# **Project Final Report**

Flappy Bird

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	User-Flow Diagram and Division of tasks between blocks

### 1 Introduction

Flappy bird exploded in popularity when it was first introduced in the apple Appstore and the google play store. The game quickly rose to popularity and in the short span of time became a fan favorite game that most wanted to play in their spare time. This popularity and boost prompted a lot of market competitors to try and replicate the game and somehow mimic the popularity and monetary gain that the developers of flappy bird experienced. This could not happen and the mimickers and fake developers of the game could never copy the success. The huge success of the game meant, it was soon taken out of the play store and the app store sent behind a pay wall that no one appreciates. The game was taken away from us, the childhood game that made us want to beat the high scores of our peers. Therefore, years later, the group has decided to make our very own flappy bird and compete.

The project is simple and subtle in its delivery physically, but emotionally it has a pretty big impact. The bird on the x co-ordinate will not move, however, on the y-axis the bird will be moving up and down to navigate between the tubes. The game will be played with the help of the input which will be our keyboard, the bird will move upward in the sky when the W key is pressed, while the bird will move downward if the S key is pressed. The user has to make sure that he/she masterfully navigates the bird to glory by navigating between the tubes and creating a high score that no one else can beat. The project will be a great trip down the memory lane for the users that have played and enjoyed this game in the past but this in no way means that new users or users that haven't played this game before will not enjoy this. The target user is anyone and everyone having a liking for casual games but they still have the competitive attitude and desire to do great.

### 2 User-Flow Diagram and Division of tasks between blocks

### 2.1 User-Flow diagram

The following is the user flow diagram of our project:

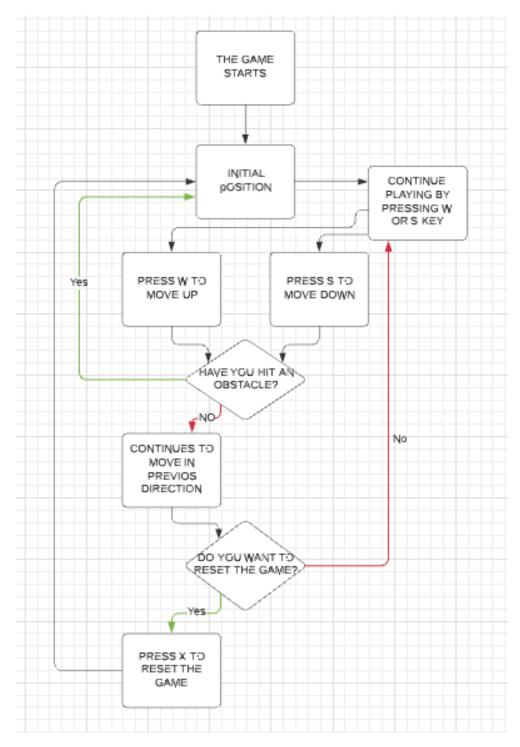


Figure 1: User Flow Diagram

#### 2.2 Explanation:

The user-flow diagram is elegantly made indicating all the possibilities for a user in this game. The user is controlling three keys. By pressing the X key the user can go into reset position at any time. The W key which will make the bird move in an upward direction, the bird will continue to move in an upward direction until the X or the S key is pressed. The S key will make the bird move in a downward position and similar to the W key, the s key will make the bird go downwards until W or X key is pressed.

It is extremely essential for the success of the user to properly navigate the bird and not hit the tubes while controlling the bird. The user can either move up by pressing W or descend downwards by pressing the S key. The tubes will keep randomly generating until the game is over and the user crashes the bird with a tube. The user will be granted two points each time it accurately navigates through one set of tubes.

#### 2.3 Division of Task:

The task division between the three blocks of our project are as followed:

- 1. The tasks of the input block of our project is when we press the keys X, W or S it has to provide the control block with an input/task for it to perform.
- 2. The task of the control block of our project is to check the entry of the input and make sure the output is being performed. In simple words, the bird moving upward and downward is a control block but since it also a function of the input we are providing, it can also be understood to be an output block.
- 3. The task of the output block of our project is that when the W key is pressed, the flappy bird will ascend(move up) until another key is pressed and descend(move down) if the S key is pressed. If the bird collides with any of the walls of the tubes or touches the upper or lower frame of the screen the game finishes and output is generated as 'GAME OVER', taking u directly to reset state.

