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no central thread of control, and require no centralized communication. They are derived using spectral properties of graphs: graphs of physical network links among computers in the load balancing problem, and graphs of logical communication channels among processes in the mapping problem. A distinguishing characteristic of these algorithms is that they are scalable: the expected cost of execution does not increase with problem scale. This is proven in a scalability theorem which shows that, for several simple disturbance models, the rate of convergence to a solution is independent of scale. This property is extended through simulated examples and informal argument to general and random disturbances. A worst case disturbance is presented and shown to occur with vanishing probability as the problem scale increases. To verify these ...

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