

P15-P16: Backlight
P3: LCD Contrast Adjustment

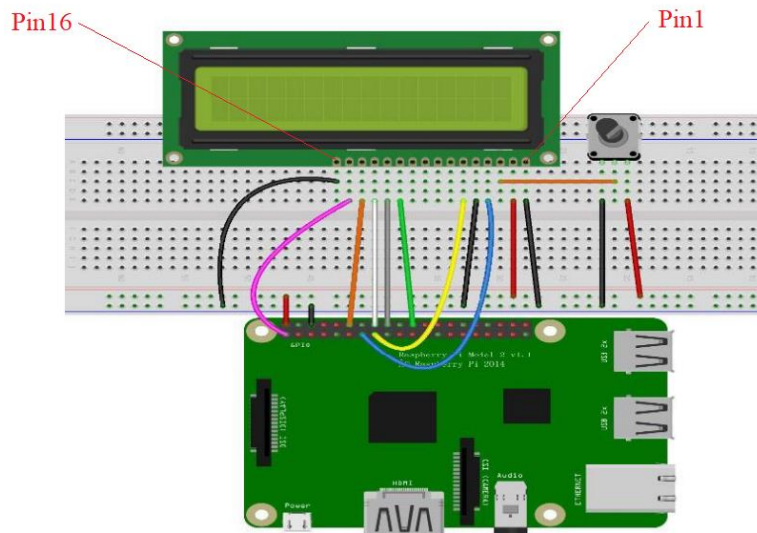
DB0-DB7: Data & Command inputs

RS--- Instruction/Data Selection

E--- Enable

R/W=0 Always in Write Mode

PIN NO.	SYMBOL	DESCRIPTION	FUNCTION
1	VSS	GROUND	0V (GND)
2	VCC	POWER SUPPLY FOR LOGIC CIRCUIT	+5V
3	VEE	LCD CONTRAST ADJUSTMENT	
4	RS	INSTRUCTION/DATA REGISTER SELECTION	RS = 0 : INSTRUCTION REGISTER RS = 1 : DATA REGISTER
5	R/W	READ/WRITE SELECTION	R/W = 0 : REGISTER WRITE R/W = 1 : REGISTER READ
6	E	ENABLE SIGNAL	
7	DB0	DATA INPUT/OUTPUT LINES	8 BIT: DB0-DB7
8	DB1		
9	DB2		
10	DB3		
11	DB4		
12	DB5		
13	DB6		
14	DB7		
15	LED+	SUPPLY VOLTAGE FOR LED+	+5V
16	LED-	SUPPLY VOLTAGE FOR LED-	0V



Raspberry Pi 3 GPIO Header

Pin#	NAME		NAME	Pin#
01	3.3v DC Power		DC Power 5v	02
03	GPIO02 (SDA1 , I²C)		DC Power 5v	04
05	GPIO03 (SCL1 , I²C)		Ground	06
07	GPIO04 (GPIO_GCLK)		(TXD0) GPIO14	08
09	Ground		(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)		(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)		Ground	14
15	GPIO22 (GPIO_GEN3)		(GPIO_GEN4) GPIO23	16
17	3.3v DC Power		(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)		Ground	20
21	GPIO09 (SPI_MISO)		(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)		(SPI_CE0_N) GPIO08	24
25	Ground		(SPI_CE1_N) GPIO07	26
27	ID_SD (I²C ID EEPROM)		(I²C ID EEPROM) ID_SC	28
29	GPIO05		Ground	30
31	GPIO06		GPIO12	32
33	GPIO13		Ground	34
35	GPIO19		GPIO16	36
37	GPIO26		GPIO20	38
39	Ground		GPIO21	40