### 3 Input Block

### 3.1 Introduction to the input peripheral: The Keyboard

The Artix 7 FPGA board is powered by connecting it to the CPU via micro USB. After turning the switch on we are required to configure the board. Bit streams generated (in .bit files) for the configuration using Vivado software. We program them using the hardware language, Verilog.

The keyboard is attached to the FPGA board at the USB connector J2. The host capability of USB HID in Basys 3 is provided by micro controller which switches to the USB host and turns on application mode

### 3.2 Inputs in the Project

In order to move our bird up, we press the key 'w'. Pressing 'w', moves the bird upwards and it keeps moving upwards until it crashes or another different input is received.

Similarly, to move the bird down, we press the key 's'. Once we press 's', the bird will keep moving downwards until it either collides or another different input is received. In order to exit/reset the game, we press 'x'. Pressing the reset key 'x', resets the game to its idle state regardless of the game progress.

### 3.3 Configuring the keyboard

We have interfaced the USB keyboard to give scan codes of PS/2 keyboard as the FPGA only takes PS/2 keyboard inputs. When we press either 'w' or 's' on the keyboard, the unique scan code of that key is generated and the game starts or continues meaning if it's the initial press then the game starts but if it is not the first press then we are already in the game and the bird is navigated by using these presses. Similarly we have an exit key 'x'. This is a reset button which resets the game and goes back to the idle state no matter where the player currently is. Pressing x also generates a unique hexadecimal scan code that we interpret, similar to how the 'w' and 's' key's hexadecimal scan code.

Scan codes:

W = 1D

S = 1B

X = 22

#### 3.4 Input translation to Output

The bird moves up when the key 'w' is pressed. It moves down when the key 's' is pressed. The clock of the keyboard sends the data on the rising edges. An important thing to note here is that the keys' ('w' and 's') functionality will be designed such that once either of the keys are pressed, the bird will keep moving in that direction until it either collides or a different input is provided.

#### 3.5 Input Code

```
23 🖨 module keyboard(
24
         input CLK, //board clock
        input PS2 CLK, //keyboard clock and data signals
25
        input PS2 DATA.
26
27
        output reg [2:0] state, //output when X is pressed
28
        output reg reset
29
30
         wire [7:0] SPACE_BAR = 8'h29;
31
         wire [7:0] X = 8'h22;
32
33
         wire [7:0] RELEASED = 8'hF0;
34
         wire [7:0] W = 8'hlD;
35
     wire [7:0] S = 8'h1B;
36
         wire [7:0] ARROW_UP = 8'hlD; //codes for arrows
37
         wire [7:0] ARROW_DOWN = 8'hlB;
38
39
                                //this is 1 if still waits to receive more bits
40
41
         reg [11:0] count reading;
                                       //this is used to detect how much time passed since it received the previous codeword
         reg PREVIOUS_STATE;
42
                                    //used to check the previous state of the keyboard clock signal to know if it changed
43
         reg scan_err;
                                    //this becomes one if an error was received somewhere in the packet
44
         reg [10:0] scan_code;
                                        //this stores 11 received bits
45
         reg [7:0] CODEWORD;
                                    //this stores only the DATA codeword
      red TRIG ARR:
46
                                   //this is triggered when full 11 bits are received
```

