Code generation and optimization

PA1-PA3

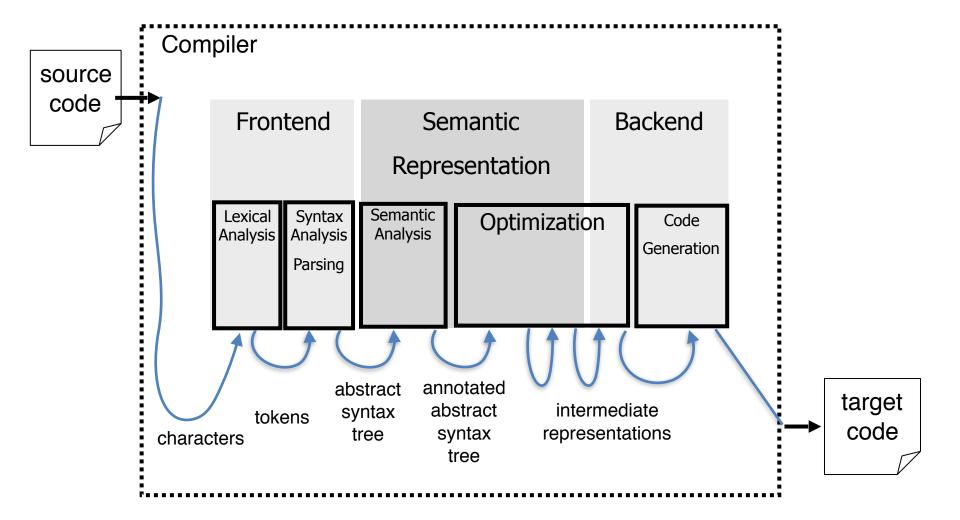
- My apologies for the delays
- Final deadline: midnight Sunday, 8 April
- Marking: best 2 out of 3 for pa1-pa3

- PA1 and PA2 code review: end of this week
- PA3
 - very small
 - you need to know this material for the exam

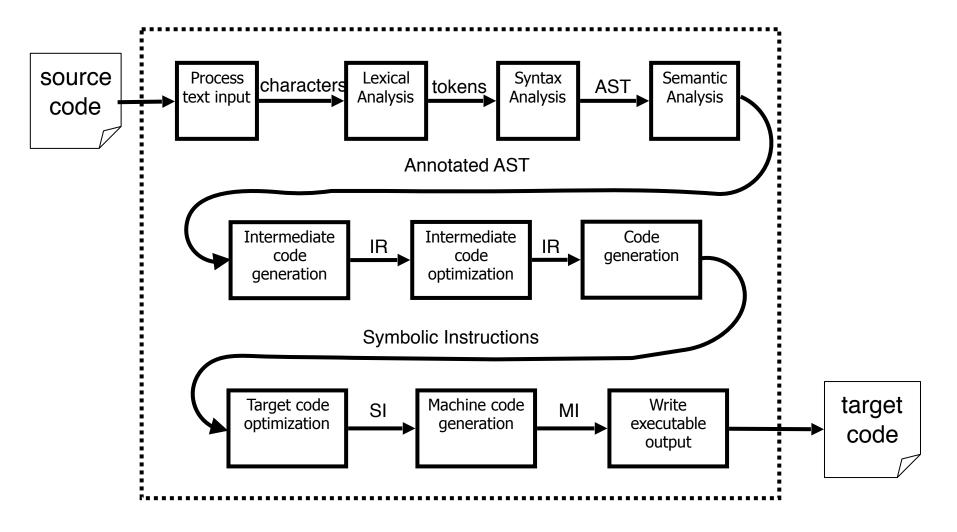
Outline

- Code generation for expressions
 - √ simple stack machine
 - √ stack machine with accumulator
 - weighted register allocation
 - graph coloring: introduction
- How to prepare for the exam?

Anatomy of a modern compiler



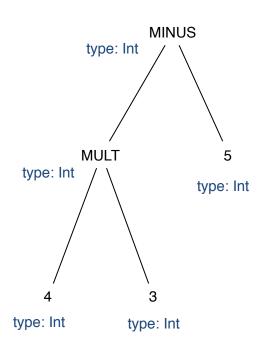
The real anatomy of a modern compiler



Recap: stack machine with accumulator

- For each expression e, function cgen(e) generates MIPS code that
 - computes the value of e in the accumulator \$a0
 - preserves the contents of the stack
- Implement cgen(e) as a traversal of AST
- For a binary operation e1 op e2,
 - after computing e1, push the accumulator on the stack
 - the result of e2 is in the accumulator before op
 - after the operation, pop one value off the stack

Example: stack machine



Intermediate representation: stack machine

```
acc := 4
push
acc := 3
acc := top * acc
pop
push
acc := 5
acc := top - acc
pop
```

MIPS Assembly

```
li $a0 4

sw $a0 0($sp)

addiu $sp $sp -4

li $a0 3

lw $t1 4($sp)

mul $a0 $a0 $t1

addiu $sp $sp 4

sw $a0 0($sp)

addiu $sp $sp -4

li $a0 5

lw $t1 0($sp)

sub $a0 $t1 a0

add $sp $sp 4
```

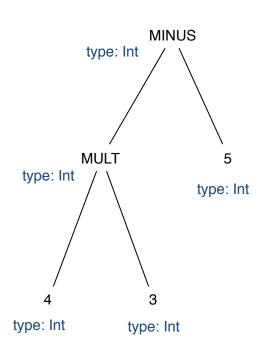
In the real world....

