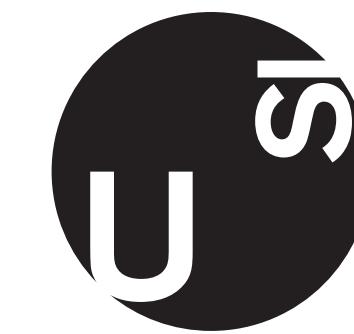


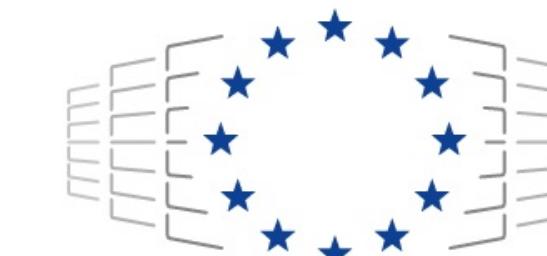
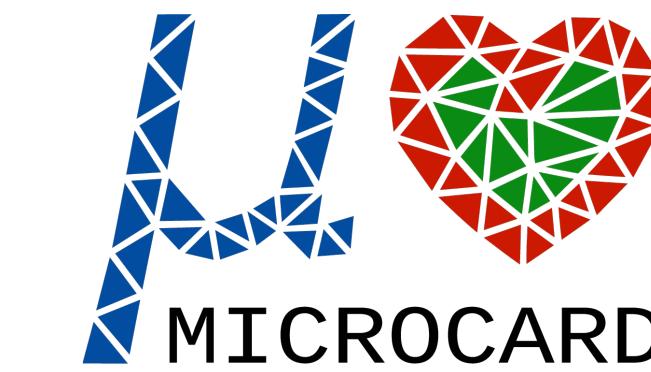
Boundary Element Method for the Cell-by-Cell Model in Cardiac Electrophysiology

Giacomo Rosilho de Souza, Simone Pezzuto, Rolf Krause

Università della Svizzera Italiana, Lugano, Switzerland



Università
della
Svizzera
italiana



EuroHPC
Joint Undertaking

WCCM - 2022 - Yokohama (Virtual)

Contents

- Microcard Project and Cell-by-Cell model,
- Crash course on Boundary Element Method,
- Reduction of Cell-by-Cell model to system of ODEs,
- Numerical experiment.

Bidomain and Cell-by-Cell Models

In the mono and bidomain models for cardiac electrophysiology, every mesh element contains hundreds of physical cells:

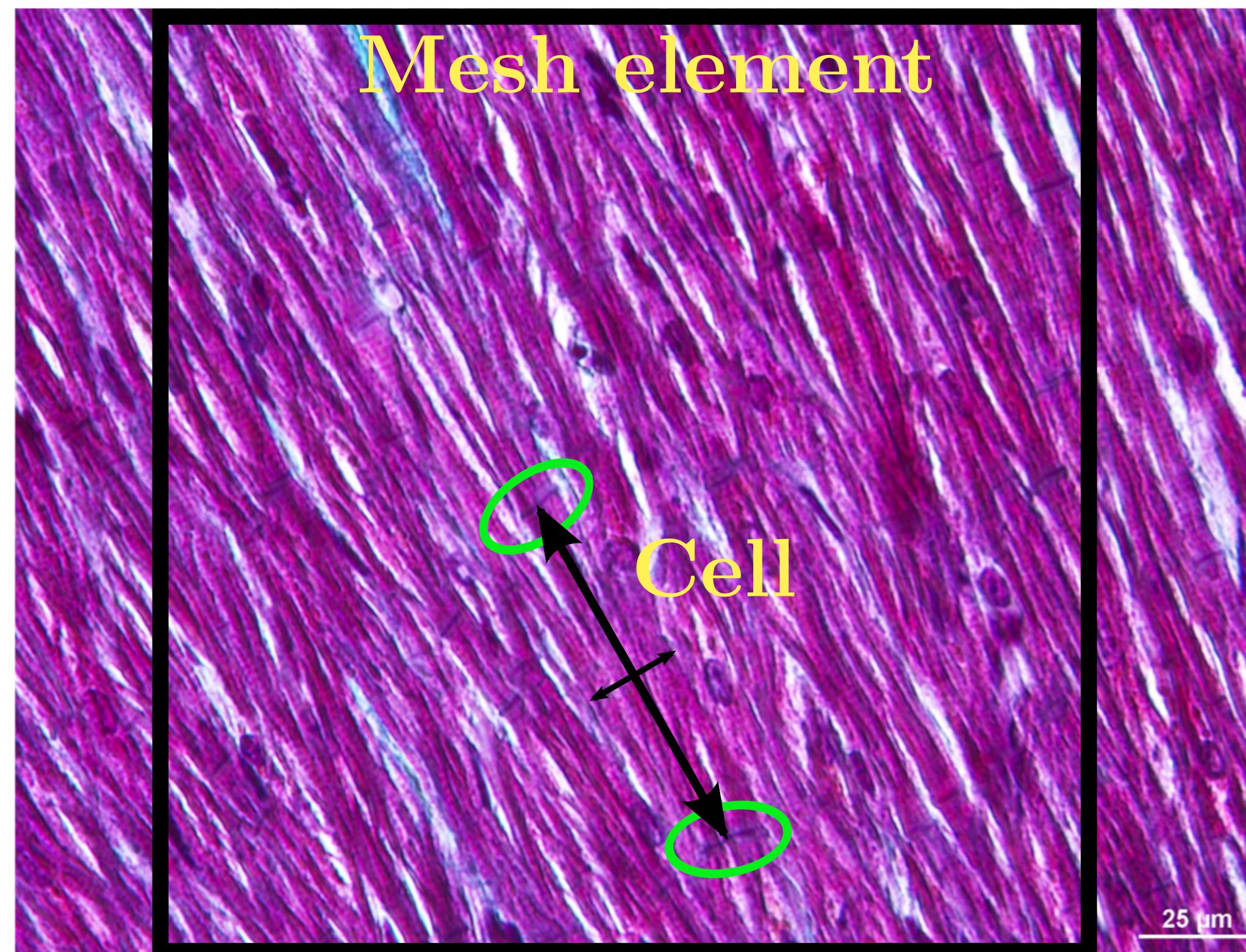


Image courtesy of Dr. D. Benoist, IHU Liryc.

This is insufficient to simulate abnormal tissues:

