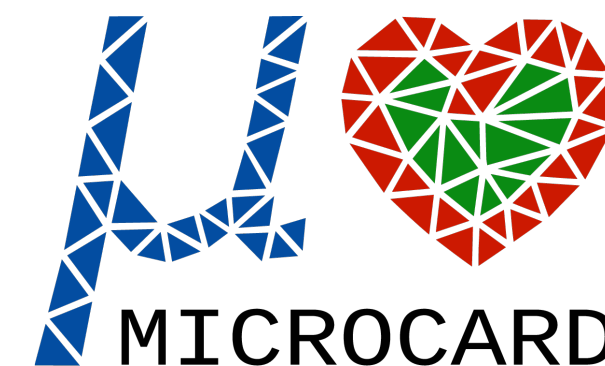


Parallel-in-Time methods for cardiac electrophysiology

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Spatially discretized monodomain equation:

$$\mathbf{V}' = A\mathbf{V} - I_{ion}(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g),$$

$$\mathbf{z}'_a = g_a(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g),$$

$$\mathbf{z}'_g = \Lambda_g(\mathbf{V})(\mathbf{z}_g - \mathbf{z}_{g,\infty}(\mathbf{V}))$$

Spatially discretized monodomain equation:

$$\begin{aligned} \mathbf{V}' &= A\mathbf{V} - I_{ion}(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g), \\ \mathbf{z}'_a &= g_a(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g), \\ \mathbf{z}'_g &= \Lambda_g(\mathbf{V})(\mathbf{z}_g - \mathbf{z}_{g,\infty}(\mathbf{V})) \end{aligned} \quad \Rightarrow \quad \begin{pmatrix} \mathbf{V}' \\ \mathbf{z}'_a \\ \mathbf{z}'_g \end{pmatrix} = \begin{pmatrix} A\mathbf{V} \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -I_{ion}(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g) \\ g_a(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g) \\ 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \Lambda_g(\mathbf{V}) \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ \mathbf{z}_g - \mathbf{z}_{g,\infty}(\mathbf{V}) \end{pmatrix}$$

With $y = (\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g)$ and

$$f_I(y) = \begin{pmatrix} A\mathbf{V} \\ 0 \\ 0 \end{pmatrix} \quad f_E(y) = \begin{pmatrix} -I_{ion}(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g) \\ g_a(\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g) \\ 0 \end{pmatrix} \quad f_g(y) = \Lambda(y)(y - y_\infty(y)) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \Lambda_g(\mathbf{V}) \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ \mathbf{z}_g - \mathbf{z}_{g,\infty}(\mathbf{V}) \end{pmatrix}$$

We get the ODE:

$$y' = f_I(y) + f_E(y) + f_g(y)$$

Consider

$$y' = f_I(y) + f_E(y) + f_g(y)$$

with $y(t_n) = y_n$ and $f_g(y) = \Lambda(y)(y - y_\infty(y))$. Then

$$\begin{aligned} y' &= \Lambda(y_n)(y - y_n) - \Lambda(y_n)(y - y_n) + f_I(y) + f_E(y) + f_g(y) \\ &= \Lambda(y_n)(y - y_n) + g(y). \end{aligned}$$

Applying variation of constants:

$$y(t) = y_n + \int_{t_n}^t e^{(t-s)\Lambda(y_n)} g(y(s)) ds.$$

Replace $g(y(s))$ with interpolating polynomial

$$g(y(s)) \approx \sum_{j=1}^M g(y_{n,j}) \ell_j(s),$$

with $0 < c_1 < \dots < c_M = 1$ collocation nodes and

$$y_{n,j} \approx y(t_n + \Delta t c_j),$$

yields system:

$$y_{n,i} = y_n + \Delta t \sum_{j=1}^M a_{ij}(\Delta t \Lambda(y_n)) g(y_{n,j}), \quad i = 1, \dots, M,$$

with

$$a_{ij}(z) = \int_0^{c_i} e^{(c_i-s)z} \ell_j(s) ds.$$

Recall $y = (\mathbf{V}, \mathbf{z}_a, \mathbf{z}_g)$ and

$$\Lambda(y_n) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \Lambda_g(\mathbf{V}_n) \end{pmatrix},$$

thus

$$a_{ij}(\Delta t \Lambda(y_n)) = \begin{pmatrix} a_{ij}(0) & 0 & 0 \\ 0 & a_{ij}(0) & 0 \\ 0 & 0 & a_{ij}(\Delta t \Lambda_g(\mathbf{V}_n)) \end{pmatrix}.$$

System

$$y_{n,i} = y_n + \Delta t \sum_{j=1}^M a_{ij}(\Delta t \Lambda(y_n)) g(y_{n,j}), \quad i = 1, \dots, M,$$

is compactly written

$$(I - \Delta t \mathbf{A}(\Delta t \Lambda(y_n) \mathbf{G})(\mathbf{y}_n) = \mathbf{1} \otimes y_n,$$

