

Appendix X

1 In this appendix, I compare the following models for estimating the probability that seedlings
2 survive to become fruiting plants: (1) maximum likelihood estimates (binomial likelihood),
3 (2) non-hierarchical model with a binomial likelihood with a beta prior, (3) a hierarchical
4 model with a binomial likelihood and year-level parameters on a beta distribution, (4) a
5 hierarchical model with a binomial likelihood and year- and population-level parameters on
6 a beta distribution.

Maximum likelihood estimate

The following logic underlies how we calculate the maximum likelihood estimate for seedling survival to fruiting. For a single observation, the likelihood that we observe y fruiting plants in a plot if n seedlings were present in the plot can be written as a function of the probability of seedling survival p as $[y|p, n] = \binom{n}{y} p^y (1-p)^{n-y}$. For a set of N observations, each with a number of seedlings n_i and a number of fruiting plants y_i in the i th observation, then we can write the likelihood as

$$\mathcal{L} = [\mathbf{y}|p, \mathbf{n}] = \prod_{i=1}^N \binom{n_i}{y_i} p_i^{y_i} (1-p)^{n_i-y_i}. \quad (1)$$

which is often written as

$$\mathcal{L} = [\mathbf{y}|p, \mathbf{n}] = \prod_{i=1}^N \text{binomial}(n_i, p). \quad (2)$$

We can use the likelihood to obtain a maximum likelihood estimate (by minimizing the negative log-likelihood). The maximum likelihood estimate \hat{p} is the overall proportion of seedlings that survive to become fruiting plants, summing all the observations. The point is that the proportion calculated in the MATLAB code corresponds to the estimate from a

maximum likelihood estimate. Specifically, it calculates a maximum likelihood estimate for each population in each year of the dataset. We thus give each site j and year k its own probability of success p_{jk} and obtain the MLEs \hat{p}_{jk} .

$$[\mathbf{y}|\mathbf{p}, \mathbf{n}] = \prod_{j=1}^J \prod_{k=1}^K \prod_{i=1}^N \text{binomial}(n_{ijk}, p_{jk}) \quad (3)$$

Binomial likelihood with a beta prior, complete pooling

We can turn this into a Bayesian model by adding a prior to our model. Because the beta is a conjugate prior for a binomial distribution, we use a beta distribution for the prior. In other words, this choice of prior matches the likelihood in a way that the posterior has the same distribution as the prior (cf. Bolker p 177). A beta distribution with shape parameters $\alpha = \beta = 1$ corresponds to noninformative prior. For a set of N observations, each with a number of seedlings n_i and a number of fruiting plants y_i in the i th observation, we can write the joint posterior as

$$[\mathbf{y}|p, \mathbf{n}] = \prod_{i=1}^N \text{binomial}(n_i, p) \text{beta}(p|1, 1). \quad (4)$$

A single probability p represents the probability of seedling survival to fruiting for the all trials (a model with *complete pooling*). The opposite extreme is a model in which each trial i has its own probability of seedling survival to fruiting p_i (a model with *no pooling*).

$$[\mathbf{y}|\mathbf{p}, \mathbf{n}] = \prod_{i=1}^N \text{binomial}(n_i, p_i) \text{beta}(p_i|1, 1). \quad (5)$$

To compare our site- and year-specific MLEs to estimates from Bayesian models, we give each site j and year k its own probability of success p_{jk} , and place a prior on each p_{jk} .

$$[\mathbf{y}|\mathbf{p}, \mathbf{n}] = \prod_{j=1}^J \prod_{k=1}^K \prod_{i=1}^N \text{binomial}(n_{ijk}, p_{jk}) \text{beta}(p_{jk}|1, 1). \quad (6)$$

This is a model in which we are completely pooling observations from each site and year. Another thing we could say about this model is that it is Bayesian but non-hierarchical. This is extends what happens with the maximum likelihood estimates when we sum across all the plots at a site in a given year and calculate the proportion of seedlings that survive to become fruiting plants. One difference between the two approaches is that with the Bayesian model we account for the number of trials and counts; the data from one plot with a single seedling compromises with the prior to give us posterior probability of success (see **Comparison**). The Bayesian and frequentist estimates converge as the sample size approaches infinity.

Binomial model with a beta prior, partial pooling, parameterization via mean: one population, one year

Next, we'll consider adding pooling to our model. To explain this, we'll focus first on the data from one population in one year. We want a hierarchical model that estimates the probability of survivorship in each plot (θ_i) and simultaneously estimates the mean probability of survivorship in the year (ϕ). The probability of survivorship for each plot i is θ_i . We then assume that the probability of survivorship for the i plots is drawn from a distribution of probabilities defined by the mean probability of survivorship in a given year ϕ and sample size κ . This effectively means that the prior on θ_i is itself a parameter; (i.e. we use hyperpriors rather than directly place priors on the probability of survivorship θ_i). We reparameterize the beta distribution with its mean ϕ and the parameter κ . The mean of

a random variable distributed $\text{beta}(\alpha, \beta)$ is $\phi = \frac{\alpha}{\alpha + \beta}$. With a $\text{beta}(1, 1)$ prior, the parameter $\kappa = \alpha + \beta$ is roughly the sample size plus two.

$$\begin{aligned}
[\mathbf{p}, \boldsymbol{\theta}, \phi, \kappa | \mathbf{y}, \mathbf{n}] &= \prod_{i=1}^N \text{binomial}(n_i, \theta_i) \\
&\times \text{beta}(\theta_i | \phi \kappa, (1 - \phi) \kappa) \\
&\times \text{uniform}(\phi | 0, 1) \text{Pareto}(\kappa | 1.5, 1).
\end{aligned} \tag{7}$$

15 We place a uniform prior on the mean probability of survivorship, ϕ , because it must lie
16 between 0 and 1. We place a bounded, positive prior on κ with the $\text{Pareto}(\alpha, c)$ distribution,
17 which is parameterized by a shape (α) and scale (c) parameter.

18 This parameterization is hierarchical because the estimates for ϕ and κ contribute to
19 estimates for θ_i . [other effects?]

Binomial model with a beta prior, partial pooling, parameterization via mean: one population, multiple years

Next, we expand the scope of our analysis to include data from plots (i) in multiple years (j) of data for a single population $k = 1$. Here, we want a hierarchical model that estimates the probability of survivorship in each plot in each year (θ_{ij}). We want to simultaneously estimate the mean probability of survivorship in each year (ϕ_j) and the mean probability of survivorship in the population. The probability of survivorship for each plot i in a year j is θ_{ij} . We then assume that the probability of survivorship for the i plots in year j is drawn from a distribution of probabilities defined by the mean probability of survivorship in a given year ϕ_j and sample size κ_j . Furthermore, we assume that the mean probability of survivorship in a given year ϕ_j is itself drawn from a distribution of probabilities defined by

the mean probability of survivorship at the population ϕ_0 and the parameter κ_0 .

$$\begin{aligned}
[\mathbf{p}, \boldsymbol{\theta}, \boldsymbol{\phi}, \boldsymbol{\kappa}, \phi_0, \kappa_0 | \mathbf{y}, \mathbf{n}] &= \prod_{j=1}^J \prod_{i=1}^N \text{binomial}(n_{ij}, \theta_{ij}) \\
&\times \text{beta}(\theta_{ij} | \phi_j \kappa_j, (1 - \phi_j) \kappa_j) \\
&\times \text{beta}(\phi_j | \phi_0 \kappa_0, (1 - \phi_0) \kappa_0) \text{Pareto}(\kappa_j | 1.5, 1) \\
&\times \text{uniform}(\phi_0 | 0, 1) \text{Pareto}(\kappa_0 | 1.5, 1).
\end{aligned} \tag{8}$$

20 This parameterization is hierarchical because the estimates for ϕ_j and κ_j contribute to esti-
21 mates for θ_{ij} , and the estimates for ϕ_0 and κ_0 contribute to estimates for ϕ_j . [other effects?]

