```
import numpy as np
import matplotlib.pyplot as plt
from tqdm import tqdm # Displays a progress bar
from pylab import *
import torch
import torchvision
from torch import nn
from torch import optim
import torch.nn.functional as F
from torchvision import datasets, transforms, utils
from torch.utils.data import Dataset, Subset, DataLoader, random_split
# Load the dataset and train, val, test splits
print("Loading datasets...")
FASHION_transform = transforms.Compose([
    transforms.ToTensor(), # Transform from [0,255] uint8 to [0,1] float
1)
FASHION trainval = datasets.FashionMNIST('.', download=True, train=True, transform=FASHION trans
FASHION_train = Subset(FASHION_trainval, range(50000))
FASHION val = Subset(FASHION trainval, range(50000,60000))
FASHION_test = datasets.FashionMNIST('.', download=True, train=False, transform=FASHION_transform
print("Done!")
    Loading datasets...
    Done!
# Hyperparameters for the network
lr = 3e-4 # Learning Rate
batch_sz = 64 # Batch Size
num_epochs = 25 # Epochs
momentum=0.9 # Momentum Value
epsilon = 25/255
steps = [1,2,5,10]
alpha = 1e-2
#Plot Variables
training_loss = []
val_loss = []
pgd_adv_examples = []
pgd_label = []
original_label = []
# Create dataloaders
trainloader = DataLoader(FASHION_train, batch_size=batch_sz, shuffle=True)
valloader = DataLoader(FASHION_val, batch_size=batch_sz, shuffle=True)
testloader = DataLoader(FASHION_test, batch_size=batch_sz, shuffle=True)
input sz = 784
class Network(nn.Module):
    def __init__(self, in_channels=1):
```

```
self.conv1 = nn.Conv2d(in_channels=1, out_channels=20, kernel_size=(5,5), stride=(1,1),
        self.pool = nn.MaxPool2d(kernel_size=(2,2), stride=(2,2))
        self.conv2 = nn.Conv2d(in_channels=20, out_channels=50, kernel_size=(5,5), stride=(1,1)
        self.fc1 = nn.Linear(2450,500)
        self.fc2 = nn.Linear(500,10)
    def forward(self,x):
        # TODO: Design your own network, implement forward pass here
        \#x = x.view(-1,28*28) \# Flatten each image in the batch
        x = F.relu(self.conv1(x))
        x = self.pool(x)
        x = F.relu(self.conv2(x))
        x = self.pool(x)
        x = x.reshape(x.shape[0],-1)
        x = F.relu(self.fc1(x))
        x = self.fc2(x)
        return x
device = "cuda" if torch.cuda.is_available() else "cpu" # Configure device
model = Network().to(device)
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=lr, weight_decay=1e-4)
def train(model, loader, num_epoch = num_epochs, valloader=valloader): # Train the model
    print("Start training...")
    model.train() # Set the model to training mode
    for i in range(num_epoch):
        model.train()
        running_loss = []
        for batch, label in tqdm(loader):
            batch = batch.to(device)
            label = label.to(device)
            optimizer.zero_grad() # Clear gradients from the previous iteration
            pred = model(batch) # This will call Network.forward() that you implement
            loss = criterion(pred, label) # Calculate the loss
            running_loss.append(loss.item())
            loss.backward() # Backprop gradients to all tensors in the network
            optimizer.step() # Update trainable weights
        training_loss.append(np.mean(running_loss))
        evaluate_val_loss(model, valloader, i)
        print("Train Epoch {} loss:{}".format(i+1,np.mean(running_loss))) # Print the average loss
    print("Done!")
def evaluate(model, loader): # Evaluate accuracy on validation / test set
    model.eval() # Set the model to evaluation mode
    correct = 0
    with torch.no_grad(): # Do not calculate gradient to speed up computation
```