$$\mathbf{C}(\mathbf{y}_n) = \mathbf{1} \otimes y_n,$$

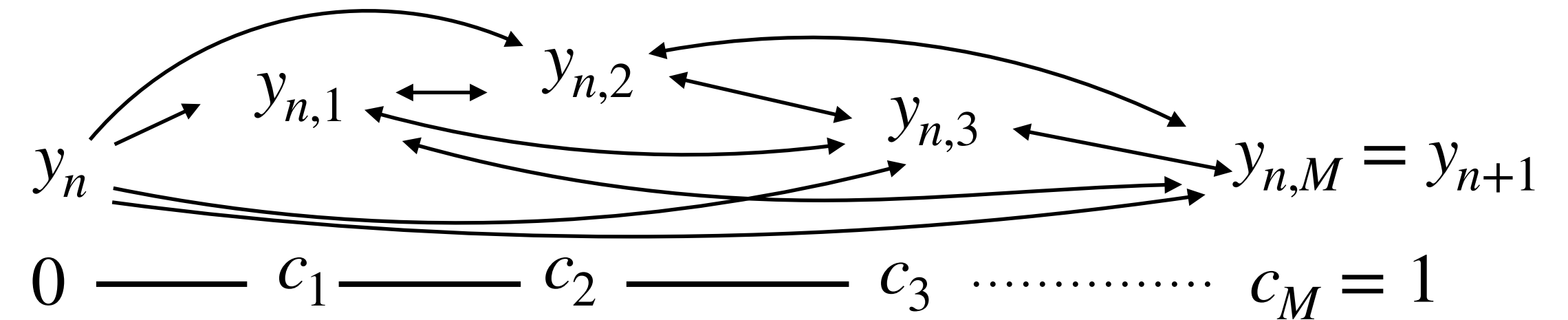
with $\mathbf{y}_n = (y_{n,1}, \dots, y_{n,M})$, \mathbf{A} matrix of a_{ij} , and \mathbf{G} vector of $g(y_{n,j})$.

Instead of Newton, SDC approach uses preconditioned fixed point iteration:

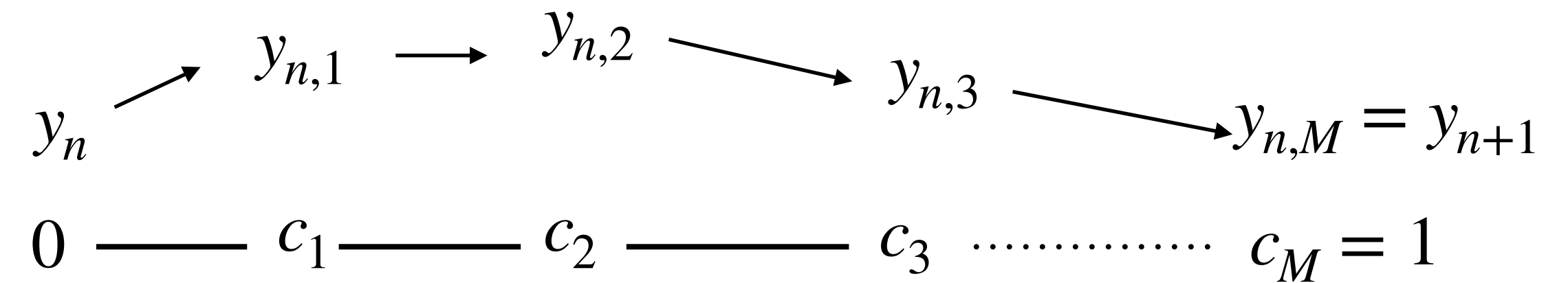
$$\mathbf{P}(\mathbf{y}_n^{k+1}) = \mathbf{P}(\mathbf{y}_n^k) + \mathbf{1} \otimes y_n - \mathbf{C}(\mathbf{y}_n^k),$$

with $\mathbf{P} \approx \mathbf{C}$ but “easy”.

\mathbf{C} is defined by an exponential collocation method on the collocation nodes:



We define \mathbf{P} by sequential application of IMEX-Rush-Larsen:



Exact operator \mathbf{C} is hybrid exponential-collocation.

Preconditioner \mathbf{P} is IMEX-Rush-Larsen.

A sequence of P consecutive steps is given by:

$$\begin{array}{ccccccc}
 \mathbf{C}(\mathbf{y}_0) = \mathbf{1} \otimes y_0, & \mathbf{C}(\mathbf{y}_1) = \mathbf{1} \otimes y_{0,M} & \mathbf{C}(\mathbf{y}_2) = \mathbf{1} \otimes y_{1,M} & \dots & \mathbf{C}(\mathbf{y}_{P-1}) = \mathbf{1} \otimes y_{P-2,M} \\
 t_0 \text{ ---} & t_1 \text{ ---} & t_2 \text{ ---} & t_3 \text{} & t_{P-1} \text{ ---} & t_P
 \end{array}$$

which is written: $\mathbf{D}(\mathbf{z}) = \mathbf{b}$,

with $\mathbf{z} = (\mathbf{y}_0, \dots, \mathbf{y}_{P-1})$, $\mathbf{b} = (\mathbf{1} \otimes y_0, 0, \dots, 0)$ and

$$\mathbf{D} = \text{diag}(\mathbf{C}, \dots, \mathbf{C}) - \mathbf{H}.$$

Where \mathbf{H} is the matrix taking the last node value of a step to be used as initial value in the next one.

The system is again solved with preconditioned fixed point

$$\mathbf{Q}(\mathbf{z}^{k+1}) = \mathbf{Q}(\mathbf{z}^k) + \mathbf{b} - \mathbf{D}(\mathbf{z}^k)$$

and two preconditioners are available:

$$\mathbf{Q}^{ser} = \text{diag}(\mathbf{P}, \dots, \mathbf{P}) - \mathbf{H}, \quad \mathbf{Q}^{par} = \text{diag}(\mathbf{P}, \dots, \mathbf{P}).$$

A sequence of P consecutive steps is given by:

$$t_0 \xrightarrow{\mathbf{C}(\mathbf{y}_0) = \mathbf{1} \otimes y_0,} t_1 \xrightarrow{\mathbf{C}(\mathbf{y}_1) = \mathbf{1} \otimes y_{0,M}} t_2 \xrightarrow{\mathbf{C}(\mathbf{y}_2) = \mathbf{1} \otimes y_{1,M}} t_3 \cdots t_{P-1} \xrightarrow{\mathbf{C}(\mathbf{y}_{P-1}) = \mathbf{1} \otimes y_{P-2,M}} t_P$$

which is written: $\mathbf{D}(\mathbf{z}) = \mathbf{b}$,

with $\mathbf{z} = (\mathbf{y}_0, \dots, \mathbf{y}_{P-1})$, $\mathbf{b} = (\mathbf{1} \otimes y_0, 0, \dots, 0)$ and

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Where \mathbf{H} is the matrix taking the last node value of a step to be used as initial value in the next one.