Binomial model with a beta prior, partial pooling, parameterization via mean: multiple populations, multiple years

Finally, we expand the scope of our analysis to include data from plots (i) in multiple years (j) of data for multiple populations k . Here, we want a hierarchical model that estimates the probability of survivorship in each plot in each year at each population (θ_{ijk}). We want to simultaneously estimate the mean probability of survivorship in each population ϕ_k , the mean probability of survivorship in each year ($\phi_j k$). The probability of survivorship for each plot i in a year j at population k is θ_{ijk} . We then assume that the probability of survivorship for the i plots in year j in population k is drawn from a distribution of probabilities defined by the mean probability of survivorship in a given year at a given population ϕ_{jk} and parameter κ_{jk} . Furthermore, we assume that the mean probability of survivorship in a given year in a given population ϕ_{jk} is itself drawn from a distribution of probabilities defined by the mean probability of survivorship for the population $\phi_{0,k}$ and the parameter $\kappa_{0,k}$. The model is similar to the one for one population except the indexing has changed so that we estimate a

mean probability of survivorship for each population.

$$\begin{aligned}
[\mathbf{p}, \boldsymbol{\theta}, \boldsymbol{\phi}, \boldsymbol{\kappa}, \phi_0, \kappa_0 | \mathbf{y}, \mathbf{n}] &= \prod_{k=1}^K \prod_{j=1}^J \prod_{i=1}^N \text{binomial}(n_{ijk}, \theta_{ijk}) \\
&\times \text{beta}(\theta_{ijk} | \phi_{jk} \kappa_{jk}, (1 - \phi_{jk}) \kappa_{jk}) \\
&\times \text{beta}(\phi_{jk} | \phi_{0,k} \kappa_{0,k}, (1 - \phi_{0,k}) \kappa_{0,k}) \text{Pareto}(\kappa_j | 1.5, 1) \\
&\times \text{uniform}(\phi_{0,k} | 0, 1) \text{Pareto}(\kappa_{0,k} | 1.5, 1).
\end{aligned} \tag{9}$$

22 This parameterization is hierarchical because the estimates for ϕ_{jk} and κ_{jk} contribute to
23 estimates for θ_{ijk} , and the estimates for $\phi_{0,k}$ and $\kappa_{0,k}$ contribute to estimates for ϕ_{jk} . [other
24 effects?]

Comparison

25 First, we want to explore estimates from a Bayesian model compare to the maximum like-
26 lihood estimates. Second, we want to explore the effect of adding hierarchical structure to
27 the parameter estimates in our models. Finally, we want to explore the effect of adding hier-
28 archical structure on how appropriate our models are (compare posterior predictive checks).

29 [need to give details of models here - trace plots, etc.]

30 First, we want to explore estimates from a Bayesian model compare to the maximum
31 likelihood estimates. The comparison I am interested in is the effect of adding a prior,
32 rather than the effect of adding hierarchy to the model. I will compare the maximum likeli-
33 hood estimates (equation (3)) and the non-hierarchical Bayeisan model (equation (6)). The
34 first panel in Figure 1 shows that the maximum likelihood estimates are pretty similar to
35 those from the Bayesian model with complete pooling per population and a beta-binomial
36 parameterization. The major differences are where the maximum likelihood estimates ap-
37 proach 0 or 1. The second panel in Figure 1 shows that this is because those estimates come

from year-population combinations with a small sample size. For example, the MLE for a year-population combination with one plot and 1 seedling that dies before fruiting would be 0. In the Bayesian model, the prior has a comparatively larger influence on the posterior in situations where there is little data. In this case, the posterior would be a compromise between our one data point and our prior. The estimates converge once we have 5 data points.

Second, we want to explore the effect of adding hierarchical structure to the parameter estimates in our models. These comparisons will all be among models fit to data for one population ($k = 1$). I am interested in comparing a non-hierarchical model (equation (6)), a hierarchical model with year-level parameters (equation (7)), and a hierarchical model with year-level and population-level parameters (equation (8)). All these comparisons are made at a randomly selected site.

The first panel in figure 2 shows that the complete pooling model produces estimates for each plot that are identical; there is one estimate per year. The second and third panels show that the posterior medians for θ_i and θ_{ij} from the hierarchical models are 'shrunk' from the point estimates y_{ij}/n_{ij} towards the year-level mean (dotted line). Figure 3 that the models shrink θ_i and θ_{ij} towards the year-level estimate, and that this effect varies across years.

In the non-hierarchical model, the posterior distribution for the probability of survivorship in each year is p_{jk} (where $k=1$) in equation (6)). In the hierarchical model with year-level parameters, the posterior distribution for the mean probability of survivorship in each year is ϕ in equation (7). In the hierarchical model with year- and population-level parameters, the posterior distribution for the mean probability of survivorship in each year is ϕ_j , and the posterior distribution for the mean probability of survivorship in the population is ϕ_0 in equation (8). Figures 4) and 5) both show that the posterior distribution for the mean probability of survivorship from the hierarchical models (red lines) is broader than for the probability of survivorship from the non-hierarchical model (blue lines). Figure 5) also shows

the posterior for the population-level probability of survivorship (black line).

Figure 6) summarizes the posterior distributions for the year-level probability of survivorship by their median and 95% credible intervals. The hierarchical structure has the effect of broadening the credible intervals associated with the estimated mean probability of survivorship in each year.

Finally, we want to explore the effect of adding hierarchical structure on how appropriate our models are (compare posterior predictive checks). The figures appended to this PDF (still need to figure out how to best integrate them) show graphical posterior predictive checks (cf. Gabry et al. 2019) for the non-hierarchical (blue), the hierarchical with year-level parameters (purple), and the hierarchical with year- and population-level parameters (gray). Gabry et al. (2019) describe how to perform PPCs: the posterior distribution is used to simulate data, and this data is summarized and compared to observed test statistics. For all three models, the mean of simulations from the posterior does a good job matching the observed mean from the data. This is perhaps not surprising because the models are parameterized via the mean probability of success. Posterior predictive checks for the variance may be more informative (variance is not a parameter in our models). The variance of simulations from the posterior of the non-hierarchical model under- or over-estimates the variance. The variance of simulations from both the hierarchical models do a reasonable job at matching the observed variance.

