Trace and Detect Adversarial Attacks on CNNs using Feature Response Maps

Deep Learning Day 2018, Sep 14th, Winterthur, Switzerland

Mohammadreza Amirian





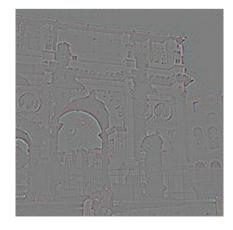










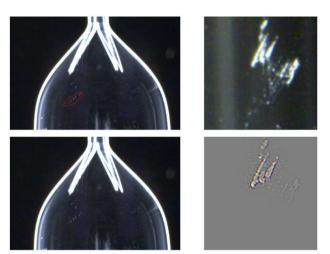


Motivation



Explainable Al:

- How does the networks learn?
- How does the networks decide?

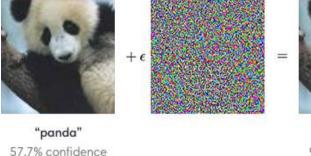






Reliability in Al:

Adversarial perturbations.



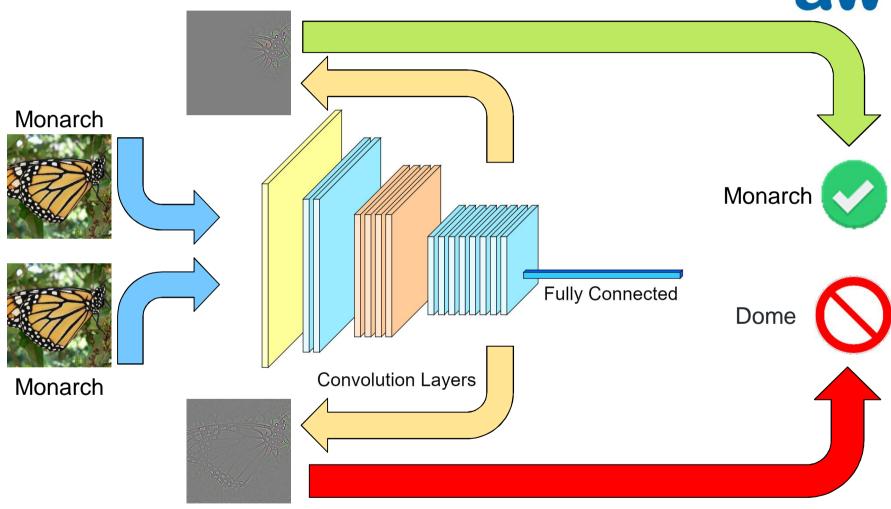
"gibbon" 99.3% confidence

 $\underline{\text{https://blog.openai.com/adversarial-example-research/}}$

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Underlying Idea



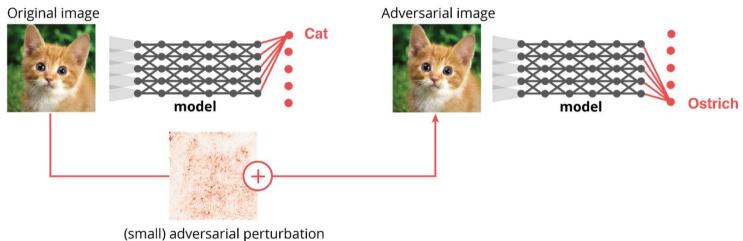


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1. Adversarial Perturbations

created by **attack**







https://www.crowdai.org/challenges/nips-2018-adversarial-vision-challengehttps://arxiv.org/pdf/1712.04248.pdf

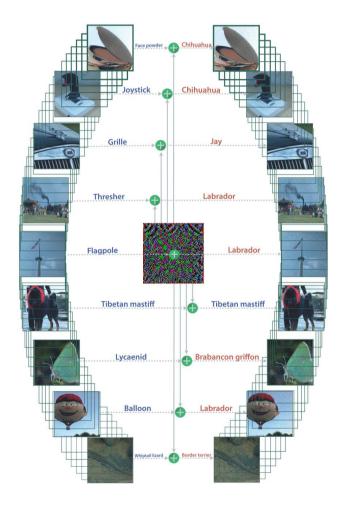
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Common Perturbation Scenarios