Figure 2: input code1

```
always @(posedge CLK) begin
         if (TRIGGER) begin
                                                                //if it still waits to read full packet of 11 bits, then (read == 1)
                 if (read)
                                                                         //and it counts up this variable
//and later if check to see how big this value is.
                           count_reading <= count_reading + 1;</pre>
                  else
                           count_reading <= 0;
                                                                         //if it is too big, then it resets the received data
         end
end
always @(posedge CLK) begin
if (TRIGGER) begin
                                                                          //If the down counter (CLK/250) is ready
        if (PS2_CLK != PREVIOUS_STATE) begin
if (!PS2_CLK) begin
                                                                         //if the state of Clock pin changed from previous state
//and if the keyboard clock is at falling edge
                           read <= 1;
                                                                          //mark down that it is still reading for the next bit
                           scan_err <= 0;
                                                                          //no errors
                           scan_code[10:0] <= {PS2_DATA, scan_code[10:1]}; //add up the data received by shifting bits and adding one new bit
COUNT <= COUNT + 1;</pre>
                  end
         end
         else if (COUNT == 11) begin
COUNT <= 0;
                                                                         //if it already received 11 bits
                  read <= 0;
                                                                         //mark down that reading stopped
//trigger out that the full pack of 11bits was received
                  TRIG ARR <= 1;
                  ^scan code[9]))
                           scan_err <= 1;
                  else
                           scan_err <= 0;
         end
         else begin
                                                                          //if it yet not received full pack of 11 bits
                  TRIG_ARR <= 0;
if (COUNT < 11 && count_reading >= 4000) begin
                                                                         //tell that the packet of 11bits was not received yet //and if after a certain time no more bits were received, then
                           COUNT <= 0;
                                                                          //reset the number of bits received
                                                                         //and wait for the next packet
                           read <= 0;
         end
PREVIOUS_STATE <= PS2_CLK;
                                                                         //mark down the previous state of the keyboard clock
end
always @(posedge CLK) begin
if (TRIGGER) begin
                                                                          //if the 250 times slower than board clock triggers
                 if (TRIG_ARR) begin
if (scan_err) begin
                                                                         //and if a full packet of 11 bits was received 
//BUT if the packet was NOT OK
```

Figure 3: input code2

```
134 🖨
           always @(posedge CLK) begin
135 🖯 //
          if (TRIGGER) begin
136
               if (TRIG_ARR) begin
137
              LED<=scan_code[8:1];
                                                //You can put the code on the LEDs if you want to, that's up to you
                                                    //if the CODEMORD has the same code as the ARROW_UP code
//count up the LED register to light up LEDs
              if (CODEWORD == ARROW_UP)
138
                  LED <= LED + 1;
139
               else if (CODEWORD == ARROW_DOWN)
                                                            //or if the ARROW_DOWN was pressed, then
140
141 0 //
                  LED <= LED - 1;
                                                    //count down LED register
142 🖯
               if (CODEWORD == SPACE_BAR || CODEWORD == W) begin
143
                  state = 3'b010;
144
                   reset <= 0;
145 🖨
               end
               else if (CODEWORD == X) begin
146 🖯
                   state = 3'b111;
147
148
                   reset <= 1;
149 (
               end
150 🕏
               else if (CODEWORD == RELEASED || CODEWORD == S) begin
151
                   state = 3'b100;
152
                   reset <= 0;
153 🖨
154
155 🖨
156
157 A endmodule
```

Figure 4: input code3

### 3.6 Input Elaborated Diagram

Here is the elaborated diagram of the input:

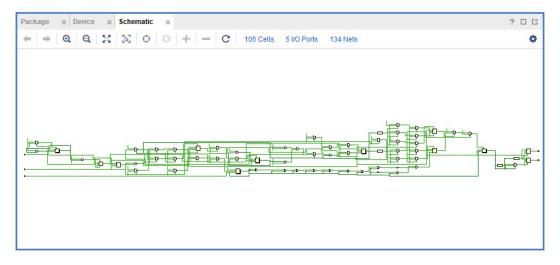


Figure 5: Elaborated Design of Input block

### 3.7 Input I/O Ports

Port configuration:

 $PS2\_CLK : C17$  $PS2\_DATA : B17$ 

CLK:W5



Figure 6: IO Ports used

### 4 Output Block

### 4.1 Introduction to the Output Block

The output block of our project is the VGA display. The most important part of our project is the output and the VGA display. What appears on the screen makes the user excited for the game that they are about to play. The following is how the group decided to map the pixels in the output display of our project.

### 4.2 Pixel Mapping

The gap between the tubes in our output display will be 80 pixels. This will remain constant throughout the game.

The tube height of both the sides will be varying because the obstacles have to be made in a challenging manner so the user has to use the key to navigate the flappy bird up and down. The width of the tube height is 40 pixels of the screen.

The dimensions of the flappy bird are 20x25. This means that the x component of the bird is 20 pixels wide and the y component is 25 pixels long. Each input press will jump the bird 30 pixels upward in the y direction. Every time the user provides an input for a jump, the bird will have 6 transitions of 5 pixels each in order to complete the 30 pixel jump, and the transitions will complete regardless of the input from the user at those instances. The game will read the input after all 6 transitions have been completed. Where as during the downfall the bird will have transitions of 5 pixels each (downwards) for as long as its in the downfall state.