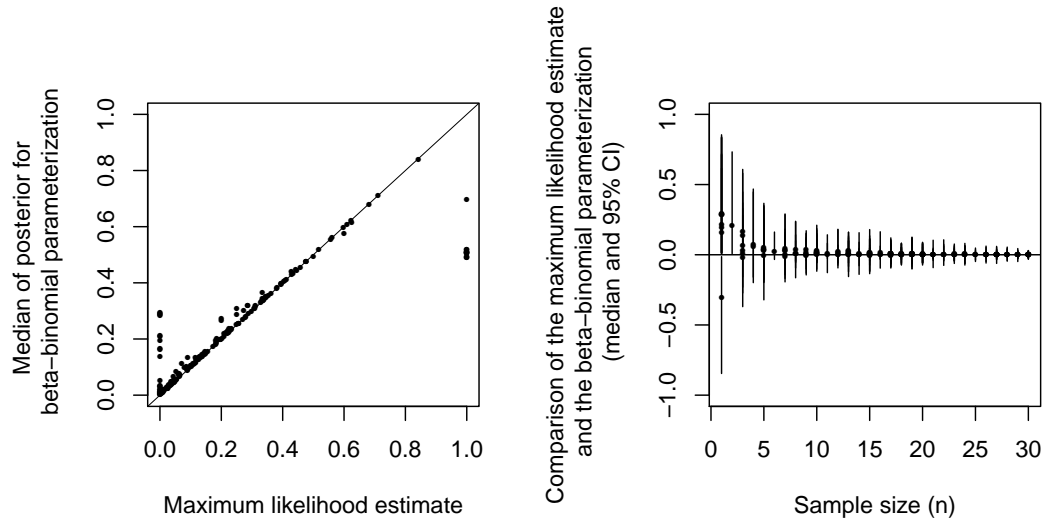


Figure 1: (A) This panel plots the median of the posterior from the beta-binomial with complete pooling per population against the maximum likelihood estimate. (B) This panel compares the full posterior distribution from the beta-binomial parameterization with the maximum likelihood estimate. The plot shows the median of the difference (with 95% CIs) against the sample size in the year-population combination for that estimate.

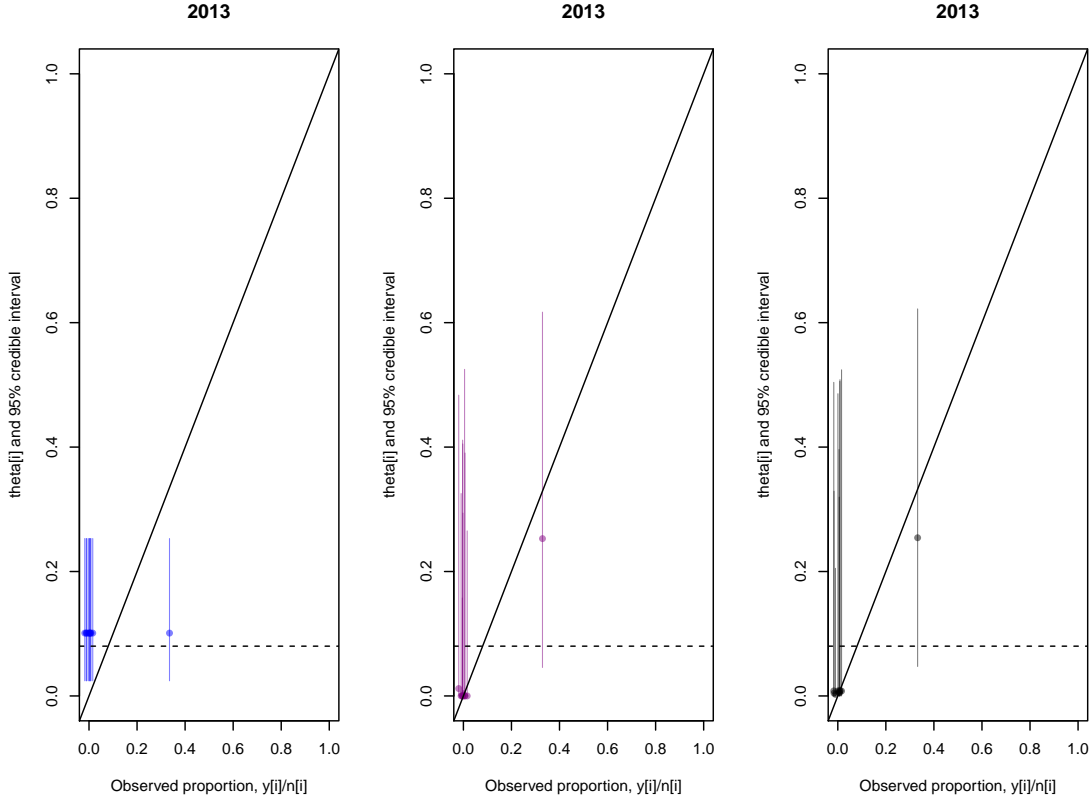


Figure 2: Posterior median and 95% credible intervals for a randomly selected year, based on simulations from the joint posterior distribution plotted against the unpooled estimates. The 1:1 line corresponds to unpooled estimates $\theta_i = y_i/n_i$. The horizontal, dashed line corresponds to the year-level maximum likelihood estimate. (A) Estimates from the complete pooling model. (B) Estimates from the hierarchical model with year-level parameters. (C) Estimates from the hierarchical model with year- and population-level parameters.