- Non-targeted attack
- Targeted attack
- White box
- Black box with probing
- Black box without probing
- Digital attack
- Physical attack
- Universal attack





https://www.youtube.com/watch?v=piYnd_wYIT8

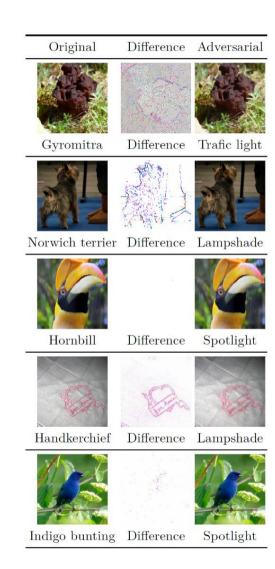
http://openaccess.thecvf.com/content_cvpr_2017/papers/Moosavi-Dezfooli_Universal_Adversarial_Perturbations_CVPR_2017_paper.pdf



Computing Adversarial Perturbations

- Fast Gradient Sign Method (FGSM)
- Gradient attack

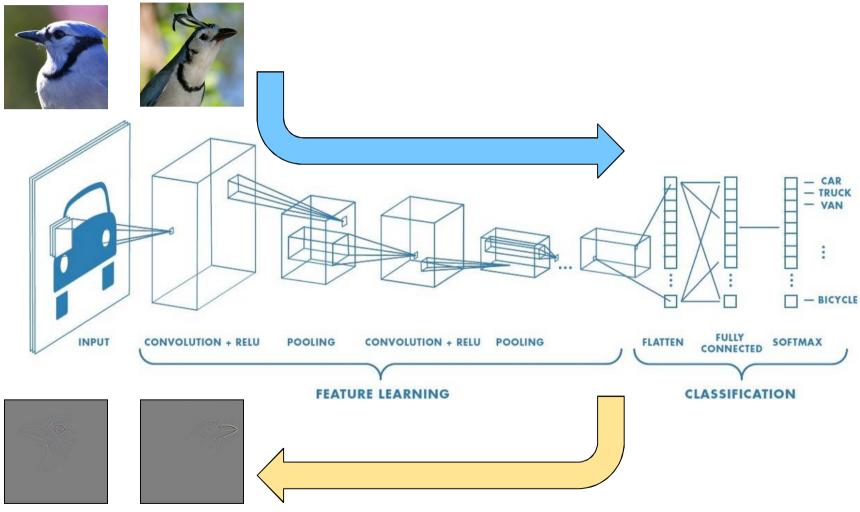
- One-pixel attack
- DeepFool
- Boundary attack



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2. Feature Response Visualization



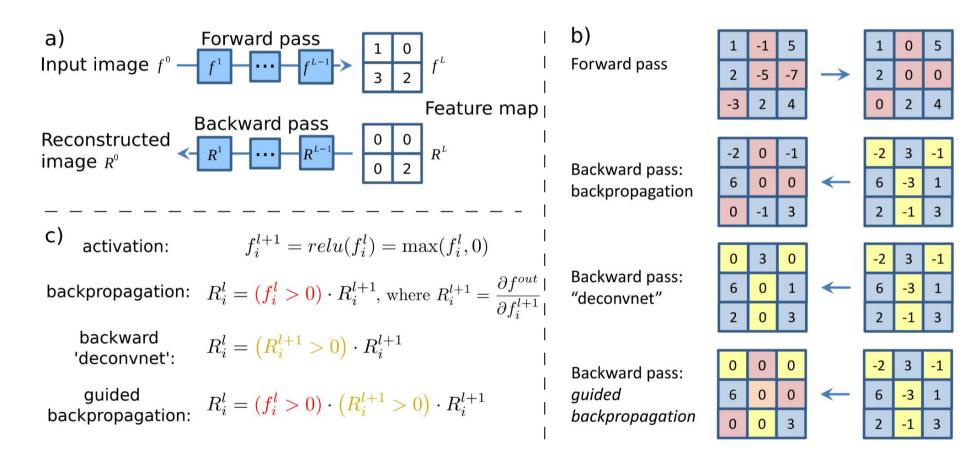


https://medium.freecodecamp.org/an-intuitive-guide-to-convolutional-neural-networks-260c2de0a050

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Computing Feature Responses





https://arxiv.org/pdf/1412.6806.pdf

3. Tracing Adversarial Perturbations



One pixel attack: Predictions:	AND THE RESERVE OF THE PARTY OF	Feature response	Thimble	Feature response
FGSM: Predictions:	Submarine	Feature response	Traffic light	Feature response
DeepFool: Predictions:	Disc brake	Feature response	Dome	Feature response

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4. Feature-Based Adversarial Image Detection



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	Original	Adversarial	Original	Adversarial
Image:				
Feature response:		e ·		
Local spatial entropy				

