A comparison between ADMB & TMB

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TMB Intro

- ADMB inspired R-package
- Combines external libraries: CppAD, Eigen, CHOLMOD
- ▶ Continuously developed since 2009, ~ 1000 lines of code
- Implements Laplace approximation for random effects
- C++ Template based
- Automatic sparseness detection
- Parallelism through BLAS
- Parallel user templates
- ▶ Parallelism through multicore package

Example 1: Linear regression

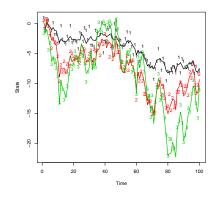
```
DATA_SECTION
init_int N
init_vector Y(1,N)
init_vector X(1,N)
PARAMETER_SECTION
init_number a
init_number b
init_number logsigma
sdreport_number sigmasq
objective_function_value nll
PROCEDURE_SECTION
sigmasq=exp(2*logSigma);
nll=0.5*(N*log(2*M_PI*sigmasq)
+sum(square(Y-(a+b*x)))/sigmasq);
```

```
#include <TMB.hpp>
template<class Type>
Type objective_function<Type>::operator() ()
{
   DATA_VECTOR(Y);
   DATA_VECTOR(x);
   PARAMETER(a);
   PARAMETER(b);
   PARAMETER(logSigma);
   Type nll=dnorm(Y,a+b*x,exp(logSigma),true).sum();
   return nll;
}
```

Example 2: Multivariate random walk

$$\begin{aligned} \mathbf{X}_{t+1} &= \mathbf{X}_t + \varepsilon_{\mathbf{t}} \quad, \varepsilon_{\mathbf{t}} \sim \textit{N}(\mathbf{0}, \Sigma) \\ \mathbf{Y}_t &= \mathbf{X}_t + \eta_{\mathbf{t}} \quad, \eta_{\mathbf{t}} \sim \textit{N}(\mathbf{0}, \sigma_Y^2 \mathbf{I}) \\ \Sigma_{i,j} &= \rho^{|i-j|} \sigma_i \sigma_j \end{aligned}$$

States (random effects) **X**, Observations **Y**. Parameters: σ , σ **Y**, ρ .

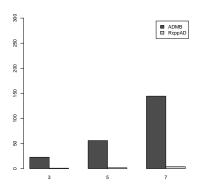


GLOBALS SECTION // Random walk with multivariate correlated increments and measurement noise. #include <df1b2fun.h> #include <RcppAD.hpp> #include "nLogNormal.h" DATA SECTION init int N template <class Type> init int stateDim Type $f(Type x)\{return Type(2)/(Type(1) + exp(-Type(2) * x)) - Type(1);\}$ init matrix obss(1,N,1,stateDim) PARAMETER SECTION template<class Type> objective function value jnll; Type objective function<Type>::operator() () init bounded number rho(0.001,0.999.1); init_vector logSdObs(1,stateDim); DATA ARRAY(obs); /* timeSteps x stateDim */ init vector logSd(1,stateDim); PARAMETER ARRAY(u); /* State */ random effects vector U(1.stateDim*N): //State PARAMETER(transf rho): PROCEDURE SECTION PARAMETER VECTOR(logsds): for(int t=1; t<=(N-1); t++) PARAMETER VECTOR(logsd0bs); step(t,U((t-1)*stateDim+1.t*stateDim).U(t*stateDim+1.(t+1)*stateDim).logSd.rho): int timeSteps=obs.dim[0]: int stateDin=obs.dim[1]: for(int t=1; t<=(N-1); t++) Type rho=f(transf rho); obs(t,U((t-1)*stateDim+1,t*stateDim),logSdObs); vector<Type> sds=exp(logsds): vector<Type> sd0bs=exp(logsd0bs); SEPARABLE FUNCTION void step(const int t, const dvar vector& ul.const dvar vector& u2, const dvar vector& logSd, const dvariable& rho) matrix<Type> cov(stateDim.stateDim): for(int i=0;i<stateDim;i++)</pre> dvar matrix fvar(1.stateDim.1.stateDim): for(int j=0:j<stateDim:j++) dvar matrix fcor(1.stateDim.1.stateDim): cov(i,j)=pow(rho,Type(abs(i-j)))*sds[i]*sds[i]: dvar vector fsd(1,stateDim); using namespace density; MVNORM t<Type> neg log density(cov): fvar.initialize(): fsd = exp(logSd); Type ans=θ; ans-=dnorm(vector<Type>(u(0)).Type(0).Type(1).1).sum(): dvar vector a=u1; for(int i=1;i<timeSteps;i++)</pre> ans+=neg log density(u(i)-u(i-1)); // Process likelihood a.shift(1): dvar vector b=u2: for(int i=1:i<timeSteps:i++) b.shift(1); ans-=dnorm(vector<Type>(obs(i)), vector<Type>(u(i)), sd0bs,1).sum(); // Data likelihood return ans: for(int i=1: i<=stateDim: ++i){ for(int j=1; j<=stateDim; ++j){</pre> if(i!=i){fcor(i,i)=pow(rho.abs(i-i));}else{fcor(i,i)=1.0;} fvar=elem prod(outer prod(fsd.fsd).fcor): jnll+=nLogNormal(a,b,fvar); //Process likelihood SEPARABLE FUNCTION void obs(const int t. const dvar vector& u. const dvar vector& logSdObs) dvar vector var = exp(2.0*logSdObs); dvar vector pred - u: pred.shift(1): for(int i=1; i<=stateDim; i++){ inll+=0.5*(log(2.0*M PI*var(i))+square(obss(t.i)-pred(i))/var(i)): // Data likelihood TOP OF MAIN SECTION arrmblsize=2000000: gradient structure::set GRADSTACK BUFFER SIZE(150000); gradient structure::set CMPDIF BUFFER SIZE(800000): gradient structure::set MAX NVAR OFFSET(100000); gradient structure::set NUM DEPENDENT VARIABLES(5000);

