

Cool Operation Semantics

Outline

- Motivation
- Notations
- Rules

Motivation

- Specify the semantics of every expression
 - what happens when an expression is evaluated
 - semantics = meaning
- Definition of a programming language:
 - regular expressions \Rightarrow lexical analysis
 - context free grammar \Rightarrow syntactic analysis
 - scoping rules \Rightarrow symbol table construction
 - typing rules \Rightarrow type checking
 - **evaluation rules** \Rightarrow code generation and optimization

Evaluation rules

- So far, we specified the evaluation rules indirectly
 - first sections in Cool Manual
- We can specify evaluation rules by
 - compilation of Cool to MIPS (stack machine)
 - the evaluation rules of MIPS
- This is a **complete** description
- Why isn't it good enough?

How to specify evaluation rules?

- Specification should avoid **irrelevant details**
 - whether to use a stack machine or not
 - which way the stack grows
 - how integers are represented
 - the particular instruction set of the architecture
- Specification should be
 - complete
 - not overly restrictive

Programming language semantics

- Multiple powerful ways to specify semantics
- Suitable for different tasks
- Operational semantics
- Denotational semantics
- Axiomatic semantics
- ...

Operational semantics

- Describes program evaluation steps
- Execution rules on an abstract machine
- Most useful for specifying implementations
- This is what we use for Cool

Denotational semantics

- Program's meaning is a **mathematical function**
- Need to define a suitable space of functions
- Foundation of programming language design

Axiomatic semantics

- Program behavior described via logical formulas
 - Hoare logic $\{ \text{PRE} \} C \{ \text{POST} \}$
 - if execution of C begins in state satisfying PRE ,
then it ends in state satisfying POST
 - PRE , POST are logical formulas
- Foundation of many program **verification** systems
 - quick sort function sorts an array

Introduction to operational semantics

- Formal notation of inference rules
- Similar to type rules
- Typing judgment
 - **typeContext** $\vdash e : T$
 - in the given **context**, expression **e** has type **T**
- Evaluation judgment
 - **evaluationContext** $\vdash e : v$
 - in the given **context**, expression **e** evaluates to value **v**

Example: evaluation rules

- The result of evaluating an expression can depend on the result of evaluating its subexpressions
- The rules specify everything needed to evaluate an expression

Context $\vdash e1 : 5$

Context $\vdash e2 : 7$

Context $\vdash e1 + e2 : 12$

Context

- Keep track of values of variables
- Variables can change their values during the evaluation
- Example: $y \leftarrow x + 1$
- **Environment** the memory location where the value of a variable stored
- **Store** the contents of each memory location

Environment

- Maps variable names to memory locations
 - records where in memory the value of a variable is stored
 - keeps track of which variables are in scope
- **$E = [x : l1, y : l2]$**
- **$E(x)$** lookup a variable **x** in environment **E**

Store

- Maps memory locations to values
- **$S = [l1 \rightarrow 5, l2 \rightarrow 7]$**
- **$S(l1)$** lookup the contents of a **location $l1$** in **store S**
- **$S' = S[12/l1]$** defines a store S' such that
 - $S'(l1) = 12$ and
 - $S'(l) = S(l)$ if $l \neq l1$
 - used to perform an assignment of 12 to location $l1$

Cool evaluation rules

- The evaluation judgment is $\mathbf{so}, \mathbf{E}, \mathbf{S} \vdash \mathbf{e} : \mathbf{v}, \mathbf{S}'$
 - \mathbf{so} the current value of the self object
 - \mathbf{E} the current variable environment
 - \mathbf{S} the current store
- If the evaluation of \mathbf{e} terminates then
 - the returned value is \mathbf{v}
 - the new store is \mathbf{S}'

Result of evaluation

- Evaluating an expression
 - value
 - new store to model **side-effects**
 - variable environment does not change
 - value of “self” does not change
- Allows non-terminating evaluations

Variable references

- Lookup of variables
 - from name to location
 - from location to value
- The store does not change
- A special case for self:

$$E(id) = lid$$

$$S(lid) = v$$

$$so, E, S \vdash id : v, S$$

$$so, E, S \vdash self : so, S$$

Assignment

- Evaluate the right hand side to get a value and a new store $S1$
- Fetch the location of the assigned variable
- The result is the value v and an updated store
- The environment does not change

$$so, E, S \vdash e : v, S1$$
$$E(id) = lid$$
$$S2 = S1[v/lid]$$

$$so, E, S \vdash id \leftarrow e : v, S2$$

Example

$$E = [x : I_x, y : I_y]$$

$$S = [I_x \rightarrow \text{Int}(3), I_y \rightarrow \text{Int}(10)]$$

$$x \leftarrow y \leftarrow 2$$

$$S_1 = S[\text{Int}(2)/I_y] = [I_x \rightarrow \text{Int}(3), I_y \rightarrow \text{Int}(2)]$$