super(Network, self).__init__()

```
for batch, label in tqdm(loader):
            batch = batch.to(device)
            label = label.to(device)
            pred = model(batch)
            correct += (torch.argmax(pred,dim=1)==label).sum().item()
    acc = correct/len(loader.dataset)
    print("Evaluation accuracy: {}".format(acc))
    return acc
def evaluate_val_loss(model, loader, i):
    model.eval()
    running_loss = []
    for batch, label in tqdm(loader):
        batch = batch.to(device)
        label = label.to(device)
        optimizer.zero_grad() # Clear gradients from the previous iteration
        pred = model(batch) # This will call Network.forward() that you implement
        loss = criterion(pred, label) # Calculate the loss
        running loss.append(loss.item())
    val_loss.append(np.mean(running_loss))
    print("Val Epoch {} loss:{}".format(i+1,np.mean(running_loss)))
def plot loss(val loss, train loss):
    # Training Loss
    plt.figure(figsize=(10,5))
    plt.title("Training Loss")
    plt.plot(train_loss,label="train")
    plt.xlabel("iterations")
    plt.ylabel("Train Loss")
    plt.legend()
    plt.savefig("trainloss.png")
    # Validation Loss
    plt.figure(figsize=(10,5))
    plt.title("Validation Loss")
    plt.plot(val_loss,label="val")
    plt.xlabel("iterations")
    plt.ylabel("Validation Loss")
    plt.legend()
    plt.savefig("valloss.png")
def fgsm_attack(image, epsilon, batch_grad):
    sign_batch_grad = batch_grad.sign()
    perturbed_image = image + epsilon*sign_batch_grad
    perturbed image = torch.clamp(perturbed image, 0, 1)
    return perturbed image
def pgd_attack(images, labels, n, eps=epsilon):
    clamp_max = 255
    for i in range(n):
```

```
images.requires_grad = True
        outputs = model(images)
        model.zero_grad()
        cost = criterion(outputs, labels).to(device)
        cost.backward()
        attack_images = images + alpha*images.grad.sign()
        a = torch.clamp(images - eps, min=0)
        b = (attack_images>=a).float()*attack_images + (a>attack_images).float()*a
        c = (b > images+eps).float()*(images+eps) + (images+eps >= b).float()*b
        images = torch.clamp(c,max=clamp_max).detach_()
    return images
def test(model, device, test_loader, epsilon):
    # Accuracy counter
    c pgd = 0
   w_pgd = 0
    correct = 0
    wrong = 0
    # Loop over all examples in test set
    for batch, label in tqdm(test_loader):
        batch, label = batch.to(device), label.to(device)
        # Set requires_grad attribute of tensor. Important for Attack
        batch.requires_grad = True
        # Forward pass the batch through the model
        output = model(batch)
        # Calculate the loss
        loss = criterion(output, label)
        # Zero all existing gradients
        model.zero_grad()
        # Calculate gradients of model in backward pass
        loss.backward()
        # Collect datagrad
        batch_grad = batch.grad.data
        # Call FGSM Attack
        perturbed_batch = fgsm_attack(batch, epsilon, batch_grad)
        # Re-classify the perturbed image
        pred = model(perturbed_batch)
        # Check for success
        correct += (torch.argmax(pred,dim=1)==label).sum().item()
        wrong += (torch.argmax(pred,dim=1)!=label).sum().item()
        # Call PGD Attack and metrics
```