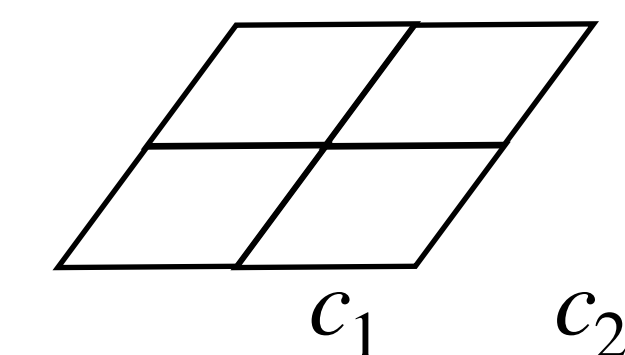
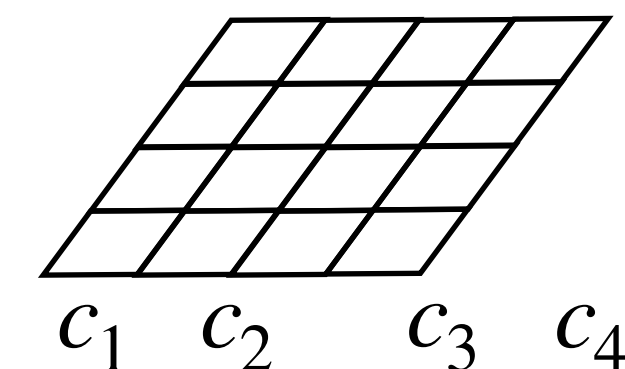
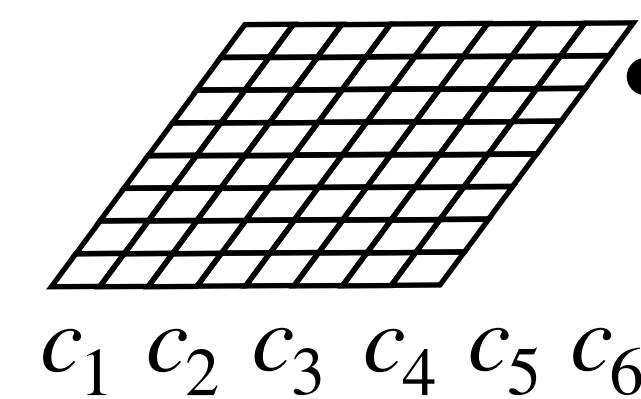
The system is again solved with preconditioned fixed point

$$\mathbf{Q}(\mathbf{z}^{k+1}) = \mathbf{Q}(\mathbf{z}^k) + \mathbf{b} - \mathbf{D}(\mathbf{z}^k)$$

and two preconditioners are available:

$$\mathbf{Q}^{ser} = \text{diag}(\mathbf{P}, \dots, \mathbf{P}) - \mathbf{H}, \quad \mathbf{Q}^{par} = \text{diag}(\mathbf{P}, \dots, \mathbf{P}).$$

Adding nonlinear multigrid:



$$\mathbf{Q}^{par}(\mathbf{z}^{k+1}) = \mathbf{Q}^{par}(\mathbf{z}^k) + \mathbf{b} - \mathbf{D}(\mathbf{z}^k)$$

plus τ and coarse
grid corrections

$$\mathbf{Q}^{par}(\mathbf{z}^{k+1}) = \mathbf{Q}^{par}(\mathbf{z}^k) + \mathbf{b} - \mathbf{D}(\mathbf{z}^k)$$

