \mathcal{L}_{1} + S\Theta_{2} \times \mathcal{L}_{2} \Rightarrow \underbrace{P_{2} - \mathcal{L}_{3} \times S(\Theta_{2} + \Theta_{3}) - \mathcal{L}_{1}}_{\mathcal{L}_{2}} = S\Theta_{2} \Rightarrow S\Theta_{2} = \underbrace{T[2,3] - \mathcal{L}_{3} \times T[0,2] - D1}_{\mathcal{L}_{2}}$ $\text{COS 2.} \quad P_{3} \times C\Theta_{1} \left(\mathcal{L}_{3} \times C(\Theta_{2} + \Theta_{3}) \right) + C\Theta_{2} \times \mathcal{L}_{2} \right) \Rightarrow \underbrace{P_{3} - \mathcal{L}_{3} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{C\Theta_{1}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow C\Theta_{1} \times \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow C\Theta_{1} \times \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2} \times \mathcal{L}_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2}}_{\mathcal{L}_{2}} \Rightarrow \underbrace{C\Theta_{1} \times C(\Theta_{2} + \Theta_{3}) + C\Theta_{2}}_{\mathcal{L}_{2$

 $C\theta_{2} = \frac{T[0,3]}{T[1,1]} - L_{3} * T[2,2]$ L_{2}