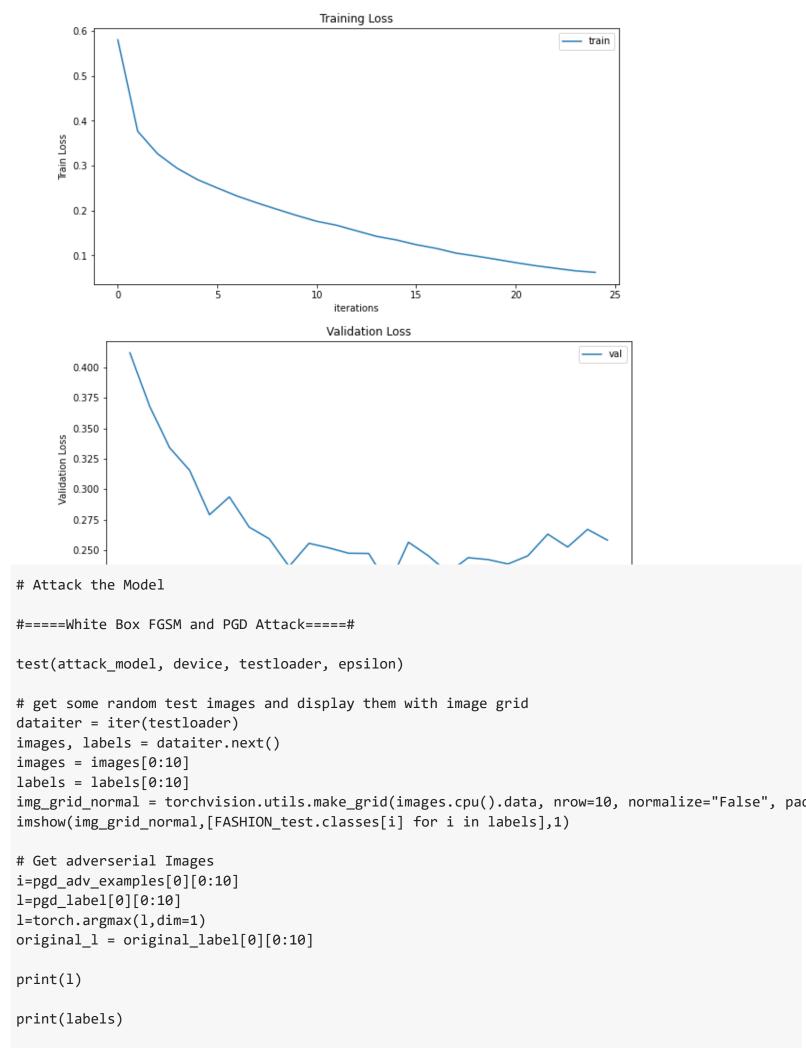
```
pgd_batch = pgd_attack(batch,label,steps[3],epsilon) #Change index of steps list here to
        pred pgd = model(pgd batch)
        # Save adv batch for later use
        pgd adv examples.append(pgd batch)
        pgd_label.append(pred_pgd)
        original_label.append(label)
        c_pgd += (torch.argmax(pred_pgd,dim=1)==label).sum().item()
        w_pgd += (torch.argmax(pred_pgd,dim=1)!=label).sum().item()
    acc = correct/len(testloader.dataset)
    attack_acc = wrong/len(testloader.dataset)
    attack_pgd = w_pgd/len(testloader.dataset)
    print("Test accuracy on Attacked Test Data is: {} and Attack Success Rate (accuracy) is: {}'
    print("Attack Success Rate (accuracy) for PGD on Test Data is: {}".format(attack_pgd))
def imshow(img, title,i):
    npimg = img.numpy()
    plt.figure(figsize = (15, 10))
    plt.imshow(np.transpose(npimg,(1,2,0)))
    plt.title(title)
    plt.tight_layout()
    plt.savefig("Plot{}.png".format(i))
def run():
    train(model, trainloader)
    print("Evaluate on validation set...")
    evaluate(model, valloader)
    print("Evaluate on test set")
    evaluate(model, testloader)
    # Print Model Architecture
    print(model)
    save_path = "Lenet5-FashionMNISTtrialv1.pt"
    # Save model
    torch.save(model, save path)
# Uncomment the comment below to retrain the model and create a new model file
# (Change torch save path)
run()
    100% | 157/157 [00:01<00:00, 155.73it/s]
    Val Epoch 15 loss:0.256417419310588
    Train Epoch 15 loss:0.13453369210128818
             782/782 [00:06<00:00, 120.32it/s]
           | 157/157 [00:01<00:00, 156.97it/s]
    Val Epoch 16 loss: 0.24524141520641413
    Train Epoch 16 loss:0.12402274702554164
    100% | 782/782 [00:06<00:00, 116.11it/s]
             157/157 [00:01<00:00, 153.98it/s]
    Val Epoch 17 loss:0.2313012615273333
    Train Fnoch 17 loss:0 11579520696097666
```

```
100%| 782/782 [00:06<00:00, 119.53it/s]
     157/157 [00:00<00:00, 157.67it/s]
Val Epoch 18 loss:0.2436873173447931
Train Epoch 18 loss:0.10517046021421433
100%| 782/782 [00:06<00:00, 120.93it/s]
100% | 157/157 [00:01<00:00, 156.85it/s]
Val Epoch 19 loss: 0.24213088000086463
Train Epoch 19 loss:0.09862132198737024
             | 782/782 [00:06<00:00, 119.55it/s]
100%
             Val Epoch 20 loss:0.23851143673157235
Train Epoch 20 loss:0.09147130147508724
     782/782 [00:06<00:00, 120.16it/s]
             | 157/157 [00:01<00:00, 156.09it/s]
100%
Val Epoch 21 loss:0.24525239392165926
Train Epoch 21 loss:0.08401766061768545
100% 782/782 [00:06<00:00, 120.12it/s]
100%
             | 157/157 [00:01<00:00, 155.83it/s]
Val Epoch 22 loss:0.2630361841789856
Train Epoch 22 loss:0.07710762176891346
         | 782/782 [00:06<00:00, 120.37it/s]
100% | 157/157 [00:01<00:00, 155.73it/s]
Val Epoch 23 loss:0.2524482058064573
Train Epoch 23 loss:0.07140273056314576
100%
         782/782 [00:06<00:00, 118.78it/s]
100% | 157/157 [00:01<00:00, 156.36it/s]
Val Epoch 24 loss: 0.26692588655811966
Train Epoch 24 loss:0.06578282328665523
100% | 782/782 [00:06<00:00, 119.11it/s]
             | 157/157 [00:01<00:00, 155.31it/s]
Val Epoch 25 loss: 0.25811262737224056
Train Epoch 25 loss:0.062239889574744515
Done!
Evaluate on validation set...
100% | 157/157 [00:00<00:00, 160.23it/s]
Evaluation accuracy: 0.9165
Evaluate on test set
100%
        | 157/157 [00:00<00:00, 158.76it/s]Evaluation accuracy: 0.9124
Network(
  (conv1): Conv2d(1, 20, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2))
  (pool): MaxPool2d(kernel size=(2, 2), stride=(2, 2), padding=0, dilation=1, ceil mode=False)
  (conv2): Conv2d(20, 50, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2))
  (fc1): Linear(in_features=2450, out_features=500, bias=True)
 (fc2): Linear(in features=500, out features=10, bias=True)
```

```
model_path = "Lenet5-FashionMNISTtrialv1.pt"

# Load model for inference
attack_model = torch.load(model_path)
attack_model.eval()

# Plot train loss and val acc
plot_loss(val_loss, training_loss)
```



