

# Solving Continuous Games With Oracle Algorithms

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## Focus of the Project

- examination of the Expected Regret Minimization algorithm (ERM, 2023)
  - modified for computing Nash Equilibria in continuous zero-sum two-player games
- experimental comparison with the Double Oracle algorithm (DO, 2021)
- experimental confirmation of proposed bounds
  - for the convergence rate
  - for the computational complexity

## A Game

a two-player, zero-sum continuous game is

$$G = (X, Y, u)$$

where:

- $X$  is the action space of player 1, a hypercube\* (e.g.  $[0, 1]^n$ )
- $Y$  is the action space of player 2, a hypercube\* ( $[0, 1]^m$ )
- $u : X \times Y \rightarrow R$  is the utility function for player 1
  - $u(x, y) = -u_2(x, y)$ , to maximize  $u_2$  is to minimize  $u$

\* or generally  $[a, b] \times [c, d] \times \dots \times [v, w]; a, \dots, w \in R$

## A Strategy, a Nash Equilibrium

- a (mixed) strategy is a prob. distribution  $p$  ( $q$ ) over  $X$  ( $Y$ )
- the final action  $a \in X$  ( $b \in Y$ ) is i.i.d drawn from  $p$  ( $q$ )
- the expected utility (for finite action spaces):

$$U(p, q) = \sum_{x_i \in X} \sum_{y_j \in Y} u(x_i, y_j) \cdot p_i \cdot q_j$$

- a Nash Equilibrium ( $\sim$  a solution of a game) is a pair of strategies  $(p^*, q^*)$  of a stable state, that is:

$$U(p, q^*) \leq U(p^*, q^*) \leq U(p^*, q); \forall p, q$$

## Finding the Nash Equilibria

- solved for games with finite action spaces
- create matrix  $M$  of the utilities of every pair of actions, then solve a LP (based on  $M$  and the *minmax* theorem)
- for infinite games, the LP is no longer applicable (cannot enumerate actions)
  - $\rightarrow$  Settle for  $\epsilon$ -NE instead
  - iterative algorithms based on *oracles*

## Expected Regret Minimization

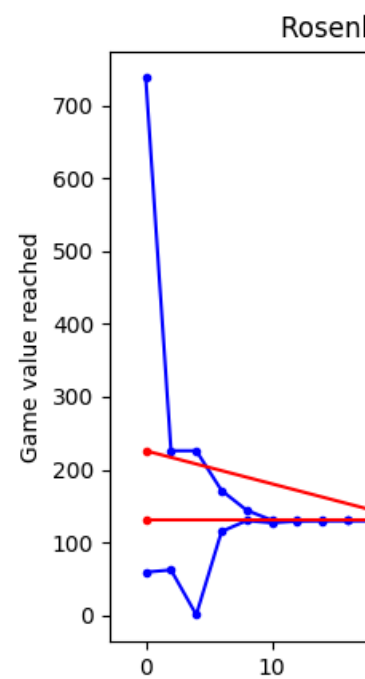
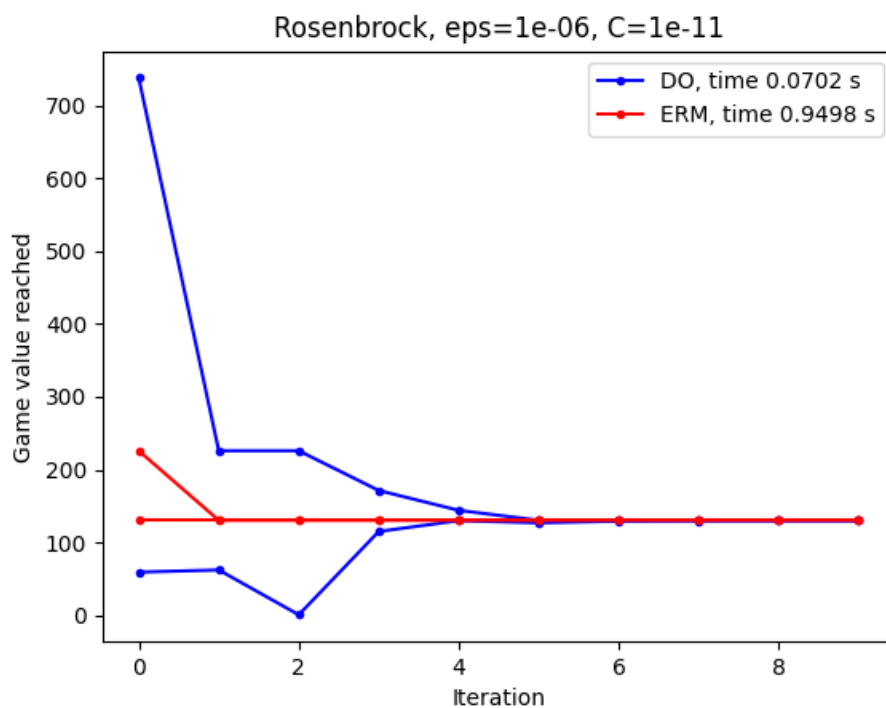
definition of the algorithm

