

# **Disentangling Trainability and Generalization in Deep Neural Networks**

**Lechao Xiao,   Jeffrey Pennington,   Samuel Schoenholz**

# Notation

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$$\mathbf{z}^{(l+1)}(\mathbf{x}) = \frac{\sigma_w}{\sqrt{d_l}} \mathbf{W}^{(l+1)} \phi \left( \mathbf{z}^{(l)}(\mathbf{x}) \right) + \sigma_b \mathbf{b}^{(l+1)}$$

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- We can control **variances**  $\sigma_w$ ,  $\sigma_b$  and study how the network behaves when varying these

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- Stack features and targets into matrices:

$$\mathbf{X} \in \mathbb{R}^{n \times d_0} \text{ and } \mathbf{y} \in \mathbb{R}^n$$

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- If network has **multiple** outputs:

$$f_{\theta,i} \perp f_{\theta,j}$$

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- **Infinite-width** limit:

$$\hat{\Theta}_t^{(L)}(\mathbf{x}, \mathbf{x}') \xrightarrow{d_1, \dots, d_L \rightarrow \infty} \Theta^{(L)}(\mathbf{x}, \mathbf{x}')$$

deterministic and  
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- Closed-form** expression for NN at  $t = \infty$  and squared loss:

$$\begin{aligned} f_{\infty}(\mathbf{x}) &= \left( \Theta^{(L)}(\mathbf{x}, \mathbf{X}) \right)^T \left( \Theta^{(L)}(\mathbf{X}, \mathbf{X}) \right)^{-1} \mathbf{y} \\ &= P(\Theta^{(L)}) \mathbf{y} \end{aligned}$$

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- We are assuming  $f_0(\mathbf{x}) = 0$  here

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- What happens if we let **depth**  $L$  go to infinity as well?



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**Two** kinds of limits:

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- Take width limit **first** and **then** consider depth limit
- Two **different** results!

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$\implies$  **Feature-learning** happening!

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$$P(\Theta^{(L)}) = \left( \Theta^{(L)}(\mathbf{x}, \mathbf{X}) \right)^T \left( \Theta^{(L)}(\mathbf{X}, \mathbf{X}) \right)^{-1}$$



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- **Incremental:**
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- Connect **chaotic** and **ordered** regimes with generalization and trainability
- How to characterize **generalization** and **trainability**?

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- Recall that we have closed-form training dynamics:

$$f_t(\mathbf{x}) = \Theta^{(L)}(\mathbf{x}, \mathbf{X}) \left( \Theta^{(L)}(\mathbf{X}, \mathbf{X}) \right)^{-1} \left( \mathbb{1} - e^{-t\eta \Theta^{(L)}(\mathbf{X}, \mathbf{X})} \right) \mathbf{y}$$

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- Diagonalize** NTK:  $\Theta^{(L)}(\mathbf{X}, \mathbf{X}) = \mathbf{U}^T \mathbf{\Lambda} \mathbf{U}$  which leads to

$$\overset{\text{rotated predictions}}{\tilde{f}_{t,i}(\mathbf{X})} = \left( \mathbb{1} - e^{-t\eta \lambda_i} \right) \tilde{y}_i \overset{\text{rotated labels}}{\leftarrow}$$

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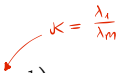
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$\implies$  **Cannot** learn training set

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- Data-dependence of course **not** best measure to study generalization performance

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- Study trajectory of  $P(\Theta^{(l)})$  to understand generalization

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- Introduce  $c_{ab}^{(l)} = \frac{q_{ab}^{(l)}}{\sqrt{q_{aa}^{(l)} q_{bb}^{(l)}}} = \frac{q_{ab}^{(l)}}{q^*}$  and write off-diagonal terms:

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 &= \sigma_w^2 \int \phi(\sqrt{q^*} z_1) \phi\left(\sqrt{q^*} (c_{ab}^{(l)} z_1 + \sqrt{1 - (c_{ab}^{(l)})^2} z_2)\right) \mathcal{D}z_1 \mathcal{D}z_2 + \sigma_b^2
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*Gaussian measure:  $\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}z^2} dz$*