create grid of adverserial images
img_grid = torchvision.utils.make_grid(i.cpu().data, nrow=10, normalize="False", padding=3)

100%| 157/157 [00:04<00:00, 33.18it/s]

Test accuracy on Attacked Test Data is: 0.1661 and Attack Success Rate (accuracy) is: 0.8339

Attack Success Rate (accuracy) for PGD on Test Data is: 0.9457

tensor([0, 4, 4, 6, 3, 6, 4, 4, 6, 5], device='cuda:0')

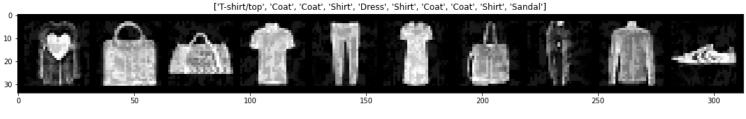
tensor([9, 2, 5, 0, 7, 1, 6, 4, 0, 4])

['Ankle boot', 'Pullover', 'Sandal', 'T-shirt/top', 'Sneaker', 'Trouser', 'Shirt', 'Coat', 'T-shirt/top', 'Coat']

10 - 20 - 30 - 50 - 100 - 150 - 200 - 250 - 300

Display Adversarial Images
imshow(img_grid,[FASHION_test.classes[i] for i in 1],2)

WARNING:matplotlib.image:Clipping input data to the valid range for imshow with RGB data ([0..1] for flo



Display Adverserial Images with True Labels
imshow(img_grid,[FASHION_test.classes[i] for i in original_1],3)

WARNING:matplotlib.image:Clipping input data to the valid range for imshow with RGB data ([0..1] for flo



evaluate(attack_model, testloader)

0.9124

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✓ 1s completed at 20:40