2. Control program in Python

Python Program

```
from time import sleep
```

```
class LCD:
```

```
    # commands
```

```
    LCD_CLEARDISPLAY          = 0x01          # 0000_0001
```

```
    LCD_RETURNHOME           = 0x02
```

```
    LCD_ENTRYMODESET         = 0x04
```

```
    LCD_DISPLAYCONTROL       = 0x08
```

```
    LCD_CURSORSHIFT          = 0x10
```

```
    LCD_FUNCTIONSET           = 0x20
```

```
    LCD_SETCGRAMADDR         = 0x40
```

```
    LCD_SETDDRAMADDR         = 0x80
```

```
    # flags for display entry mode
```

```
    LCD_ENTRYRIGHT            = 0x00
```

```
    LCD_ENTRYLEFT             = 0x02
```

```
    LCD_ENTRYSHIFTINCREMENT   = 0x01
```

```
    LCD_ENTRYSHIFTDECREMENT   = 0x00
```

```
    # flags for display on/off control
```

```
    LCD_DISPLAYON             = 0x04
```

```
    LCD_DISPLAYOFF            = 0x00
```

```
    LCD_CURSORON              = 0x02
```

```
    LCD_CURSOROFF             = 0x00
```

```
    LCD_BLINKON               = 0x01
```

```
    LCD_BLINKOFF              = 0x00
```

```
    # flags for display/cursor shift
```

```
    LCD_DISPLAYMOVE           = 0x08
```

```

LCD_CURSORMOVE = 0x00

# flags for display/cursor shift
LCD_DISPLAYMOVE = 0x08
LCD_CURSORMOVE = 0x00
LCD_MOVERIGHT = 0x04
LCD_MOVELEFT = 0x00

# flags for function set
LCD_8BITMODE = 0x10
LCD_4BITMODE = 0x00
LCD_2LINE = 0x08
LCD_1LINE = 0x00
LCD_5x10DOTS = 0x04
LCD_5x8DOTS = 0x00

def __init__(self, pin_rs=27, pin_e=22, pins_db=[25, 24, 23, 18], GPIO = None):
    # Emulate the old behavior of using RPi.GPIO if we haven't been given
    # an explicit GPIO interface to use if not GPIO:
    import RPi.GPIO as GPIO
    self.GPIO = GPIO
    self.pin_rs = pin_rs
    self.pin_e = pin_e
    self.pins_db = pins_db

    self.used_gpio = self.pins_db[:]
    self.used_gpio.append(pin_e)
    self.used_gpio.append(pin_rs)

    self.GPIO.setwarnings(False)
    self.GPIO.setmode(GPIO.BCM)
    self.GPIO.setup(self.pin_e, GPIO.OUT)
    self.GPIO.setup(self.pin_rs, GPIO.OUT)

    for pin in self.pins_db:
        self.GPIO.setup(pin, GPIO.OUT)

    self.write4bits(0x33) # initialization
    self.write4bits(0x32) # initialization
    self.write4bits(0x28) # 2 line 5x7 matrix
    self.write4bits(0x0C) # turn cursor off 0x0E to enable cursor
    self.write4bits(0x06) # shift cursor right

    self.displaycontrol = self.LCD_DISPLAYON |
    self.LCD_CURSOROFF | self.LCD_BLINKOFF

    self.displayfunction = self.LCD_4BITMODE | self.LCD_1LINE
    | self.LCD_5x8DOTS
    self.displayfunction |= self.LCD_2LINE

    """ Initialize to default text direction (for romance languages) """
    self.displaymode = self.LCD_ENTRYLEFT |
    self.LCD_ENTRYSHIFTDECREMENT
    self.write4bits(self.LCD_ENTRYMODESET | self.displaymode)
    # set the entry mode

    self.clear()

```

```

def begin(self, cols, lines):
    if (lines > 1):
        self.numlines = lines
        self.displayfunction |= self.LCD_2LINE
        self.currline = 0

def home(self):
    self.write4bits(self.LCD_RETURNHOME) # set cursor position to zero
    self.delayMicroseconds(3000) # this command takes a long time!

def clear(self):
    self.write4bits(self.LCD_CLEARDISPLAY) # command to clear display
    self.delayMicroseconds(3000)
    # 3000 microsecond sleep, clearing the display takes a long time

def setCursor(self, col, row):
    self.row_offsets = [ 0x00, 0x40, 0x14, 0x54 ]

    if ( row > self.numlines ):
        row = self.numlines - 1 # we count rows starting w/0

    self.write4bits(self.LCD_SETDRAMADDR | (col +
self.row_offsets[row]))

def noDisplay(self):
    # Turn the display off (quickly)
    self.displaycontrol &= ~self.LCD_DISPLAYON
    self.write4bits(self.LCD_DISPLAYCONTROL |
self.displaycontrol)

def display(self):
    # Turn the display on (quickly)
    self.displaycontrol |= self.LCD_DISPLAYON
    self.write4bits(self.LCD_DISPLAYCONTROL |
self.displaycontrol)

def noCursor(self):
    # Turns the underline cursor on/off
    self.displaycontrol &= ~self.LCD_CURSORON
    self.write4bits(self.LCD_DISPLAYCONTROL |
self.displaycontrol)

def cursor(self):
    # Cursor On
    self.displaycontrol |= self.LCD_CURSORON
    self.write4bits(self.LCD_DISPLAYCONTROL |
self.displaycontrol)

def noBlink(self):
    # Turn on and off the blinking cursor
    self.displaycontrol &= ~self.LCD_BLINKON
    self.write4bits(self.LCD_DISPLAYCONTROL |
self.displaycontrol)

def noBlink(self):
    # Turn on and off the blinking cursor

