

ChestX-ray14 [16] 2025 Analysis

George Fisher

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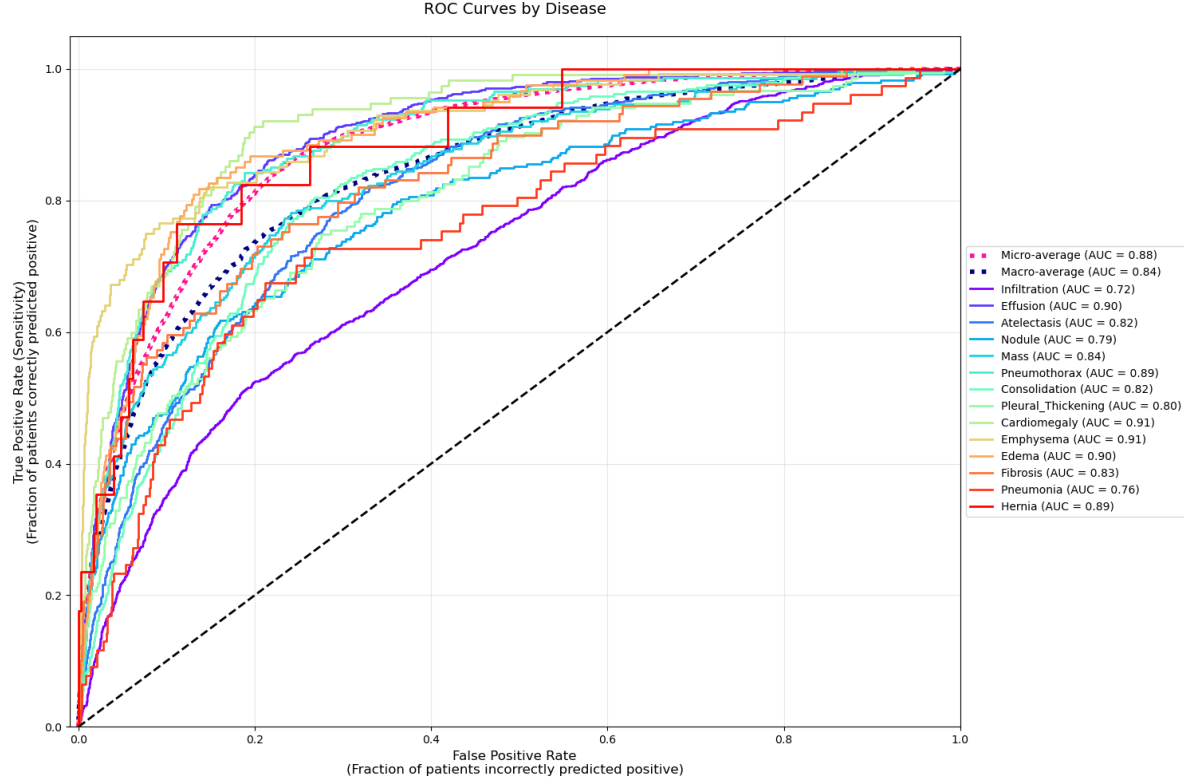
Convolutional Neural Networks have become increasingly useful in medical imaging problems. This analysis (Fisher 2025) uses the NIH ChestX-ray14 dataset of 112,120 chest x-rays representing 14 diseases in 30,805 unique patients to produce the human practitioner-level AUC scores shown in the graph below for this study (Fisher, 2025) and other well-known studies.

The goal is to improve diagnostic accuracy by using an improved loss function and a simpler model than is conventionally done while producing the same or better AUC for each disease.

1 Summary of results and process

The AUC value reflects the test's ability to distinguish between diseased and non-diseased individuals. The range is from less than 0.5, which is a coin flip, to 1.0, perfection.