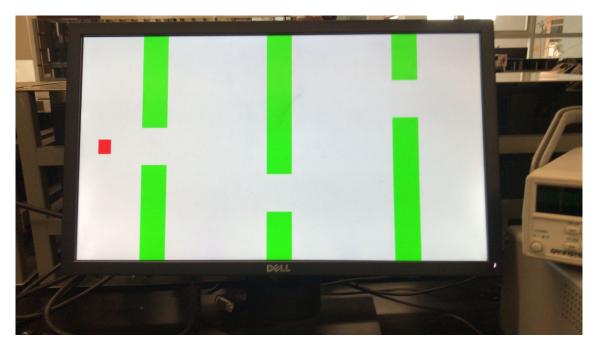


Figure 7: Display screen of the game

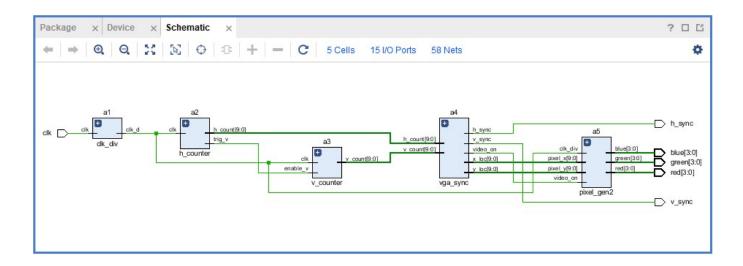
### 4.3 Output Demo Code

Following is the display output and the output code for the demo display:

```
module pixel_gen2(
    input [9:0] pixel_y,
    input [9:0] pixel_y,
    input clk_ddv,
    input clk_ddv,
```

### 4.4 Output Elaborated Diagram

Here is the elaborated diagram of the sample output:



### 4.5 Output I/O Ports

Port configuration:

blue[3]:J18

blue[2]:K18

blue[1]:L18

blue[0]:N18

green[3]:D17

green[2]:G17

green[1]: H17

green[0]:J17

red[3]:N19

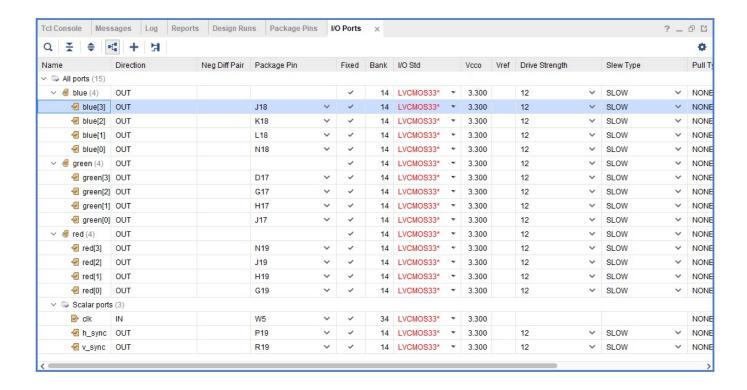
red[2]: J19

red[1]:H19

red[0]:G19

clk: W5 $h\_sync: P19$ 

 $v\_sync:R19$ 



### 5 Control Block

The description of the states of our project are as followed. In addition, the state transition diagram of the project is also attached below.

#### 5.1 States of our project

- 1. Reset: Before starting the game, the bird is in the reset state and so is the game. If the X key is pressed during any phase of the game, it returns to its reset state. If the X key is not pressed, the game remains in the state it currently is unless the game ends due to collision with a tube.
- 2. Up: The bird will move in an upward direction if the W key is pressed. The bird will continue moving up until and unless the S key is pressed to change its direction downward, X key is pressed for the game to return in the initial stage or a tube is hit by the bird which automatically brings the game in initial position.
- 3. Down: The bird will move in a downward direction if the S key is pressed. The bird will continue moving in the downward direction if the S key is pressed. The bird will only change the direction if W or X key is pressed. Consequently, the game will also return to intial state if the bird hits a tube.

