

Apache Beam Overview

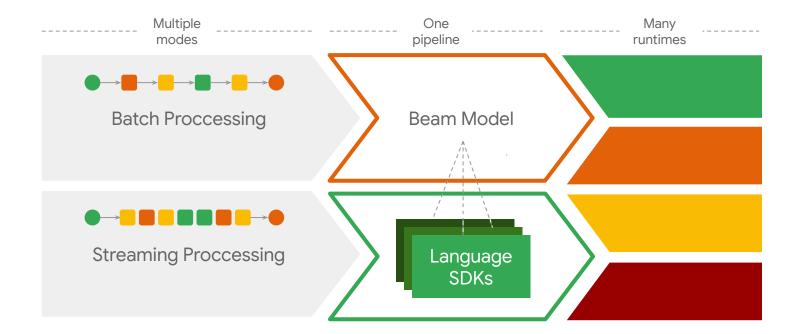
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What is Apache Beam?

Apache Beam is an open source, unified model for defining both batch and streaming data-parallel processing pipelines. Using the open source Beam SDKs, you build a program defining the pipeline, that then is executed by one of Beam's supported distributed processing backends.





SDKs









Pipeline Runners

















A **Pipeline** is a Directed Acyclic Graph (DAG) of data transformations applied to one or more collections of data. It might include multiple input sources and output sinks and its operations (PTransforms) can both read and output PCollections.

Creating a Pipeline

```
import apache_beam as beam
from apache_beam.options.pipeline_options import PipelineOptions
with beam.Pipeline(options=PipelineOptions()) as p:
    pass # build your pipeline here
```

Setting PipelineOptions from command-line arguments

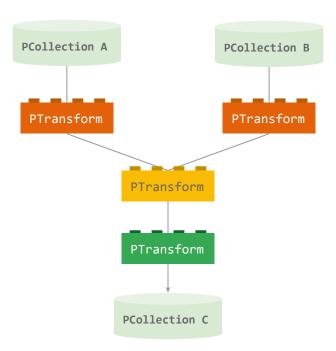
from apache_beam.options.pipeline_options import PipelineOptions
options = PipelineOptions(flags=argv)



This interprets command-line arguments that follow the format: --<option>=<value>

Creating custom options

```
from apache beam.options.pipeline options import PipelineOptions
class MyOptions(PipelineOptions):
    @classmethod
    def _add_argparse_args(cls, parser):
        parser.add argument(
            '--input',
            help='Input for the pipeline',
            default='gs://my-bucket/input')
        parser.add_argument(
            '--output',
            help='Output for the pipeline',
            default='gs://my-bucket/output')
with beam.Pipeline(options=MyOptions()) as p:
    pass
```



PCollection

A **PCollection** is an immutable collection of values. It can contain a bounded or unbounded number of elements. Beam transforms use PCollection objects as **inputs** and **outputs**.

PCollection

A PCollection is owned by the specific Pipeline object for which it was created. Multiple pipelines cannot share one.

Elements in a PCollection may be of any type, but all must be of the same type.

PCollections can be **bounded** (batch) or **unbounded** (streaming) in size.

Beam needs to encode elements as a byte strings to support distributed processing. The SDKs include **built-in encoding mechanisms** for common types as well as support for specifying **custom encodings**.

PCollections do not support random access to elements.

In many cases, the element type in a PCollection has a an associated schema (e.g., JSON, Protocol Buffer, Avro, database records)

A PCollection is **immutable**. A transform might process each element in it and generate a new PCollection, but it does modify the original one.

Each element in a PCollection has an associated **intrinsic timestamp**. Timestamps can be manually assigned to the elements if the source doesn't do it for you.

A PTransform is an operation in a pipeline. Developers provide processing logic as a function object applied to each element of one or more input PCollection(s). Depending on the runner, multiple workers across a cluster may execute the code in parallel and generate the output elements ultimately added to the final PCollection produced by the transform.

To invoke a transform, you must **apply** it to the input PCollection.



Transforms can be **nested** to form composite transforms.

Transforms can be **chained** to be applied sequentially to an input PCollection.

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Beam SDKs contain generic **core transforms** and **pre-written composite transforms** combining one or more of the core ones.

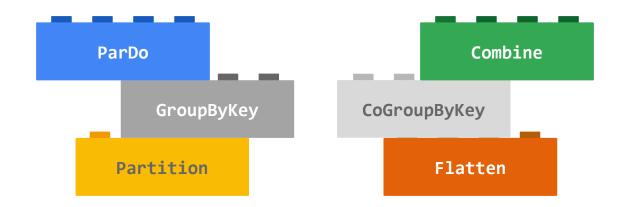
A transform does **not alter** the input collection.