Disease	Fisher 2025 [7]	Rajpurkar 2017 [15]	Bhusala 2024 [11]	Hasanah 2024 [8]	Ahmad 2023 [1]
Cardiomegaly	0.915	0.924	0.896	0.922	0.920
Emphysema	0.913	0.937	0.820	0.935	0.870
Edema	0.899	0.927	0.820	0.850	0.860
Effusion	0.898	0.887	0.820	0.810	0.840
Pneumothorax	0.892	0.888	0.890	0.850	0.870
Hernia	0.886	0.916	0.840	0.936	0.850
Mass	0.837	0.848	0.867	0.820	0.830
Fibrosis	0.833	0.804	0.810	0.780	0.810
Consolidation	0.824	0.893	0.810	0.790	0.830
Atelectasis	0.816	0.809	0.810	0.820	0.850
Pleural Thickening	0.803	0.806	0.810	0.790	0.820
Nodule	0.791	0.780	0.655	0.760	0.700
Pneumonia	0.756	0.768	0.770	0.810	0.800
Infiltration	0.723	0.734	0.730	0.700	0.750
Mean	0.842	0.852	0.811	0.827	0.829
St Dev	0.061	0.067	0.062	0.068	0.054



Keras/TensorFlow 2.17 [5][12] was used on an AWS g5.xlarge on-demand instance [2], running Amazon Linux 2023, in Jupyter notebooks [10], with Cuda compilation tools release 12.2 [13]. The DenseNet121 [9] base model was combined with additional techniques described in detail below. The data set was very unbalanced (many more normal than diseased), and I successfully used a *DynamicWeightedBCE_wgt_smooth* loss function rather than the more common standard weighted cross entropy loss function. In addition, the model architecture is much simpler than many others while producing similar results.

The chart above reflects the results of an analysis that was terminated after only four epochs by early stopping, indicating that overfitting had begun, giving hope that better results can be achieved with more work, which is ongoing.

The steps taken were the following

1. Download the NIH images to an AWS S3 bucket.
2. Resize the images from (1024, 1024, 1) to (320, 320, 3) on local storage. The DenseNet121 base model requires three channels, and the choice of 320, 320 merely followed the convention set by others, probably balancing quality and memory considerations. It seems likely that with the large machines available today more detail could be wrung from the original-sized images, and I am considering trying it on an AWS g5.24xlarge spot instance, which has 384Gb of RAM compared to the 16Gb on my current g5.xlarge.

3. Created train, val, test datasets (90%, 5%, 5%) with evenly-distributed diseases and no patient overlap.
4. Using a 'toy' model, I tested 18 loss functions and settled on DynamicWeightedBCE_wgt_smooth, which produced the best results.
5. I then tested the entire dataset with all 14 diseases on a 'real' model, modifying it until I achieved the best single-run results.
6. Finally, I ensembled five models, run with different hyper-parameters, to produce the results shown here.

2 Dynamic Weighted Binary Cross-Entropy Loss Function with Label Smoothing

This section explains a custom TensorFlow loss function implementation that combines dynamic class weighting with label smoothing for binary classification tasks.

Overview

The DynamicWeightedBCE_wgt_smooth class implements a specialized version of binary cross-entropy (BCE) loss that addresses two common challenges in binary classification:

1. Class imbalance through dynamic weighting
2. Model overconfidence through label smoothing

Implementation

```
class DynamicWeightedBCE_wgt_smooth(tf.keras.losses.Loss):
    def __init__(self, smoothing_factor=0.1):
        super().__init__()
        self.smoothing_factor = smoothing_factor

    def call(self, y_true, y_pred):
        epsilon = tf.keras.backend.epsilon()
        y_pred = tf.clip_by_value(y_pred, epsilon, 1-epsilon)

        # Calculate class ratios with smoothing
        pos_ratio = tf.reduce_mean(y_true, axis=0)
        smoothed_ratio = pos_ratio * (1 - self.smoothing_factor) + 0.5 * self.smoothing_factor

        pos_weights = 1.0 / (smoothed_ratio + epsilon)
        neg_weights = 1.0 / (1.0 - smoothed_ratio + epsilon)

        return -tf.reduce_mean(
            y_true * pos_weights * tf.math.log(y_pred) +
```

```

        (1-y_true) * neg_weights * tf.math.log1p(-y_pred)
    )

```

Key Features

1. Dynamic Class Weighting

Unlike standard weighted BCE which uses fixed weights, this implementation calculates weights dynamically based on the current batch composition:

- Computes the positive class ratio (**pos_ratio**) for each batch
- Derives weights inversely proportional to class frequencies
- Automatically adjusts to changing class distributions

2. Label Smoothing

The implementation incorporates label smoothing through the **smoothing_factor** parameter:

- Moves class ratios slightly towards 0.5 (balanced distribution)
- Helps prevent the model from becoming overconfident
- Reduces the impact of noisy labels
- Default smoothing factor of 0.1 provides mild regularization