### 5.2 State Transition Diagram

Here is the state transition diagram:

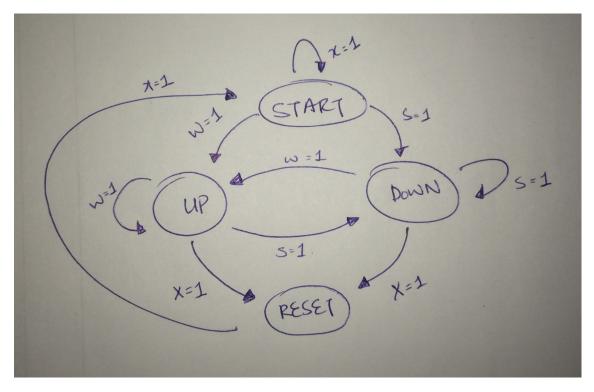


Figure 8: X = reset, W = up, S = down

### 6 FSM Design Procedures

### 6.1 Assumptions

- 1. We can have only one input at a given time.
- 2. The previous input will keep in motion until a new input is put in place through a new input by pressing any key.
- 3. The game ends if the bird keeps going up or down and eventually hits the top or the bottom of the screen.

### 6.2 State Table

CS A/B	Input W/S/X	Next States A(t+1)/B(t+1)	Output play	States	Logi
00	00x	00	0	START	00
00	010	10	0	UP	01
00	100	01	0	DOWN	10
01	000	01	1	RESET	11
01	001	11	1		
01	010	10	1		
01	100	01	1		
10	000	10	1		
10	001	11	1		
10	010	10	1		
10	100	01	1		
11	xx0	11	0		
11	001	00	0		

Figure 9: State table

### 6.3 State Equations

```
A(t+1) = ABX' + A'W'SX' + AB'W'S' + A'BW'S'X
B(t+1) = WS'X' + ABX' + A'BWS' + AB'W'S'X
Output = A'B + AB'
```

