

Writing Applications using Contiki

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30. Juli 2015

Structure

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Structure

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 - Features
- 3 Processes
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- 5 Example: The Single-Hop-Protocol

Features

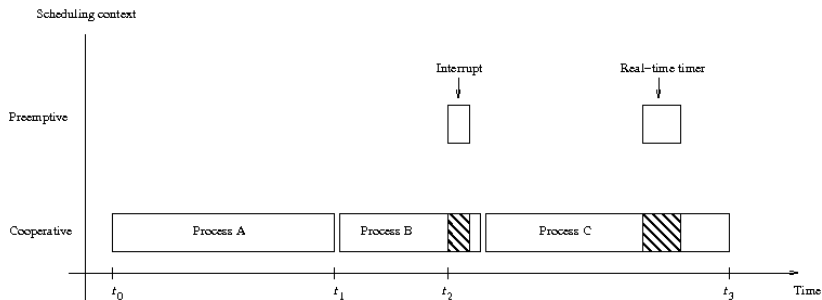
- Open Source Software
- Community and Commercial Support
- IP Networking
 - IPv4, IPv6
 - 6lowpan, RPL, CoAP
- Rime Network Stack
- Sleepy Routers
- Memory Allocation (memb, mmem, malloc)
- Simulation Environment (Cooja)

Structure

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 - General
 - Events
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General

- All programs are processes
- Processes are cooperative
- Interrupts and Real-time timer are preemptive



Process Structure

Process Control Block:

```
PROCESS( hello_world_process , " Hello_world_process" );
```

Process Thread:

```
PROCESS_THREAD( hello_world_process , ev , data )  
{  
    PROCESS_BEGIN();  
  
    printf(" Hello ,_world\n" );  
  
    PROCESS_END();  
}
```

Events

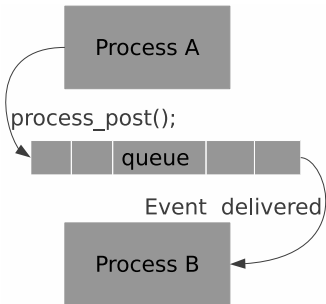


Abbildung: Asynchronous Event.

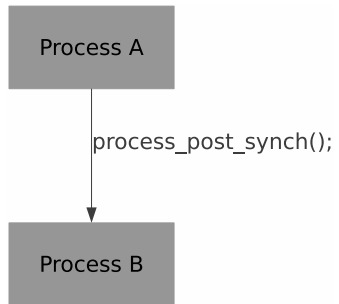


Abbildung: Synchronous Event.

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 - Clock module
 - Timer modules
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Clock Module

- handling system time
- block CPU
- base for timer module

Functions:

```
clock_time_t clock_time();           //Get the system time.  
unsigned long clock_seconds();       //Get the system time(s)  
void clock_delay(unsigned int delay); //Delay the CPU.  
void clock_wait(int delay);          //Delay the CPU (ticks).  
CLOCK_SECOND;                       //Ticks per second.
```

Timer Module

- Timer: timer, stimer, etimer, ctimer, rtimer
- declared as: struct timer
- timer + stimer has to be checked manually
- etimer throws event: `PROCESS_EVENT_TIMER`
- ctimer calls a function with data pointer as argument
- rtimer
 - preemptiv
 - uses own clock module with higher resolution