Comparison with Standard Weighted BCE

Standard Weighted BCE:

```

class WeightedBinaryCrossentropy(tf.keras.losses.Loss):
    def __init__(self, pos_weight):
        super().__init__()
        self.pos_weight = pos_weight

    def call(self, y_true, y_pred):
        return tf.reduce_mean(
            -(self.pos_weight * y_true * tf.math.log(y_pred) +
              (1 - y_true) * tf.math.log(1 - y_pred))
        )

```

Key differences:

1. Weight Calculation

- Standard: Uses fixed pre-defined weights
- Dynamic: Calculates weights based on batch statistics

2. Numerical Stability

- Standard: Basic implementation may have numerical stability issues

- Dynamic: Includes epsilon terms and value clipping for stability

3. Label Smoothing

- Standard: No built-in smoothing mechanism
- Dynamic: Incorporates smoothing to prevent overconfidence

Usage Example

```
# Create loss function instance
loss_fn = DynamicWeightedBCE_wgt_smooth(smoothing_factor=0.1)

# Create and compile model
model = tf.keras.Sequential([...])
model.compile(
    optimizer='adam',
    loss=loss_fn,
    metrics=['accuracy']
)
```

Best Practices

1. Smoothing Factor Selection

- Start with the default value of 0.1
- Increase for noisier datasets (up to 0.2)
- Decrease for cleaner datasets (down to 0.05)

2. Monitoring

- Track both loss and accuracy metrics
- Watch for signs of underconfident predictions with high smoothing

3. Batch Size Considerations

- The theory is that larger batch sizes (128/256) work better but the empirical fact is that batch_size=16 worked best for me
- Ensures stable ratio estimates for weight calculation

Limitations

1. Only suitable for binary classification tasks
2. Requires batch sizes large enough for reliable ratio estimation
3. May need tuning of smoothing factor for optimal performance
4. Additional computational overhead compared to standard BCE

3 DenseNet121 Model with CBAM Attention Architecture

This section details a deep learning model that combines DenseNet121 with Convolutional Block Attention Module (CBAM) for improved feature attention and classification performance.

Architecture Overview

The model architecture consists of three main components:

1. DenseNet121 as the backbone feature extractor
2. CBAM attention mechanism
3. Classification head with regularization

```
def create_model(num_labels=NUM_CLASSES, input_shape=INPUT_SHAPE, dropout_rate=0.3):
    inputs = tf.keras.layers.Input(shape=input_shape)

    # Base DenseNet121
    base_model = tf.keras.applications.DenseNet121(
        weights='imagenet',
        include_top=False,
        input_tensor=inputs
    )

    # All layers are trainable by default
    x = base_model.output

    # Add Convolutional Block Attention Module (CBAM)

    # Channel Attention
    avg_pool = tf.keras.layers.GlobalAveragePooling2D()(x)
    max_pool = tf.keras.layers.GlobalMaxPooling2D()(x)

    avg_pool = tf.keras.layers.Reshape((1, 1, 1024))(avg_pool)
    max_pool = tf.keras.layers.Reshape((1, 1, 1024))(max_pool)

    shared_dense_1 = tf.keras.layers.Dense(512, activation='relu')
    shared_dense_2 = tf.keras.layers.Dense(1024)

    avg_pool = shared_dense_1(avg_pool)
    max_pool = shared_dense_1(max_pool)
    avg_pool = shared_dense_2(avg_pool)
    max_pool = shared_dense_2(max_pool)

    channel_attention = tf.keras.layers.Add()([avg_pool, max_pool])
    channel_attention = tf.keras.layers.Activation('sigmoid')(channel_attention)
```

```

# Apply channel attention
x = tf.keras.layers.Multiply()([x, channel_attention])

# Spatial Attention
avg_pool = tf.keras.layers.Lambda(lambda x: tf.keras.backend.mean(x, axis=-1, keepdims=True))(x)
max_pool = tf.keras.layers.Lambda(lambda x: tf.keras.backend.max(x, axis=-1, keepdims=True))(x)
spatial_attention = tf.keras.layers.Concatenate()([avg_pool, max_pool])

spatial_attention = tf.keras.layers.Conv2D(1, kernel_size=7, padding='same', activation='sigmoid')(x)

# Apply spatial attention
x = tf.keras.layers.Multiply()([x, spatial_attention])

# Global pooling and classification layers
x = tf.keras.layers.GlobalAveragePooling2D()(x)

x = tf.keras.layers.Dense(128, activation='relu', kernel_regularizer=tf.keras.regularizers.L2(0.001))(x)
x = tf.keras.layers.Dropout(dropout_rate)(x)

x = tf.keras.layers.Dense(64, activation='relu', kernel_regularizer=tf.keras.regularizers.L2(0.001))(x)
x = tf.keras.layers.Dropout(dropout_rate)(x)

outputs = tf.keras.layers.Dense(num_labels, activation='sigmoid')(x)

model = tf.keras.models.Model(inputs=inputs, outputs=outputs)
return model