Figure 10: State Equations

### 6.4 Circuit Diagram

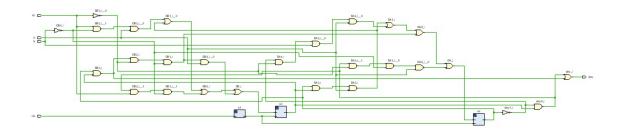


Figure 11: Circuit Diagram

### 6.5 Gate level Implementation of FSM

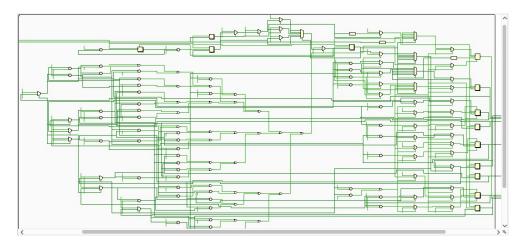


Figure 12: FSM on a gate level

### 7 Final Game

### 7.1 Elaborated Design

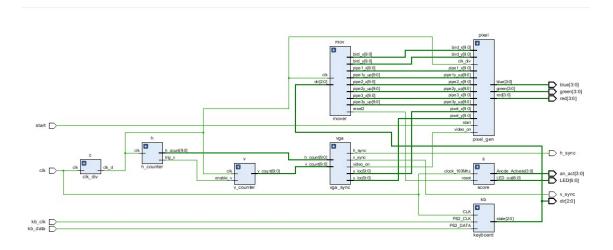


Figure 13: elaborated design for the game

#### 7.2 Mover

Our entire game's function including the FSM is integrated in this module. This module updates the location of the bird and the pipe at each instance according to the state of the game which is then outputted to pixel gen which maps the pixels accordingly. Following is the code for the module:

```
module mover(clk, dir, reset2, bird_x, bird_y, pipe1_x, pipe1y_up, pipe2_x, pipe2y_up, pipe3_x, pipe3y_
input clk;
//reset;
input [2:0] dir;
reg [2:0] c_state;
reg [2:0] state;
reg [2:0] next;
parameter UP = 3'b010;
parameter DOWN = 3'b100;
parameter START = 3'b000;
parameter RESET = 3'b111;
output reg reset2;
output reg [9:0] bird_x = 30;
output reg [9:0] bird_y = 230;
output reg [9:0] pipe1_x = 300;
output reg [9:0] pipe1y_up = 300;
// output reg [9:0] pipe1y_down = 380;
output reg [9:0] pipe2_x = 500;
```

```
output reg [9:0] pipe2y_up = 100;
// output reg [9:0] pipe2_down = 180;
output reg [9:0] pipe3_x = 100;
output reg [9:0] pipe3y_up = 200;
// output reg [9:0] pipe3y_down = 280;
reg [22:0] counter;
reg collision;
initial begin
 state = 000;
 collision = 0;
 counter = 0;
 reset2 <= 1;
always @ (posedge clk)
 begin
 c_state <= dir;</pre>
  counter <= counter + 1;</pre>
  if (counter >= 2499999)
    begin
      case (state)
      UP:
      begin
        if (bird_y > 0) begin
          bird_y <= bird_y - 10;</pre>
        end
        else begin
          state = RESET;
        end
        if (c_state == UP) begin
          next = UP;
        end
        if (c_state == DOWN) begin
          next = DOWN;
        end
        if (c_state == RESET) begin
          next = RESET;
        end
      end
      DOWN:
      begin
        if (bird_y < 460) begin
          bird_y <= bird_y + 10;</pre>
```

```
end
 if (c_state == UP) begin
   next = UP;
 end
 if (c_state == DOWN) begin
   next = DOWN;
 end
 if (c_state == RESET) begin
   next = RESET;
  end
end
START:
begin
 if (c_state == UP) begin
   reset2 <= 0;
   next = UP;
 end
 if (c_state == DOWN) begin
   reset2 <= 0;
   next = DOWN;
 end
 if (c_state == RESET) begin
   next = START;
 end
end
RESET:
begin
 if (dir == RESET) begin
   next = START;
   reset2 <= 1;
  end
  end
endcase
if (state != RESET && state != START) begin
 if (pipe1_x < 1) begin
   pipe1_x <= 640;
 end
 else begin
   pipe1_x \le pipe1_x - 5;
 if (pipe2_x < 1) begin
   pipe2_x <= 640;
  end
  else begin
   pipe2_x \le pipe2_x - 5;
```

```
end
                                                                   if (pipe3_x < 1) begin
                                                                               pipe3_x <= 640;
                                                                   end
                                                                   else begin
                                                                               pipe3_x \le pipe3_x - 5;
                                                                   end
                                                     end
                                                     if (state == START) begin
                                                                  bird_x = 30;
                                                                  bird_y = 230;
                                                                  pipe1_x = 300;
                                                                  pipe1y_up = 300;
                                                                  pipe2_x = 500;
                                                                  pipe2y_up = 100;
                                                                  pipe3_x = 100;
                                                                  pipe3y_up = 200;
                                                     end
                                                     if (bird_y < 1 || bird_y > 459 ||
                                                     ((((bird_x + 20) > pipe1_x \&\& (bird_x + 20) < pipe1_x + 40) || ((bird_x + 20) == pipe1_x) || (bird_x + 20) = pipe1_x) || (bird_x + 20) = pipe1_x) || (bird_x + 20) = pipe1_x || (bird
                                                      ((((bird_x + 20) > pipe_x \&\& (bird_x + 20) < pipe_x + 40) || ((bird_x + 20) == pipe_x) || (bird_x + 20) == pipe_x) || (bird_x + 20) == pipe_x || (((bird_x + 20) = pipe_x) || ((bird_x + 20) = pipe_
                                                     ((((bird_x + 20) > pipe_3_x \&\& (bird_x + 20) < pipe_3_x + 40) || ((bird_x + 20) == pipe_3_x) || (bird_x + 20) = pipe_x || (((bird_x + 20) = pipe_x) || ((bird_x + 20) = 
                                                                 next = START;
                                                                 reset2 <= 1;
                                                     end
                                                     // if (bird_y < 1 || bird_y > 479 ||
                                                     // ((bird_y < pipe1y_up || bird_y > pipe1y_up+80) && (bird_x+20 > pipe1_x || bird_x+20 < pipe1_x+5
                                                     // ((bird_y < pipe2y_up || bird_y > pipe2y_up+80) && (bird_x+20 > pipe2_x || bird_x+20 < pipe2_x+5
                                                     // ((bird_y < pipe3y_up || bird_y > pipe3y_up+80) && (bird_x+20 > pipe3_x || bird_x+20 < pipe3_x+5
                                                     // next = RESET;
                                                     //
                                                                                     reset2 <= 1;
                                                     // end
                                                     state = next;
                                                     counter <= 0;</pre>
                                         end
                           end
endmodule
```