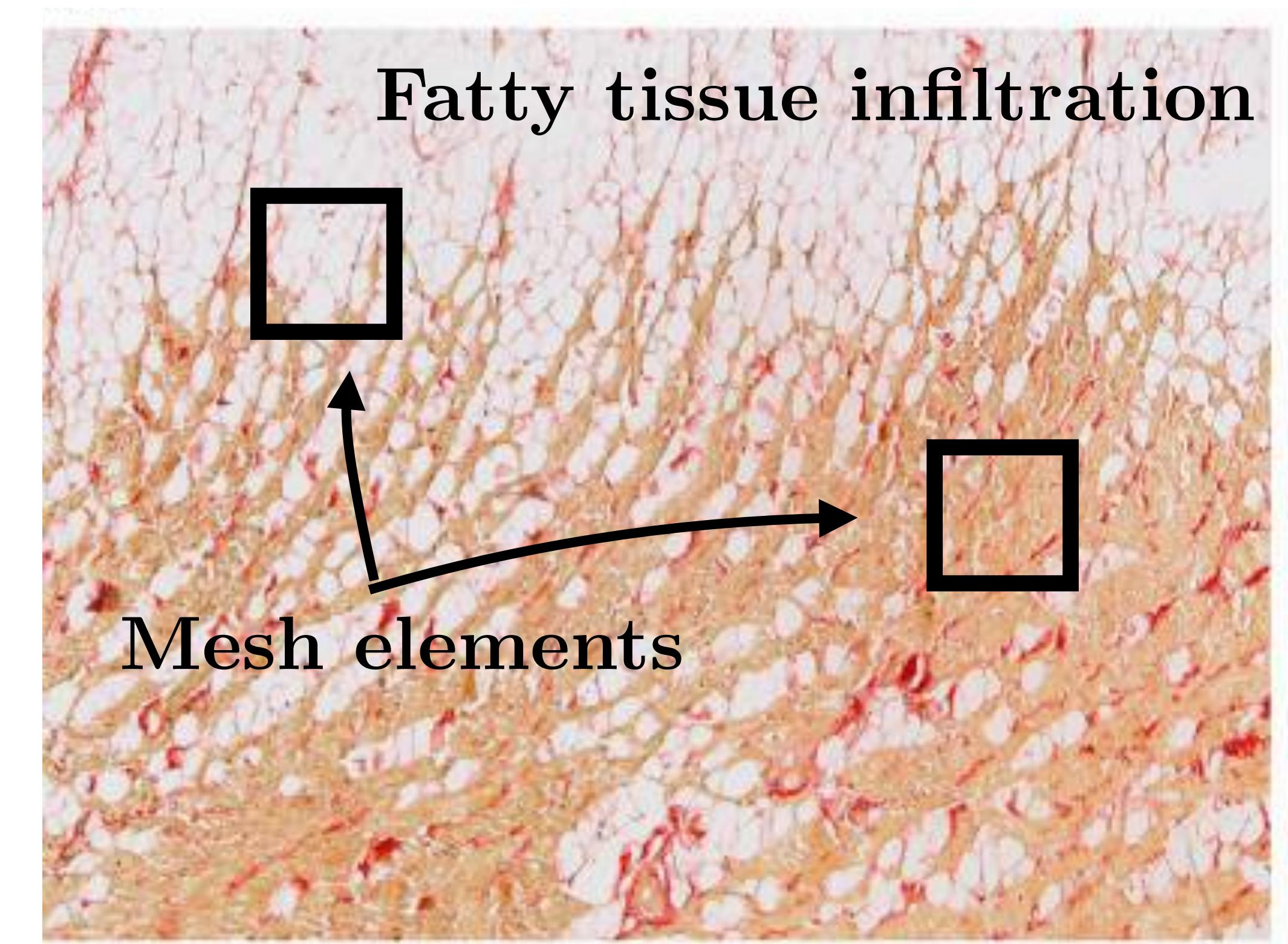
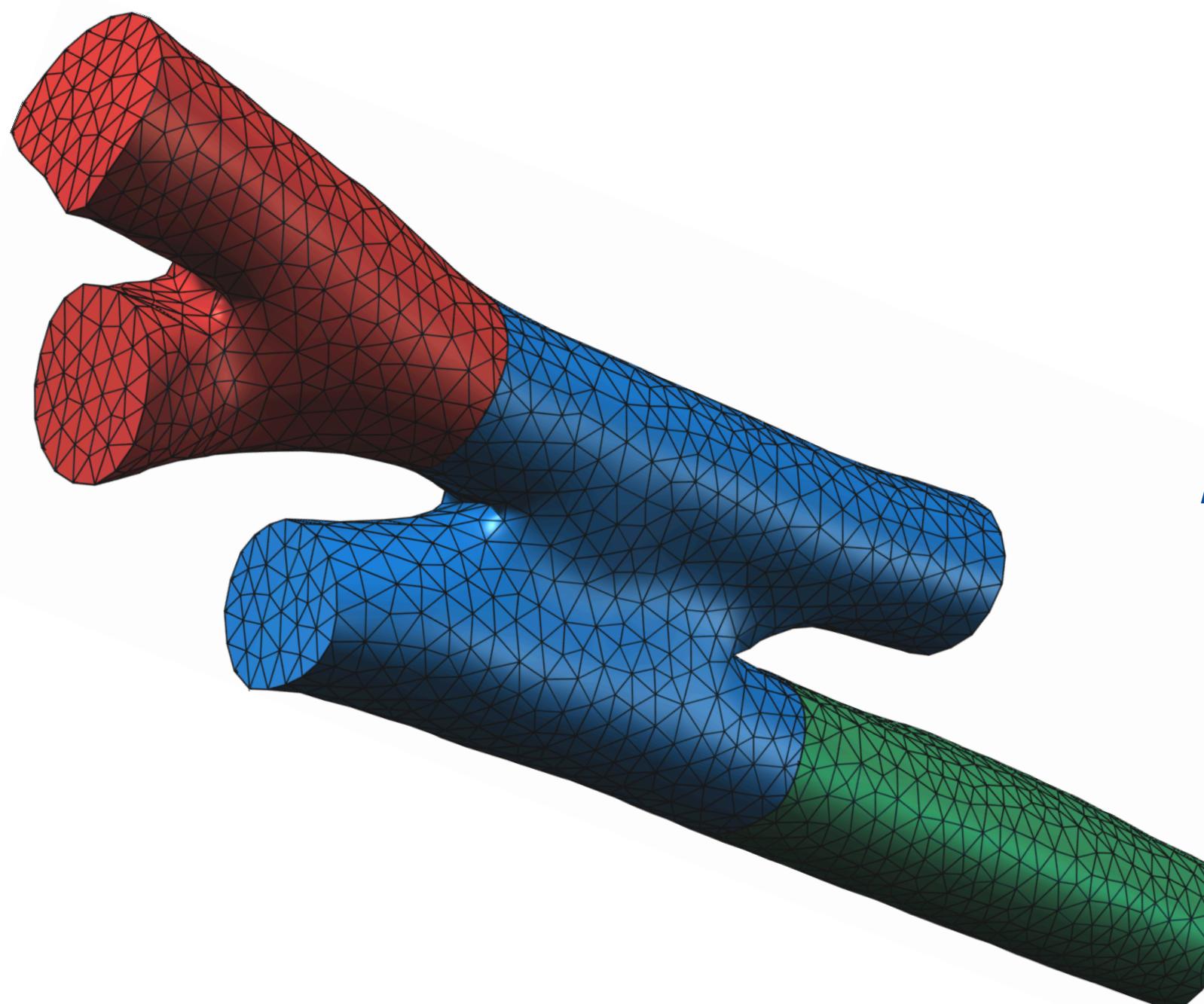