- Production compilers do different things
- Emphasis is on keeping values in registers
- Intermediate results are laid out on the stack, not pushed and popped from the stack

LIR vs. Assembly

	LIR	Assembly	
Register number	Unlimited	Limited	
Function calls	Implicit	Runtime stack	
Instruction set	Abstract	Concrete	
Types	Basic and user defined	Limited basic types	

Example: registers

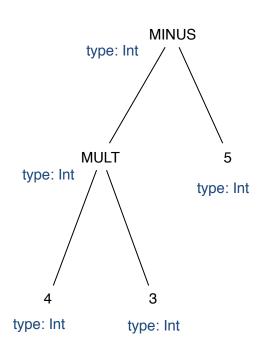


Intermediate representation: three address code

MIPS Assembly



Example: simple optimization



Intermediate representation: after constant propagation

a0 := 7

MIPS Assembly

li \$a0 7

Lexical Analysis Syntax Analysis Semantic Analysis

Optimization

Code Generation

CODE GENERATION FOR EXPRESSIONS

Instruction selection: example

Which instructions to use for each expression?

$$x + (2 + 3)$$

lw \$t0 x	lw \$t0 x
li \$t1 2	li \$t1 2
li \$t2 3	addi \$t1 \$t1 3
add \$t1 \$t1 \$t2	add \$t0 \$t0 \$t1
add \$t0 \$t0 \$t1	

Register allocation

What computational results are kept in registers?

- Possibly not enough registers for all values
- Some instructions have restrictions on registers they can access

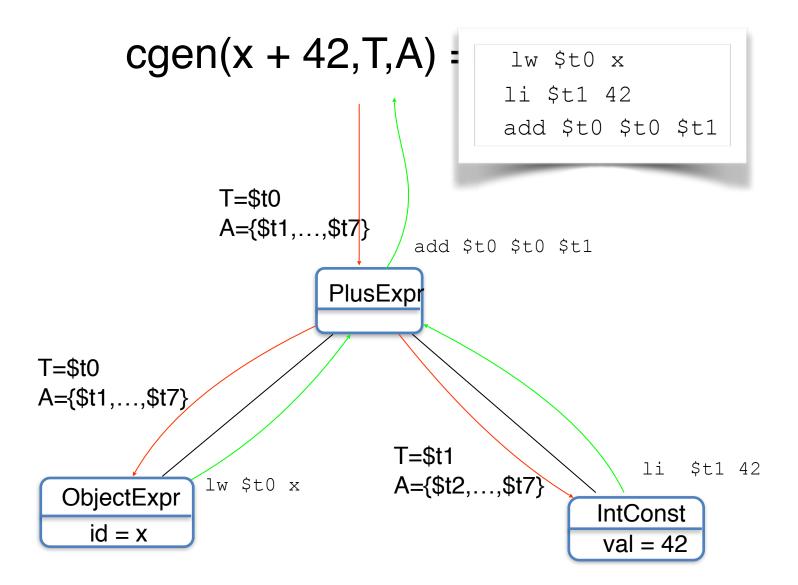
Recap: Registers

- One register stores a single word (4 bytes)
- Number of registers is limited
- Very fast access, even compared to cached memory
- Typical uses of registers
 - operands of instructions
 - store temporary results
 - loop indexes
 - store administrative info
 - \$sp for top of the runtime stack
 - \$a0 used to return values

- Assumptions
 - enough registers
 - all registers are general-purpose
 - we have all registers available for our use
 - ignore registers allocated for stack management
- Formals and locals not given registers (always spilled on stack)

AST traversal

- Top-down: assign registers to subtrees
 - T is target register designated for storing result
 - A is a set of auxiliary registers for temporaries
- Bottom-up: use code templates for AST nodes
 - cgen(node, T, A)



• cgen(x + 42,T,A)

add \$t0 \$t0 \$t1

cgen(x,T,A)

lw \$t0 x

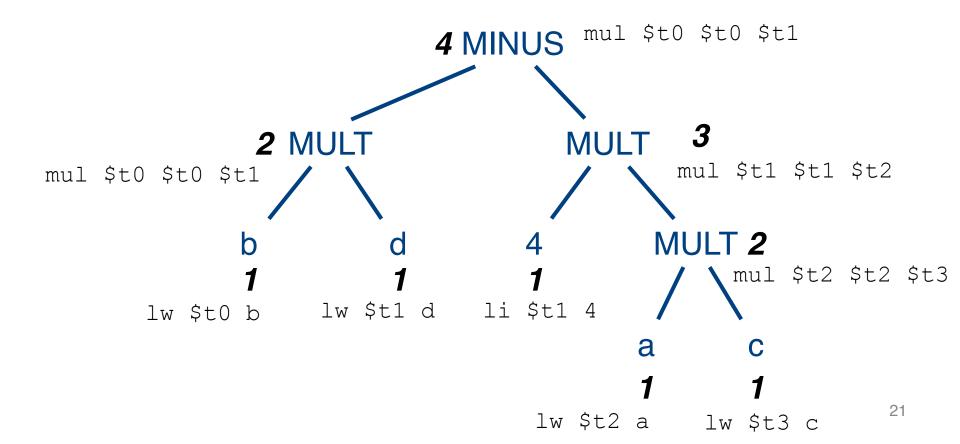
cgen(42,T,A)

li \$t1 42

- Leaf nodes
 - emit code using target register
 - no auxiliaries required
- Internal nodes
 - process first child, store result in target register t
 - process second child
 - target is now occupied by first result
 - allocate a new target register t' from available set for result of second child
 - apply node operation on t and t'
 - store result in target register
 - all initially available register now available again
 - result of internal node stored in target