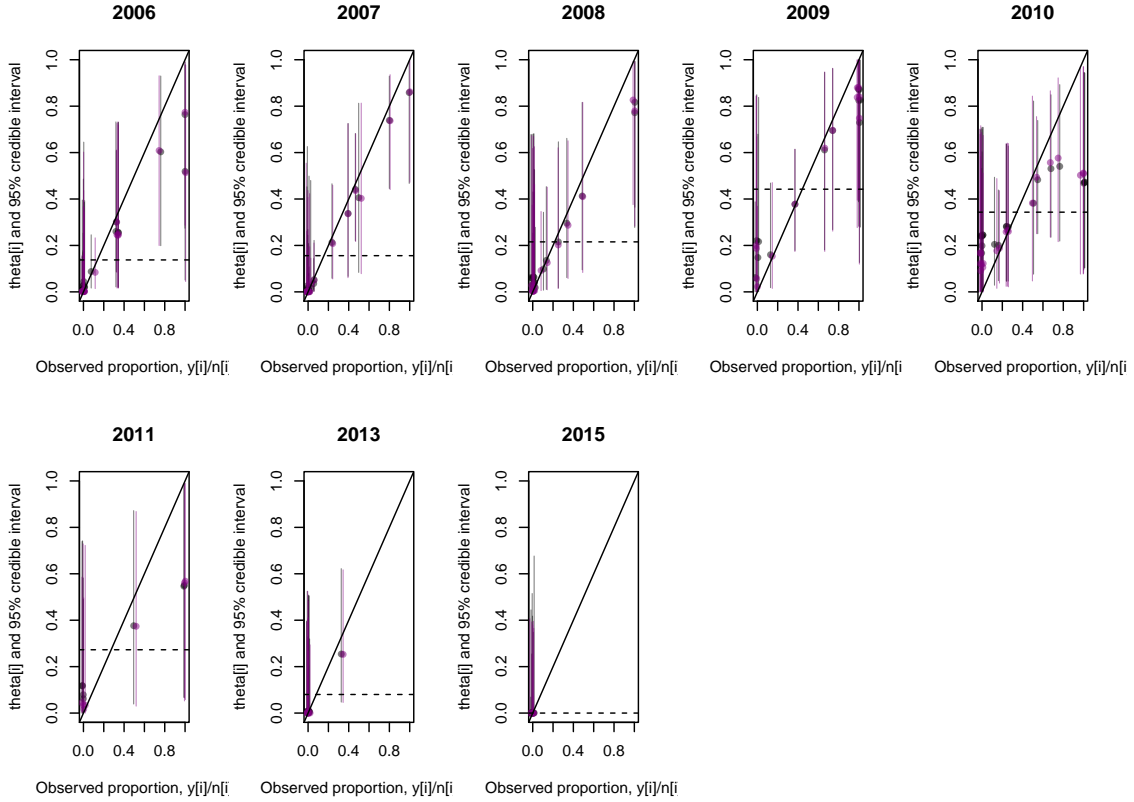


Figure 3: (A) Posterior median and 95% credible intervals for a randomly selected year, based on simulations from the joint posterior distribution plotted against the unpooled estimates. The 1:1 line corresponds to unpooled estimates $\theta_i = y_i/n_i$. The horizontal, dashed lines corresponds to the year-level maximum likelihood estimates.

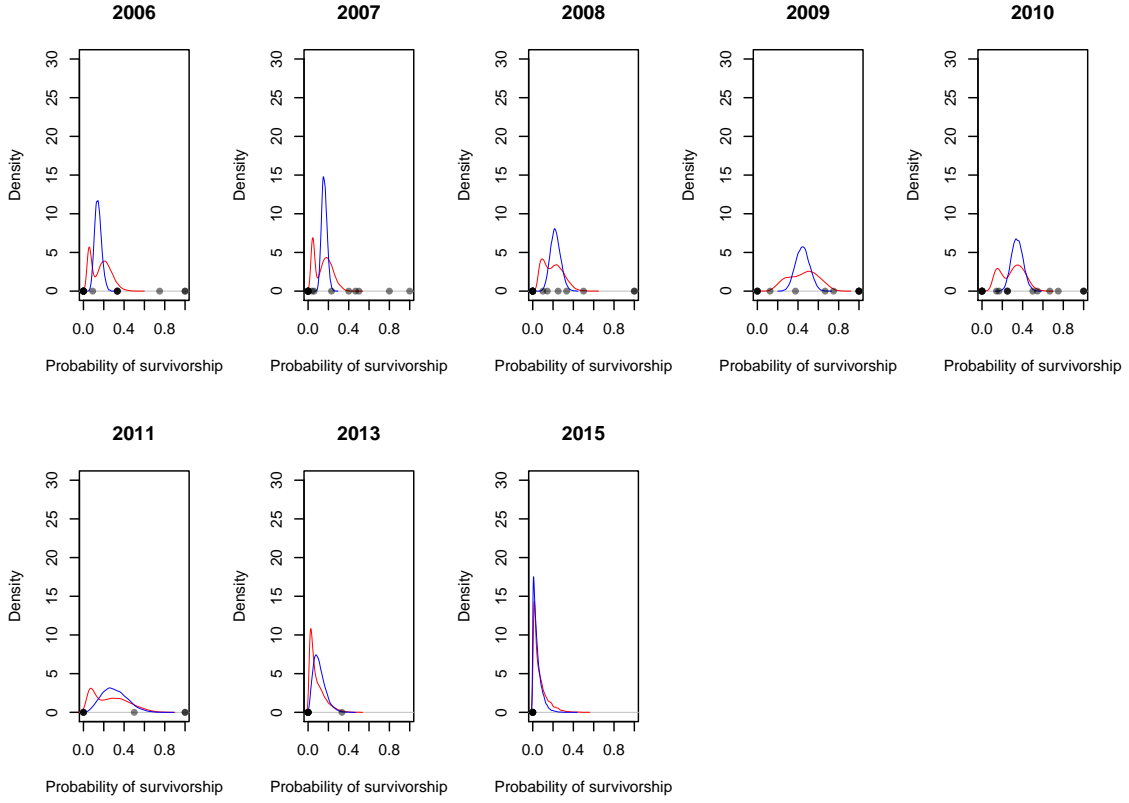


Figure 4: (A) Comparison of nonhierarchical (blue) and year-level parameter hierarchical (red) model. The curves are posterior density distributions for the probability of survivorship p_{jk} (blue) and ϕ (red).