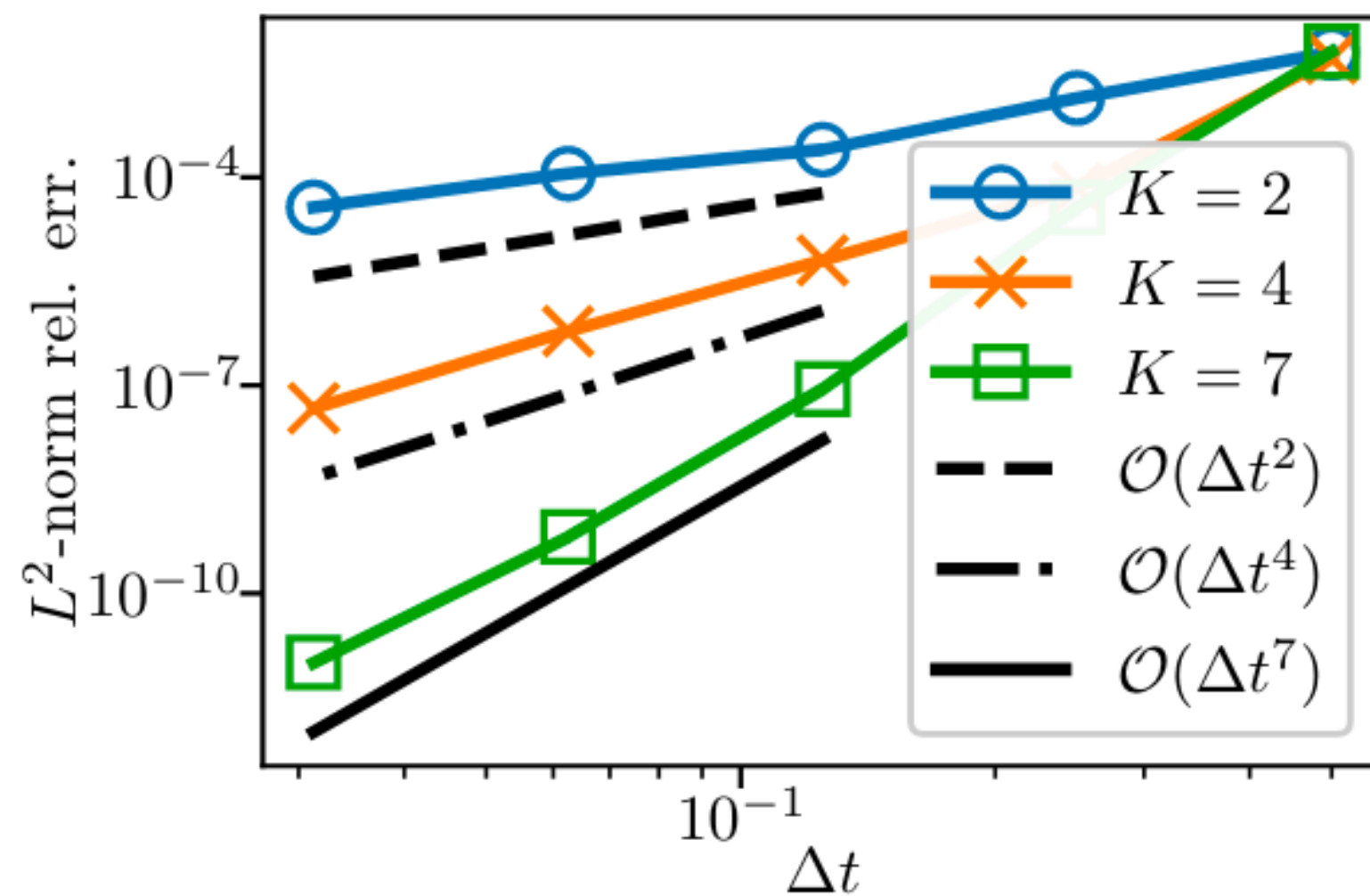
$$\mathbf{Q}^{ser}(\mathbf{z}^{k+1}) = \mathbf{Q}^{ser}(\mathbf{z}^k) + \mathbf{b} - \mathbf{D}(\mathbf{z}^k)$$