Image courtesy of Dr. M. Hoogendoijk, AMC, Amsterdam.

The MICROCARD Project

“MICROCARD is a European research project to build software that can simulate cardiac electrophysiology using whole-heart models with sub-cellular resolution, on future exascale supercomputers.”



To do so, we solve the cell-by-cell model

$$-\sigma_i \Delta u_i = 0,$$

$$-\sigma_i \partial_n u_i = I_t(V_m, z),$$

$$-\sigma_0 \partial_n u_0 = -I_t(V_m, z),$$

$$u_i - u_0 = V_m,$$

$$\frac{dz}{dt} = g(V_m, z),$$

$$-\sigma_i \partial_n u_i = \kappa(u_i - u_j),$$

$$\text{in } \Omega_i \quad i = 0, \dots, N,$$

$$\text{on } \Gamma_{i,0} \quad i = 1, \dots, N,$$

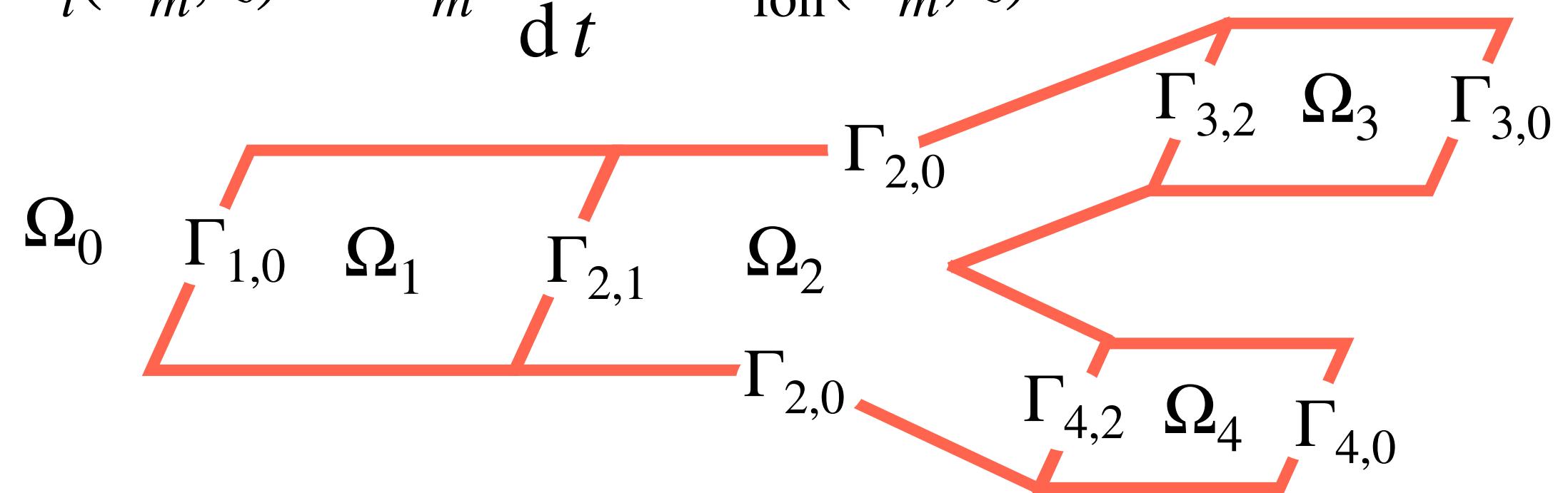
$$\text{on } \Gamma_0,$$