main routine epsilon-approximate Nash Equilibrium for a zero-sum game	subroutine epsilon Nash Equilibrium
inputs: game $G = (X, Y, u)$ , number $\epsilon$ output: equilibrial strategies $p_t^*, q_t^*$	inputs: game $G = (X, Y, u)$ , output: equilibrial strategies
1. $A_0 \leftarrow \{a\}, B_0 \leftarrow \{b\}$ , where $a \in X$ and $b \in Y$ are arbitrary actions 2. For $t = 1, 2, \dots$ <ol style="list-style-type: none"> <li><math>(responses_a, probabilities_b) \leftarrow NASH(G, B_{t-1}, \epsilon)</math></li> <li><math>A_t \leftarrow A_{t-1} \cup responses_a</math></li> <li><math>(responses_b, probabilities_a) \leftarrow NASH(G, A_t, \epsilon)</math></li> <li><math>B_t \leftarrow B_{t-1} \cup responses_b</math></li> <li>if <math>Val(A_t, B_{t-1}) \geq Val(A_{t-1}, B_{t-1}) - \epsilon</math> or <math>Val(A_t, B_t) \leq Val(A_t, B_{t-1}) + \epsilon</math>:                Return NE <math>(p_t^*, q_t^*)</math> of subgame <math>G' = (A_t, B_t, u)</math> </li> </ol>	1. $V \leftarrow \left\lceil \frac{C \log  A_t }{\epsilon^2} \right\rceil$ ; $\eta \leftarrow \sqrt{\frac{\log}{V}}$ 2. $p^1 = (p_1^1, \dots, p_n^1)$ is a uniform distribution 3. $responses \leftarrow bestResponse(A_t, p^1)$ 4. for $v = 2, \dots, V$ <ol style="list-style-type: none"> <li>for <math>i = 1, \dots, N</math>: <math>p_i^v</math>                where:  <math>Z^v = \sum_{j=1}^n p_j^{v-1} \cdot responses_j</math>  <math>b_v \leftarrow bestResponse(A_t, p^v)</math> </li> </ol>
	5. Return $(responses, avg(p^1, \dots, p^V))$

## Convergence Comparison, 1

the Rosenbrock function:

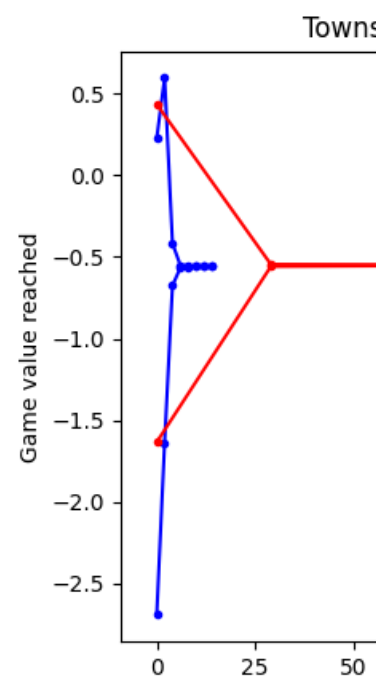
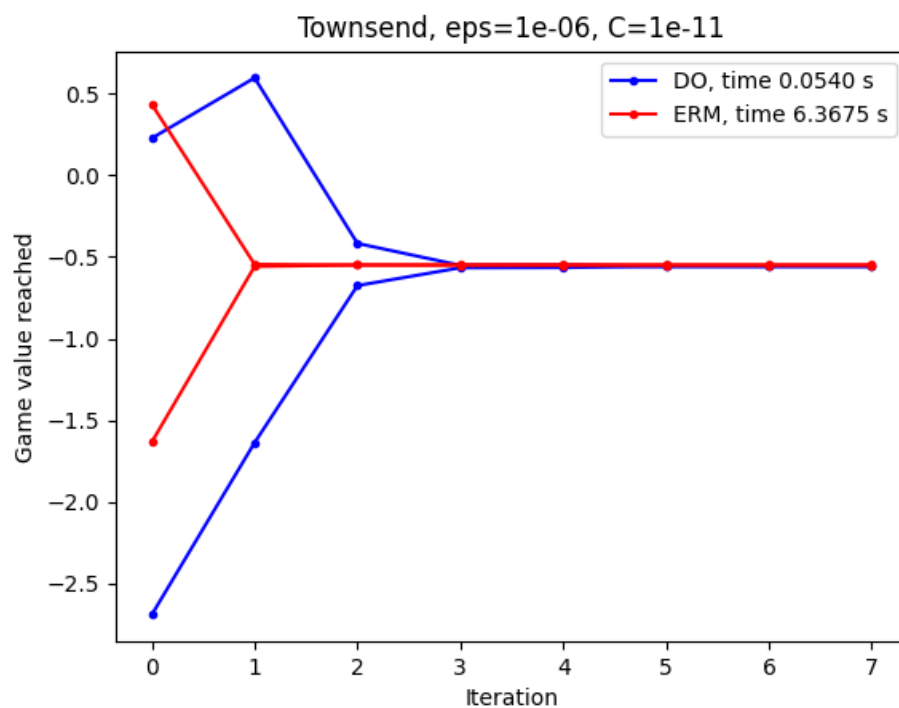
$$u(x, y) = (1 - x)^2 + 100(y - x^2)^2$$