Convergence experiments: Serial setting

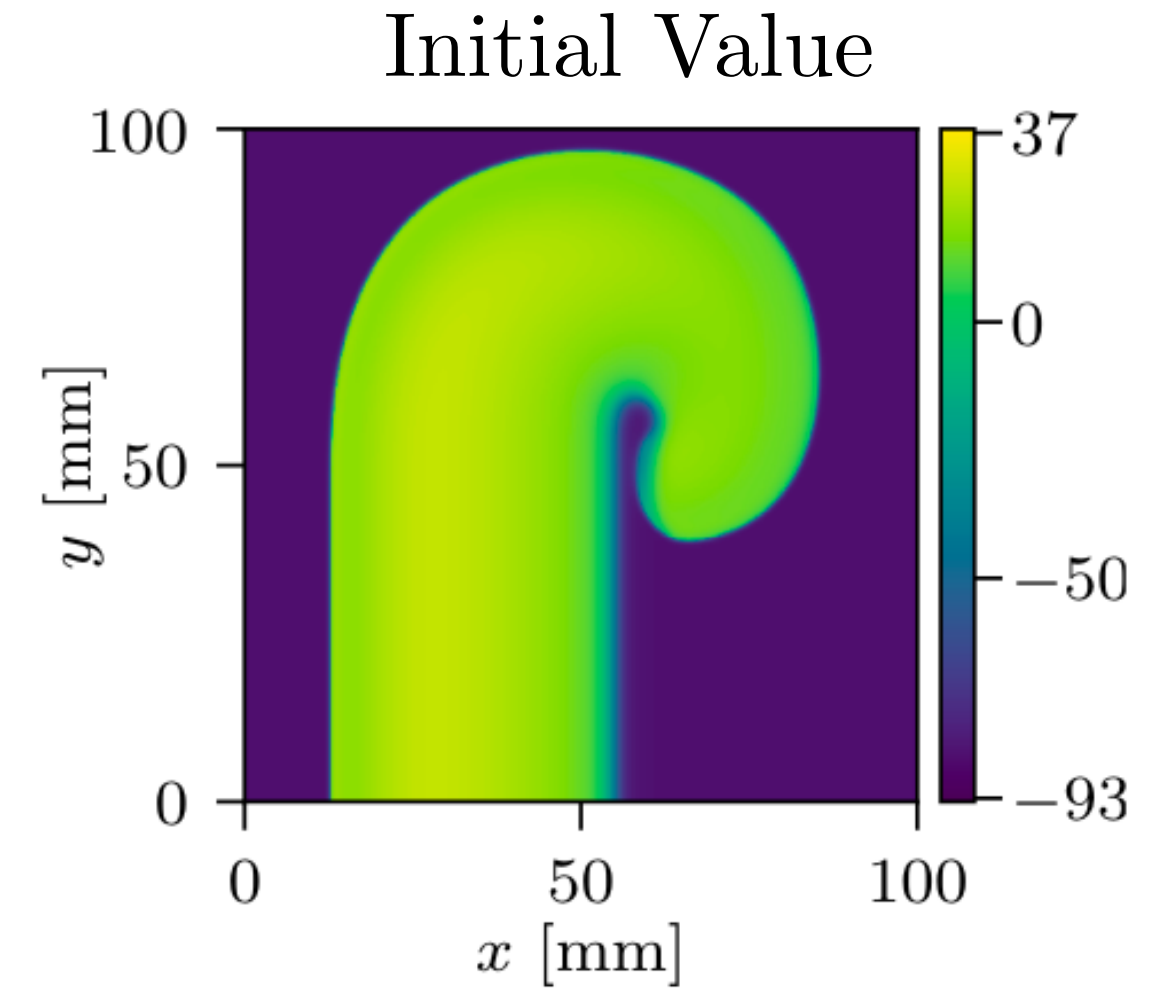
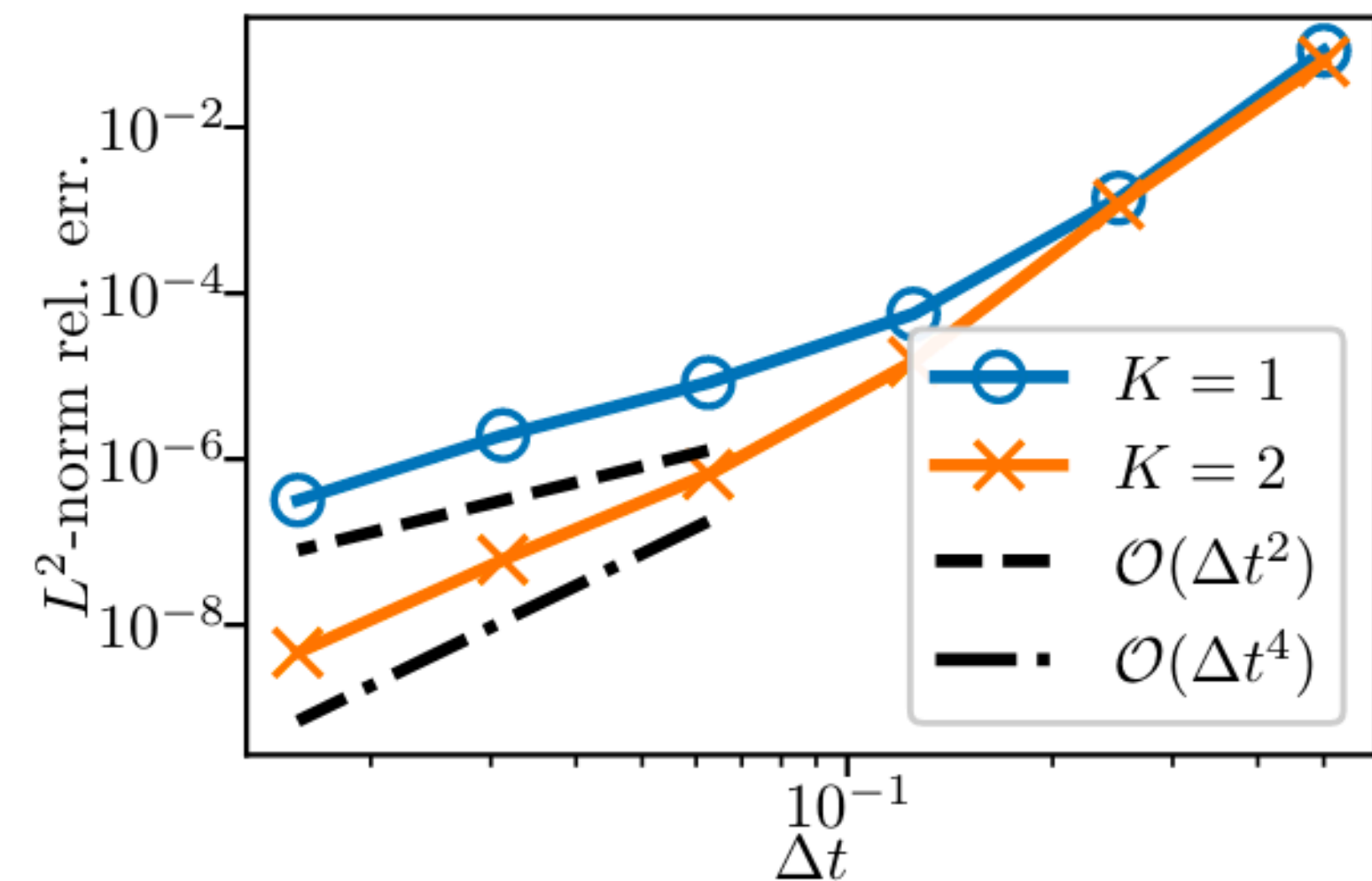
Solve Monodomain equation with $\Omega = [0,100] \times [0,100]\text{mm}^2$, $T = 1\text{ms}$, $\Delta x = 0.2\text{mm}$,

◆ ten Tusscher-Panfilov (smoothed), ◆ Coarsening in time only.

- $P = 1$ serial steps,
- $L = 1$ multigrid levels,
- $M = 6$ collocation nodes.



- $P = 1$ serial steps,
- $L = 2$ multigrid levels,
- $M = 4,2$ collocation nodes.