Example 2: Results (timings)

	3	5	7
ADMB	22.74	55.93	144.47
TMB	0.91	1.63	3.85
Speed-up	24.88	34.34	37.56

Table: Runtime in seconds for multivariate random walk example.



Parallel user templates intro

Most objective functions are a result of commutative accumulation (θ = random and fixed effects):

$$I(\theta) = \sum_{i=1}^{n} I_i(\theta)$$

- If e.g. two cores then let core 1 do AD of the "even terms" and core 2 do AD of the "odd terms".
- ► The book keeping is handled by template class parallel_accumulator<Type>.
- From user perspective: change one line of template to get parallel version.

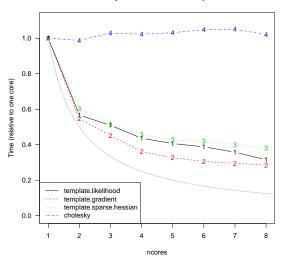
Parallel Code

```
Type ans=0; ... parallel_accumulator<Type> ans(this); ...
```

- ▶ Parallel accumulator initialized to zero and has only methods "+ =" and "- =".
- When modified code is compiled from R the template is detected to be parallel and the openmp flag is set.

Results: benchmark plot

Scalability: stateDim=10 timeSteps=1000



Parallel Code with multicore package

- High level parallelization gives best performance.
- ► Easy with multicore package ¹.

Examples:

- Parallel likelihood evaluations
 - mclapply(1:10,function(x)obj\$fn(obj\$par))
- ▶ Parallel gradient evaluations mclapply (1:10, function (x) obj\$gr(obj\$par))
- ► Parallel optimization
 mclapply(1:10, function(x) do.call("optim", obj))

```
^1\text{Note:} Before calling mclapply do openmp (1) to avoid forking a multithreaded process
```

- Slow compile times
- Standalone applications not possible
- Fewer built-in specialized functionalities (e.g. profile-likelihood, sd_report_number etc.)
- Sparse documentation
- Depends on external libraries

- + Fast run times
- The use of external libraries means a compact code base that is highly optimized
- + Can handle very high dimensional problems (∼ 10⁶ random effects)
- No SEPARABLE_FUNCTION construct needed, fully automatic sparseness detection
- + Full R integration no need for data+results import/export
- + No use of temporary files on the disc
- Template based no code duplication needed as for dflb2variables etc.
- + Analytical Hessian for fixed effects.
- + High-level parallelization with multicore package.