```

Component Details

1. DenseNet121 Backbone

- Pre-trained on ImageNet
- Weights are retained and fine-tunable
- Top layers are removed for custom classification head

Key characteristics of DenseNet:

- Dense connectivity pattern
- Feature reuse through direct connections
- Reduced number of parameters
- Strong gradient flow

2. CBAM Attention Module

The CBAM consists of two sequential sub-modules:

Channel Attention

1. Parallel processing of input features through:
 - Global Average Pooling
 - Global Max Pooling
2. Shared Multi-Layer Perceptron network:
 - First dense layer: $1024 \rightarrow 512$ (ReLU)
 - Second dense layer: $512 \rightarrow 1024$
3. Feature fusion:
 - Addition of processed pooled features
 - Sigmoid activation for attention weights
4. Channel-wise multiplication with input features

Spatial Attention

1. Feature aggregation across channels:
 - Average pooling across channels
 - Max pooling across channels
2. Concatenation of pooled features
3. 7×7 convolution with sigmoid activation
4. Spatial-wise multiplication with input features

3. Classification Head

The classification layers include:

1. Global Average Pooling
 - Reduces spatial dimensions
 - Translation invariance
2. Dense Blocks
 - 128, 64 units with ReLU activation
 - L2 regularization ($\lambda=0.001$)
 - Dropout (rate=0.3)
3. Output Layer
 - num_labels (14 in this case) units
 - Sigmoid activation for multi-label classification

Implementation Details

Input Requirements

- Input shape: Configurable through INPUT_SHAPE parameter, (320, 320, 3) in this case
- Preprocessing: `tf.keras.applications.densenet.preprocess_input`
- RGB (3 channel) images expected

Model Parameters

- num_labels: Number of classification categories (14, `len(label_text)`)
- label_text: in order by frequency ['Infiltration', 'Effusion', 'Atelectasis', 'Nodule', 'Mass', 'Pneumothorax', 'Consolidation', 'Pleural_Thickening', 'Cardiomegaly', 'Emphysema', 'Edema', 'Fibrosis', 'Pneumonia', 'Hernia']
- dropout_rate: Dropout probability (default: 0.3)

Regularization Techniques

1. Dropout layers (rate=0.3)
2. L2 regularization on dense layers ($\lambda=0.001$)
3. Attention mechanisms act as implicit regularization

Advantages of This Architecture

1. Feature Enhancement
 - CBAM helps focus on relevant features
 - Both channel and spatial attention
 - Adaptive feature refinement
2. Regularization Benefits
 - Multiple dropout layers & L2 regularization
 - Attention-based feature selection
3. Transfer Learning
 - Pre-trained DenseNet backbone
 - Feature reuse from ImageNet
4. Flexibility
 - Adjustable number of output classes
 - Configurable dropout rate
 - Modifiable dense layer dimensions

5. Much simpler than models employed by other studies

4 Deep Learning Model Training Callbacks

This section describes the callbacks used during model training to monitor performance, prevent overfitting, and save training progress.

Overview

The training process utilizes four key callbacks:

1. Early Stopping
2. Learning Rate Reduction
3. Model Checkpointing
4. Custom CSV Training Logger

Early Stopping Callback

The Early Stopping callback prevents overfitting by monitoring validation loss stopping training when improvement stalls and restoring the weights from the best epoch.

Key Parameters:

- Monitor: Validation loss
- Patience: 10 epochs
- Minimum Delta: 0.00001
- Restore Best Weights: Yes
- Mode: Minimize

Learning Rate Schedule Callback

The ReduceLROnPlateau callback dynamically adjusts the learning rate during training to fine-tune model performance.

Key Parameters:

- Monitor: Validation loss
- Reduction Factor: 0.5 (halves the learning rate)
- Patience: 3 epochs
- Minimum Delta: 0.0001
- Minimum Learning Rate: 1e-6

This adaptive learning rate strategy adjusts after 3 epochs of no improvement, which allows at least three such periods before early stopping kicks in.