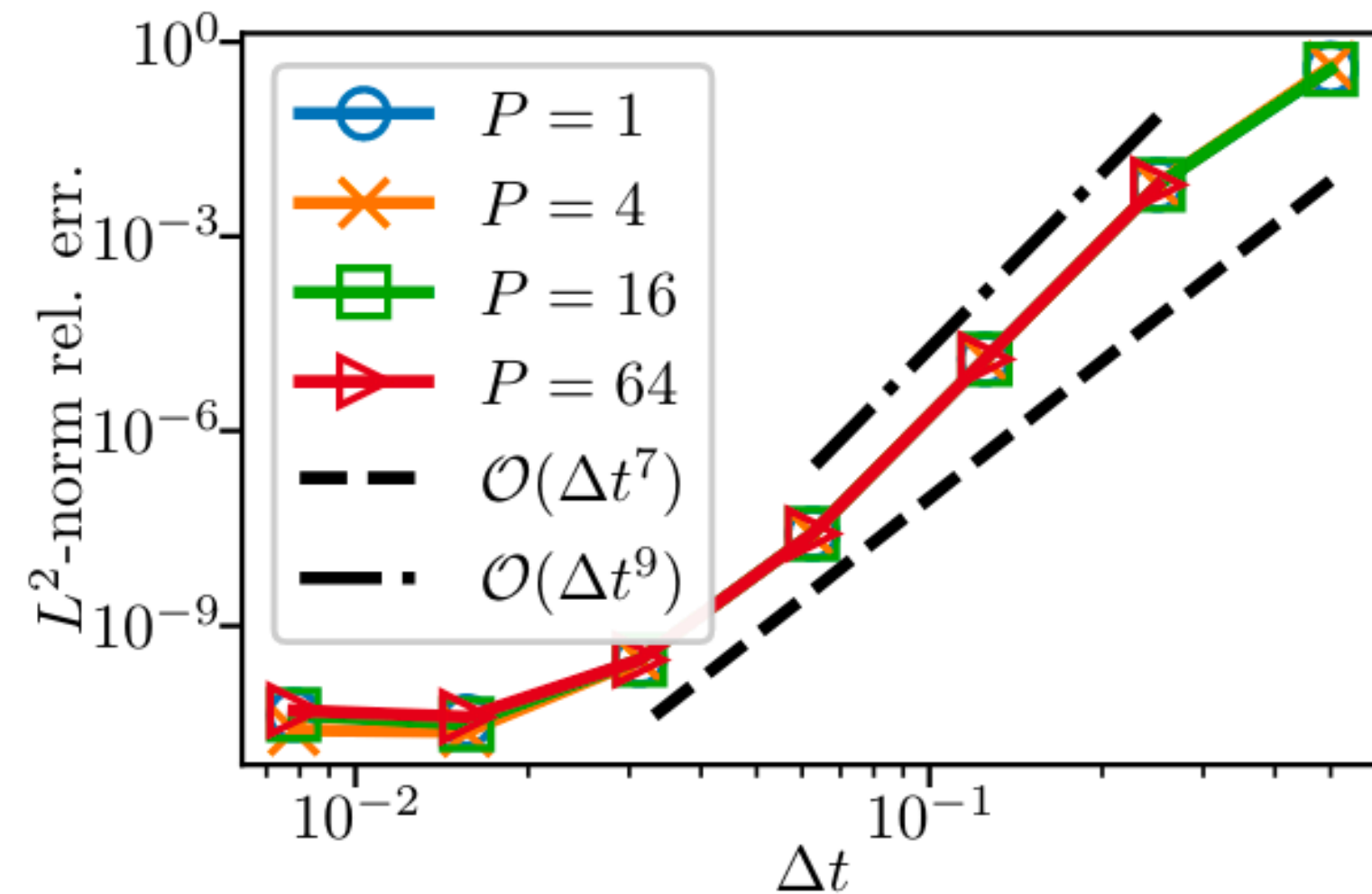


¹: Radau has order $2M - 1$, but exponential collocation has order $M + 1$.

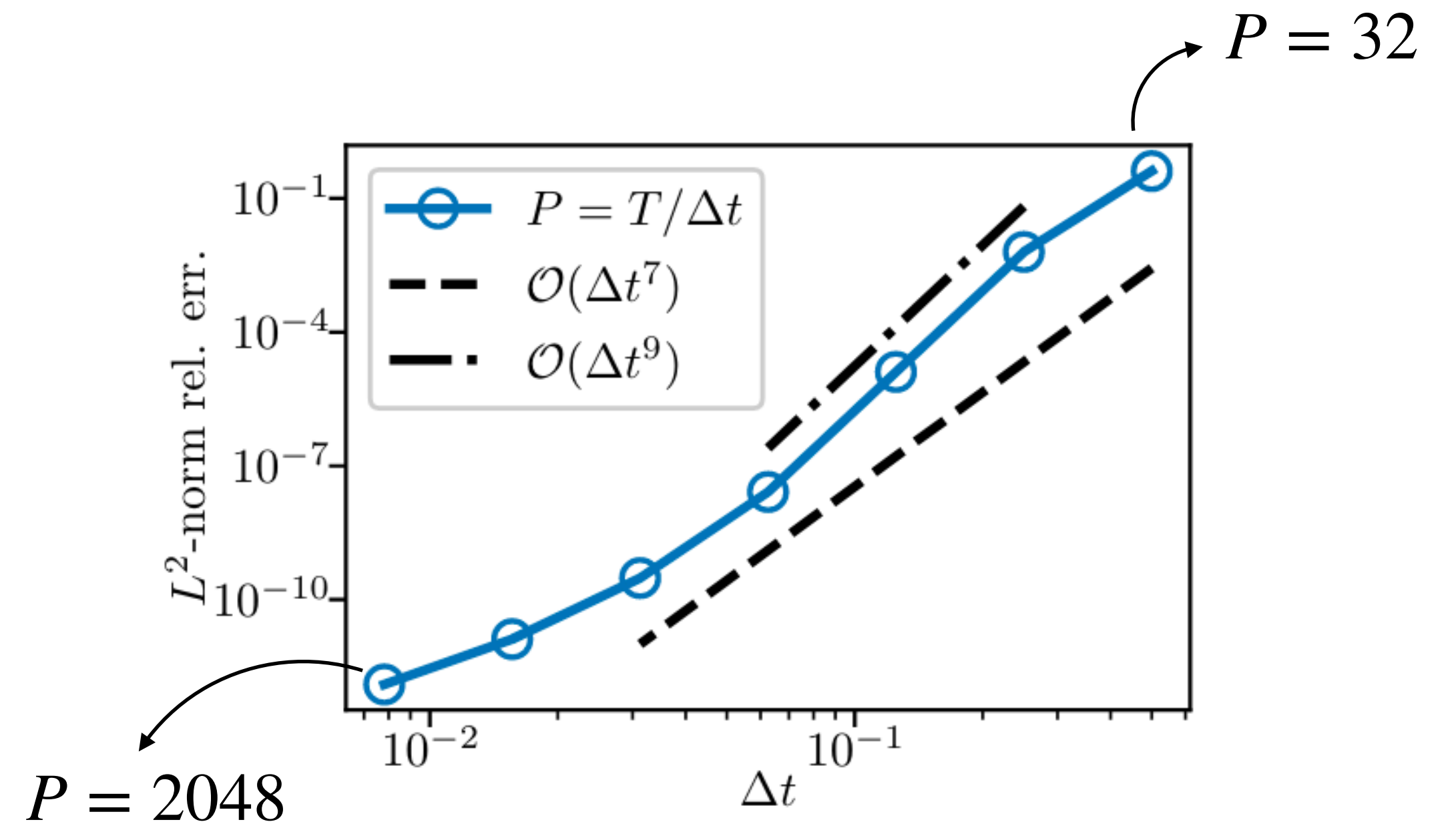
Convergence experiments: Parallel setting