```

```

        self.displaycontrol &= ~self.LCD_BLINKON
        self.write4bits(self.LCD_DISPLAYCONTROL |
            self.displaycontrol)

def DisplayLeft(self):
    # These commands scroll the display without changing the RAM
    self.write4bits(self.LCD_CURSORSHIFT |
        self.LCD_DISPLAYMOVE | self.LCD_MOVELEFT)

def scrollDisplayRight(self):
    # These commands scroll the display without changing the RAM
    self.write4bits(self.LCD_CURSORSHIFT |
        self.LCD_DISPLAYMOVE | self.LCD_MOVERIGHT);

def leftToRight(self):
    # This is for text that flows Left to Right
    self.displaymode |= self.LCD_ENTRYLEFT
    self.write4bits(self.LCD_ENTRYMODESET |
        self.displaymode);

def rightToLeft(self):
    # This is for text that flows Right to Left
    self.displaymode &= ~self.LCD_ENTRYLEFT
    self.write4bits(self.LCD_ENTRYMODESET | self.displaymode)

def autoscroll(self):
    # This will 'right justify' text from the cursor
    self.displaymode |= self.LCD_ENTRYSHIFTINCREMENT
    self.write4bits(self.LCD_ENTRYMODESET | self.displaymode)

def noAutoscroll(self):
    # This will 'left justify' text from the cursor
    self.displaymode &= ~self.LCD_ENTRYSHIFTINCREMENT
    self.write4bits(self.LCD_ENTRYMODESET | self.displaymode)

def write4bits(self, bits, char_mode=False): # one of functions in class LCD
    # Send command to LCD
    self.delayMicroseconds(1000) # 1000 microsecond sleep
    bits=bin(bits)[2:].zfill(8)
    self.GPIO.output(self.pin_rs, char_mode)
    for pin in self.pins_db:
        self.GPIO.output(pin, False)
    for i in range(4):
        if bits[i] == "1":
            self.GPIO.output(self.pins_db[::-1][i], True)
    self.pulseEnable()
    for pin in self.pins_db:
        self.GPIO.output(pin, False)
    for i in range(4,8):
        if bits[i] == "1":
            self.GPIO.output(self.pins_db[::-1][i-4], True)
    self.pulseEnable()

def delayMicroseconds(self, microseconds):
    seconds = microseconds / float(1000000)
    # divide microseconds by 1 million for seconds
    sleep(seconds)

```

```

def pulseEnable(self):
    self.GPIO.output(self.pin_e, False)
    self.delayMicroseconds(1) # 1 microsecond pause - enable pulse must be > 450ns
    self.GPIO.output(self.pin_e, True)
    self.delayMicroseconds(1) # 1 microsecond pause - enable pulse must be > 450ns
    self.GPIO.output(self.pin_e, False)
    self.delayMicroseconds(1) # commands need > 37us to settle

def message(self, text):
    # Send string to LCD. Newline wraps to second line
    print "message: %s"%text
    for char in text:
        if char == '\n':
            self.write4bits(0xC0) # next line
        else:
            self.write4bits(ord(char), True)

def destroy(self):
    print "clean up used_gpio"
    self.GPIO.cleanup(self.used_gpio)

def print_msg():
    print ("=====")
    print ("|                      LCD1602                      |")
    print ("| -----|")
    print ("|          D4 connect to BCM25          |")
    print ("|          D5 connect to BCM24          |")
    print ("|          D6 connect to BCM23          |")
    print ("|          D7 connect to BCM18          |")
    print ("|          RS connect to BCM27          |")
    print ("|          CE connect to bcm22          |")
    print ("|          RW connect to GND            |")
    print ("|                                     |")
    print ("|          Control LCD1602              |")
    print ("|                                     |")
    print ("|                                     SunFounder|")
    print ("=====\\n")
    print 'Program is running...'
    print 'Please press Ctrl+C to end the program...'
    raw_input ("Press Enter to begin\\n")

def main():
    global lcd
    print_msg()
    lcd = LCD() # obj: lcd
    line0 = " sunfounder.com"
    line1 = "---SUNFOUNDER---"

    lcd.clear()
    lcd.message("Welcome to --->\\n sunfounder.com")
    sleep(3)

    msg = "%s\\n%s" % (line0, line1)
    while True:
        lcd.begin(0, 2)
        lcd.clear()

