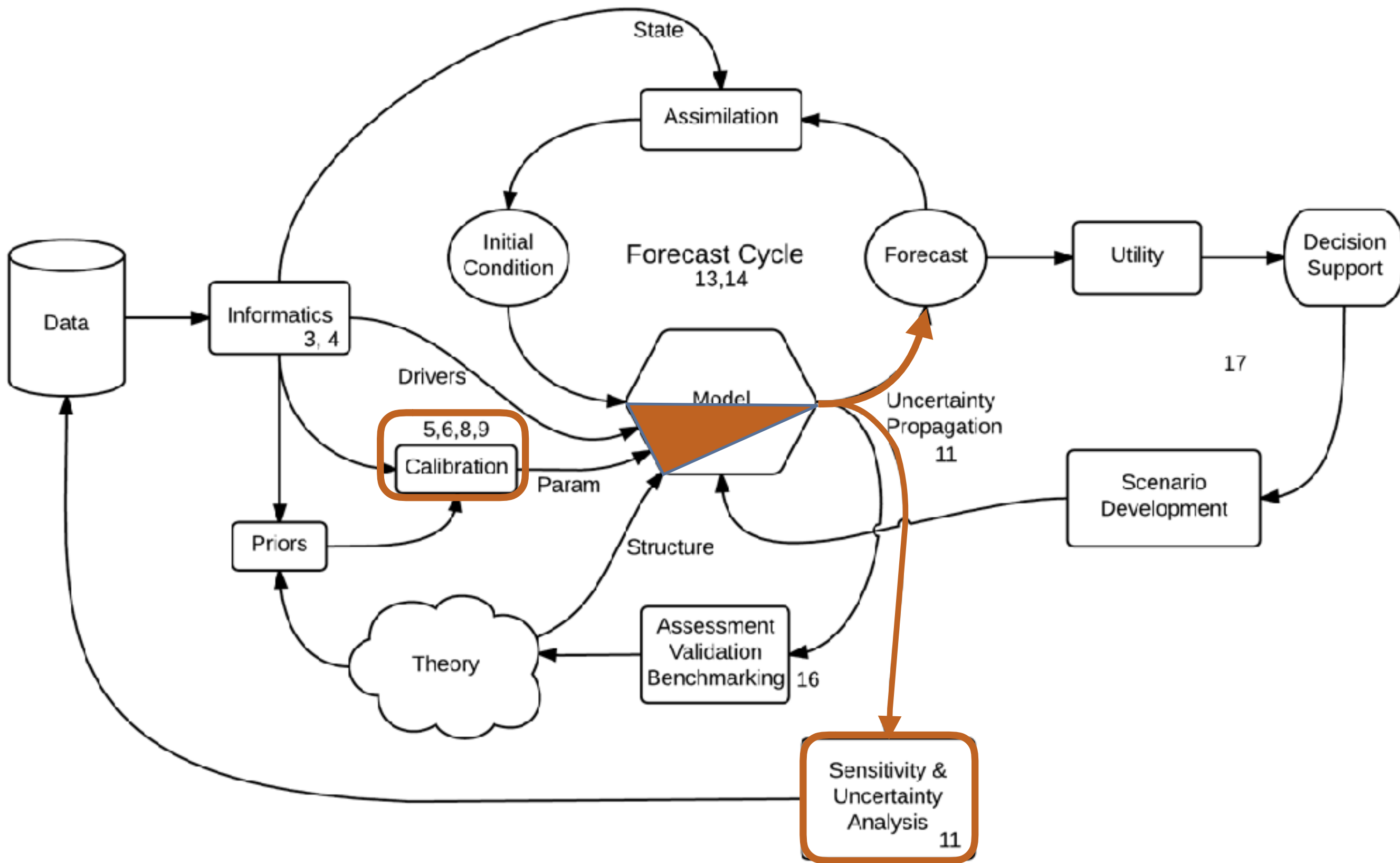




**PROPAGATING, ANALYZING,
AND REDUCING UNCERTAINTY**

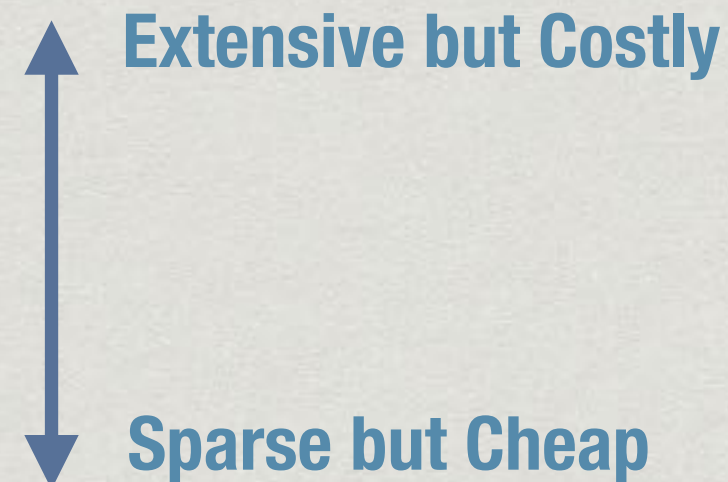


Concepts

- * Sensitivity Analysis $\partial x \rightarrow \partial y$
How does a change in X translate into a change in Y?
- * Uncertainty Propagation $Var[x] \rightarrow Var[y]$
How does the uncertainty in X affect the uncertainty in Y?
How do we forecast Y with uncertainty?
- * Uncertainty Analysis
which sources of uncertainty are most important?
- * Optimal Design
How do we best reduce the uncertainty in our forecast?

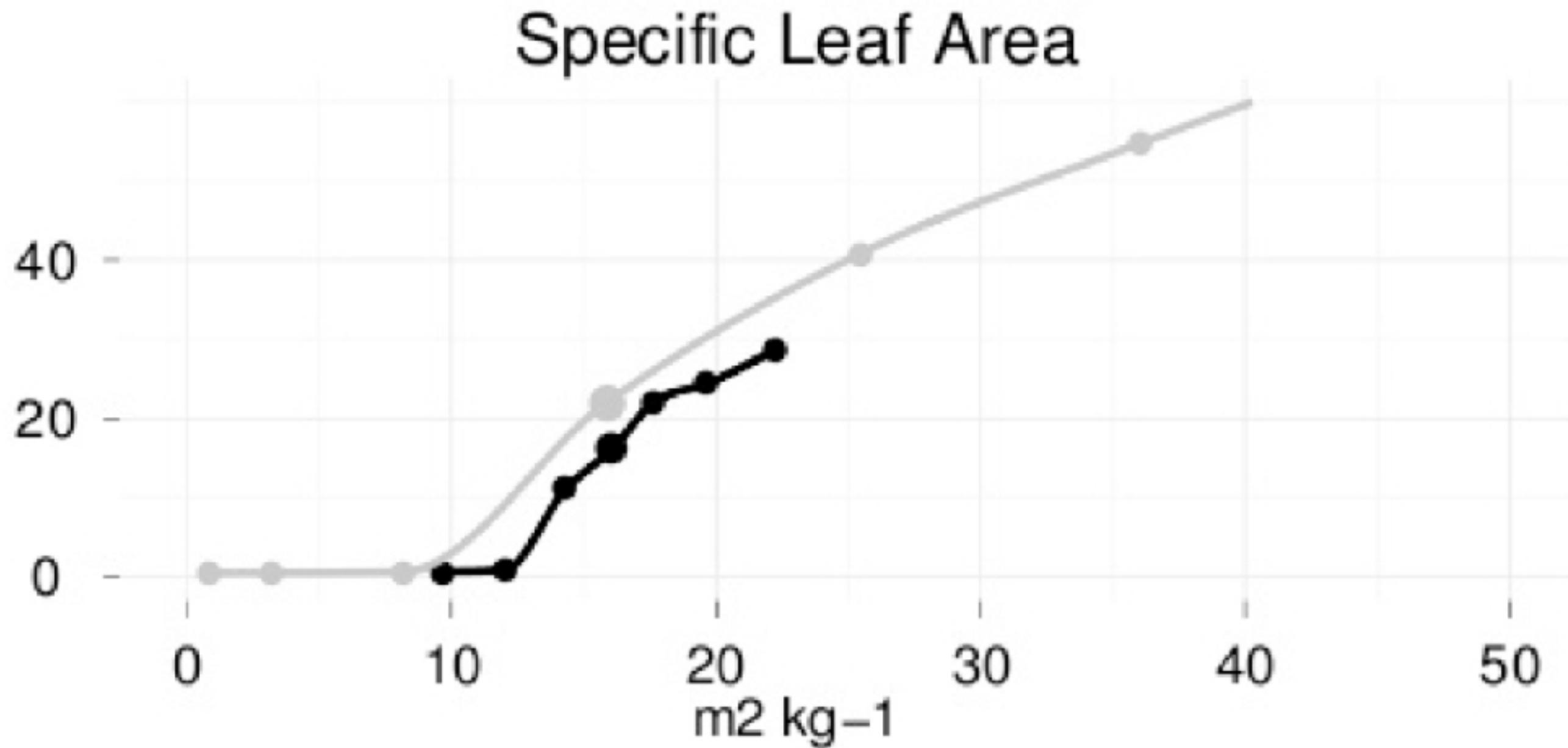
Sensitivity Methods

- * Local
 - * Analytical: $df/d\theta$
 - * One-at-a-time perturbations
- * Global
 - * Monte Carlo
 - * Sobol
 - * Emulators
 - * Elementary Effects
 - * Group Sampling