Similar problem as before, but $\Omega = [0,100]\text{mm}$ and $T = 16\text{ms}$.

- $P = 1, 4, 16, 64$ parallel steps,
- $L = 2$ multigrid levels,
- $M = 6, 3$ collocation nodes.



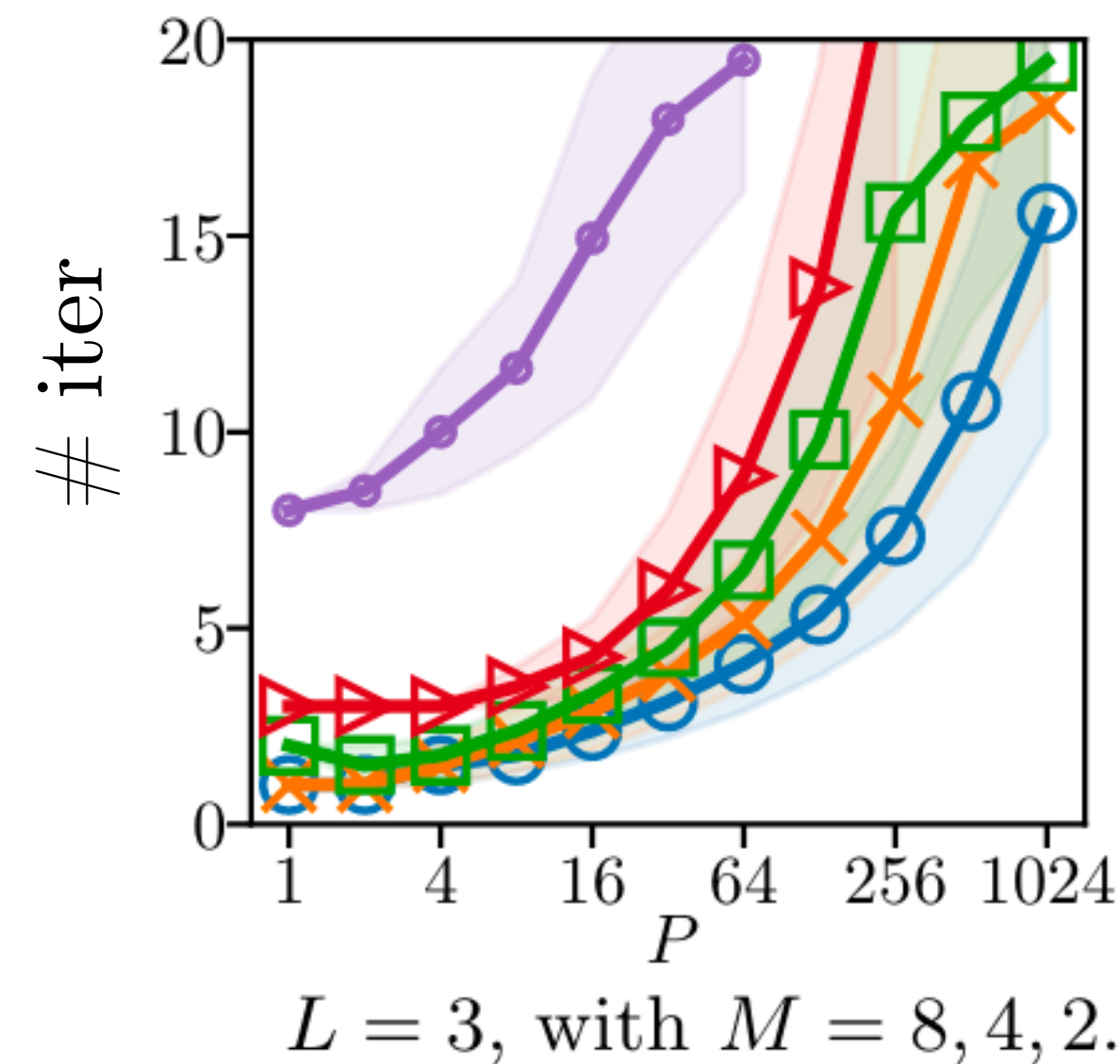
- $P = T/\Delta t$ (whole interval in parallel),
- $L = 2$ multigrid levels,
- $M = 6, 3$ collocation nodes.



P and Δt VS Iterations

Check how number of iterations is affected by:

- number of processors P ,
- step size Δt .