4 temporaries

b*d-4*a*c

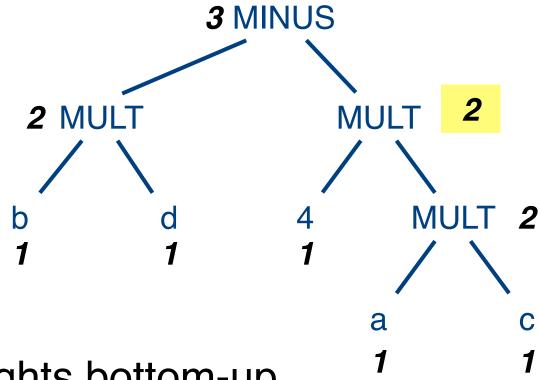


- Bottom-up: label each node with its weight
 - weight is the minimal number of temporaries needed
 - if w(e1) > w(e2) then w(e1+e2) := w(e1)
 - if w(e1) < w(e2) then w(e1+e2) = w(e2)
 - if w(e1) = w(e2) then w(e1+e2) = w(e1) + 1

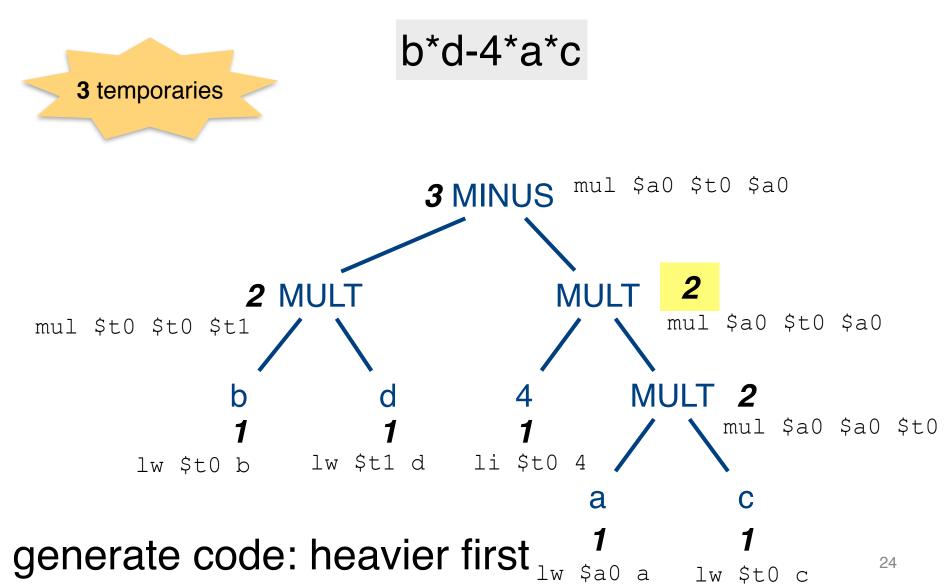
Top-Down: generate code for heavier subtree first

b*d-4*a*c

3 temporaries



assign weights bottom-up



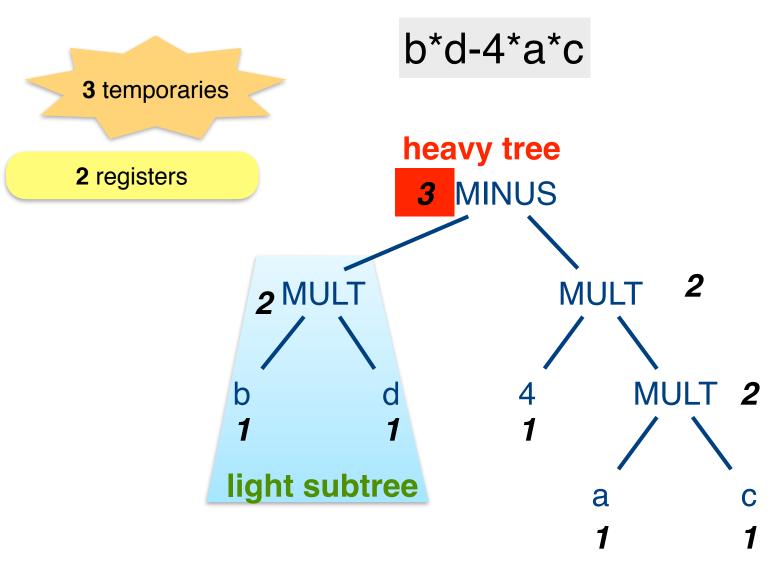
- Re-ordering subtree computations
- Register reuse
- Optimal under certain conditions
 - uniform instruction cost
 - "symbolic" trees
- Correct for subexpressions without side-effects

What if we need more registers than available?