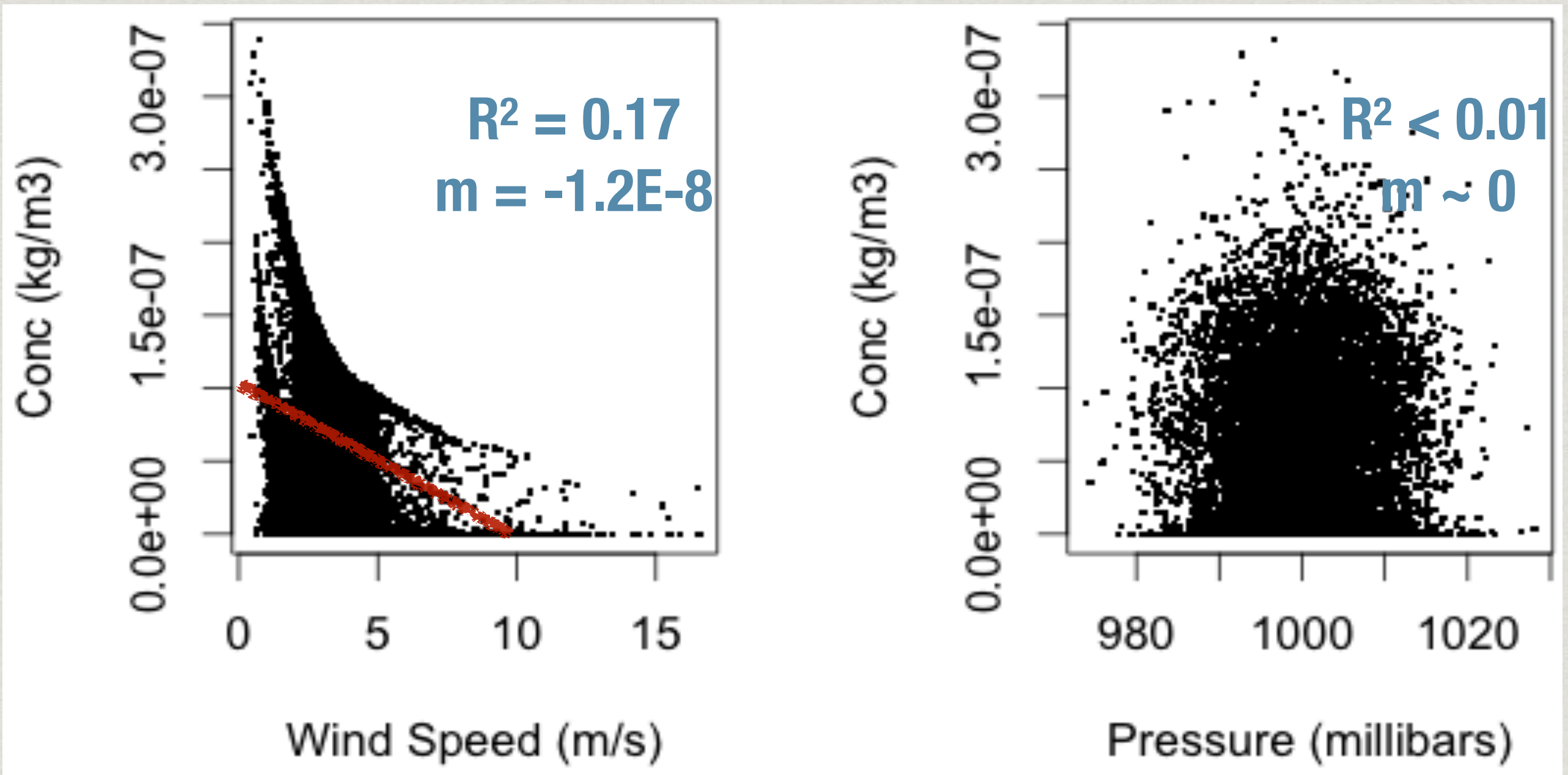


Saltelli et al. 2008. Global Sensitivity Analysis

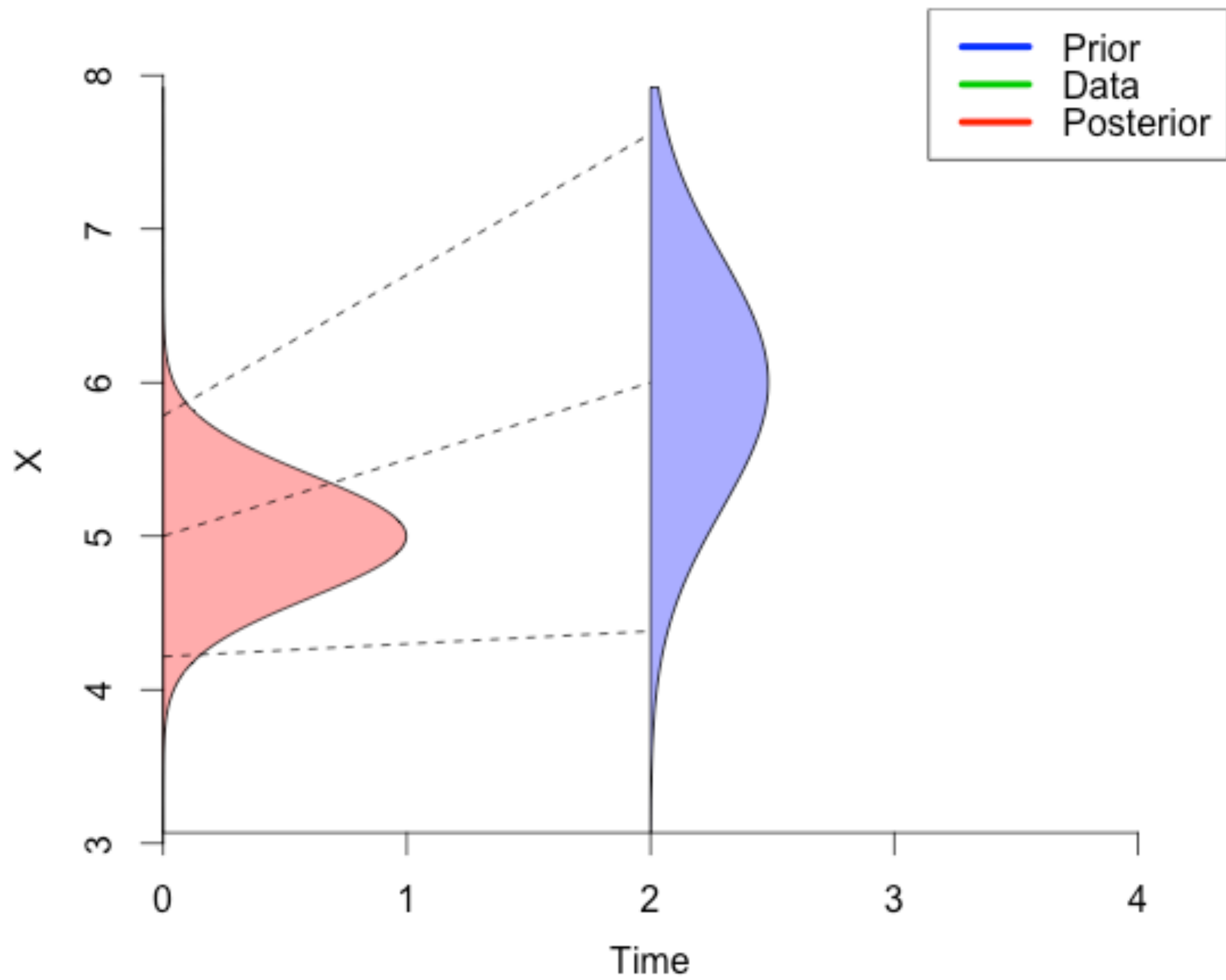
Sensitivity Analysis



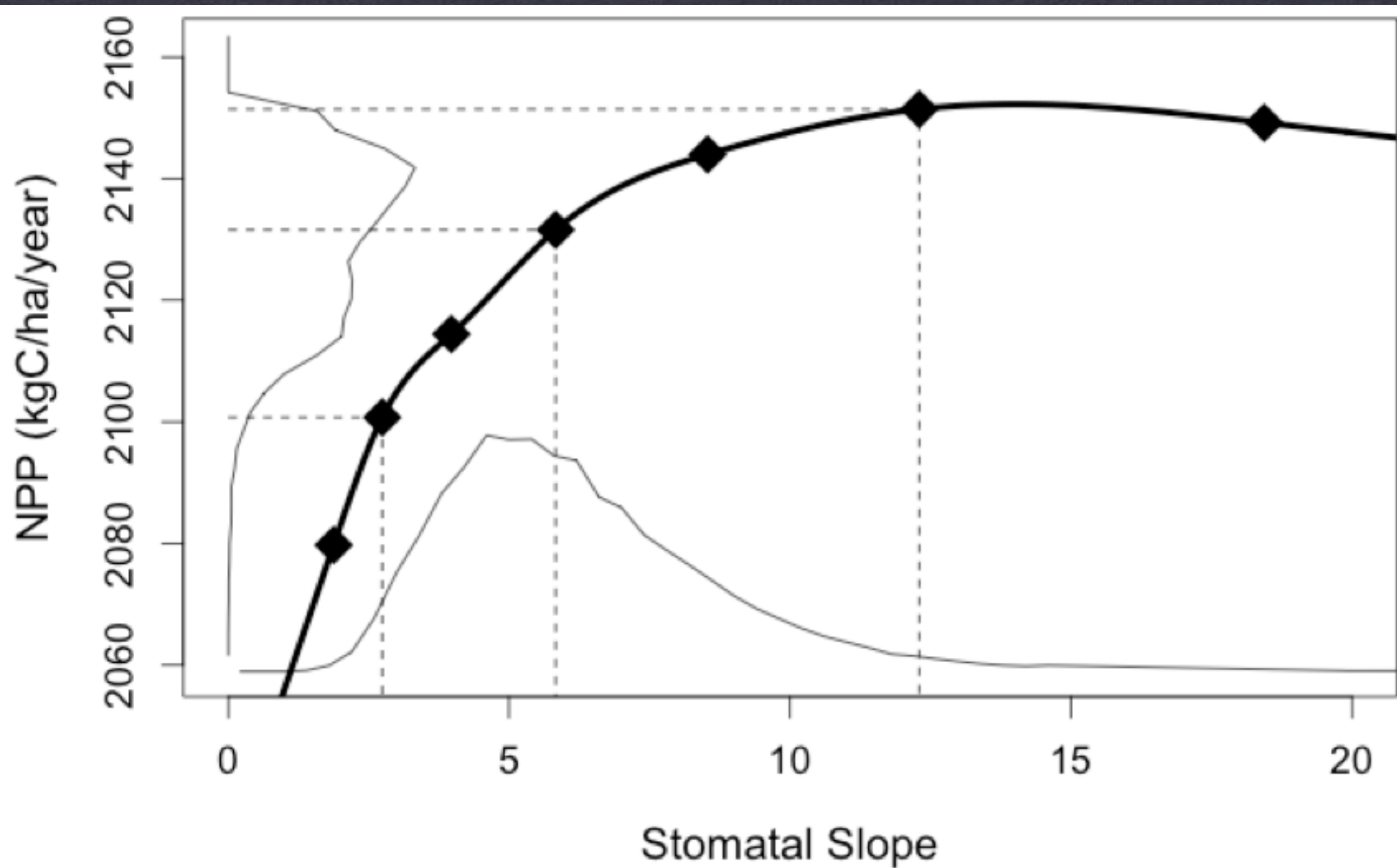
Monte Carlo Sensitivity



Free if you do MC uncertainty propagation or MCMC

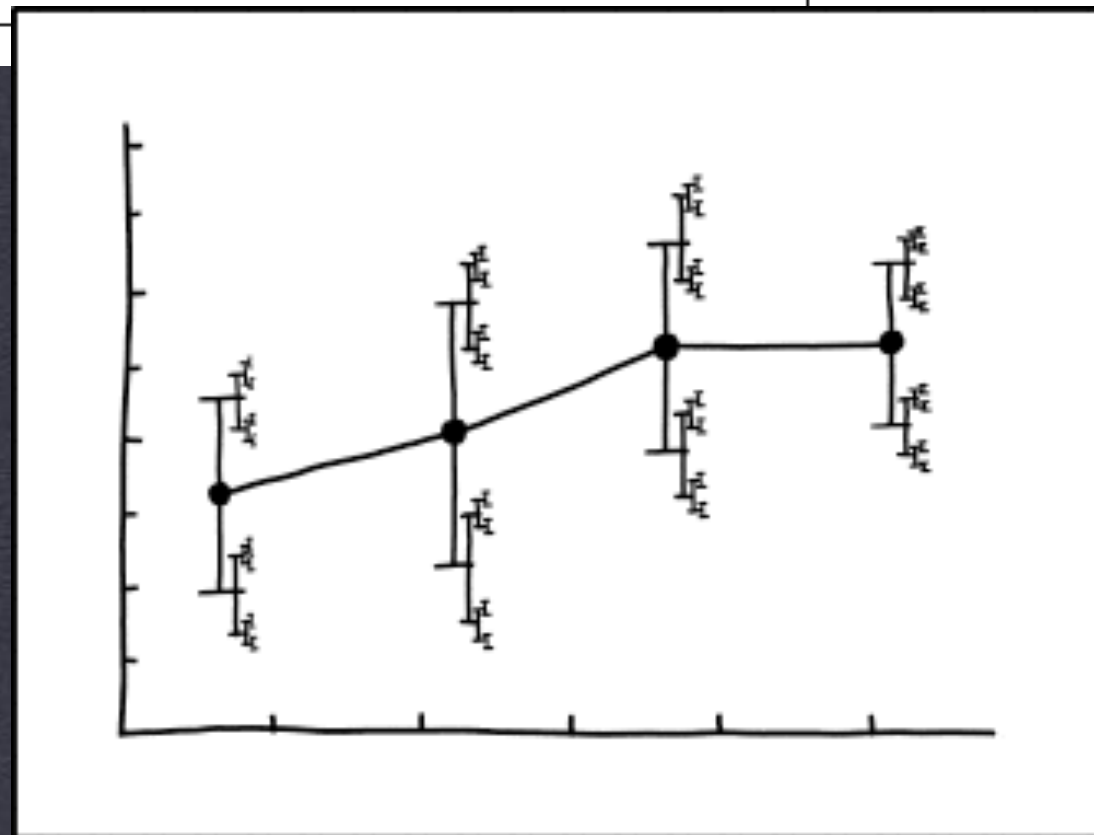


UNCERTAINTY PROPAGATION



UNCERTAINTY PROPAGATION

Approach	Output	
	Distribution	Moments
Analytic	Variable Transform	Analytical Moments Taylor Series
Numeric	Monte Carlo	Ensemble



I DON'T KNOW HOW TO PROPAGATE
ERROR CORRECTLY, SO I JUST PUT
ERROR BARS ON ALL MY ERROR BARS.