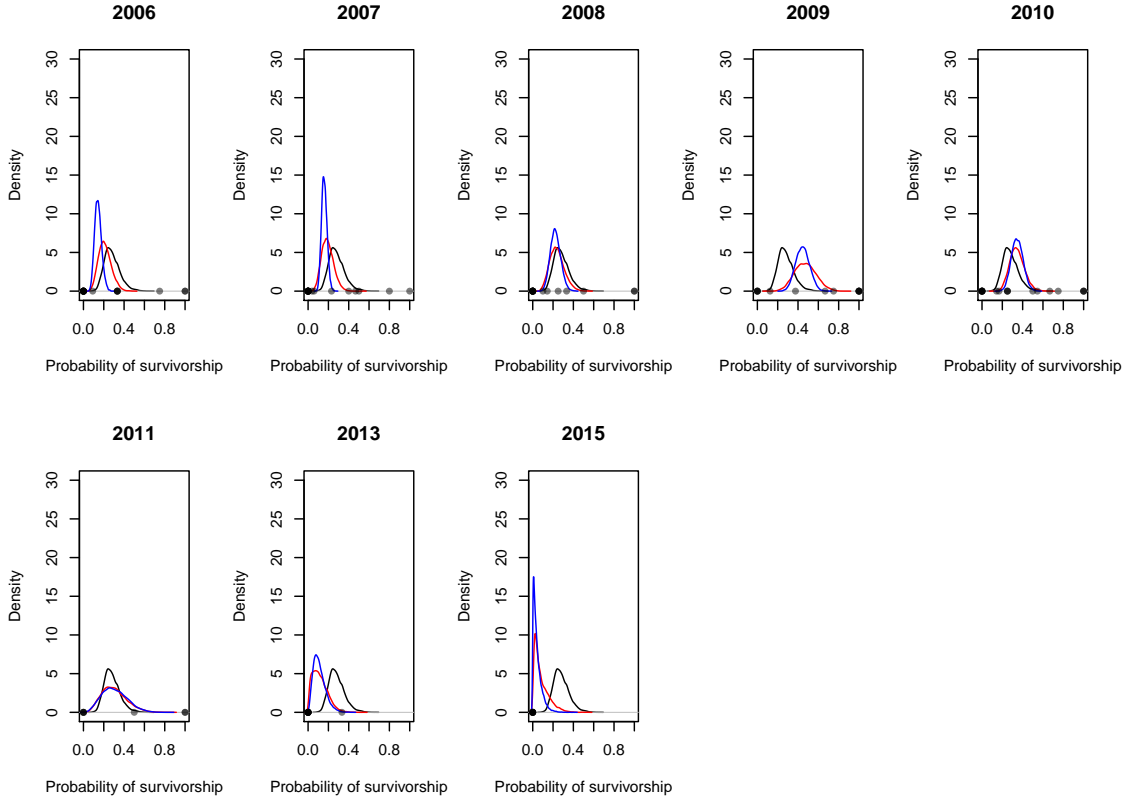


Figure 5: (A) Comparison of hierarchical and nonhierarchical model for year- and population-level parameter. The curves are posterior density distributions for the probability of survivorship p_{jk} (blue), ϕ_j (red), and ϕ_0 (black).

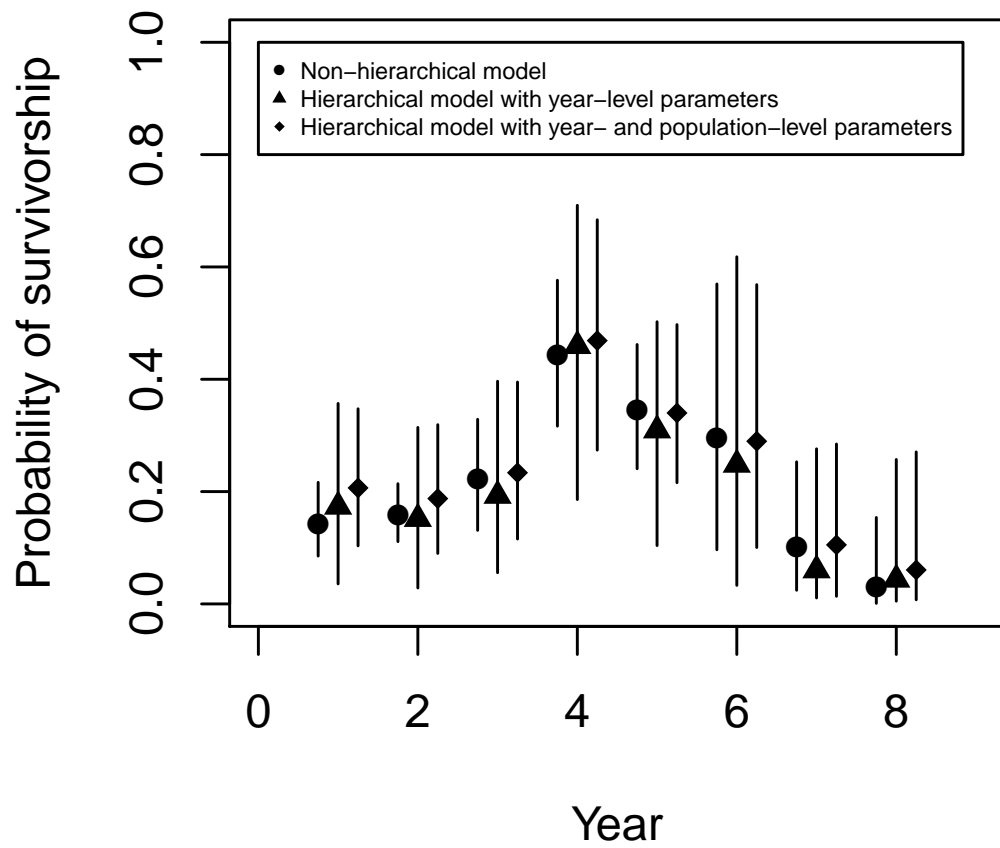
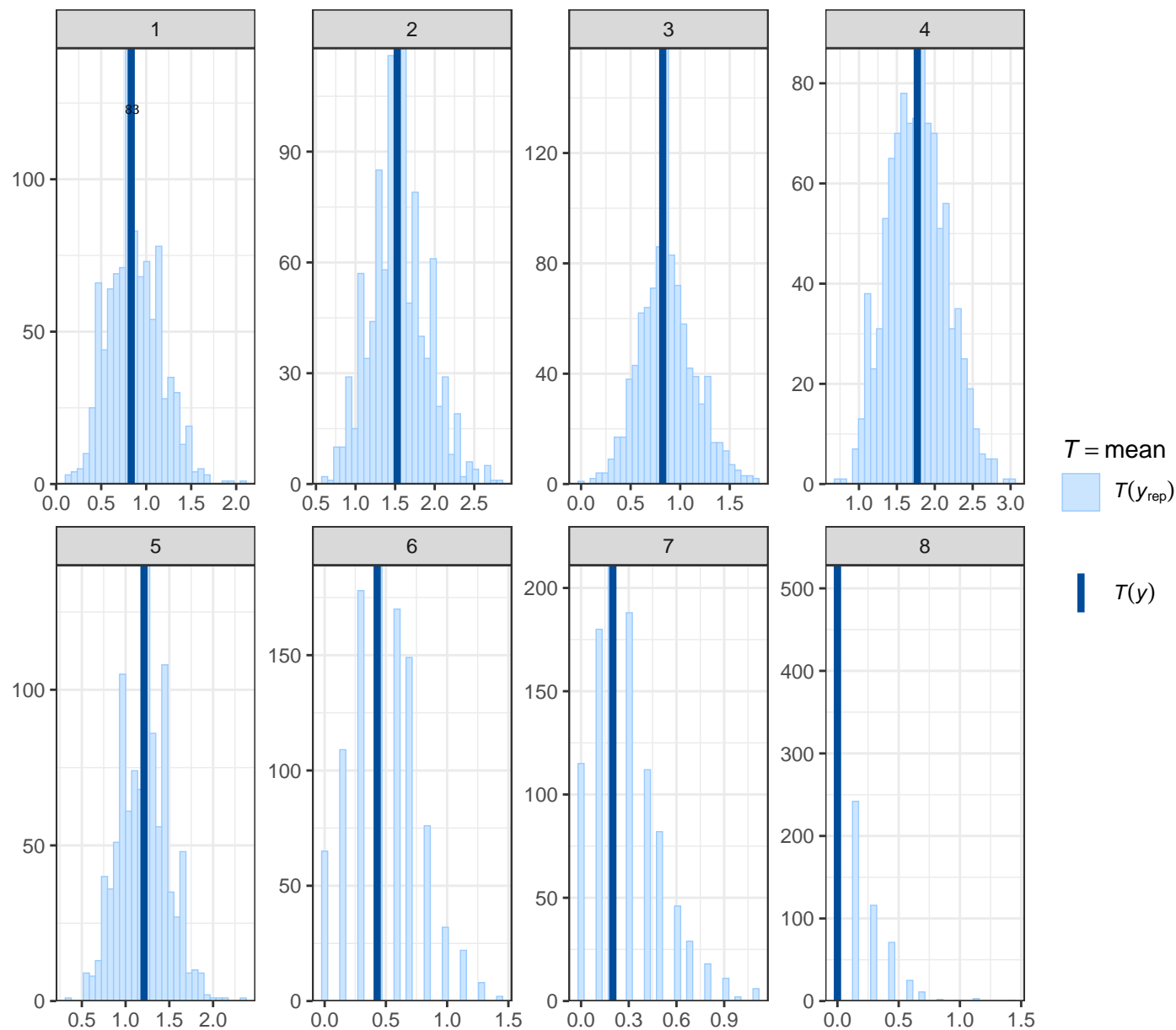