#### 7.3 Pixel Gen

We are defining the pixels for the bird and the pipes at each instance. Following is the code for the module:

```
// Code your design here
module pixel_gen(
       input [9:0] pixel_x,
       input [9:0] pixel_y,
       input clk_div,
       input start,
       input video_on,
       input [9:0] bird_x,
       input [9:0] bird_y,
        input [9:0] pipe1_x,
        input [9:0] pipe1y_up,
        input [9:0] pipe2_x,
        input [9:0] pipe2y_up,
        input [9:0] pipe3_x,
        input [9:0] pipe3y_up,
       output reg [3:0] red = 0,
       output reg [3:0] blue = 0,
       output reg [3:0] green = 0
);
       reg w = 1'b1;
       reg [22:0] counter = 0;
       parameter UP = 3'b010;
       parameter DOWN = 3'b100;
       parameter START = 3'b000;
       parameter RESET = 3'b111;
       always @ (posedge clk_div && start)
             begin
                    if ((pixel_y >= bird_y && pixel_y <= (bird_y + 20)) && (pixel_x >= bird_x && pixel_x < (bird_x + 20)
//
                                 drawing the bird
                          begin
                                 red <= 4'hf;
                                 blue <= 4'h0;
                                 green <= 4'h0;
                          end
                    else if (((pixel_x >= pipe1_x && pixel_x < (pipe1_x + 40)) && ((pixel_y >= (pipe1y_up + 80) && pixel_x < (pipe1_x + 40))
                     ((pixel_x >= pipe2_x \&\& pixel_x < (pipe2_x + 40)) \&\& ((pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_x >= pipe2_x \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_x >= pipe2_x \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pipe2y_up)) \mid \mid (pixel_y >= 0 \&\& pixel_y < (pixel_y >=
                    ((pixel_x >= pipe3_x && pixel_x < (pipe3_x + 40)) && ((pixel_y >= (pipe3y_up + 80) && pixel_y < 480)
```

```
//
          drawing the pipes
        begin
          red <= 4'h0;
          blue <= 4'h0;
          green <= 4'hf;
        end
       else
//
           painting the rest of the background white
         begin
           red <= video_on ? 4'h0 : 4'h0;
           green <= video_on ? 4'h0 : 4'h0;</pre>
           blue <= video_on ? 4'h0 : 4'h0;
         end
    end
```

endmodule

#### 7.4 Score

We have added a score module which calculates the score of the user according to the time the user is successful in playing the game without losing. Following is the code for the module:

```
module score(
input clock_100Mhz, // 100 Mhz clock source on Basys 3 FPGA
 input reset, // reset
 output reg [3:0] Anode_Activate, // anode signals of the 7-segment LED display
 output reg [6:0] LED_out// cathode patterns of the 7-segment LED display
 );
reg [26:0] one_second_counter; // counter for generating 1 second clock enable
 wire one_second_enable;// one second enable for counting numbers
 reg [15:0] displayed_number; // counting number to be displayed
 reg [3:0] LED_BCD;
 reg [19:0] refresh_counter; // 20-bit for creating 10.5ms refresh period or 380Hz refresh rate
          // the first 2 MSB bits for creating 4 LED-activating signals with 2.6ms digit period
 wire [1:0] LED_activating_counter;
              // count
                                -> 1 ->
                                           2 -> 3
           // activates
                           LED1
                                   LED2
                                          LED3
                                                LED4
          // and repeat
 always @(posedge clock_100Mhz or posedge reset)
 begin
     if(reset==1)
         one_second_counter <= 0;</pre>
     else begin
         if(one_second_counter>=99999999)
              one_second_counter <= 0;</pre>
```

```
else
            one_second_counter <= one_second_counter + 1;</pre>
    end
end
assign one_second_enable = (one_second_counter==99999999)?1:0;
always @(posedge clock_100Mhz or posedge reset)
begin
    if(reset==1)
        displayed_number <= 0;</pre>
    else if(one_second_enable==1)
        displayed_number <= displayed_number + 2;</pre>
end
always @(posedge clock_100Mhz or posedge reset)
begin
    if(reset==1)
        refresh_counter <= 0;
    else
        refresh_counter <= refresh_counter + 1;</pre>
end
assign LED_activating_counter = refresh_counter[19:18];
// anode activating signals for 4 LEDs, digit period of 2.6ms
// decoder to generate anode signals
always @(*)
begin
    case(LED_activating_counter)
    2'b00: begin
        Anode_Activate = 4'b0111;
        // activate LED1 and Deactivate LED2, LED3, LED4
        LED_BCD = displayed_number/1000;
        // the first digit of the 16-bit number
          end
    2'b01: begin
        Anode_Activate = 4'b1011;
        // activate LED2 and Deactivate LED1, LED3, LED4
        LED_BCD = (displayed_number % 1000)/100;
        // the second digit of the 16-bit number
          end
    2'b10: begin
        Anode_Activate = 4'b1101;
        // activate LED3 and Deactivate LED2, LED1, LED4
        LED_BCD = ((displayed_number % 1000)%100)/10;
        // the third digit of the 16-bit number
            end
    2'b11: begin
        Anode_Activate = 4'b1110;
```

```
// activate LED4 and Deactivate LED2, LED3, LED1
        LED_BCD = ((displayed_number % 1000)%100)%10;
        // the fourth digit of the 16-bit number
           end
    endcase
end
// Cathode patterns of the 7\text{-segment LED} display
always @(*)
begin
    case(LED_BCD)
    4'b0000: LED_out = 7'b0000001; // "0"
    4'b0001: LED_out = 7'b1001111; // "1"
    4'b0010: LED_out = 7'b0010010; // "2"
    4'b0011: LED_out = 7'b0000110; // "3"
    4'b0100: LED_out = 7'b1001100; // "4"
    4'b0101: LED_out = 7'b0100100; // "5"
    4'b0110: LED_out = 7'b0100000; // "6"
    4'b0111: LED_out = 7'b0001111; // "7"
    4'b1000: LED_out = 7'b0000000; // "8"
    4'b1001: LED_out = 7'b0000100; // "9"
    default: LED_out = 7'b0000001; // "0"
    endcase
end
endmodule
```