Typo in book
(puts Taylor in with Ensemble)

VARIABLE TRANSFORM

$$P_Y[y] = P_\theta[f^{-1}(y)] \cdot \left| \frac{d f^{-1}(y)}{dy} \right|$$

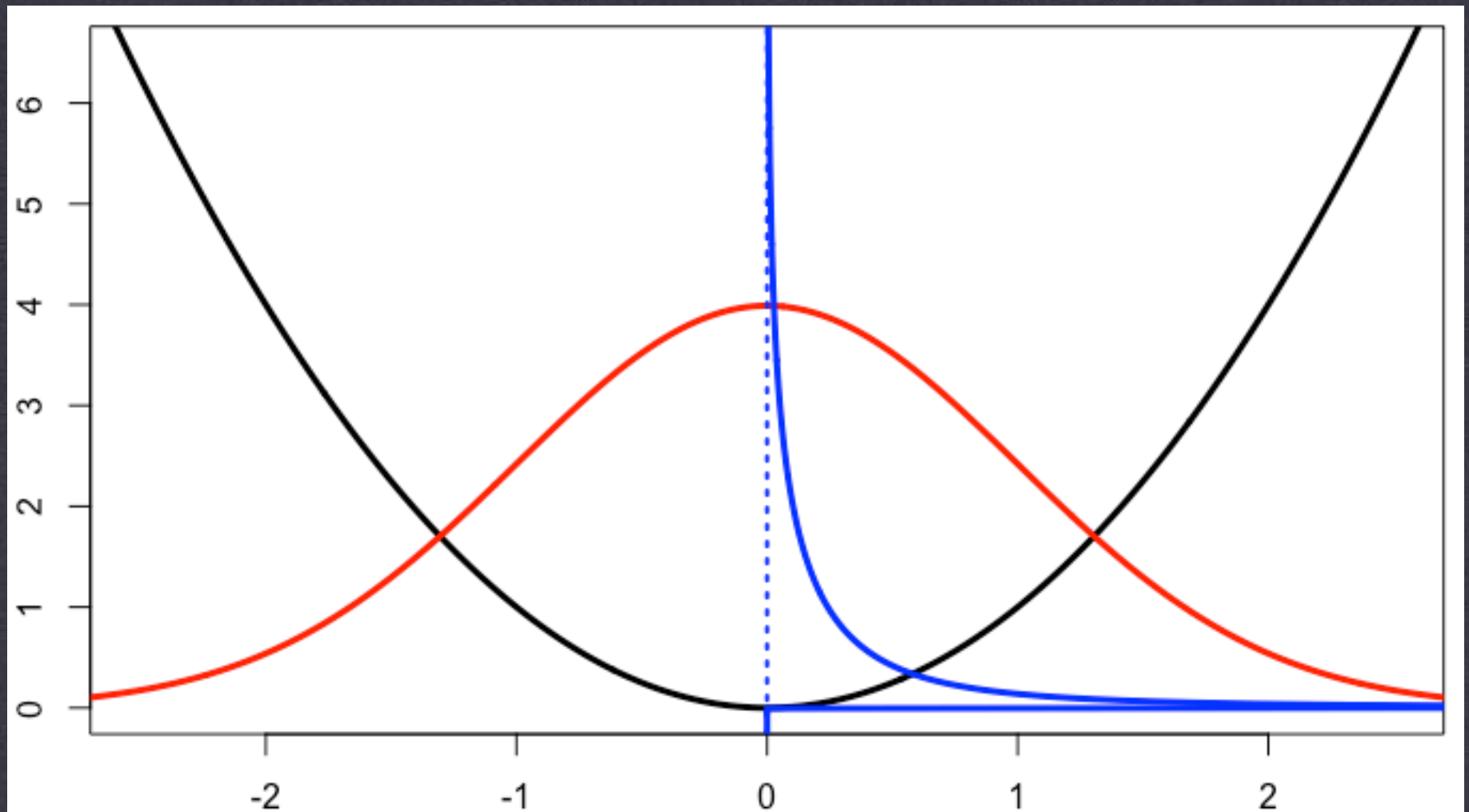
$$X \sim N(0,1)$$

$$Y = X^2$$

$$Y \sim \chi^2$$

$$E[f(\bar{X})] = 0$$

$$E[\overline{f(X)}] = 1$$



Analytical Moments

$$\text{Var}(aX) = a^2 \text{Var}(X)$$

$$\text{Var}(X + b) = \text{Var}(X)$$

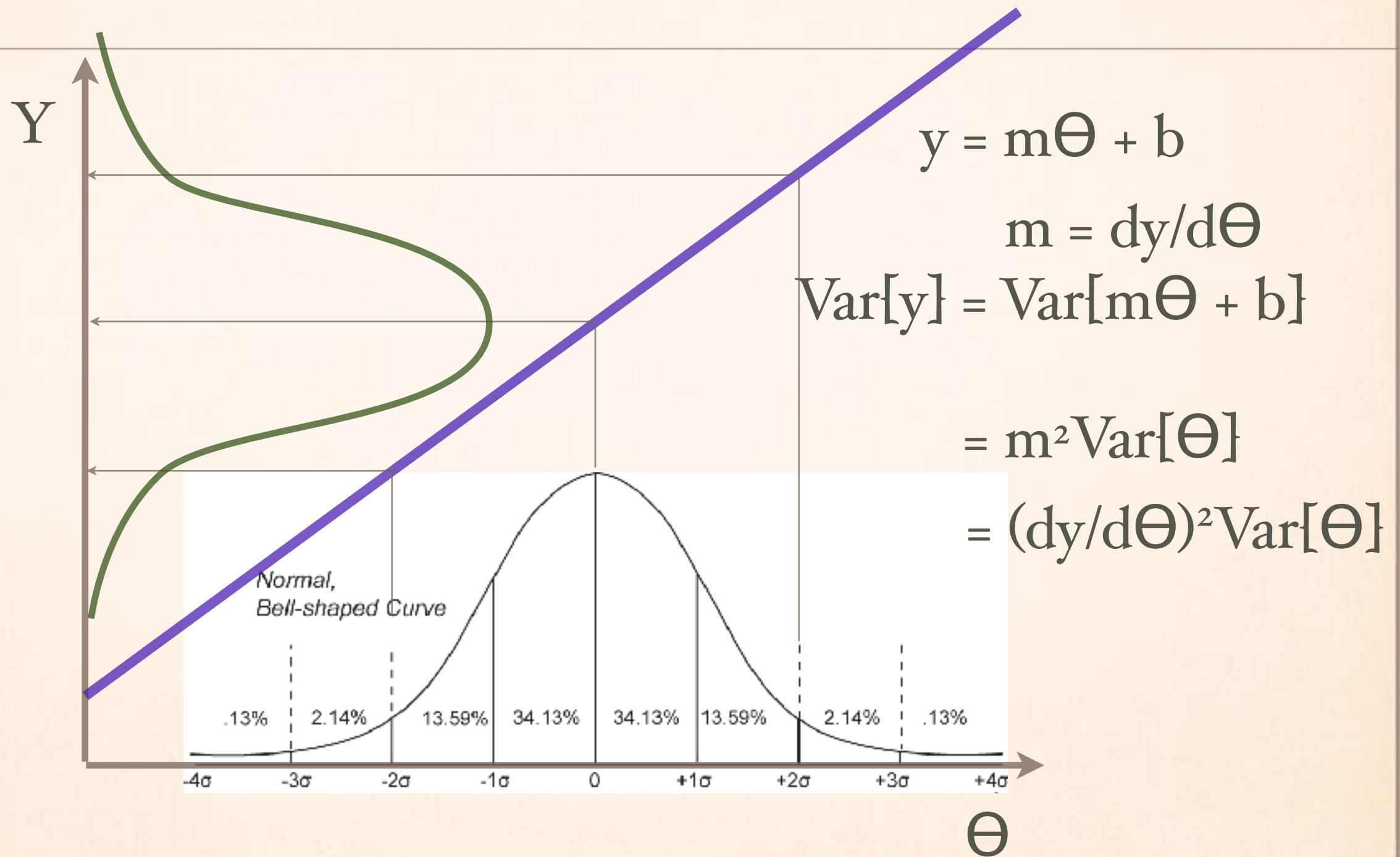
$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

$$\text{Var}(aX + bY) = a^2 \text{Var}(X) + b^2 \text{Var}(Y) + 2ab\text{Cov}(X, Y)$$

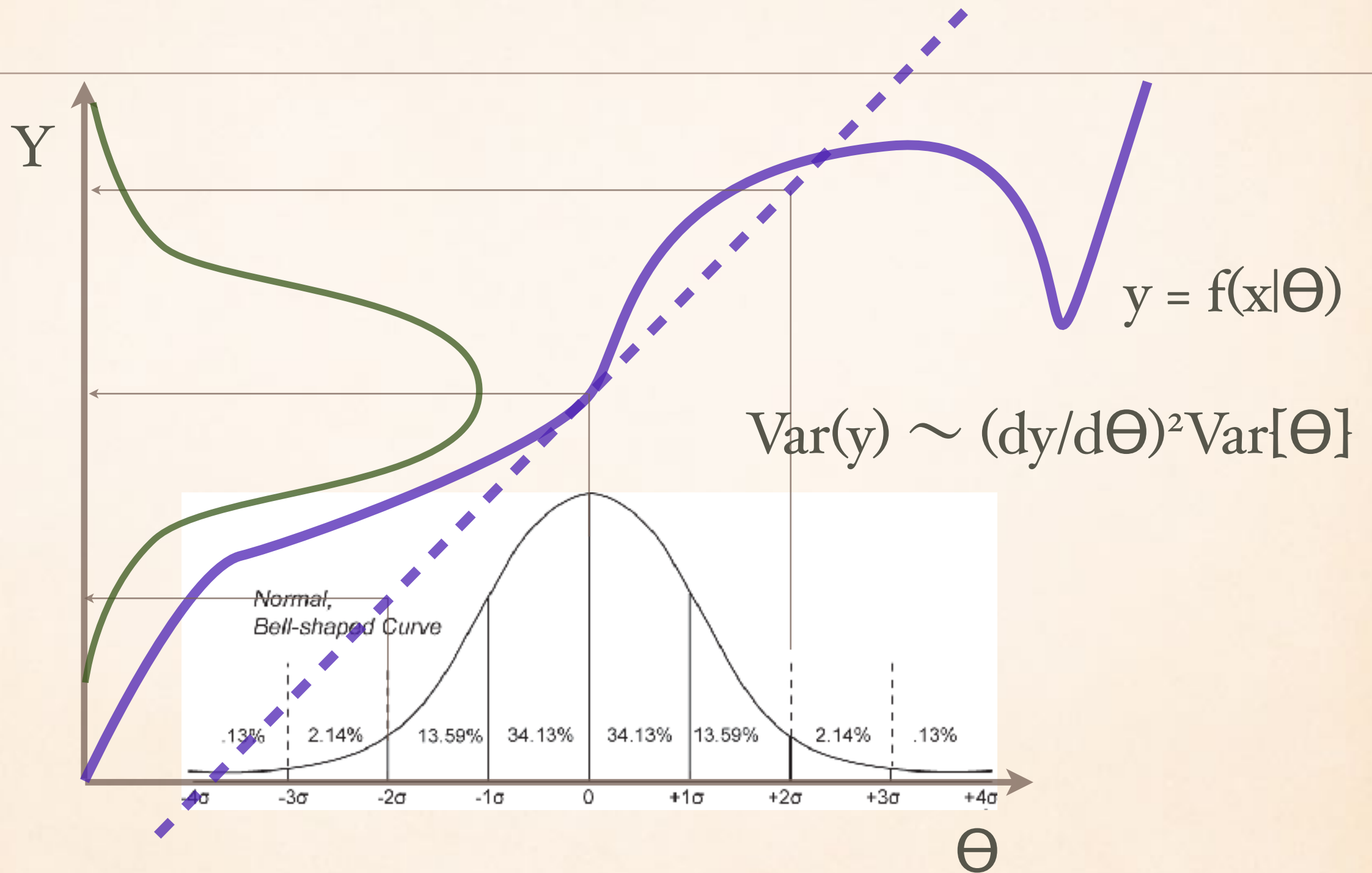
$$\text{Var}\left(\sum X\right) = \sum \text{Var}(X_i) + 2 \sum_{i < j} \text{Cov}(X_i, X_j)$$

$$\text{Var}(X) = \text{Var}(E[X|Y]) + E[\text{Var}(X|Y)]$$

REL'N TO SENSITIVITY



LINEAR APPROX



TAYLOR SERIES

$$\text{Var}[f(x|\theta)] \approx \text{Var}\left[f(x|\bar{\theta}) + \frac{\frac{df}{d\theta}(x|\bar{\theta})}{1!}(\theta - \bar{\theta}) + \dots\right]$$

$$\text{var}[f(x)] \approx \left(\frac{\partial f}{\partial \theta_i}\right)^2 \text{var}[\theta]$$