$$\text{on } \Gamma_{i,0} \quad i = 1, \dots, N,$$

$$\text{on } \Gamma_0,$$

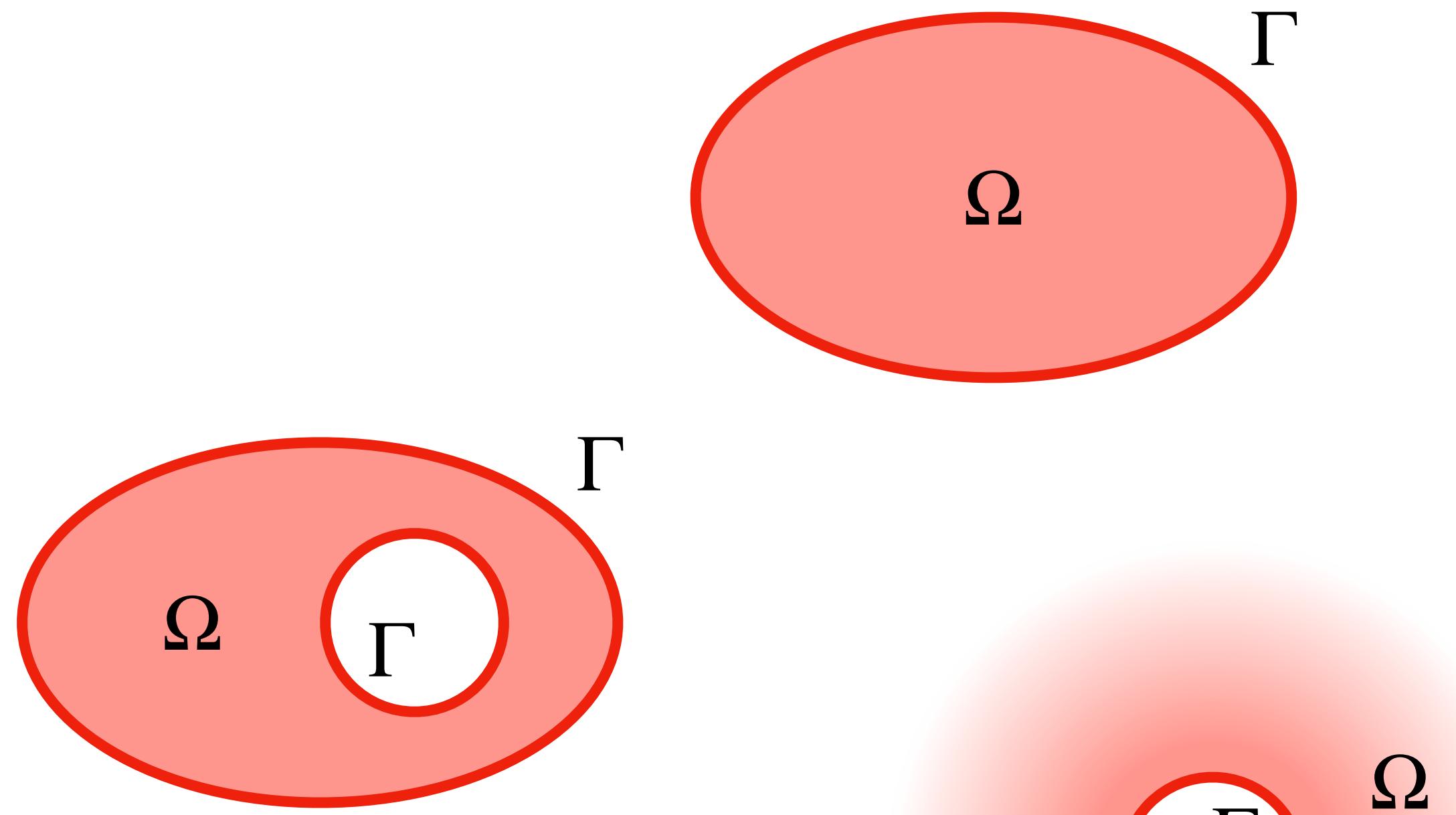
$$\text{on } \Gamma_{i,j} \quad 1 \leq j, i \leq N,$$

$$\text{With } I_t(V_m, z) = C_m \frac{dV_m}{dt} + I_{\text{ion}}(V_m, z)$$



Boundary Integral Equations

Let $\Omega \subset \mathbb{R}^d$ a domain and its boundary $\Gamma = \partial\Omega$ be as one of:



Let u be any solution to

$$-\Delta u = 0 \quad \text{in } \Omega.$$

The Green representation formula gives

$$u(x) = \int_{\Gamma} G(x, y) \partial_n u(y) ds_y - \int_{\Gamma} \partial_n G(x, y) u(y) ds_y \quad x \in \Omega,$$

with $u(y)$ the Dirichlet and $\partial_y u(y)$ the Neumann data, and $G(x, y)$ is the fundamental solution.

