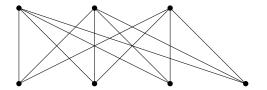


Figure 1: Sampling with a time step similar to (or longer than) characteristic time may obscure the important features of a biological signal.



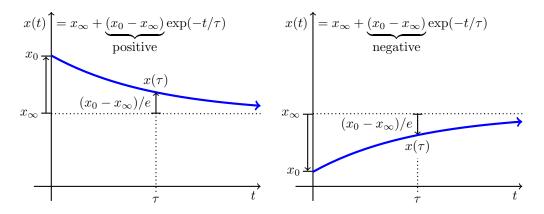
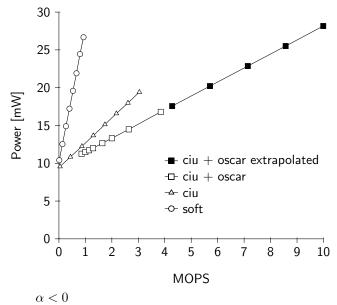


Figure 2: Exponential relaxation.



 $\alpha < 0$ $t_2 > t_1$ $x(t_2) < x(t_1)$ $x'(t_2) < x'(t_1)$



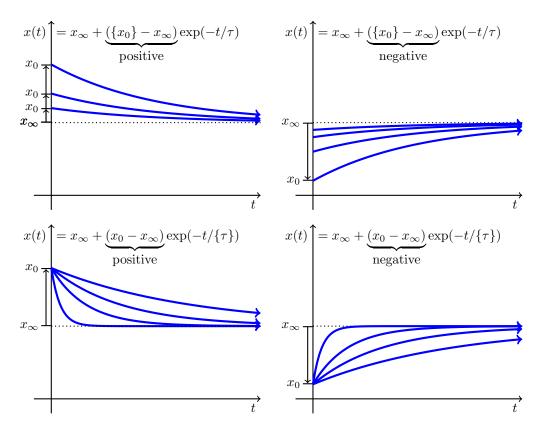


Figure 3: Exponential relaxation.

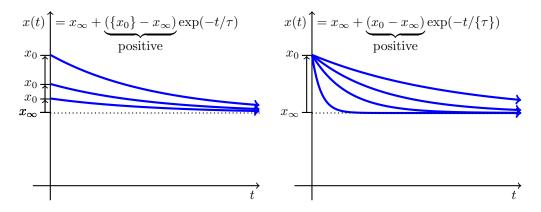


Figure 4: Exponential relaxation.

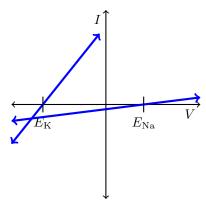


Figure 5: Current-voltage relation.

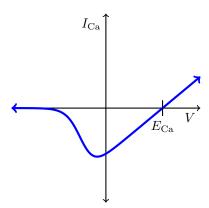


Figure 6: Current-voltage relation.

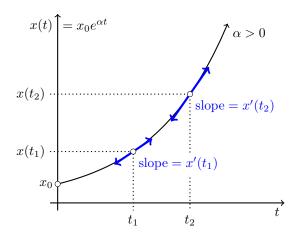


Figure 7: Exponential growth slopes.

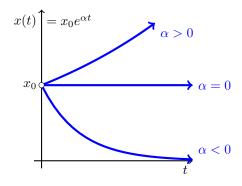
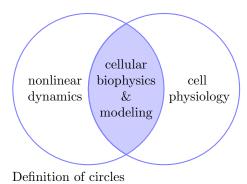


Figure 8: Caption.



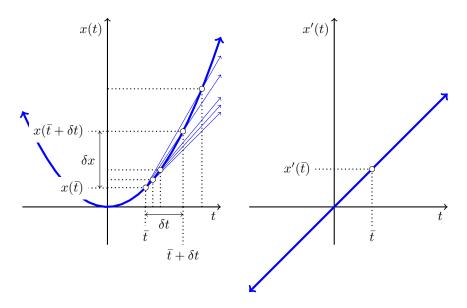
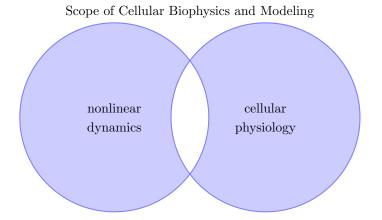


Figure 9: Definition of a derivative



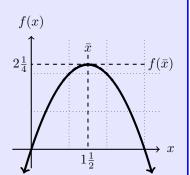
Analytical / Pencil & Paper

$$f(x) = 3x - x^2$$

$$f'(x) = 3 - 2x$$

$$f'(\bar{x}) = 3 - 2\bar{x} = 0$$
$$\bar{x} = \frac{3}{2} = 1\frac{1}{2}$$

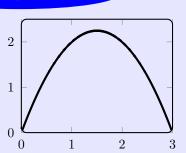
$$f(\bar{x}) = 3\left(\frac{3}{2}\right) - \left(\frac{3}{2}\right)^2 = \frac{9}{4} = 2\frac{1}{4}$$



Numerical / Computer

$$ans = 2.2500$$

>> plot(x,f)



A fancy title

To calculate the horizontal position the kinematic differential equations are needed:

$$\dot{n} = u\cos\psi - v\sin\psi \tag{1}$$

$$\dot{e} = u\sin\psi + v\cos\psi \tag{2}$$

For small angles the following approximation can be used:

$$\dot{n} = u - v\delta_{\psi} \tag{3}$$

$$\dot{e} = u\delta_{\psi} + v \tag{4}$$

Fermat's Last Theorem

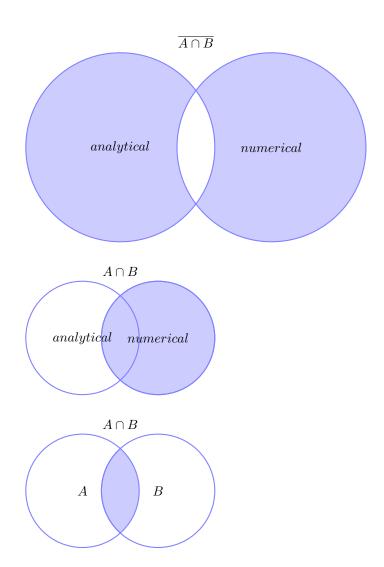
Fermat's Last Theorem states that

$$x^n + y^n = z^n$$

has no non-zero integer solutions for x,

y and z when n > 2.

Figure 10: kldfjadls;fjadl;sfj.



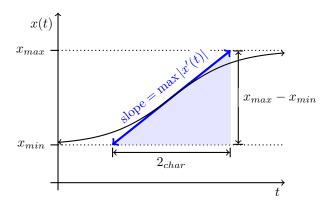


Figure 11: Characteristic time for changes in a bounded function.