RoutePlannerState

String getStartLoc();  
String getEndLoc();

List<String> getRouteSelected();  
String getError();  
String getPlane();  
String getLevel();  
String getFocusOn();

IModel

**void** start(NodeCheck check);  
**void** addListener(RoutePlannerListener listener);  
**void** startLoc(String item);  
**void** endLoc(String item);  
**void** newRoute();  
**void** setError(String error);  
**void** setPlane(String plane,String level);  
String getStart();  
String getEnd();  
**void** setCheck(NodeCheck check);

Model

Map<INode,INode> findRoute();

DijkstrasModel

ModelState

IEdge

INode getOtherINode();  
**double** getWeight();

INode

String getName();  
List<IEdge> getIEdges();

**boolean** canPassThrough();

NodeCheck

**boolean** canUse(INode node);

RoutePlannerListener

**void** update(RoutePlannerState state);