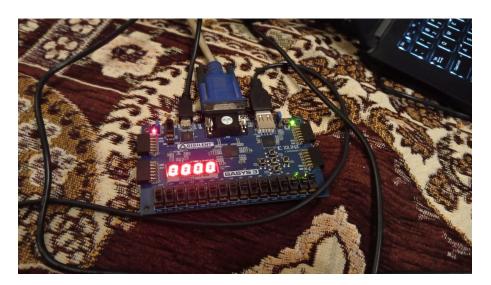


Figure 14: 7 Segment Display

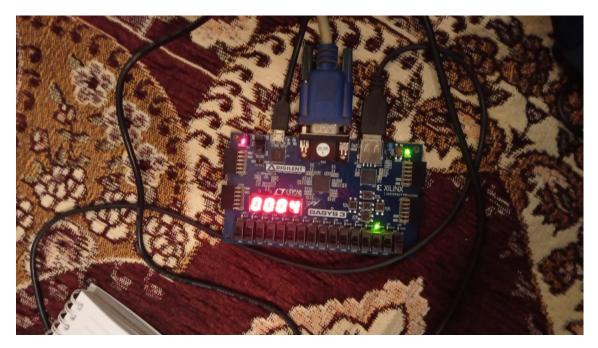


Figure 15: 7 Segment Display

### 8 Conclusion

The report presented is a detailed explanation to our very project, Flappy Bird, which is an FPGA emulation of the actual "Flappy Bird" game. Our report brings forward the ideas involved in making of the game.

The report introduces the audience of the user-flow diagram along with its division of blocks. Moreover, it gives a complete insight to the input, control and output blocks of the game made. With that said, lets briefly include what they comprise of as well.

The focal point of the input block makes us understand the Input Output (IO) pins involved, which in our case are keys from the basic keyboard. The bird moves with respect to the order assigned to it. Pressing 'W' would make the bird go up and 'S' to make it come back down.

The basis of the control block is to check the validity of the inputs provided and make sure the output is generated. Besides its usual function, it explains the states, in company with the state transition diagram.

The output block, is the main block considering that's what the user interacts with, explains the pixel division of the components stated in our project which are the bird and the tubes it has pass through. If at any point, the user is unable to get through the desired tube, the game resets and points are set back to zero.

### 9 References

Keyboard Input: https://www.instructables.com/PS2-Keyboard-for-FPGA/

Key scan codes and IO pins: https://digilent.com/reference/programmable-logic/basys-3/start

Reference paper: Gladyshev, P., Patel, A. (2004). Finite state machine approach to digital event reconstruction.

Digital Investigation, 1(2), 130-149.

# 10 Github Repository

https://github.com/princebiscuits/DLD-Project.git