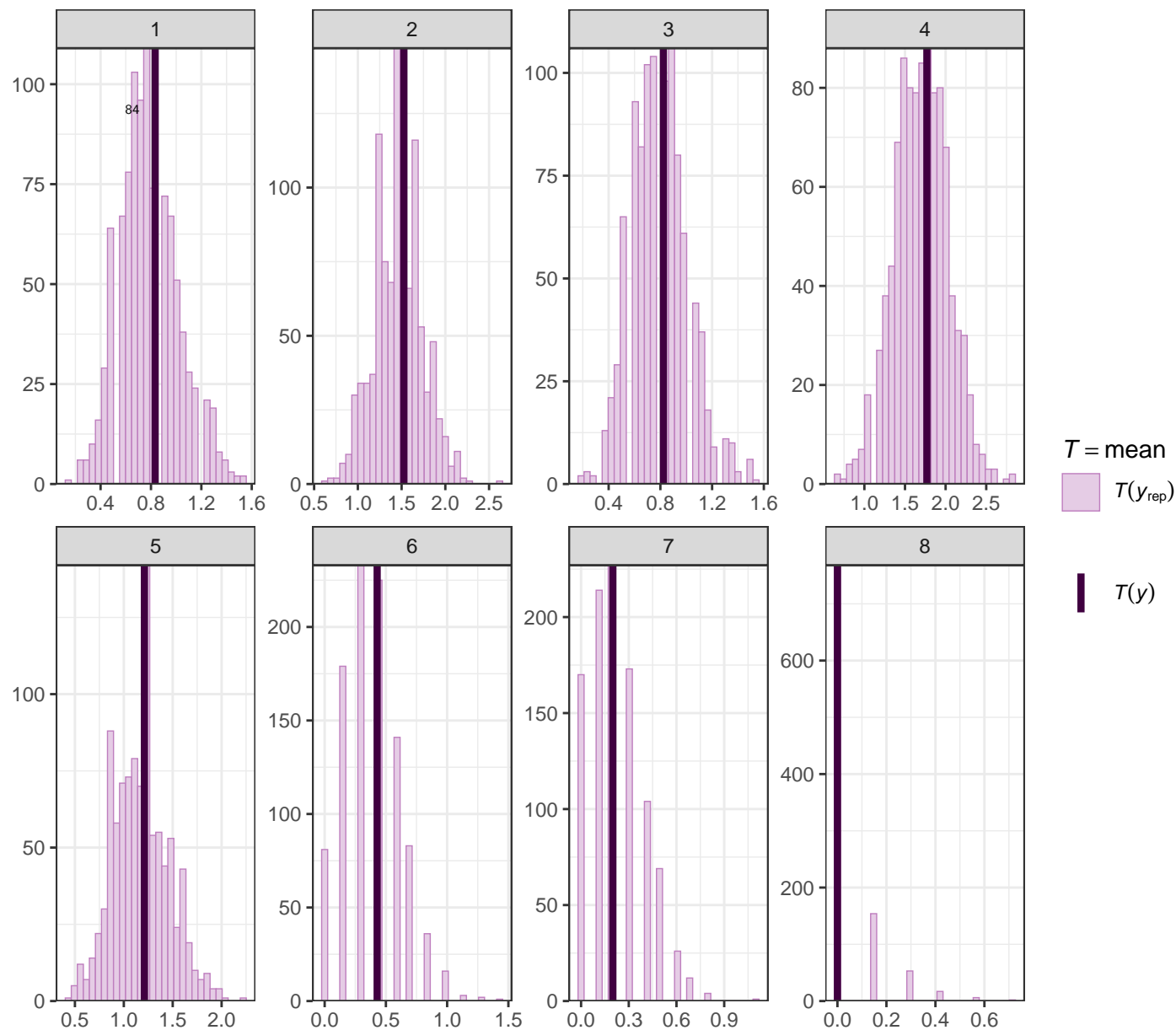
Figure 6: (A) Comparison of median and 95% confidence intervals for models with three levels of structure, fit to the same dataset.

Posterior predictive checks for number of fruiting plants; non-hierarchical model



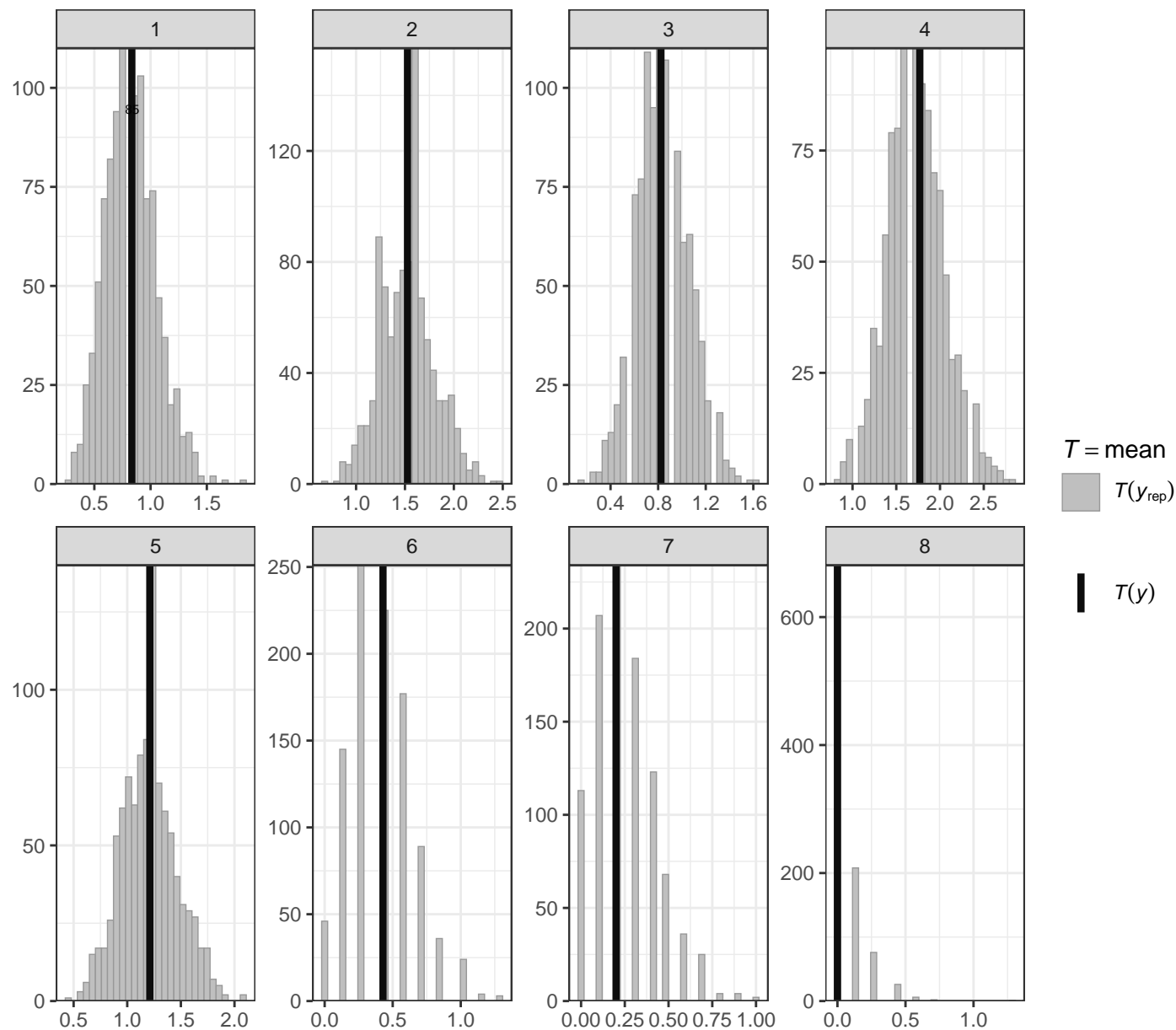
the density of observed data (y) and the lighter lines show the densities of Y_{rep} from 1000 draws of the posterior