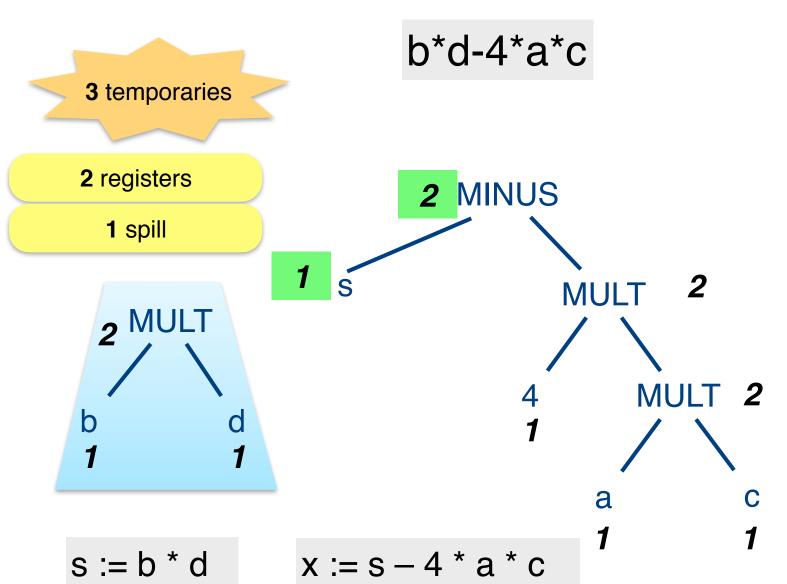
Simple spilling method

- A heavy tree contains a heavy subtree whose dependents are light
- Heavy tree needs more registers than available
- Generate code for the light tree
- Spill the result to memory and replace subtree by temporary
- Generate code for the resultant tree

Example: simple spilling



Example: simple spilling



Generalization

- More than two arguments for operators
- Function calls
- Register/memory operations
- Multiple effected registers
- Handle non-uniform instruction costs

- Share registers between different expressions
- Keep frequently accessed values in registers
 - example: loop counters

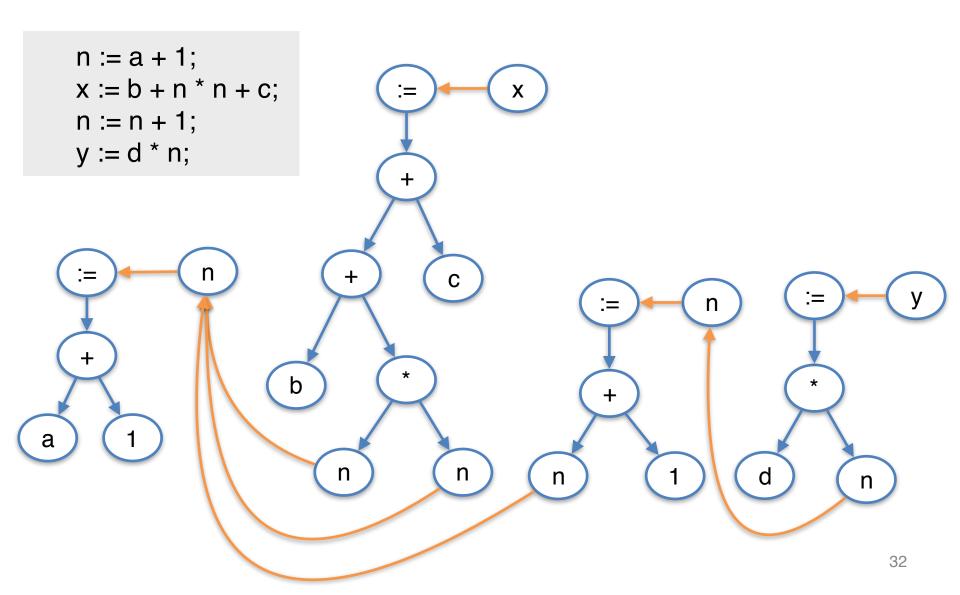
Global code generation

- Construct
 - dependency graph
 - control flow graph
 - liveness information for each variable
 - interference graph for variables

- Code selection: linearizations of dependencies
- Register allocation: interference graph coloring

Dependency graph

- Nodes are variable occurrences
- Edge between use and definition of a variable
 - for example, x := y + z
 - defines x
 - uses y and z
- Variable: definition vs declaration
 - definition is an assignment of a value to the variable
 - declaration is an association of a scope/type with a variable



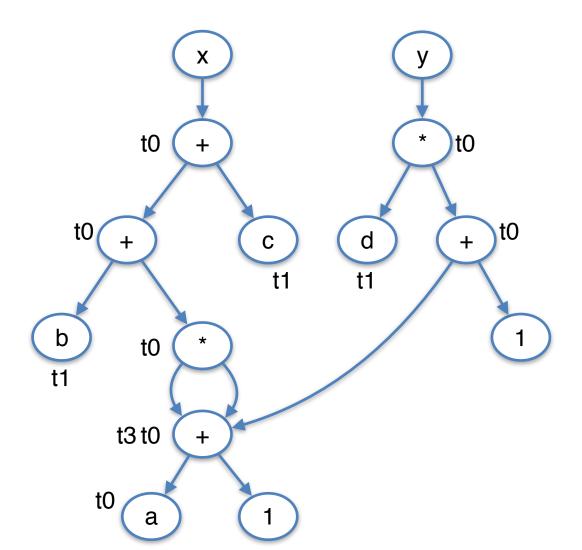
```
n := a + 1;

x := b + n * n + c;

n := n + 1;

y := d * n;
```

```
t0 a
lw
addi t0 t0 1
move t3 t0
mul t0 t0 t0
lw t1 b
add t0 t1 t0
lw t1 c
   t0 t0 t1
add
   t0 x
sw
addi t0 t3 1
     t1 d
lw
mul t0 t1 t0
     t0 y
SW
```