TAYLOR SERIES

$$\text{Var}[f(x|\theta)] \approx \text{Var}\left[f(x|\bar{\theta}) + \frac{df}{d\theta}(x|\bar{\theta}) (\theta - \bar{\theta}) + \dots\right]$$

$$\begin{aligned} \text{var}[f(x)] \approx & \sum \left(\frac{\partial f}{\partial \theta_i} \right)^2 \text{var}[\theta_i] + \\ & \sum_{i \neq j} \left(\frac{\partial f}{\partial \theta_i} \right) \left(\frac{\partial f}{\partial \theta_j} \right) \text{cov}[\theta_i, \theta_j] \end{aligned}$$

$$Y_{t+1} = f(Y_t, X_t | \theta) + \varepsilon$$

$$\text{Var}[Y_{t+1}] \approx \underbrace{\left(\frac{df}{dY}\right)^2}_{\text{stability}} \underbrace{\text{Var}[Y_t]}_{\substack{\text{IC} \\ \text{uncert}}} + \underbrace{\left(\frac{df}{dX}\right)^2}_{\substack{\text{driver} \\ \text{sens}}} \underbrace{\text{Var}[X]}_{\substack{\text{driver} \\ \text{uncert}}} + \underbrace{\left(\frac{df}{d\theta}\right)^2}_{\substack{\text{param} \\ \text{sens}}} \underbrace{\text{Var}[\theta]}_{\substack{\text{param} \\ \text{uncert}}} + \underbrace{\text{Var}[\varepsilon]}_{\substack{\text{process} \\ \text{error}}}$$

COV & SCALING

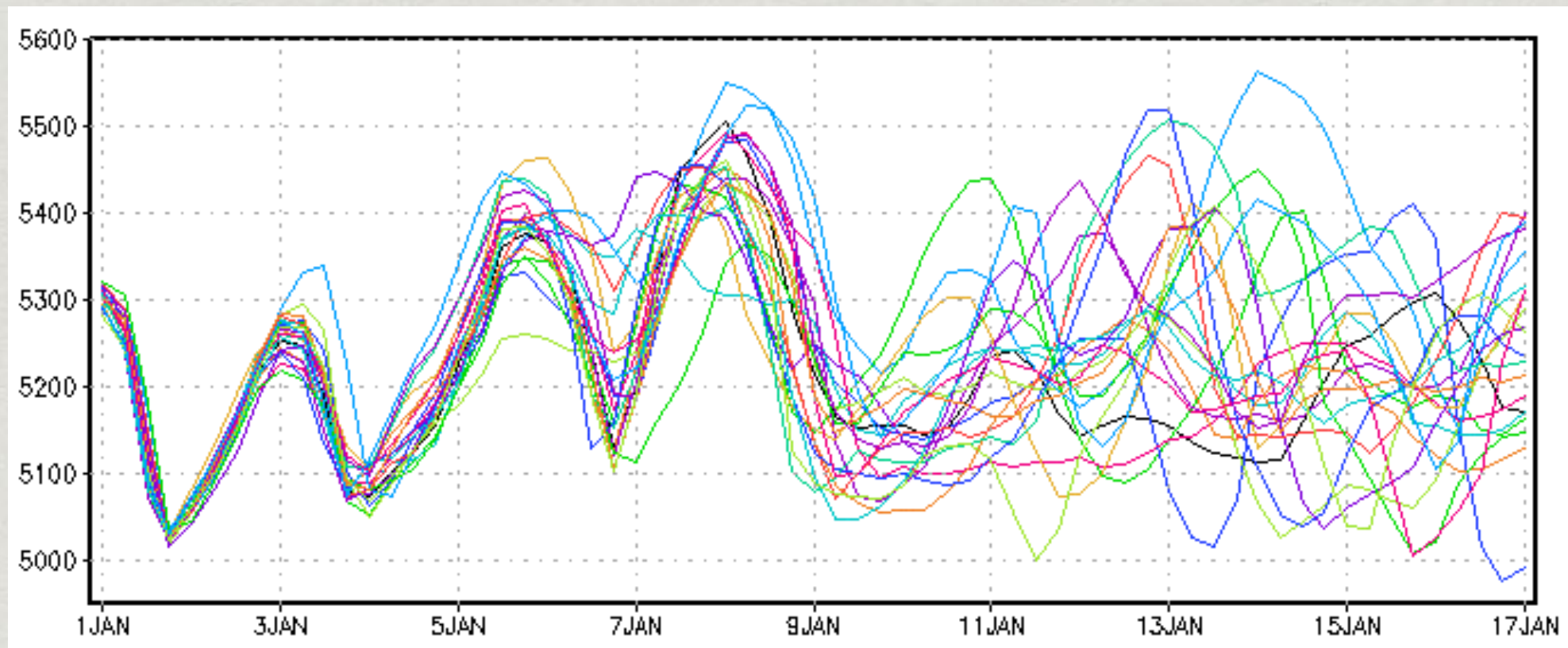
- Scaling very dependent on spatial and temporal auto- & cross-correlation

$$\sum \sum \frac{\partial f}{\partial X_i} \frac{\partial f}{\partial X_j} COV[X_i, X_j]$$

UNCERTAINTY PROPAGATION

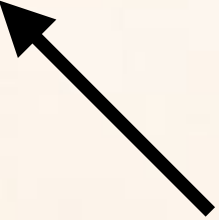
Approach	Output	
	Distribution	Moments
Analytic	Variable Transform	Analytical Moments Taylor Series
Numeric	Monte Carlo	Ensemble

Numerical Approximation

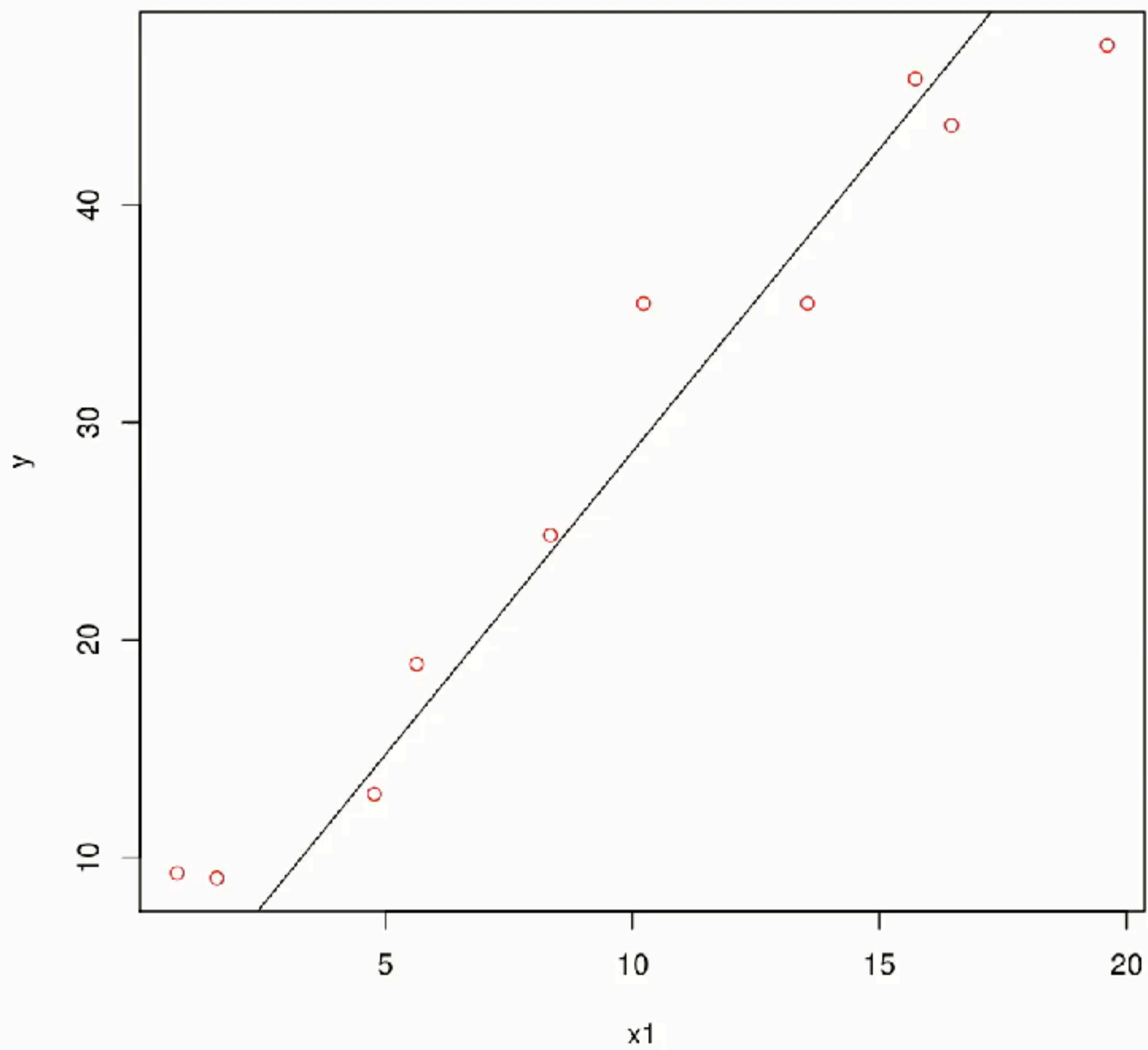


- * Monte Carlo Simulation --> Distribution
- * Ensemble Analysis --> Moments


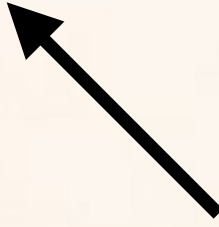
MONTE CARLO UNCERTAINTY

- ❖ for (i in 1:n)
 - ❖ draw random values from distributions
 - ❖ run model
 - ❖ save results
 - ❖ summarize distributions
- Already have this from MCMC!
- 