Posterior predictive checks for number of fruiting plants; hierarchical model with year-level

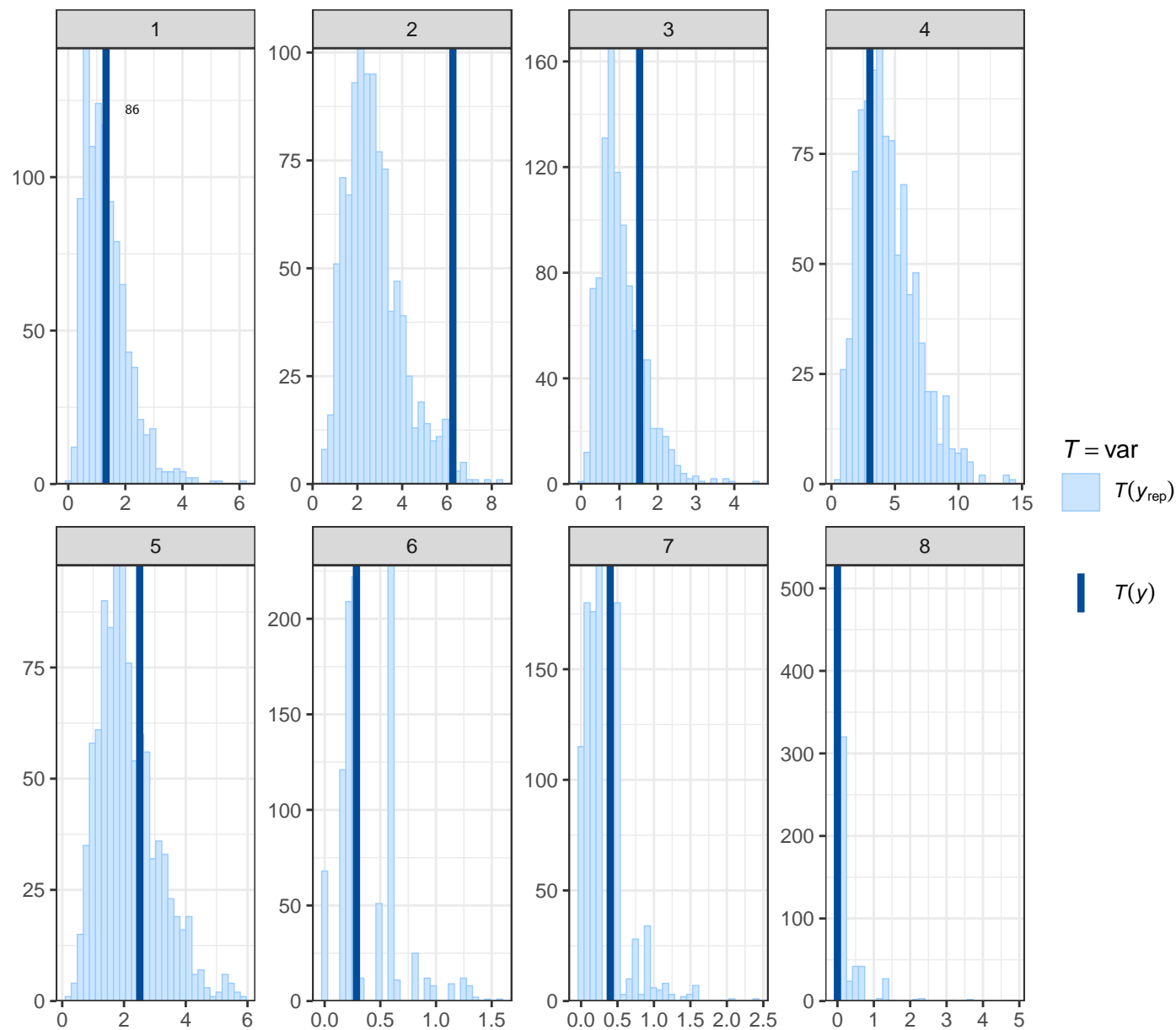


the density of observed data (y) and the lighter lines show the densities of Y_{rep} from 1000 draws of the posterior