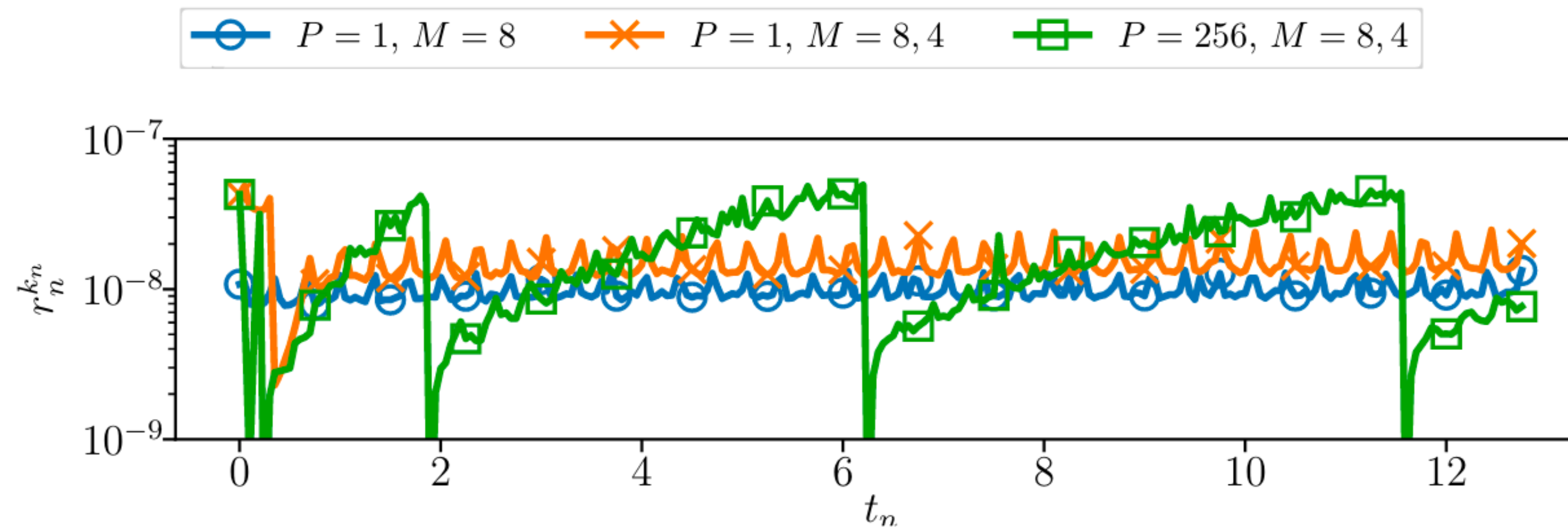


Average number of iterations versus number of processors, for different step sizes. Shaded areas represent standard deviation.

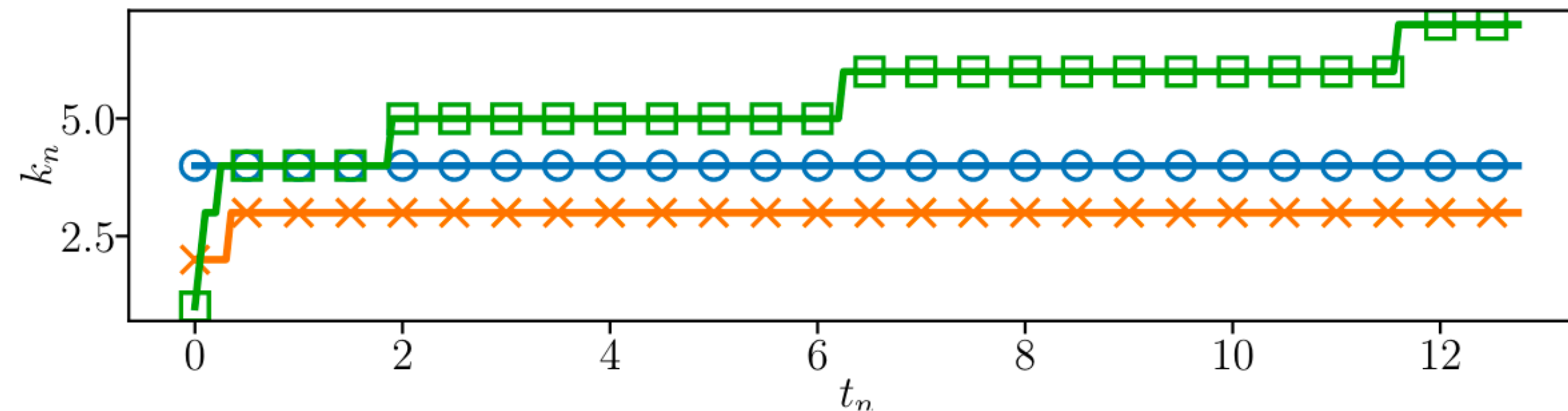
Iterations and residuals over time

Monodomain with $\Delta t = 0.05\text{ms}$, up to $T = 256\Delta t = 12.8\text{ms}$.

Compare the residuals and iterations of serial single-level and multilevel-methods and a parallel method.

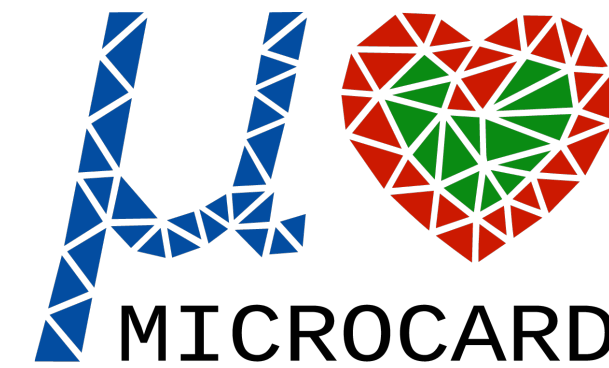


(a) Relative residuals at last iteration



(b) Iterations needed for convergence over time.

Thank you for your attention 😊



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