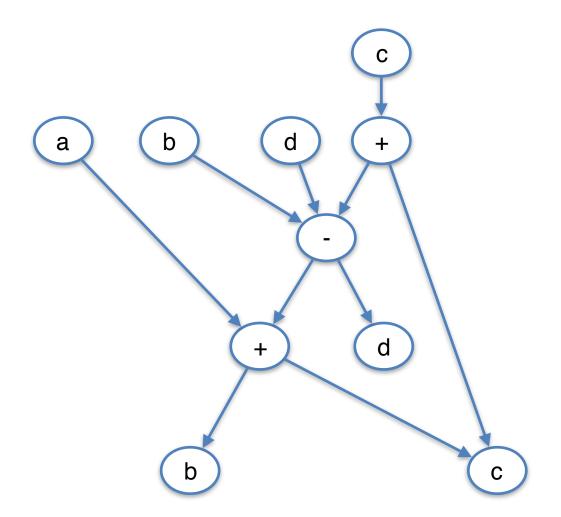
```
a = b + c

b = a - d

c = b + c

d = a - d
```

t0 b lw lw t1 c add t0 t0 t1 t0 a SW lw t2 d t0 t0 t2 sub t0 b SW t0 d SW t0 t0 t1 add t0 c SW



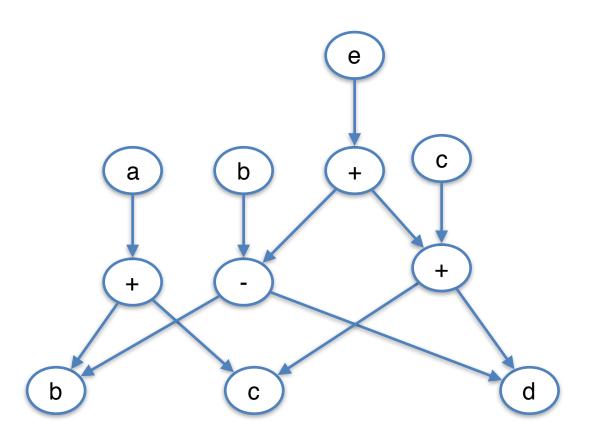
```
a = b + c

b = b - d

c = c + d

e = b + c
```

lw	t0	b	
lw	t1	C	
add	t2	t0	t1
sw	t1	a	
lw	t3	d	
sub	t0	t0	t2
sw	t0	b	
sw	t0	d	
add	t0	t0	t1
SW	t0	С	



Dependencies

- Fundamental concept in programming languages
 - control dependencies
 - data dependencies
- Example: loop parallelization respect dependencies between loop iterations

```
#pragma omp parallel for for (i=0; i<n; i++)
    a[i] = b[i]
```

```
#pragma omp parallel for for (i=1; i<n; i++) a[i] = a[i-1]
```

Basic Block

- A sequence of instructions
- Single entry
 - to first instruction
 - no jumps to the middle of the block
- Single exit
 - last instruction
 - no jumps (explicit/implicit) out of the block in the middle
- Code executes as a sequence from first instruction to last instruction without any jumps

Control flow graph (CFG)

- Nodes are basic blocks
- Edge from basic block B1 to block B2 when the last statement of B1 may jump to B2

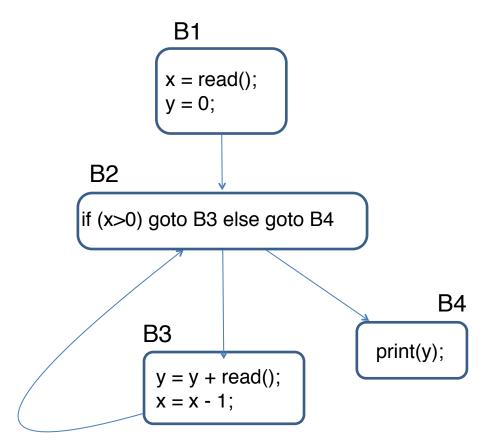
Example: CFG for conditionals

```
B1: a = x[i];
    b = x[j];
    c = x[k];
    a = a + b + c;
    if (a<10) {
B2: d = c + 8;
       print(c);
    } else
B3: if (a<20) {
B4: e = 10;
      d = e + a;
      print(e);
    } else {
B5: f = 12;
       d = f + a;
       print(f);
B6: print(d);
```

```
B1
                 a = x[i];
                 b = x[j];
                c = x[k];
                 a = a + b + c:
                 if (a<10) goto B2 else goto B3
B2
                                                     B3
 d = c + 8;
                                      if (a<20) goto B4
 print(c);
                                      else goto B5
                    B4
                                                       B5
                   e = 10;
                   d = e + a;
                                             f = 12;
                   print(e);
                                              d = f + a;
                                              print(f);
                        B6
                        print(d);
                                                           39
```

Example: CFG for loop

```
B1: x = read();
y = 0;
B2: while (x > 0) {
B3: y = y + read();
x = x - 1;
}
B4: print(y);
```



Variable liveness

- A variable x is live at program point L
 if the value that x has at point L is used later in an
 execution
- Backwards analysis

print(x)
uses x

Example: liveness

```
b = a + 2 {a}

c = b * b {b, a}

b = c + 1 {a, c}

return b * a {b, a}
```