$$\text{so, } E, S \vdash y \leftarrow 2 : \text{Int}(2), S_1$$

$$S_2 = S_1[\text{Int}(2)/I_x] = [I_x \rightarrow \text{Int}(2), I_y \rightarrow \text{Int}(2)]$$

$$\text{so, } E, S \vdash x \leftarrow y \leftarrow 2 : \text{Int}(2), S_2$$

Cool values

- All values in Cool are objects
- All objects are instances of some class
 - the dynamic type of the object
- To denote a Cool object we use the notation **$X(a_1 = l_1, \dots, a_n = l_n)$**
 - **X** is the class of the object (its dynamic type)
 - **a_i** are the attributes **including inherited** ones
 - **l_i** is the location where the value of a_i is stored

Classes without attributes

- Special notation for cool values
 - `Int(5)` the integer 5
 - `Bool(true)` the boolean true
 - `String(4, "Cool")` the string "Cool" of length 4

Base values

- The store does not change

$$\text{so, E, S} \vdash \text{true} : \text{Bool}(\text{true}), \text{S}$$

$$\text{so, E, S} \vdash \text{false} : \text{Bool}(\text{false}), \text{S}$$

i is an integer literal

$$\text{so, E, S} \vdash i : \text{Int}(i), \text{S}$$

s is a string literal
 n is the length of s

$$\text{so, E, S} \vdash s : \text{String}(n,s), \text{S}$$

Special value: void

- Member of all types
- Supports *isvoid* test
- No other operations can be performed on it
- Concrete implementations might use NULL here

Conditionals

- Evaluation sequence
 - e_1 must be evaluated first to produce S_1
 - then e_2 can be evaluated to produce S_2
- The result of evaluating e_1 is a Bool object (why?)
- There is another, similar, rule for Bool(false)

$$\frac{\begin{array}{l} \text{so, } E, S \vdash e_1 : \text{Bool}(\text{true}), S_1 \\ \text{so, } E, S_1 \vdash e_2 : v, S_2 \end{array}}{\text{so, } E, S \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : v, S_2}$$

Sequential composition

- Evaluation sequence
- Only the last value is used
- But all the side-effects are collected

$$so, E, S \vdash e_1 : v_1, S_1$$
$$so, E, S_1 \vdash e_2 : v_2, S_2$$
$$\dots$$
$$so, E, S_{n-1} \vdash e_n : v_n, S_n$$

$$so, E, S \vdash \{ e_1; \dots; e_n; \} : v_n, S_n$$

Loops

- If e_1 evaluates to $\text{Bool}(\text{false})$ then the loop terminates immediately
- Use the side-effects from the evaluation of e_1
- Result value void
- The typing rules ensure that e_1 evaluates to a Bool object

$$\text{so, } E, S \vdash e_1 : \text{Bool}(\text{false}), S1$$

$$\text{so, } E, S \vdash \text{while } e_1 \text{ loop } e_2 \text{ pool} : \text{void}, S1$$

Loops

- Evaluation sequence (S, S1, S2, S3)
- Evaluation of a loop is expressed in terms of the evaluation of itself in another state
- The result of evaluating e2 is discarded
- Only the side-effect is preserved

$so, E, S \vdash e1 : \text{Bool}(\text{true}), S1$

$so, E, S1 \vdash e2 : v, S2$

$so, E, S2 \vdash \text{while } e1 \text{ loop } e2 \text{ pool} : \text{void}, S3$

$so, E, S \vdash \text{while } e1 \text{ loop } e2 \text{ pool} : \text{void}, S3$

Let

- What is the context in which e_2 must be evaluated?
- Environment like E but with a new binding of id to a fresh location l_{new}
- Store like S_1 but with l_{new} mapped to v_1

$$so, E, S \vdash e_1 : v_1, S_1$$
$$so, ?, ? \vdash e_2 : v, S_2$$

$$so, E, S \vdash \text{let } id : T \leftarrow e_1 \text{ in } e_2 : v, S_2$$

Let

- $l_{\text{new}} = \text{newloc}(S)$
- l_{new} is a location that is not already used in S
- newloc is like dynamic memory allocation

$$\frac{\begin{array}{l} \text{so, } E, S \vdash e_1 : v_1, S_1 \\ l_{\text{new}} = \text{newloc}(S_1) \\ \text{so, } E[l_{\text{new}}/\text{id}], S_1[v_1/l_{\text{new}}] \vdash e_2 : v_2, S_2 \end{array}}{\text{so, } E, S \vdash \text{let id} : T \leftarrow e_1 \text{ in } e_2 : v_2, S_2}$$

new T

- Allocate new locations to hold the values for all attributes of an object of class T
 - essentially, allocate a new object
- Initialize those locations with the default values of attributes
- Evaluate the initializers and set the resulting attribute values
- Return the newly allocated object

