CAN

I / O

Laser / Ultraschlall

UBS - Empfänger

LBS - Rx / Tx

[*1] [*2] [*3]

Robo Board

Kern

Naherkennung

Peripherie

[*4] [*5] [*6] [*7]

Not Aus

Low Energy

[*8] [*9] [*10] [*11]

Kalman **Odometrie** **Antrieb**

Speisungsprint

Not Aus

[*1] UBS (ELP) an Kalman

[*2] ELP von Kalman an LBS

[*3] LBS (ELP) an Kern (3x)

[*4] LBS (ELP) von Navi (3x)

[*5] ELP von Kalman

[*6] GoTo an Antrieb

[*7] GoTO Response

[*8] ELP von Navi

[*9] ELP an Navi

[*10] GoTo von Kern

[*11] GoTo Response