Model Checkpoint Callback

The ModelCheckpoint callback saves model states during training, ensuring no progress is lost and allowing for model recovery.

Key Features:

- Saves complete model (not just weights)
- Saves only when validation loss improves
- Filename includes epoch number and validation loss
- Checkpoint directory: "model_checkpoints/"

The naming convention "weights.{epoch:04d}-{val_loss:.5f}.keras" provides:

- Easy identification of training progress
- Quick comparison of model performance
- Chronological tracking of improvements

Custom CSV Training Logger

A custom callback that logs comprehensive training metrics to a CSV file for detailed analysis and visualization, particularly the creation of loss-function graphs.

Key Features:

- Creates logging directory if needed and handles file creation and headers automatically
- Timestamps each training epoch
- Records multiple metrics including:
 - Loss values (training and validation)
 - AUC scores
 - Recall metrics
 - Specificity measures
 - F1 scores
 - Hamming loss
 - Positive/Negative Predictive Values

5 Model Evaluation Metrics

This section describes the metrics used to evaluate model performance, including both custom implementations and standard TensorFlow metrics.

Overview

The evaluation framework includes seven key metrics:

1. Recall (Standard TensorFlow)
2. Specificity (Custom)
3. AUC (Standard TensorFlow)
4. Positive Predictive Value/Precision (Standard TensorFlow)
5. Negative Predictive Value (Custom)
6. F1 Score (Standard TensorFlow)
7. Hamming Loss (Custom)

Custom Metrics

1. Specificity (True Negative Rate)

A custom implementation that measures the model's ability to correctly identify negative cases.

Key Features:

- Tracks true negatives (TN) and total negatives (PN)
- Calculated as TN / PN
- Handles batch-wise updates
- Includes epsilon term for numerical stability

Use Cases:

- Critical in medical diagnosis where false positives must be minimized
- Important for imbalanced datasets
- Complementary to sensitivity/recall

2. Hamming Loss

A custom metric that quantifies the fraction of incorrect predictions (both false positives and false negatives).

Key Features:

- Configurable prediction threshold (default: 0.5)
- Batch-wise computation
- Normalized by sample count
- Suitable for multi-label classification

Use Cases:

- Multi-label classification evaluation
- When prediction errors have equal cost
- General model performance assessment

Standard TensorFlow Metrics

1. Recall (Sensitivity)

- Measures proportion of actual positive cases correctly identified
- Built-in TensorFlow implementation
- Crucial for medical diagnosis and fraud detection

2. Area Under Curve (AUC)

- Configured for multi-label classification
- Measures model's ability to distinguish between classes
- Independent of classification threshold

3. Precision (Positive Predictive Value)

- Measures proportion of positive predictions that are correct
- Standard TensorFlow implementation
- Important for minimizing false positives