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$$f(c) = \frac{1}{q^*} \left( \sigma_w^2 \int \phi(u_1(z_1)) \phi(u_2(z_1, z_2, c)) \mathcal{D}z_1 \mathcal{D}z_2 + \sigma_b^2 \right)$$



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Two outputs thus become more and more **dissimilar** to each other

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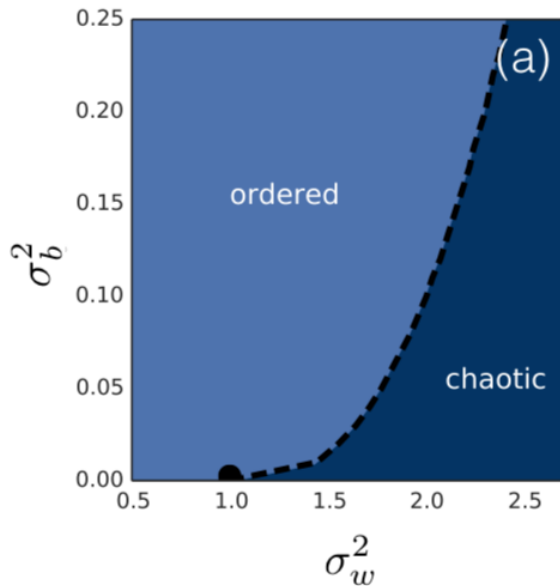
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- Analyze the limits in the two different regimes

## An Example





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- **Hence:**  $\epsilon_{ab}^{(l+1)} \approx \sigma_w^2 \dot{\mathcal{T}} (q_{ab}^*) \epsilon_{ab}^{(l)} = f'(c^*)^{l+1} \epsilon_{ab}^{(0)}$
- **Similarly:**  $\delta_{ab}^{(l+1)} \approx f'(c^*)^{l+1} \left( \delta_{ab}^{(0)} + l \left( 1 + \frac{f''(c^*)}{f'(c^*)} p_{ab}^* \right) \epsilon_{ab}^{(0)} \right)$

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*Note: In the original image, red arrows point from the  $p_{aa}^{(l)}$  terms in the third and fourth lines to infinity symbols ( $\infty$ ), indicating the limit process.*

- We hence get the trivial prediction **independent** of the data!

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 $\implies$  Network **fails** to generalize

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$$f : GL_n(\mathbb{R}) \rightarrow GL_n(\mathbb{R}), \quad \mathbf{A} \mapsto f(\mathbf{A}) = \mathbf{A}^{-1}$$

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- Write  $\Theta^{(l)}(\mathbf{X}, \mathbf{X}) = p^* \mathbf{1}\mathbf{1}^T + l(f'(1))^l \mathbf{A}^{(l)}(\mathbf{X}, \mathbf{X})$

• Width correction matrix  
that depends on the data  
•  $A^{(l)}(\mathbf{X}, \mathbf{X}) \rightarrow A^{(l)}(\mathbf{X}, \mathbf{X})$

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 \left( \Theta^{(j)}(\mathbf{X}, \mathbf{X}) \right)^{-1} &= \left( p^* \mathbf{1} \mathbf{1}^T + \lambda \mathbf{A}_{\mathbf{X}}^{(j)} \right)^{-1} \\
 &= \lambda^{-1} \left( \mathbf{A}_{\mathbf{X}}^{(j)} \right)^{-1} - \frac{\lambda^{-2} \left( \mathbf{A}_{\mathbf{X}}^{(j)} \right)^{-1} \mathbf{1} \mathbf{1}^T \left( \mathbf{A}_{\mathbf{X}}^{(j)} \right)^{-1}}{\frac{1}{p^*} + \lambda^{-1} \mathbf{1}^T \left( \mathbf{A}_{\mathbf{X}}^{(j)} \right)^{-1} \mathbf{1}}
 \end{aligned}$$

$(\mathbf{A} + \mathbf{u} \mathbf{v}^T)^{-1} = \mathbf{A}^{-1} + \frac{\mathbf{A}^{-1} \mathbf{u} \mathbf{v}^T \mathbf{A}^{-1}}{1 + \mathbf{v}^T \mathbf{A}^{-1} \mathbf{u}}$

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 &= \lambda^{-1} \left( \left( \mathbf{A}_X^{(j)} \right)^{-1} - \hat{p} \mathbf{a} \mathbf{a}^T \right)
 \end{aligned}$$