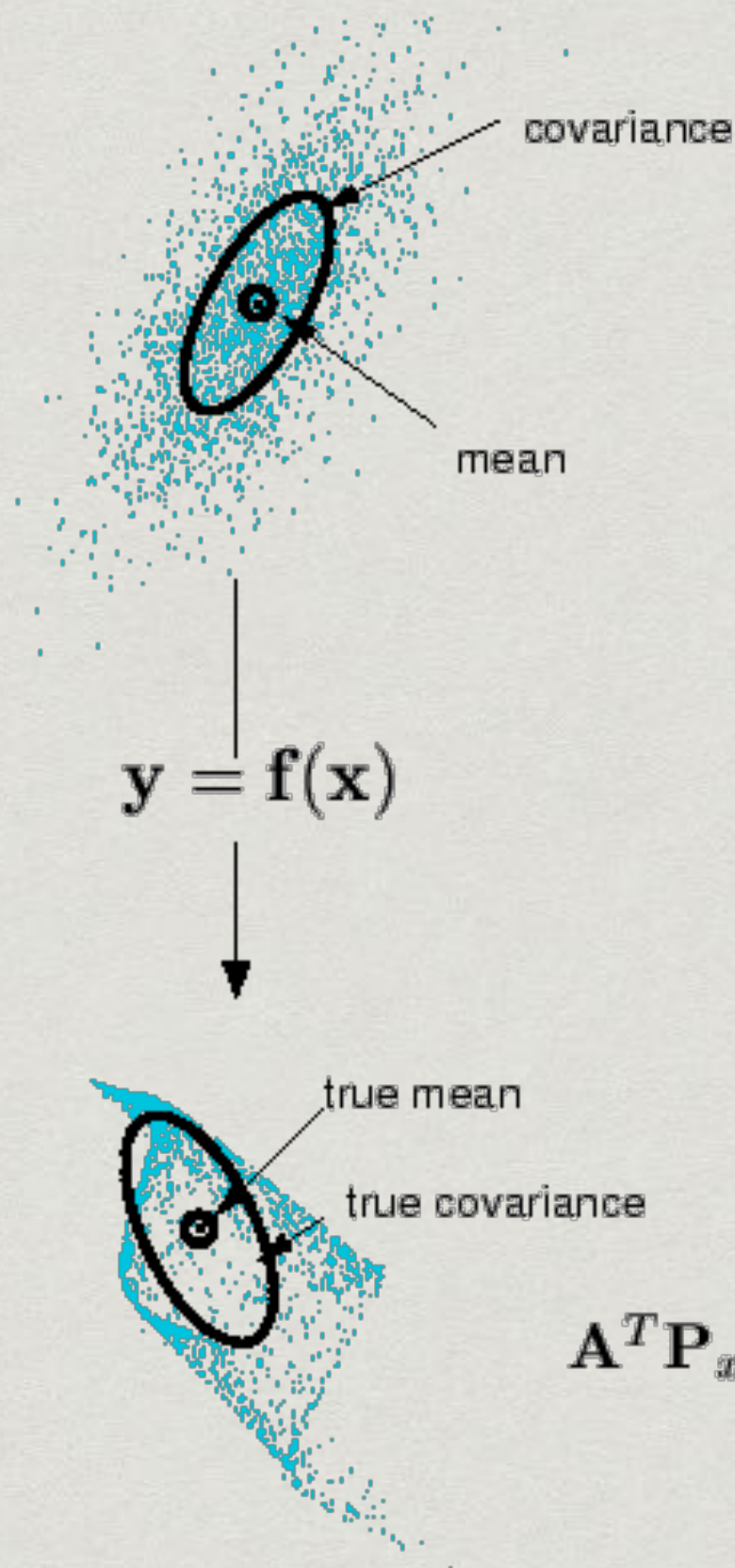
$n = 1$



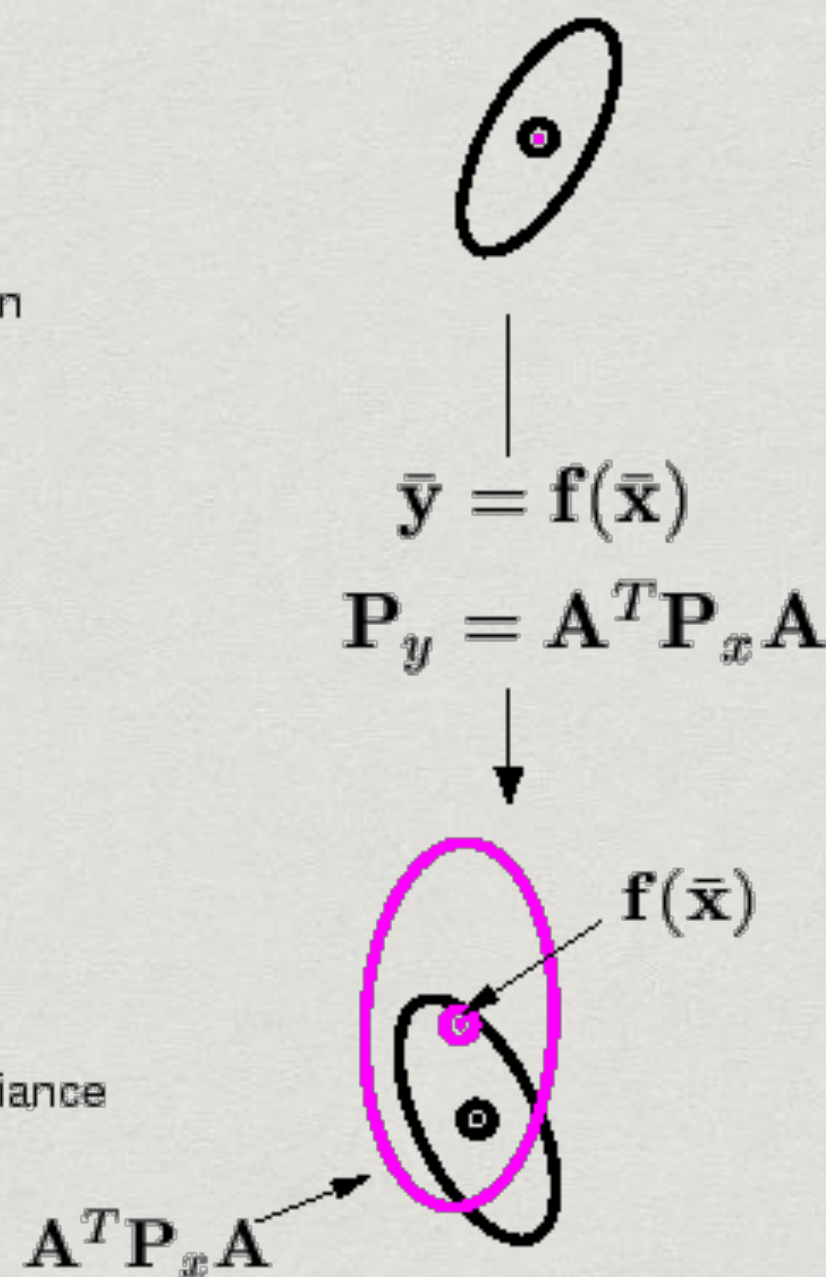
ENSEMBLE UNCERTAINTY

- ❖ for (i in 1:n)  **Requires smaller N to estimate moments
than to approximate full PDF**
- ❖ draw random values from distributions
- ❖ run model  Already have this from MCMC!
- ❖ save results
- ❖ **Fit PDF to results**
- ❖ **Use PDF for intervals, etc.**

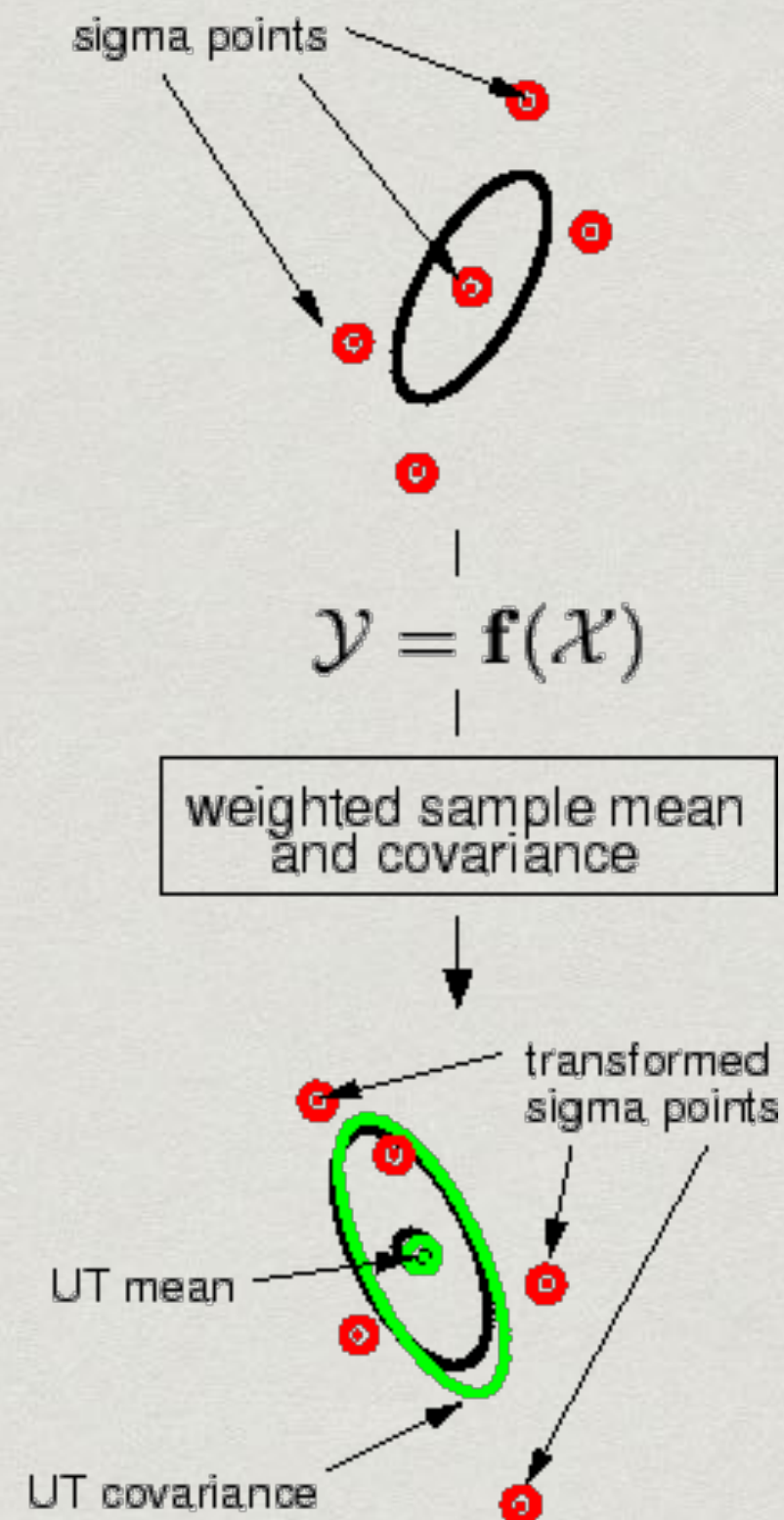
Monte Carlo



Taylor Series



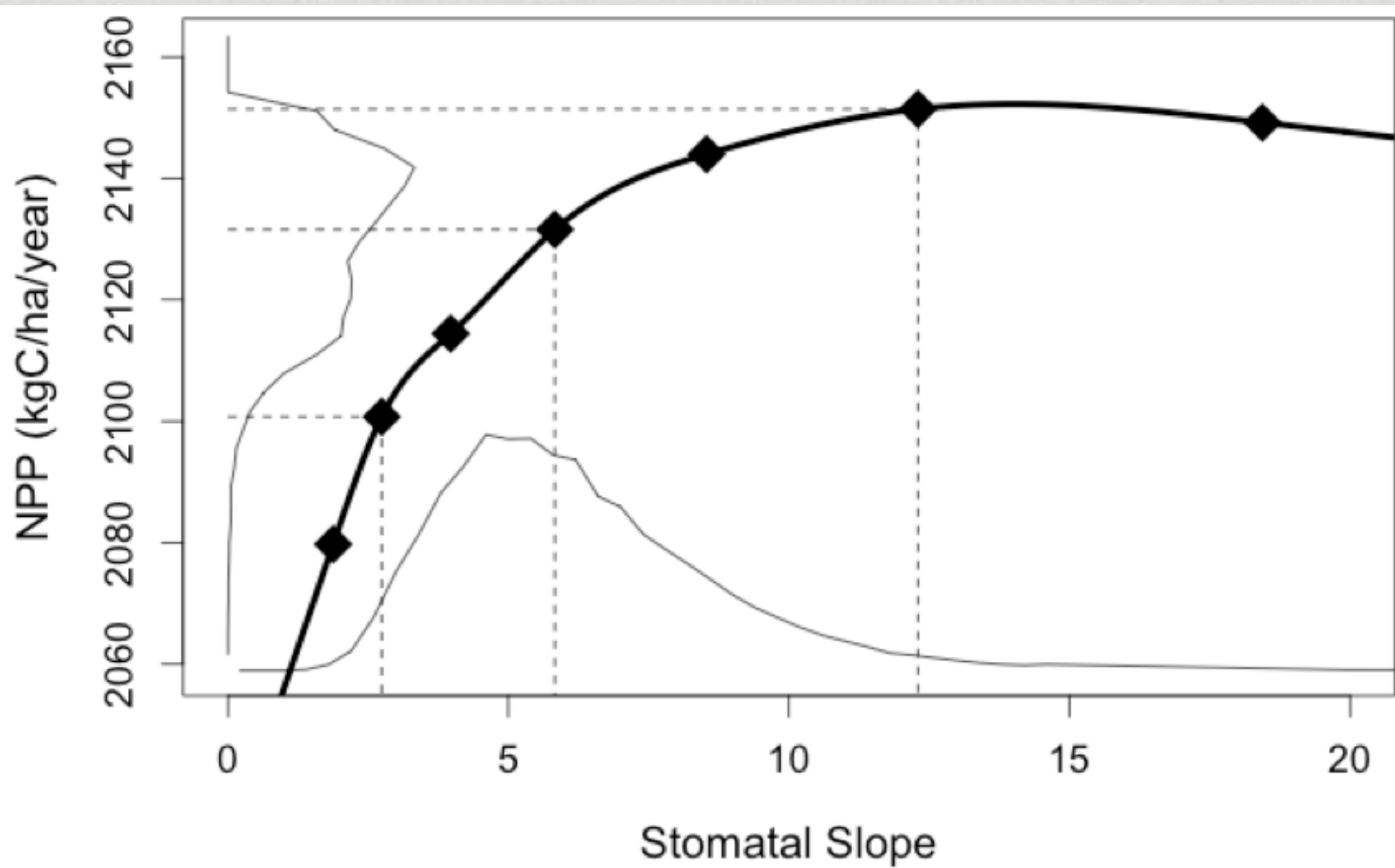
Unscented Transform



UNCERTAINTY PROPAGATION

Approach	Output	
	Distribution	Moments
Analytic	Variable Transform	Analytical Moments Taylor Series
Numeric	Monte Carlo	Ensemble