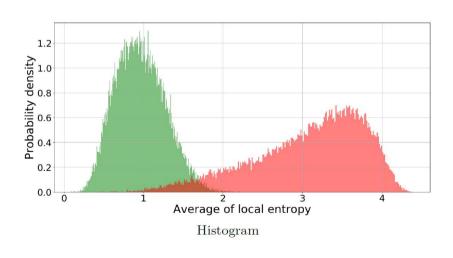
Decision Metric and Method Performance

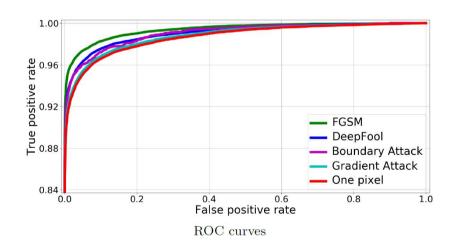


Average local spatial entropy:

$$S_k = -\sum_i \sum_j \boldsymbol{h}_k(i,j) \log_2(h_k(i,j))$$

• Results:





zh

Numerical Evaluation and Comparison

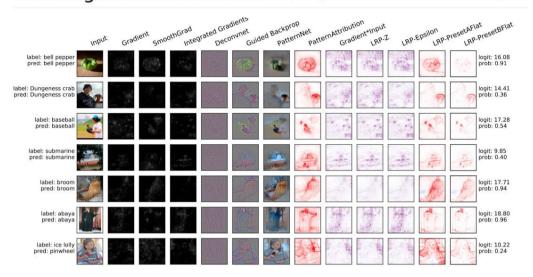
Adversarial attack	#Images (run time [days])	Success rate	Ground truth confidence			
FGSM	50,014 (3)	0.925	0.022	0.588	0.954 0.974	0.983
Gradient attack	50,014 (15)	0.499	0.052	0.371	0.922 0.954	0.969
One pixel attack	50,014 (32)	0.620	0.037	0.463	0.917 0.951	0.966
DeepFool	47,858 (42)	0.606	0.041	0.446	0.936 0.963	0.976
Boundary attack	4,013 (17)	0.940	0.023	0.583	0.934 0.960	0.972

Method	Dataset Network Attack		Performance Recall Precision AUC			
Uncertainty density estimation	SVHN	LeNet	FGSM	-	-	0.890
Adaptive noise reduction	ImageNet (4 classes)	CaffeNet	DeepFool	0.956	0.911	-
Feature squeezing	ImageNet-1000	VGG19	Several attacks	0.859	0.917	0.942
Statistical analysis	MNIST	Self-designed	FGSM ($\epsilon = 0.3$)	0.999	0.940	
Feature response (our approach)	ImageNet validation	VGG19	Several attacks	0.979	0.920	0.990

References:



iNNvestigate neural networks! https://github.com/albermax/innvestigate



https://www.crowdai.org/challenges/nips-2018-adversarial-vision-challenge





Conclusions and Future Works



- Feature response visualizations help to debug & understand
- Improving the adversarial perturbation detection algorithm based on the feature responses
- Design a defense algorithm against adversarial perturbations
- Using the feature responses to design and enhance the network architectures





On me:

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Research interests:

- Deep learning
- Explainable Al
- Medical image processing
- → Happy to answer questions & requests.

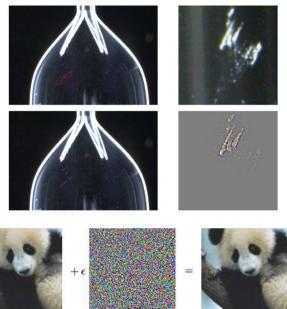


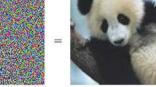


APPENDIX

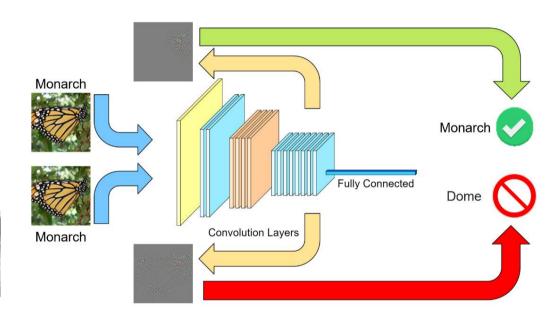
Any Question?







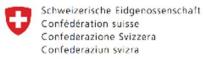
"gibbon" 99.3% confidence











Swiss Confederation

Innosuisse - Swiss Innovation Agency

"panda"

57.7% confidence