Example: liveness

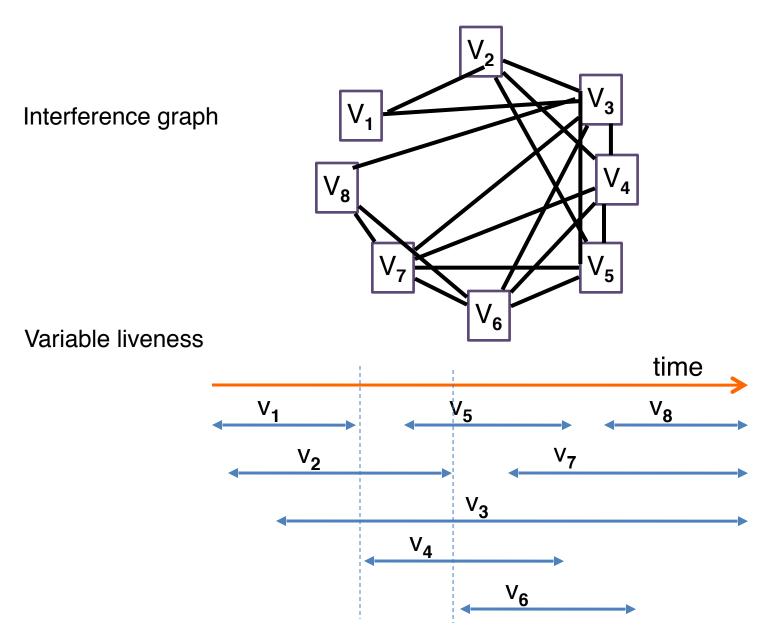
can we change the order between assignment to y and z?

$$x = 1$$
 {}
 $y = x + 3$ {x}
 $z = x * 3$ {x}
 $x = x * z$ {x, z}

Interference graph

- Node for every variable
- Edges between variables that interfere
- Variables interfere if they are live at the same time
- Variables do not interfere if they have disjoint live ranges

Examples: interference graph



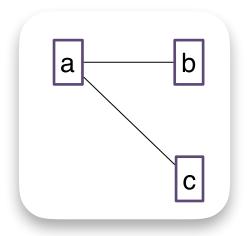
Examples: interference graph

$$b = a + 2$$

$$c = b * b$$

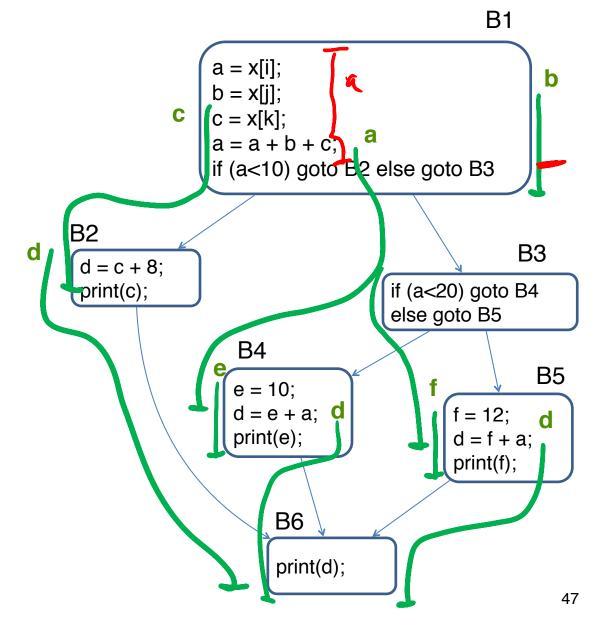
$$b = c + 1$$

return b * a

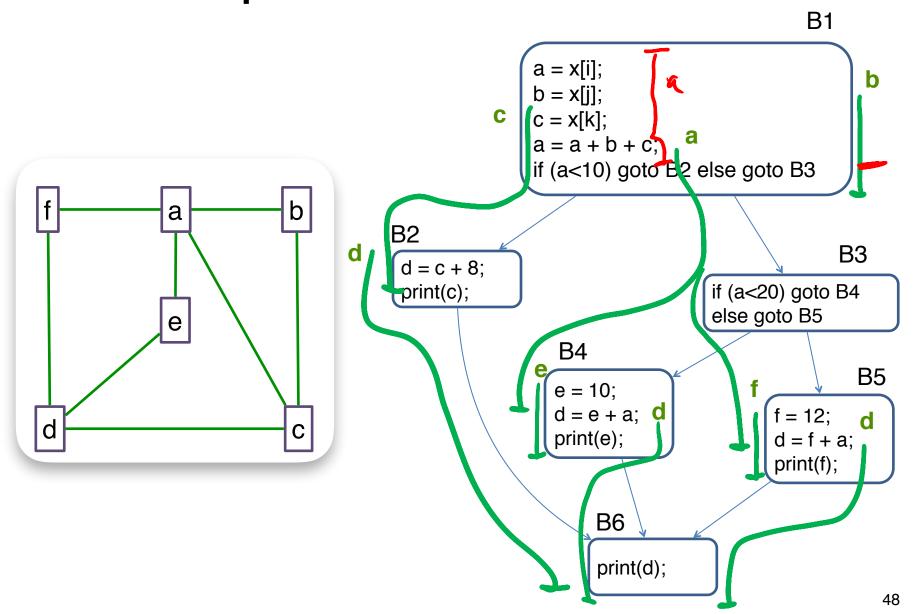


Example: variable liveness

```
B1: a = x[i];
    b = x[j];
    c = x[k];
    a = a + b + c;
    if (a<10) {
B2: d = c + 8;
       print(c);
    } else
B3: if (a<20) {
B4: e = 10;
      d = e + a;
      print(e);
    } else {
    f = 12;
B5:
       d = f + a;
       print(f);
B6: print(d);
```