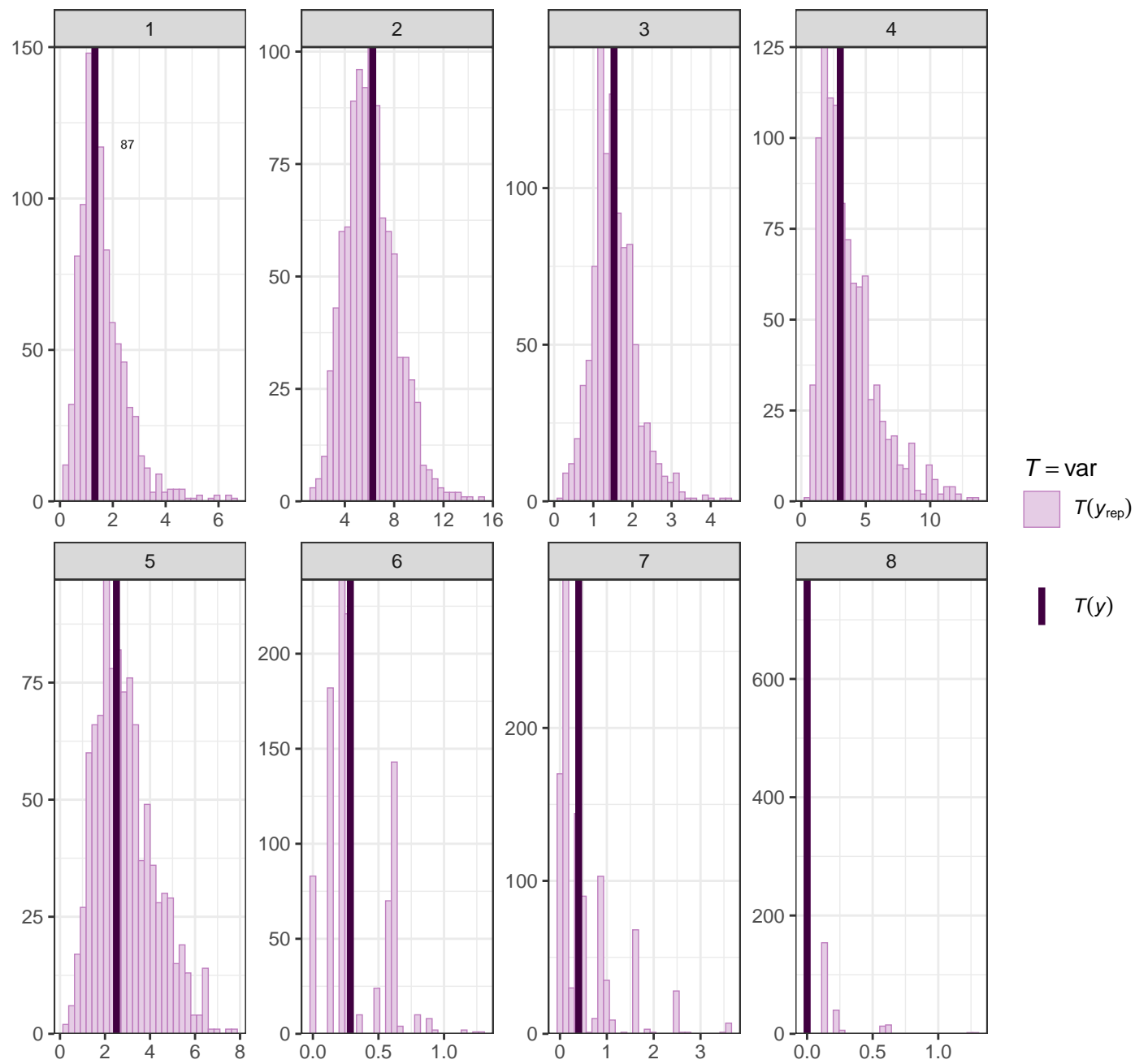
Posterior predictive checks for number of fruiting plants; hierarchical model with year– an



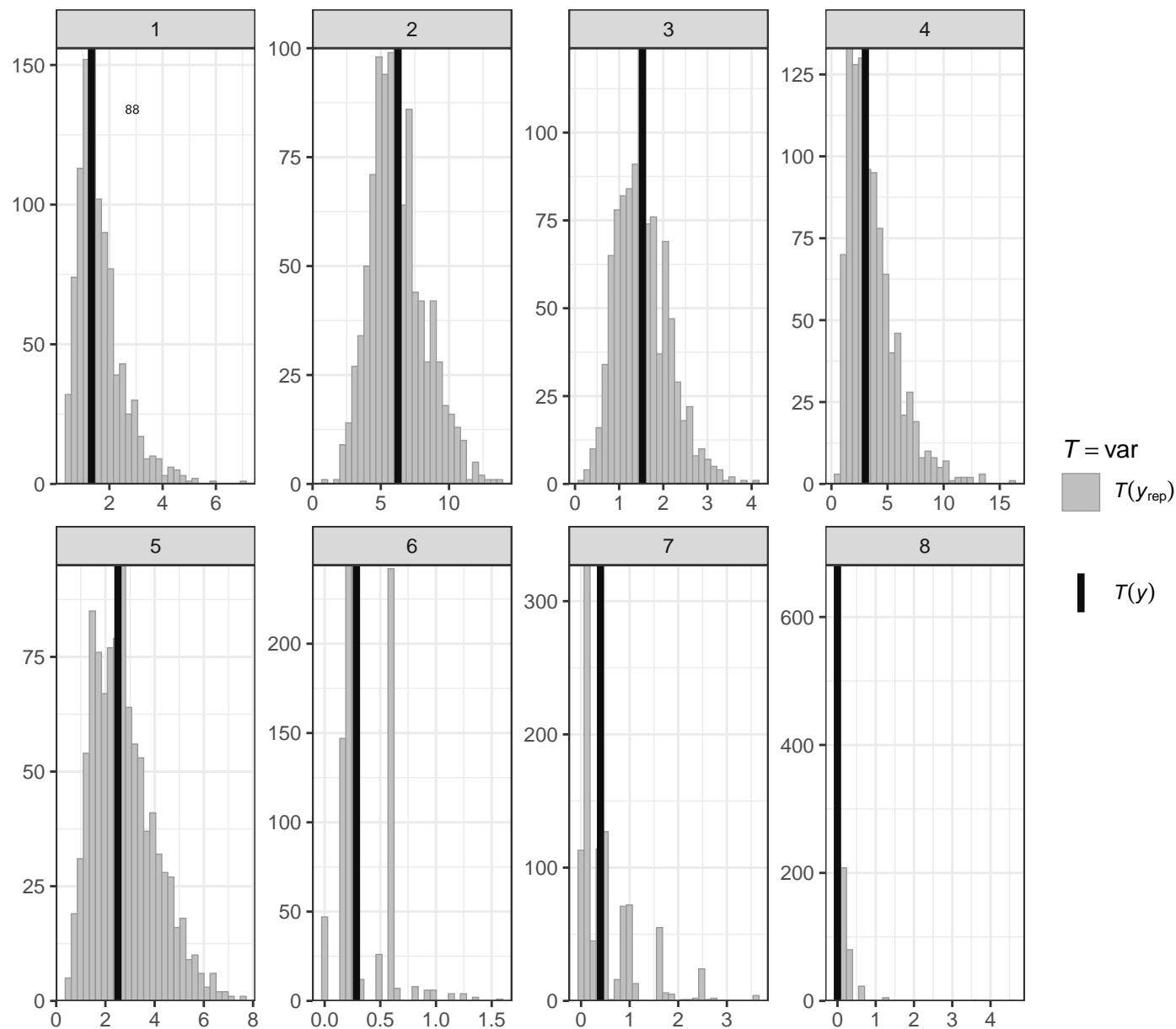
Posterior predictive checks for number of fruiting plants; non-hierarchical model



the density of observed data (y) and the lighter lines show the densities of Y_{rep} from 1000 draws of the posterior



Posterior predictive checks for number of fruiting plants; hierarchical model with year– an



the density of observed data (y) and the lighter lines show the densities of Y_{rep} from 1000 draws of the posterior