Default values

- For each class A there is a default value denoted by D_A
 - $D_{\text{int}} = \text{Int}(0)$
 - $D_{\text{bool}} = \text{Bool}(\text{false})$
 - $D_{\text{string}} = \text{String}(0, "")$
 - $D_A = \text{void}$ for any other class A

More Notation

- For a class A we write
$$\text{class}(A) = (a_1 : T_1 \leftarrow e_1, \dots, a_n : T_n \leftarrow e_n)$$
 - a_i are the attributes (including inherited)
 - T_i are their declared types
 - e_i are the initializers

new T

$T0 = \text{if } T == \text{SELF_TYPE} \text{ and } so = X(\dots) \text{ then } X \text{ else } T$
 $\text{class}(T0) = (a1 : T1 \leftarrow e1, \dots, an : Tn \leftarrow en)$
 $li = \text{newloc}(S) \text{ for } i = 1, \dots, n$
 $v = T0(a1 = l1, \dots, an = ln)$
 $E' = [a1 : l1, \dots, an : ln]$
 $S1 = S[D_{T1}/l1, \dots, D_{Tn}/ln]$
 $v, E', S1 \vdash \{ a1 \leftarrow e1; \dots; an \leftarrow en; \} : vn, S2$

 $so, E, S \vdash \text{new } T : v, S2$

new T

- Observation: new SELF_TYPE allocates an object with the same dynamic type as self
- The first three steps allocate the object
- The remaining steps initialize it by evaluating a sequence of assignments
- State in which the initializers are evaluated
 - self is the current object
 - only the attributes are in scope
 - same as in typing
 - starting value of attributes are the default ones
- The side-effect of initialization is preserved

Dispatch $e_0.f(e_1, \dots, e_n)$

- Evaluate the arguments in order e_1, \dots, e_n
- Evaluate e_0 to the target object
- Let X be the dynamic type of the target object
- Find the definition of f for X
- Create n new locations
- Create an environment that maps formal arguments of f to those locations
- Initialize the locations with the actual arguments
- Set self to the target object
- Evaluate the body of f

More Notation

- For a class A and a method f of A
 $\text{impl}(A, f) = (x_1, \dots, x_n, e_{\text{body}})$
 - x_i are the names of the formal arguments
 - e_{body} is the body of the method
 - f can be inherited

Dispatch

$$\begin{array}{l}
 \text{so, } E, S \vdash e_1 : v_1, S_1 \\
 \text{so, } E, S_1 \vdash e_2 : v_2, S_2 \\
 \dots \\
 \text{so, } E, S_{n-1} \vdash e_n : v_n, S_n \\
 \text{so, } E, S_n \vdash e_0 : v_0, S_{n+1} \\
 v_0 = X(a_1 = l_1, \dots, a_m = l_m) \\
 \text{impl}(X, f) = (x_1, \dots, x_n, e_{\text{body}}) \\
 l_{xi} = \text{newloc}(S_{n+1}) \text{ for } i = 1, \dots, n \\
 E' = [x_1 : l_{x1}, \dots, x_n : l_{xn}, a_1 : l_1, \dots, a_m : l_m] \\
 S_{n+2} = S_{n+1}[v_1 / l_{x1}, \dots, v_n / l_{xn}] \\
 v_0, E', S_{n+2} \vdash e_{\text{body}} : v, S_{n+3} \\
 \hline
 \text{so, } E, S \vdash e_0.f(e_1, \dots, e_n) : v, S_{n+3}
 \end{array}$$

Dispatch

- The body of the method is invoked with
 - E mapping formal arguments and self's attributes
 - S like the caller's except with actual arguments bound to the locations allocated for formals
- The notion of the frame is implicit: new locations are allocated for actual arguments
- The semantics of **static** dispatch is similar, except the implementation of f is taken from the specified class

Runtime errors in dispatch

- What happens if $\text{impl}(X, f)$ is not defined?
- What happens if target object is void?

$$\begin{array}{l} \dots \\ \text{so, } E, S_n \vdash e_0 : v_0, S_{n+1} \\ v_0 = X(a_1 = l_1, \dots, a_m = l_m) \\ \text{impl}(X, f) = (x_1, \dots, x_n, \text{ebody}) \\ \dots \\ \hline \text{so, } E, S \vdash e_0.f(e_1, \dots, e_n) : v, S_{n+3} \end{array}$$

Runtime errors

- There are some runtime errors that the type checker does not try to prevent (can it ?)
 - dispatch on void
 - case on void
 - no matching branch in case
 - division by zero
 - substring out of range
 - heap overflow
- Execution must abort gracefully
 - with an error message not with segfault
- Operational rules do not cover these cases

Conclusions

- Cool operational rules are **precise and detailed**
- Most languages do not have a well specified operational semantics
- When portability is important an operational semantics becomes essential
- Notation we used for Cool is very limited