Example: variable liveness



Register Allocation by Graph Coloring

- Reduction from register allocation to graph coloring
- Coloring of an interference graph
- Number of colors = number of registers
- Color of a node corresponds to the register assigned to the variable
- Variables that do not interfere with each other can be assigned the same register

Graph coloring

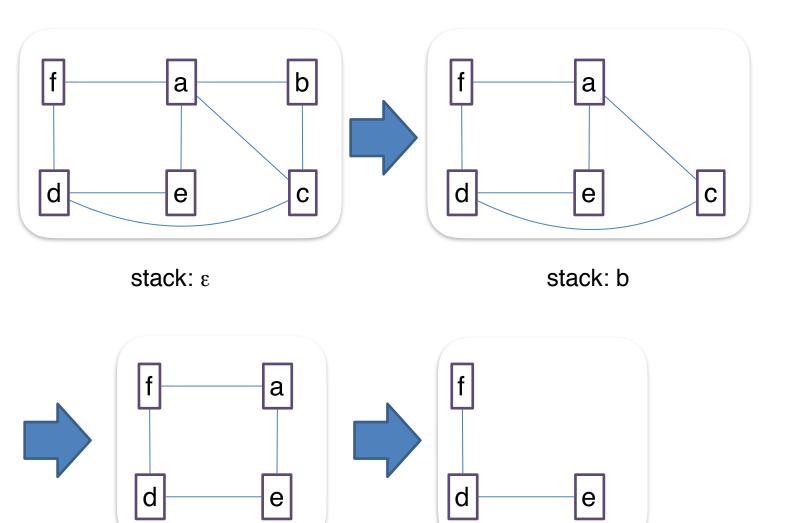
- Classical problem
- How to color all nodes of a graph using the smallest possible number of colors such that no two adjacent nodes have the same color

- NP-complete
- There are pretty good heuristic approaches

Heuristic graph coloring

- Easiest nodes to color are nodes with the lowest degree
 - degree of a node is the number of neighbors
 - lowest degree means fewer conflicts
- Color nodes one by one, coloring the easiest nodes last
- Algorithm at high-level
 - find the least connected node
 - remove least connected node from the graph
 - color the reduced graph recursively
 - re-attach the least connected node

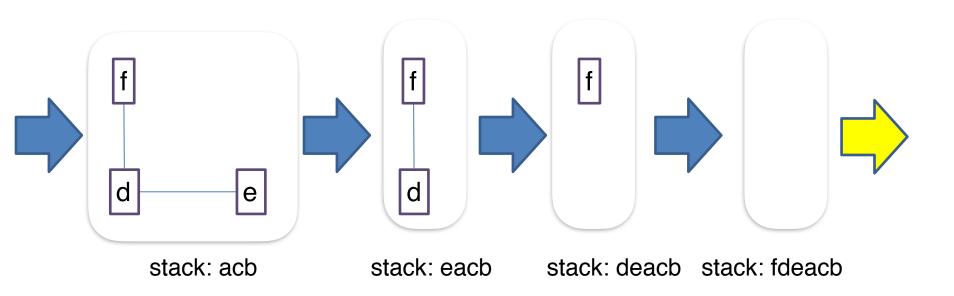
Example: heuristic graph coloring

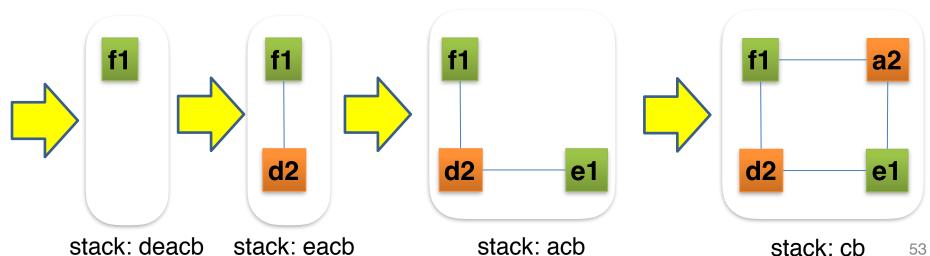


stack: cb stack: acb

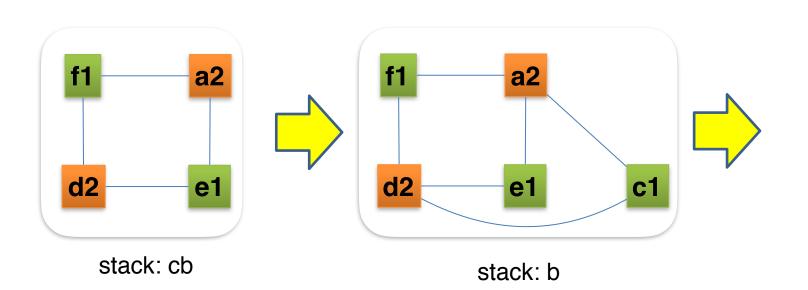
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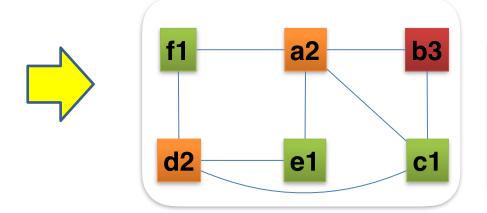
Example: heuristic graph coloring