Uncertainty Analysis

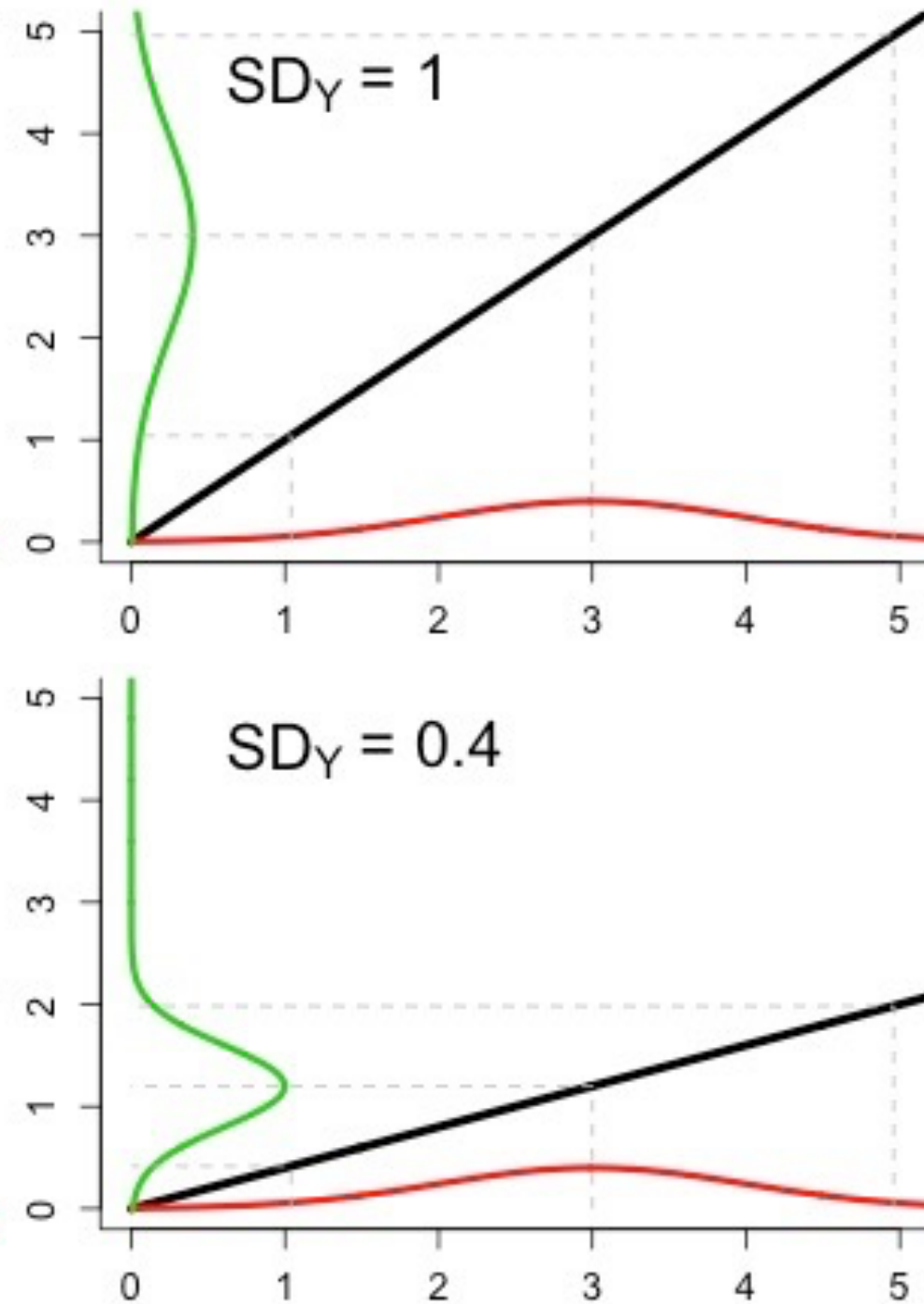
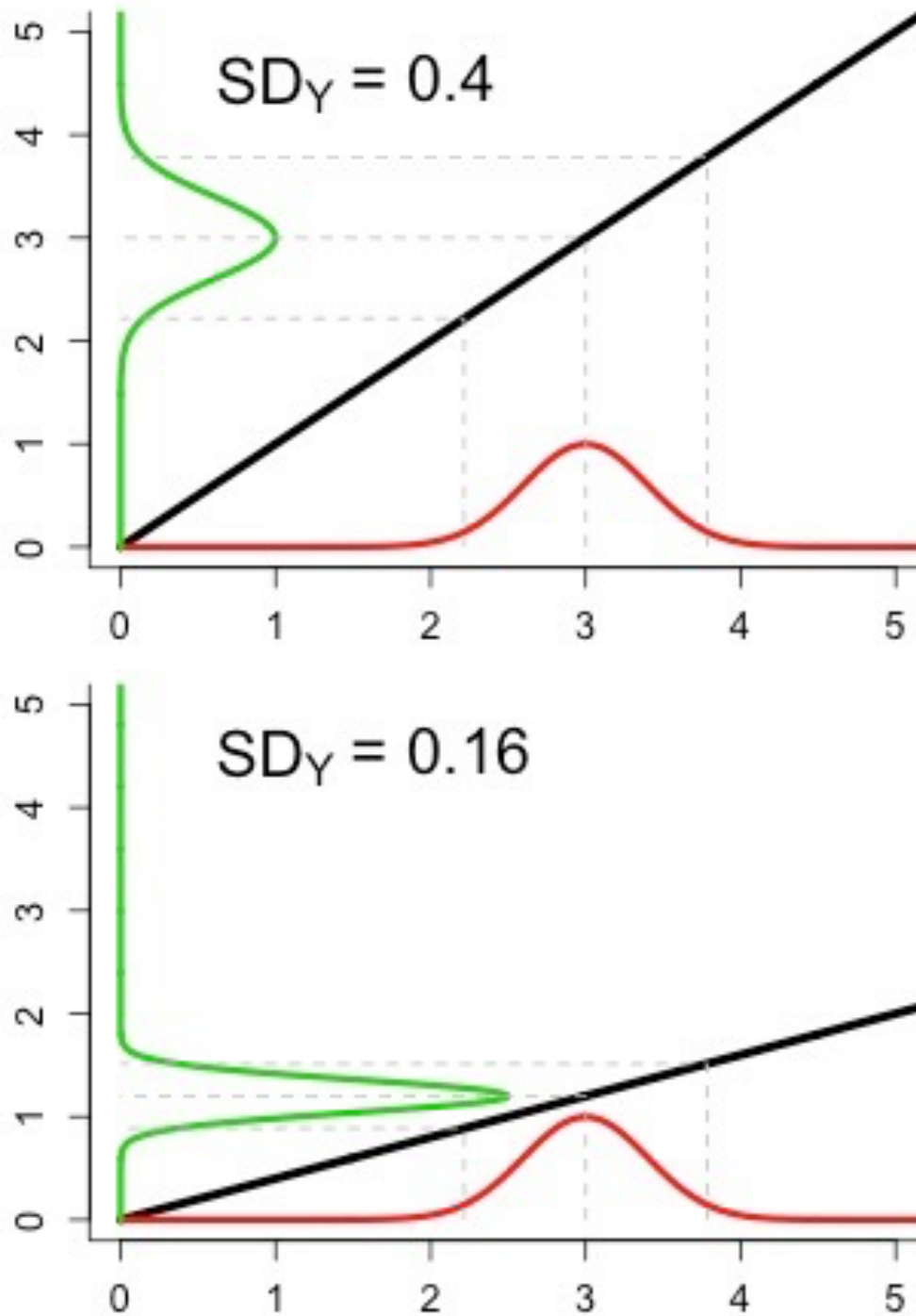


PARAMETER UNCERTAINTY

LOW

HIGH

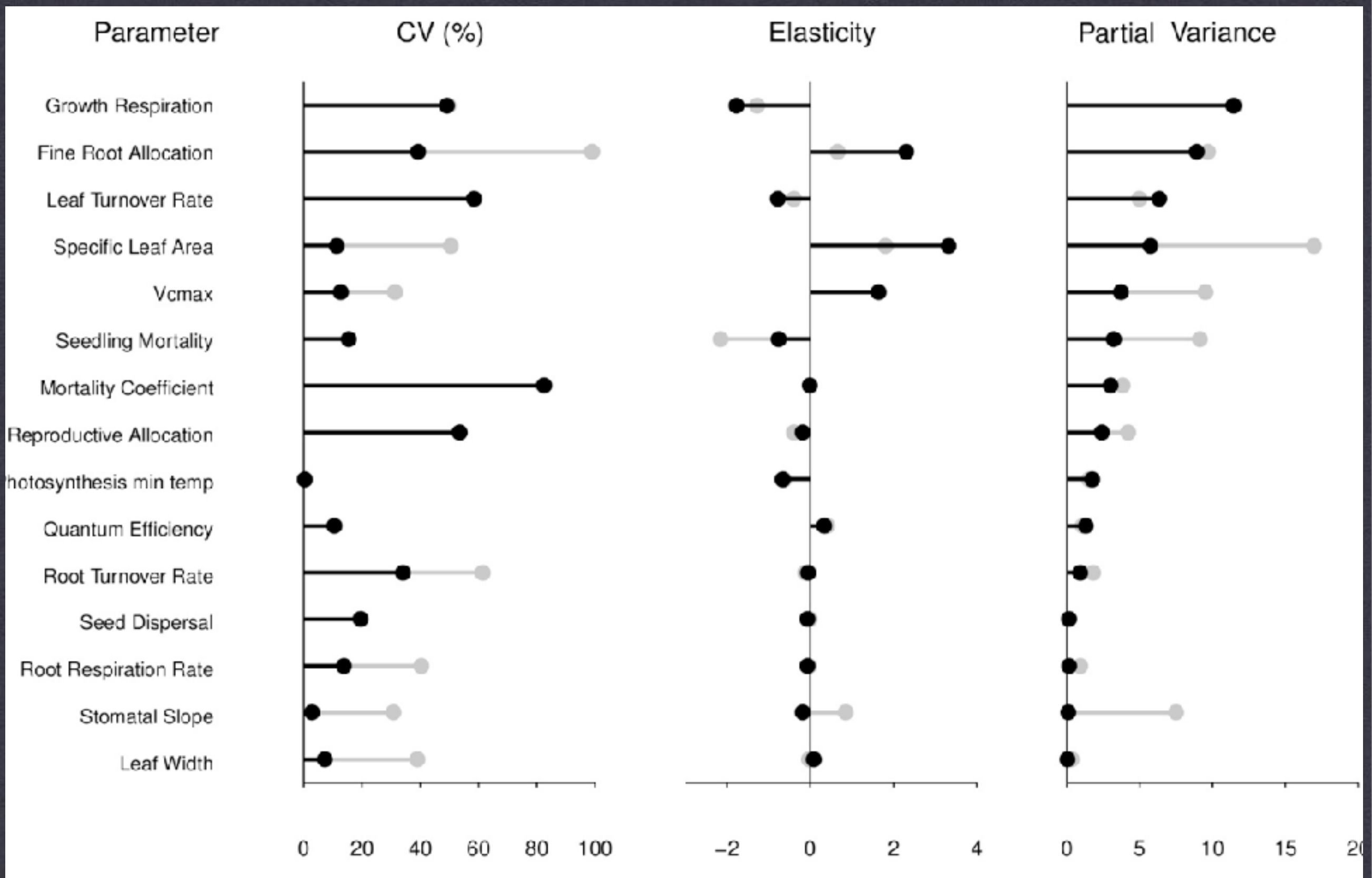
PREDICTIVE UNCERTAINTY



SENSITIVITY

HIGH

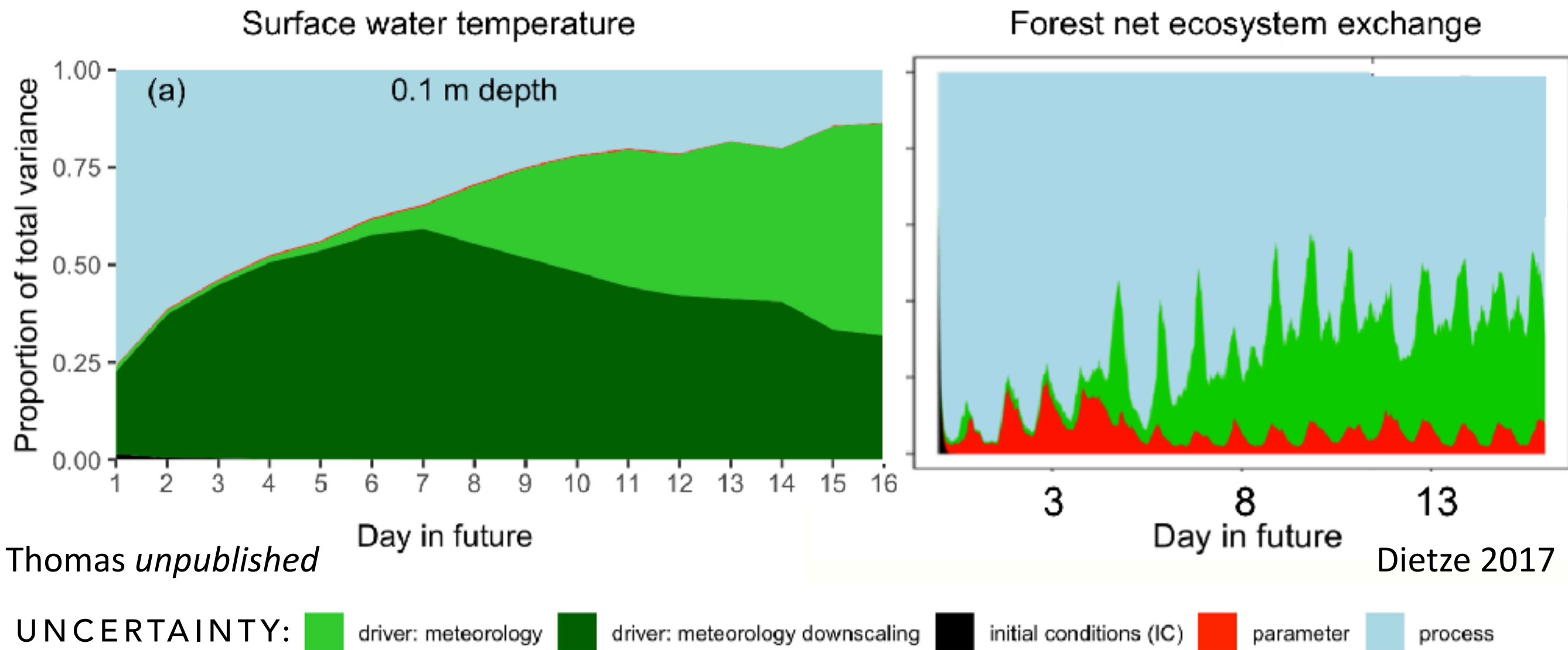
LOW



VARIANCE DECOMPOSITION

SWITCHGRASS YIELD, CENTRAL ILLINOIS

How do the drivers of forecast uncertainty vary across ecological system?