Handwritten notes:

- $(\tilde{A} + uv^T)^{-1} = \tilde{A}^{-1} + \frac{\tilde{A}^{-1} u v^T \tilde{A}^{-1}}{1 + v^T \tilde{A}^{-1} u}$  (with a red arrow pointing to the denominator)
- $\mathbf{a} = (\mathbf{A}_X^{(j)})^{-1} \mathbf{1}$  (with a red arrow pointing to the term  $\hat{p} \mathbf{a} \mathbf{a}^T$ )

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- **Thus:**  $f_{\infty}(\mathbf{z}) = \left( \mathbf{A}_z^{(\infty)} \left( \mathbf{A}_X^{(\infty)} \right)^{-1} + \hat{\mathbf{A}} \right) \mathbf{y}$

**Non-trivial** generalization possible!

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- $\lim_{l \rightarrow \infty} \lambda_1 (\Theta^{(l)}(\mathbf{X}, \mathbf{X})) = np^*$
- $\lim_{l \rightarrow \infty} \lambda_{\text{bulk}} (\Theta^{(l)}(\mathbf{X}, \mathbf{X})) = 0$
- $\lim_{l \rightarrow \infty} \kappa (\Theta^{(l)}(\mathbf{X}, \mathbf{X})) = \infty \implies$  Becomes **untrainable**

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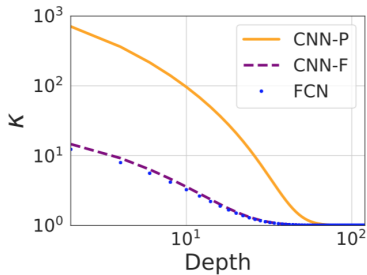
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- $\lim_{l \rightarrow \infty} f_{\infty}^{(l)}(\mathbf{x}) = \left( \mathbf{A}_z^{(\infty)} \left( \mathbf{A}_x^{(\infty)} \right)^{-1} + \hat{\mathbf{A}} \right) \mathbf{y}$

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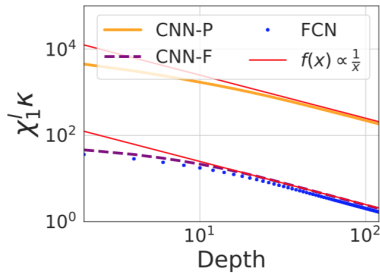
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 $\implies$  Network might be **able** to generalize

# Experiments (I)

Chaotic:  $\kappa \rightarrow 1$



Ordered:  $\kappa \approx (\kappa_1^L \cdot C)^{-1} \rightarrow \infty$

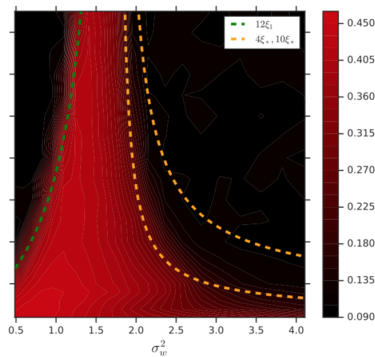
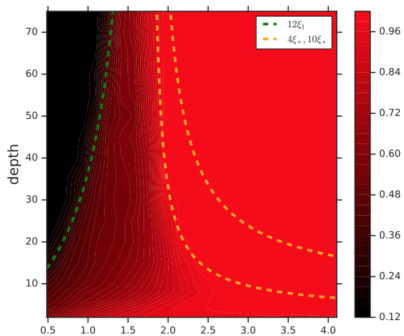


Condition number in the chaotic and ordered regime

# Experiments (II)

Train accuracy

Test accuracy



Test and Training Accuracy for Finite Depth and Width Networks

# Discussion

- Important to also study **infinite depth**, after all seems to be more important in practice than big widths
- Interesting **tradeoff** between generalization and trainability
- Characterization of generalization a bit **weak** but seems to be true empirically
- Approximation of the diagonal  $\Sigma^{(l)}(\mathbf{x}, \mathbf{x}) = q^*$  **very strong** assumption, unclear how this affects the obtained limits
- Very **messy** paper, lots of referencing to prior work and some statements are a bit unclear