Applying a transform

</>>

[Output PCollection] = [Input PCollection] | [Transform]

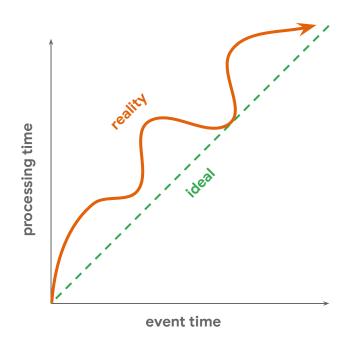
Core transforms



Event time vs. processing time

In any streaming data processing system:

- There is a certain amount of lag between:
 - The event time, when a data event occurs (determined by the timestamp on the data element itself).
 - The processing time, when a data element gets processed at any stage in a pipeline (determined by the clock on the processing system).
- There are no guarantees that data events will appear in a pipeline in the same order that they were generated.



Event time vs. processing time

Event Time



Processing Time

Source: Introduction to Apache Flink by Ellen Friedman, Kostas Tzoumas

Event time vs. processing time

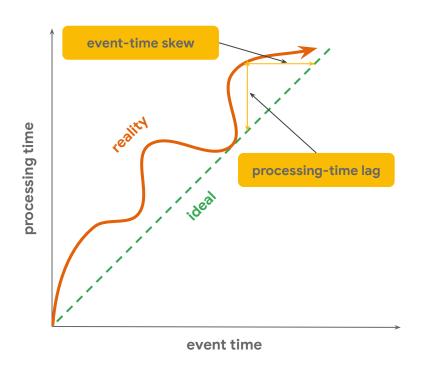
Processing-time lag

It measures the delay observed between the time when the event occurred and the time when it was processed

Event-time skew

It measures how far behind the ideal in event time the pipeline currently is.

processing-time lag = event-time skew



Window

A Window subdivides a PCollection according to the timestamps of its individual elements, which is especially useful for unbounded PCollections, as it allows operating on sub-groups of elements.



Processing-time windowing



Inferring information about a data source as it is observed

Processing-time windowing

- No need to worry about shuffling data within time, just buffer elements as they arrive until the window closes.
- Easy to judge window completeness.

Event-time windowing



Inferring information about a data source as it occurs

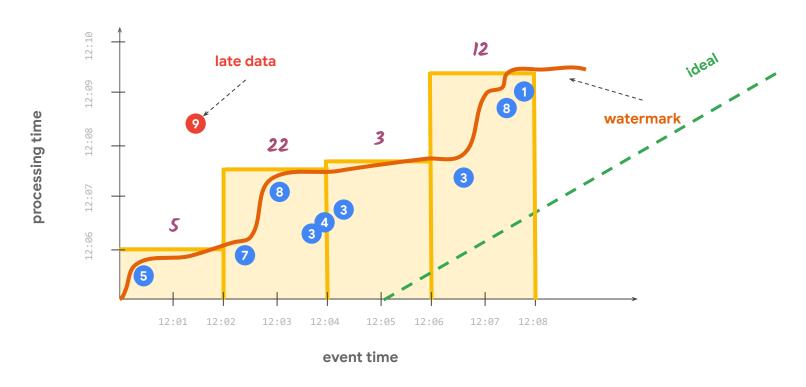
Event-time windowing

- More buffering of data occurs, as windows must often live longer in processing time than their actual length.
- Hard to judge window completeness, we can only estimate.

Watermark and late data

A watermark is the system's notion of when all data in a certain window can be expected to have arrived in the pipeline. Once the watermark progresses past the end of a window, any further element arriving with a timestamp in that window is considered late data.

Watermark and late data

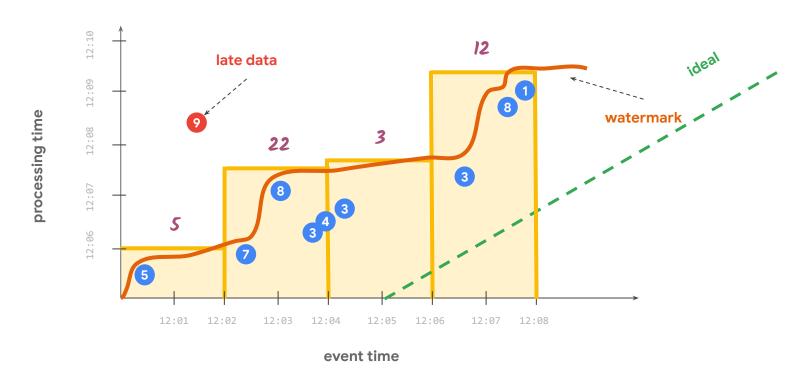


Trigger

A **Trigger** determines when to emit the aggregated results of each window.



Watermark and late data



Window

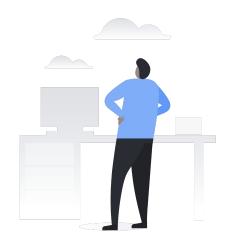
How is my data grouped?

Watermark

When is my data complete?



When should I produce results?



Apache Beam defaults



- All elements of a PCollection, even in the case of unbounded ones, are assigned to a single global window.
- Aggregated results are emitted when it estimates that all the data has arrived.
- Late data is discarded.

Thank you!

Questions?