## Convergence Comparison, 2

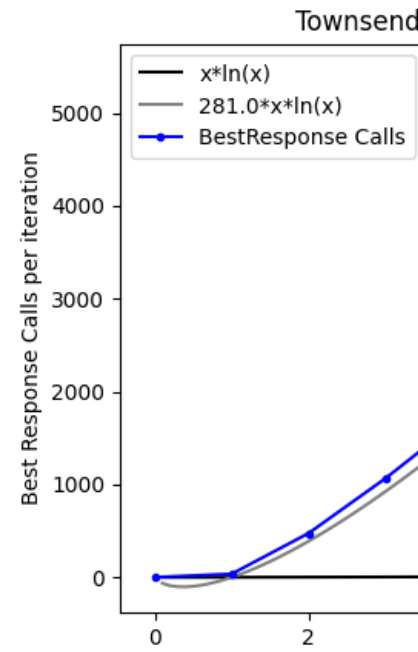
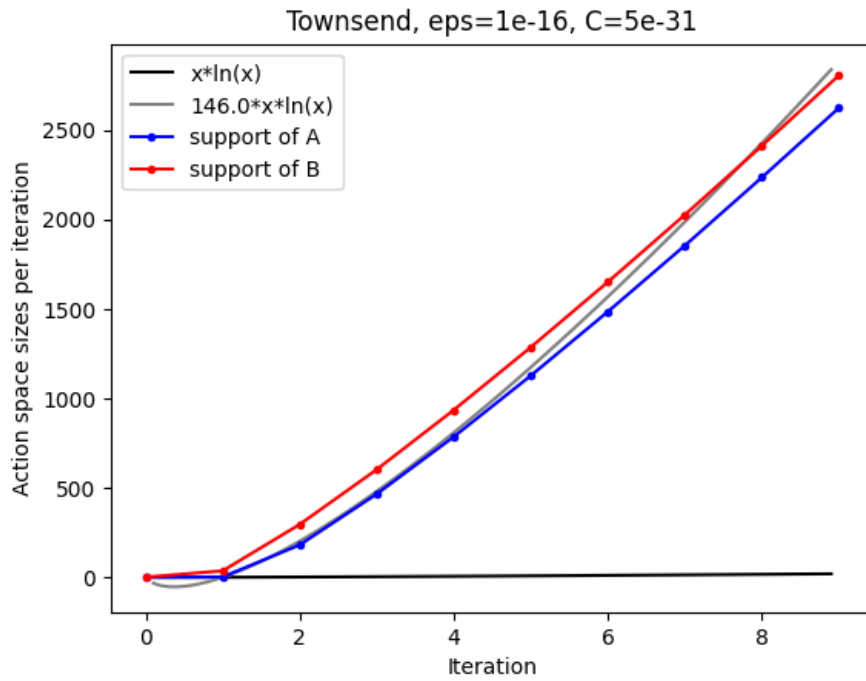
the Townsend function:

$$u(x, y) = -[\cos((x - 0.1) \cdot y)]^2 - x \sin(3x + y)$$



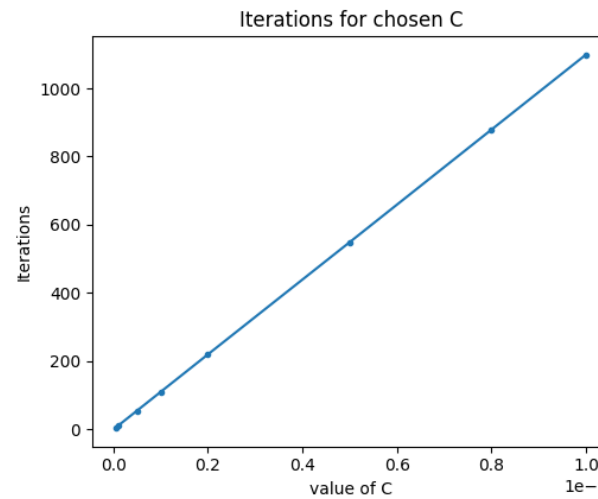
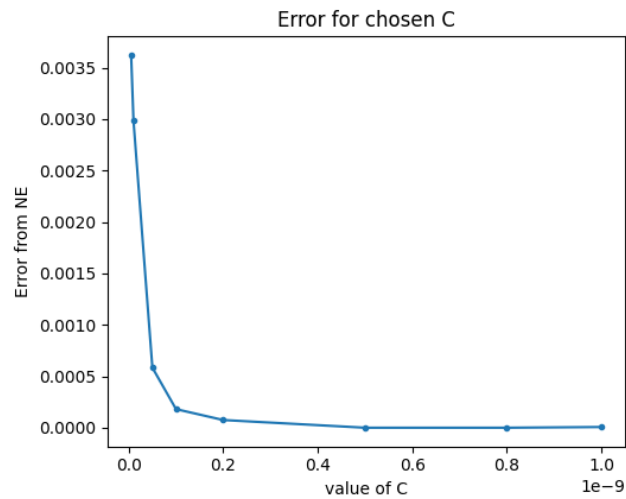
## Testing Complexity Claims

“Assume that the ERM algorithm runs for  $T$  iterations. Then, the number of *oracle* calls is bounded by  $O((T/\epsilon^2) \log(T/\epsilon^2))$ .”



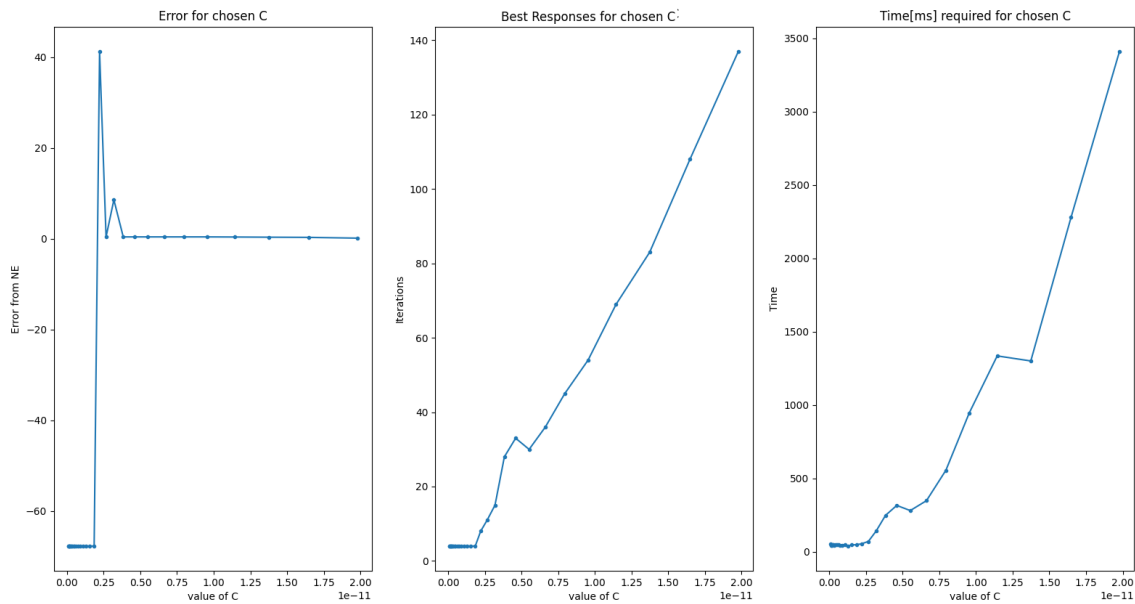
### More Claims, Value of $C$ , part 1

“Let  $G = (A = a_1, \dots, a_n, Y, u)$  be a zero-sum game where  $|A| = n$  and  $Y$  is possibly infinite, and let  $\epsilon > 0$ . Then, the subroutine, executed with the parameter  $\epsilon$ , finds an  $O(\epsilon)$ -Nash equilibrium, after  $V = O(\log n/\epsilon^2)$  iterations.” - Tested on Rock-Paper-Scissors



## More Claims, Value of $C$ , part 2

the Rosenbrock function (with infinite action spaces):



## Conclusions

- the ERM algorithm solves continuous games
- a possible tradeoff
  - ERM requires less iterations (LP calls)
  - DO requires less *bestResponse* calls
- how to find adequate value of  $C$ ?
  - to be examined

## Thank you

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Software or Research Project

Open Informatics

FEE CTU in Prague