Tools for model-data feedbacks

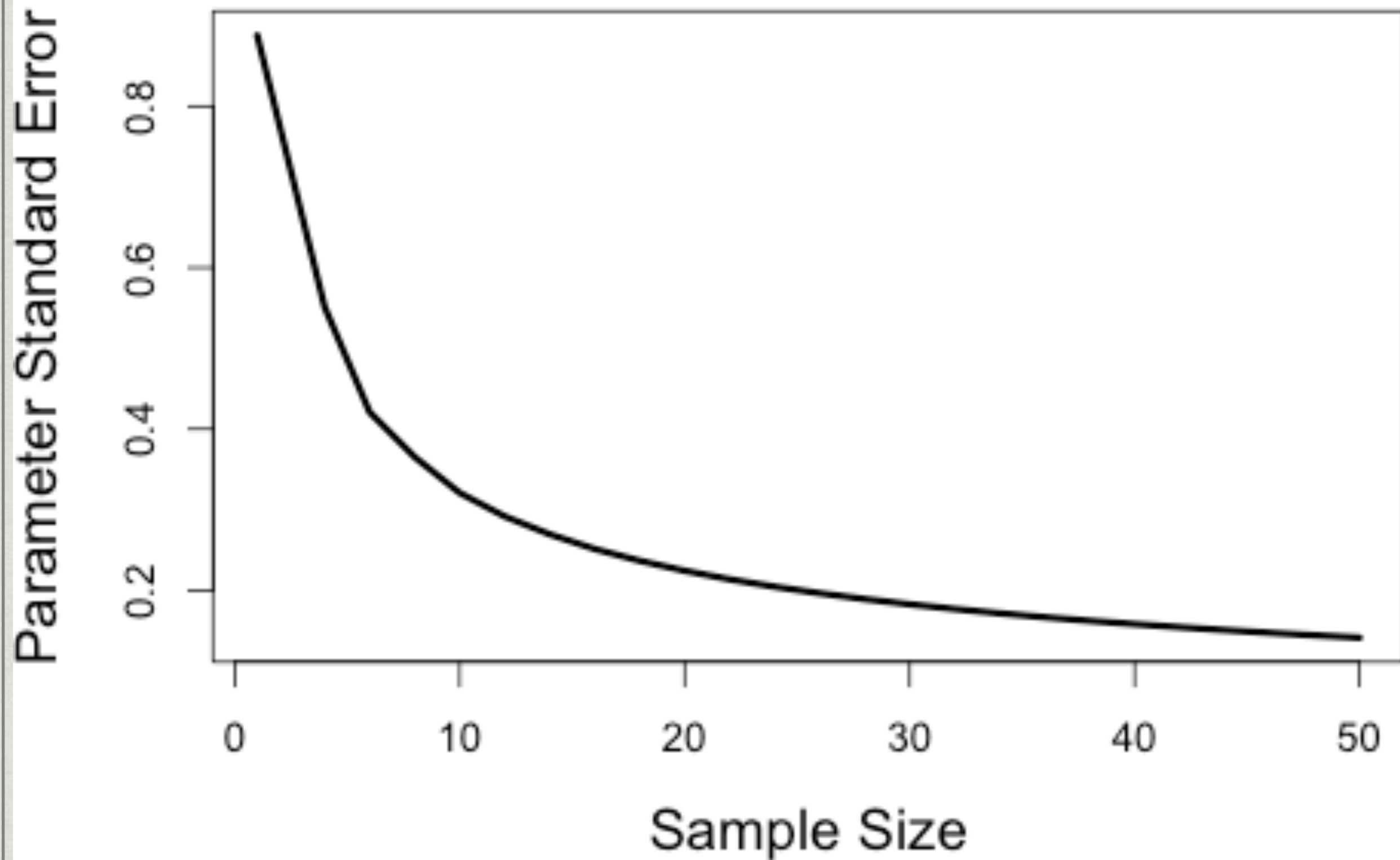
- ✱ **Power analysis**

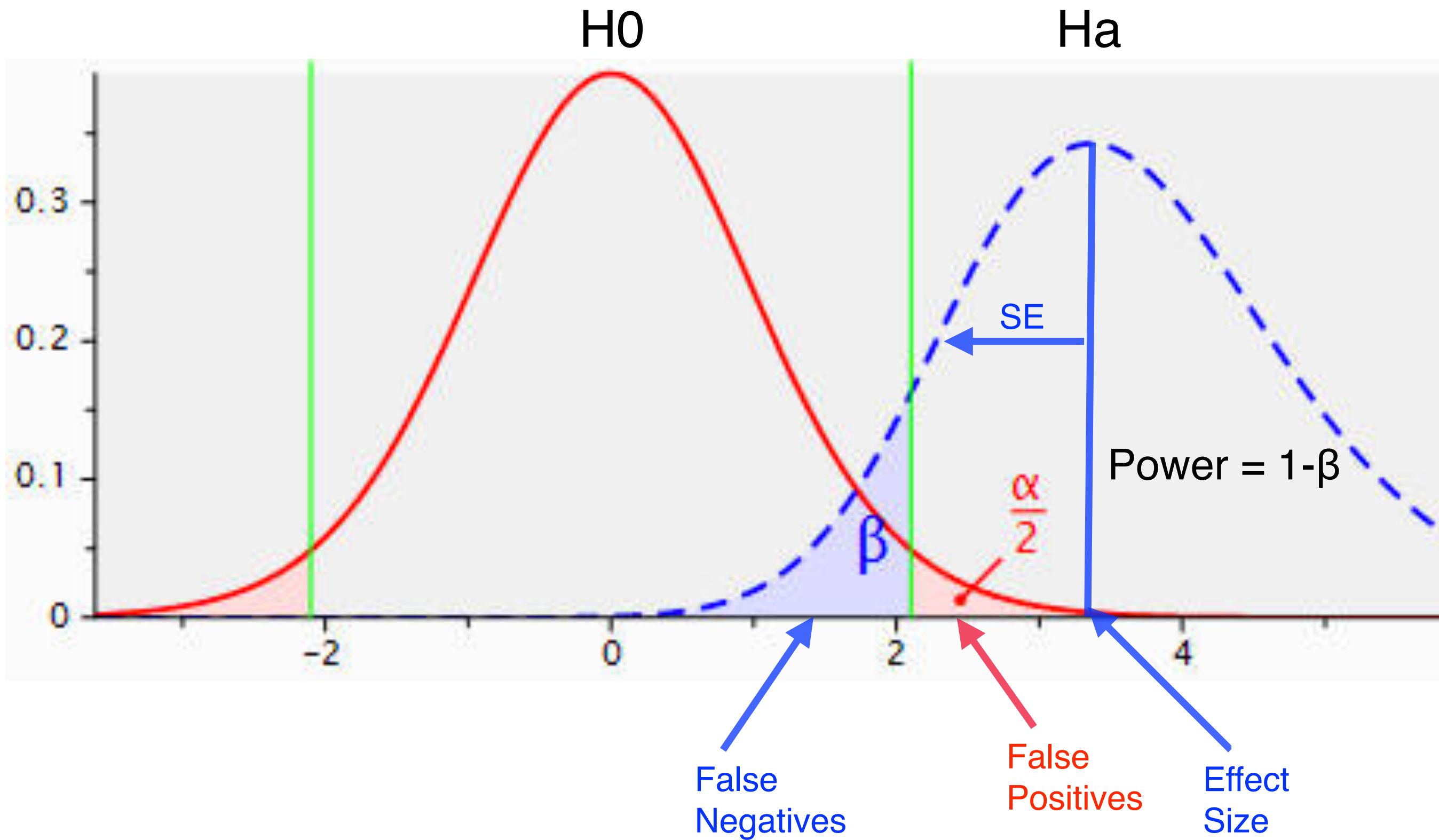
- ✱ Sample size needed to detect an effect size
- ✱ Minimum effect size detectable given a size

- ✱ **Observational design**

- ✱ What do I need to measure?
- ✱ Where should I collect new data?
- ✱ How do I gain new info most efficiently?

$$SE \propto 1/\sqrt{n}$$





$$\text{Power} = f(\text{effect size}, SE)$$

Pseudo-data simulation

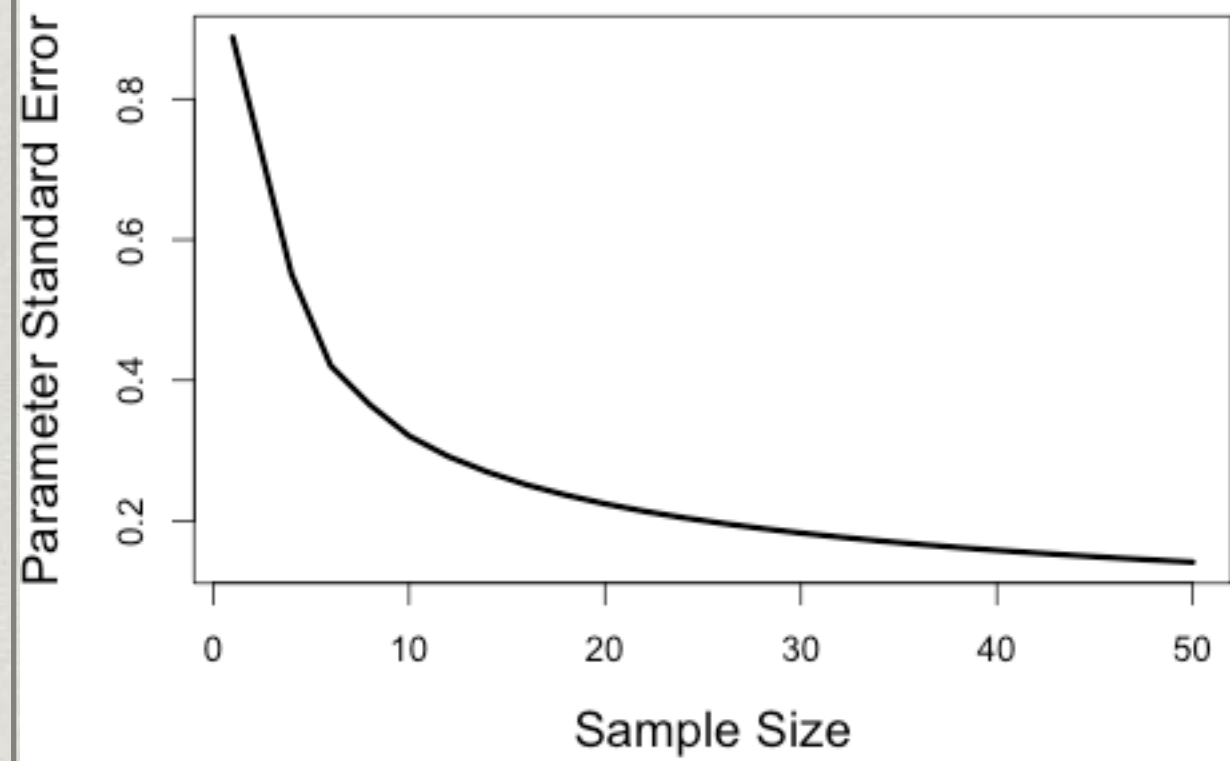
for(k in 1:M)