```

```

        for i in range(0, len(line0)):
            lcd.setCursor(i, 0)
            lcd.message(line0[i])
            sleep(0.1)
        for i in range(0, len(line1)):
            lcd.setCursor(i, 1)
            lcd.message(line1[i])
            sleep(0.1)
        sleep(1)

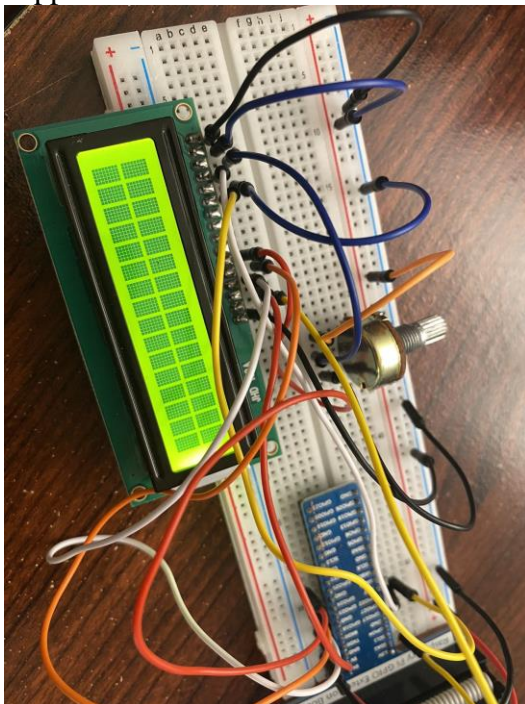
if __name__ == '__main__':
    try:
        main()
    except KeyboardInterrupt:
        lcd.clear()
        lcd.destroy()

```

Note: Hardware connection reference and running **command*
<https://learn.sunfounder.com/lesson-16-lcd1602/>
<https://learn.sunfounder.com/category/super-kit-v3-0-for-raspberry-pi/>

The Laboratory Assignments:

1. Build up the hardware circuit and run the example program to observe what will happen



Youtube link:

<https://youtube.com/shorts/8EaOnyF-IwM?feature=share>

2. Display “you did good job” in LCD by left shifting from right.

Code:

```
LCD_MATRIXPERLINE = 16

def __init__(self, pin_rs=27, pin_e=22, pins_db=[25, 24, 23, 18], GPIO = None):
    self.numlines = 0
    self.nummatrixes = self.LCD_MATRIXPERLINE
    # Emulate the old behavior of using RPi.GPIO if we haven't been given
    # an explicit GPIO interface to use if not GPIO:
    import RPi.GPIO as GPIO
    self.GPIO = GPIO
    self.pin_rs = pin_rs
    self.pin_e = pin_e
    self.pins_db = pins_db

def main():
    global lcd
    print_msg()
    lcd = LCD()          # obj: lcd
    line0 = "you did good job"
    #line0 = "  sunfounder.com"
    line1 = "---SUNFOUNDER---"

    lcd.clear()
    lcd.message("Welcome to --->\n  sunfounder.com")
    sleep(3)

    msg = "%s\n%s" % (line0, line1)

    lcd.rightToLeft()
    while True:
        for index in range(lcd.nummatrixes-1, -1, -1):
            lcd.clear()
            lcd.setCursor(index, 0)
            lcd.message(line0)
            sleep(0.3)
```

Youtube link:

<https://youtube.com/shorts/8epgbHchUp0?feature=share>