4. F1 Score

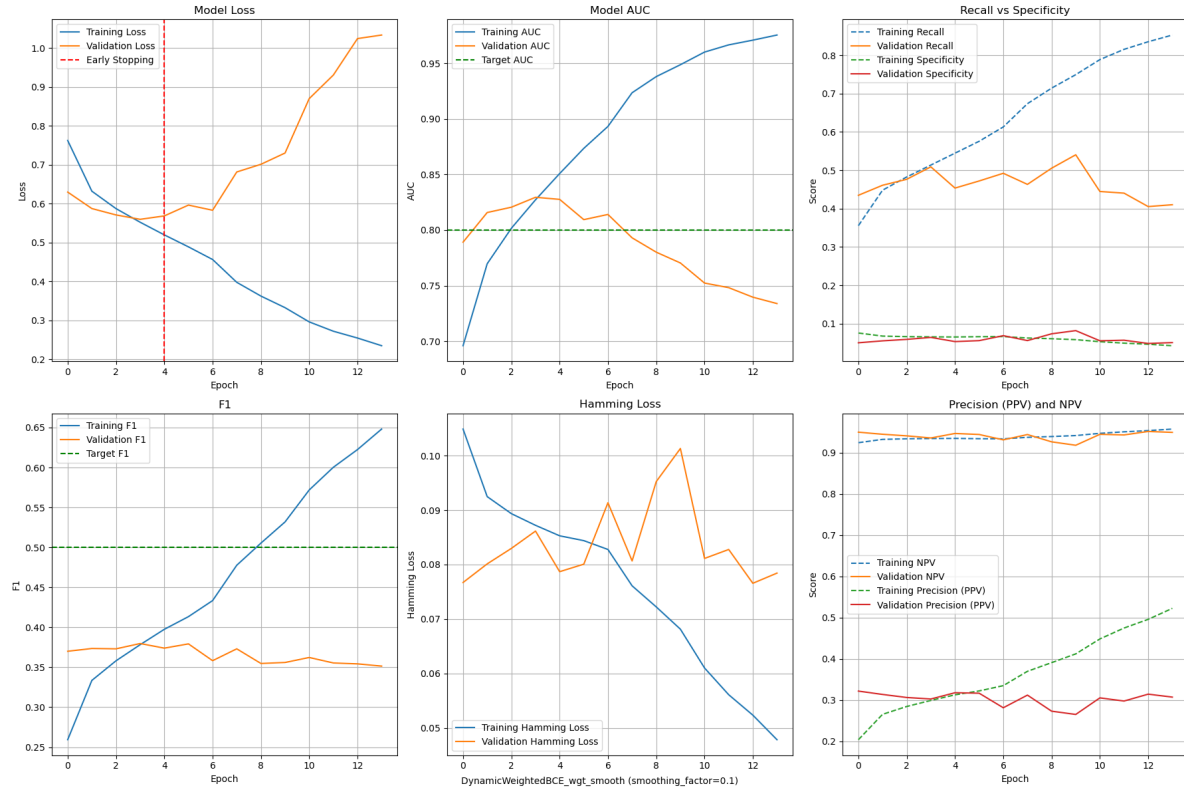
- Harmonic mean of precision and recall
- Micro-averaged across labels
- Balanced metric for overall performance

Key Parameters

1. Threshold Settings:
 - Prediction threshold for binary decisions
 - Affects Hamming Loss and F1 Score calculations
 - Configurable based on application needs
2. Multi-label Configuration:
 - AUC configured for multi-label scenarios
 - Number of labels specified
 - Micro-averaging for F1 Score

6 Model Performance Analysis

Training History



The training history reveals several key insights about the model's learning progression:

Loss Curves

- Training loss shows consistent decrease throughout training
- Validation loss initially decreases but starts increasing after epoch 4 (red dashed line)
- Early stopping triggered to prevent overfitting

AUC Performance

- Training AUC steadily improves, reaching ~0.98
- Validation AUC peaks around epoch 4 at ~0.82
- Clear signs of overfitting as training and validation AUC diverge
- Model achieves the target AUC of 0.80 (green dashed line)

Recall vs Specificity

- Training recall significantly improves over time (~ 0.85)
- Training specificity remains relatively stable (~ 0.45)
- Validation metrics show minimal improvement, suggesting potential learning issues
- Trade-off between recall and specificity is evident

F1 Score

- Training F1 score shows steady improvement
- Validation F1 score remains relatively flat (~ 0.35)
- Target F1 score of 0.50 (green dashed line) not achieved in validation

Hamming Loss

- Training Hamming loss decreases consistently
- Validation Hamming loss shows fluctuations
- Final validation Hamming loss ~ 0.08

Precision and NPV

- High NPV (~ 0.9) for both training and validation
- Lower Precision/PPV (~ 0.3) indicates challenges with false positives
- Stable metrics throughout training

7 Overall Conclusions

Strengths

1. Good overall discrimination ability (micro-AUC = 0.87)
2. Excellent performance on several critical conditions
3. High NPV across conditions

Areas for Improvement

1. Manage overfitting (evident in training curves)
2. Improve detection of challenging conditions
3. Better balance between precision and recall

8 Author

George Fisher

For more information about the model and processes, visit GitHub <https://github.com/grfiv/ChestX-ray14>

For information about me, visit <https://georgefisher.com/resume/resume.pdf>

As a solo operator, I relied heavily on ChatGPT [14] for general information and Anthropic/Claude [3] for documentation and coding help. I began my neural network journey in 2015 using Theano to identify whales from aerial photographs [6], gaining a Kaggle Bronze Medal in the *Right Whale Recognition* contest. More recently, I studied the book *Deep Learning with Python, Second Edition* by Francois Chollet [4], the original author of Keras. (Both my use of Theano and my introduction to Keras by Francois Chollet explain my preference for TensorFlow, despite the much-hyped "Pythonic" nature of PyTorch, whatever that means).

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