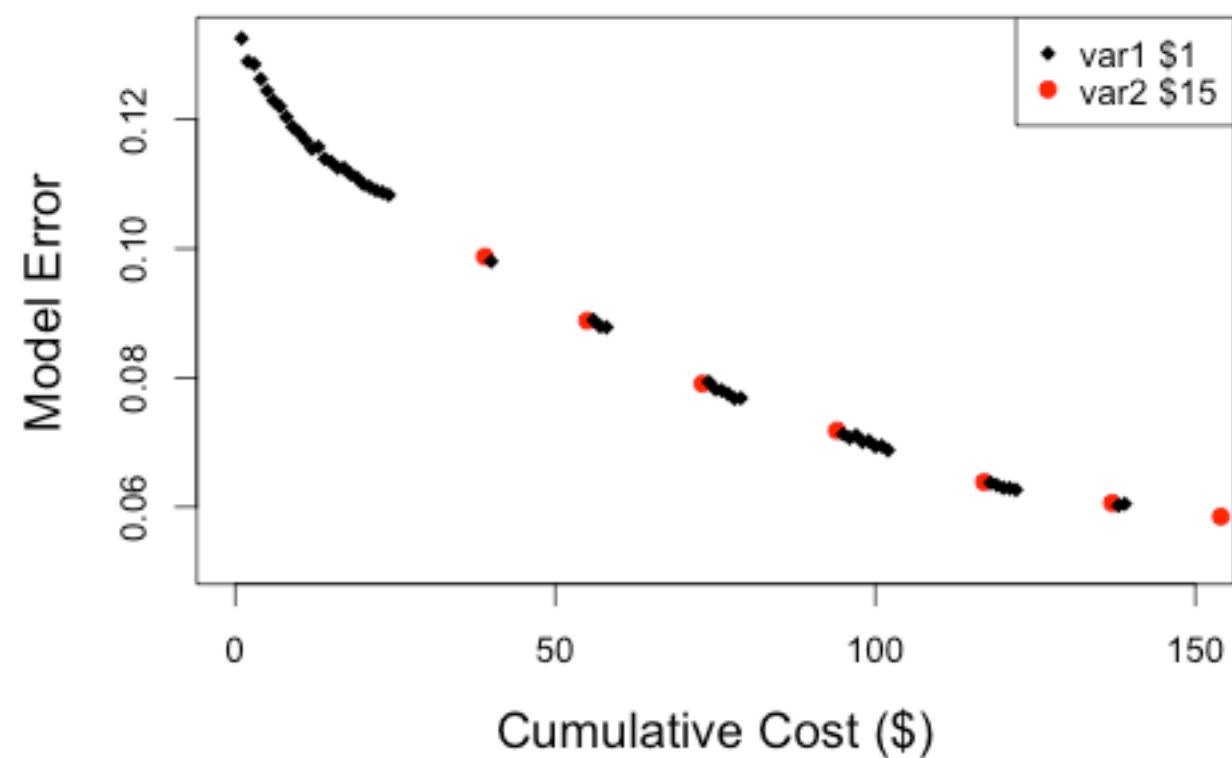
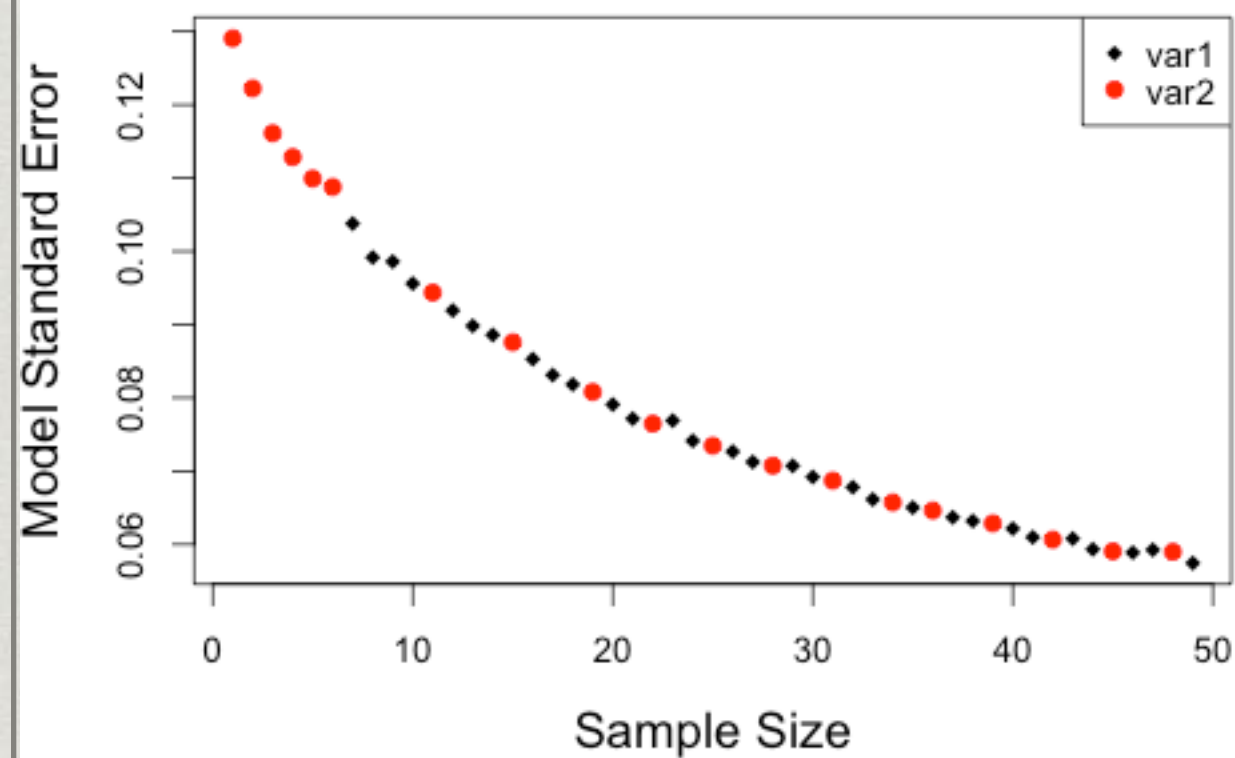
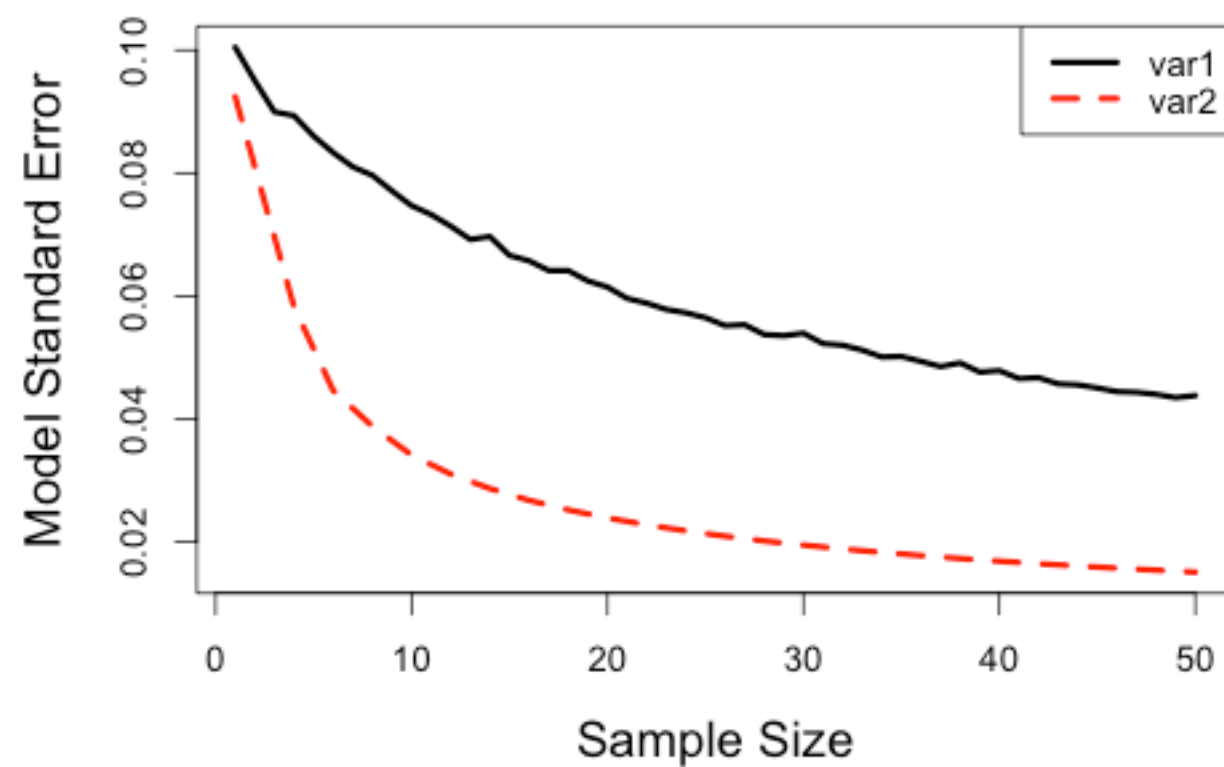
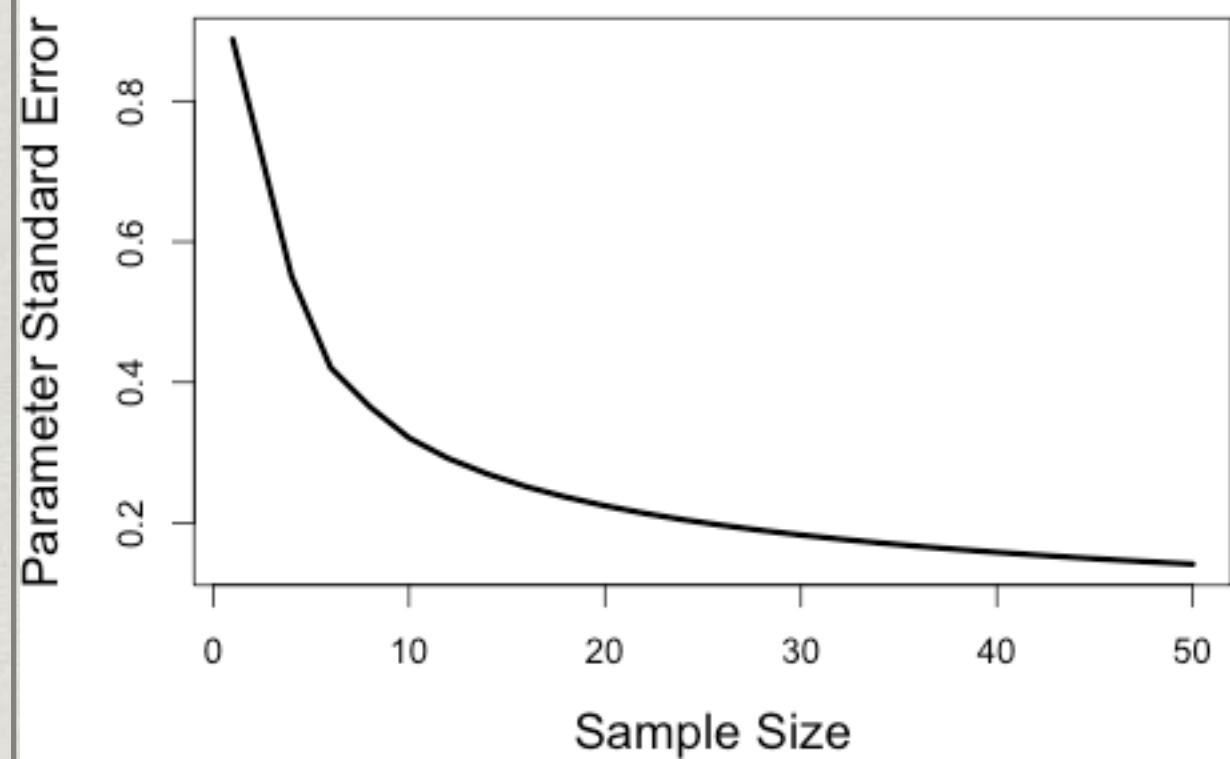
Draw random data of size N

Fit model

Save Parameter(S) of interest

- * Nonparameteric bootstrap: resample data
- * Parameteric bootstrap: assume param, sim data
- * Embed in overall loop over N or different effect sizes
- * Summarize distribution





Observing System Simulation Experiments

- * Simulate “true” system
 - * Simulate pseudo-observations
 - * Assimilate pseudo-observations
 - * Assess impact on estimates
-
- **Augment an existing network**
 - **Additional locations**
 - **New Sensors**
 - **Common in Weather, Remote Sensing, Oceanography**