Example: heuristic graph coloring





Result: 3 registers for 6 variables

Can we do with 2 registers?

stack: ε

Heuristic graph coloring

- Sources of non-determinism in the algorithm
 - choosing which of the (possibly many) nodes of lowest degree should be detached
 - choosing which of the available colors to use

Spilling

- If every node has at least K neighbors, the graph cannot be colored with K colors
- Which node to spill?
 - try to pick node not used much, not in inner loop
- How to spill?
 - rewrite code to spill, recompute liveness, and try to color again
- Precolored nodes for registeres with designated uses
 - infinite degree: cannot be spilled or coaleased

Coalescing

- Eliminate register-to-register moves
 - move r1 r2
 - r1 and r2 do not interfere
 - merge nodes r1 and r2 and unify the sets of neighbors
- Might fail to color the graph (why?)
- Conservative: merge nodes if the resulting node has fewer than K neighbors with degree K (in the resulting graph)

Why not graph coloring?

- Interference graph is too expensive to build
- Flexibility is more important than efficiency
 - spill code placement
 - aliases and overlapping register classes

Summary: code generation and optimizaton

- Multiple passes: register allocation, instruction selection, instruction scheduling,...
- Well-defined goals and clear specification for each pass
- Reduction to known problems/algorithms
- Easier to write, maintain, prove correctness, achieve optimality
- In reality...
 - correctness depends on (implicit) invariants between phases
 - non-monotonic effect on performance: one pass counteracts another
 - missed optimization opportunities
 - peephole optimizations

Superoptimization

- Exhaustive search in the space of (small) programs for finding optimal code sequences
 - often counterintuitive results, not what a human would write
 - generated code can be very efficient
 - generate/test paradigm

Compiler correctness

- Generated code correctly implements the source code
- Concerns with correctness of translation
- Different from code correctness
- Compilers do not guarantee to generate "correct code"
- For example, consider a program that throws a NullPointerException at runtime

Compiler design goals

- Correctness: generated code correctly implements the source code
- Metrics for generated code
 - performance/speed
 - size
 - power consumption/energy efficiency
 - security/reliability
 - easy to debugging
 - portable
- Metrics for compilers
 - fast/efficient compilation
 - good error reporting

Optimizations

- "Optimal code" is out of reach
 - many problems are undecidable or too expensive
 - use approximation and/or heuristics
 - optimizations must guarantee correctness of compiler
 - should (mostly) improve code
- Majority of compilation time is spent in optimizations
- Leverage compile-time information to save work at runtime (precompute)

Example optimizations

- Loop optimizations: hoisting, unrolling
- Peephole optimizations
- Constant propagation
- Dead code elimination
- Instruction selection: convert IR to machine instructions
- Instruction scheduling: reorder instructions
- Register allocation: assign variables to memory locations
 - optimal register assignment is NP-Complete
 - in practice, known heuristics perform well
- Modern architectures include challenging features
 - multicore
 - memory hierarchies

Compiler construction tools

- Parts of the compiler are automatically generated from specification
 - simplify compiler construction
 - less error prone
 - more flexible
 - use of pre-canned tailored code
 - use of dirty programming tricks
 - reuse of specification

Compiler construction tools

- Lexical analysis generators
 - lex, flex, jflex, antlr
- Parser generators
 - yacc, bison, java_cup, antlr
- Syntax-directed translators
- Dataflow analysis engines

Summary

- Compiler is a program that translates code from source language to target language
- Compilers play a central role
 - bridge from high-level programming languages to machines
 - many useful techniques
 - many useful tools (e.g., lexer/parser generators)
- Compiler vs Interpreter
- Just-In-Time compilation
- Time of events: compiler, linker, loader, runtime
- Bootstrapping a compiler
- Compiler constructed from modular phases

Meanwhile, in the real world

- new compilers for new languages
- new compilers for old languages
 - e.g., Java->JavaScript
- new uses of compiler technology

• . . .

HOW TO PREPARE FOR THE EXAM?

How to prepare for the exam?

- Make sure you understand the material covered in
 - slides on QM+ for lectures and tutorials
 - exercises and their solutions
 - programming assignments
 - cool reference manual
- Solve the mock exam and compare to model answers
- Revision lecture: Tuesday, 24 April Arts Two 3.16
- Solve questions from past exams
- How to get more help?
 - use the forum on qm+
 - office hours: email me to arrange

What is **not** for the exam?

- Bottom-up parsing algorithms
- Tail recursion
- Register allocation via graph coloring
- Static vs dynamic scoping
- Cool operational semantics rules [section 13 of Cool Reference Manual]

Structure of the exam

Answer ALL FOUR questions

Question 1 [30 marks] Parsing
Question 2 [20 marks] Classify events
Question 3 [20 marks] Concepts in compilers
Question 4 [30 marks] Modify Cool Compiler

Examples: modify cool compiler

- Add new control flow constructs
 - repeat expr until expr teaper
 - for i ← [0..n] do expr rof
- Add data types
 - records
 - arrays
- Change OO features
 - inheritance
 - interfaces / abstract / virtual

THANK YOU!