Collocation Boundary Integral Method

Taking the trace yields

$$u = \mathcal{V}\partial_n u - (\mathcal{K} - \frac{1}{2}I)u \quad \text{on } \Gamma \quad (1)$$

with

$$\mathcal{V}\rho(x) = \int_{\Gamma} G(x, y)\rho(y)ds_y, \quad x \in \Gamma,$$

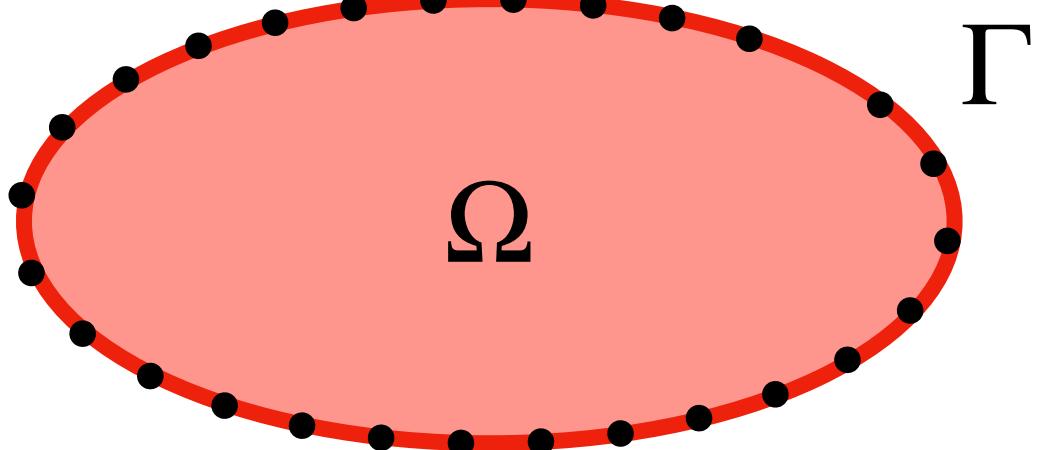
$$\mathcal{K}\rho(x) = \int_{\Gamma} \partial_n G(x, y)\rho(y)ds_y, \quad x \in \Gamma$$

the single and double layer potentials.

Rearranging (1):

$$\mathcal{V}\partial_n u = (\mathcal{K} + \frac{1}{2}I)u, \quad \text{on } \Gamma. \quad (2)$$

Discretize Γ in M points x_j



and impose (2) on x_j only

$$\mathcal{V}\partial_n u(x_j) = (\mathcal{K} + \frac{1}{2}I)u(x_j) \quad \forall j.$$

We represent $u, \partial_n u$ with trigonometric Lagrangian basis $L_j(x)$, with $L_j(x_k) = \delta_{jk}$:

$$\partial_n u = \sum_{j=1}^M \tilde{u}^j L_j, \quad u = \sum_{j=1}^M u^j L_j$$

Collocation Boundary Integral Method

$$\mathcal{V}\partial_n u(x_j) = (\mathcal{K} + \frac{1}{2}I)u(x_j) \quad \forall j$$

$$\partial_n u = \sum_{j=1}^M \tilde{u}^j L_j, \quad u = \sum_{j=1}^M u^j L_j$$

Matrix formulation

$$V\tilde{\mathbf{u}} = (K + \frac{1}{2}I)\mathbf{u},$$

$$\tilde{\mathbf{u}} = P_S \mathbf{u}$$

with

$$P_S = V^{-1}(K + \frac{1}{2}I)$$

the Poincaré-Steklow operator (or Dirichlet-to-Neumann map).

Henceforth on the boundary Γ :

$$u \longrightarrow \mathbf{u} \qquad \qquad \partial_n u \longrightarrow P_S \mathbf{u}$$

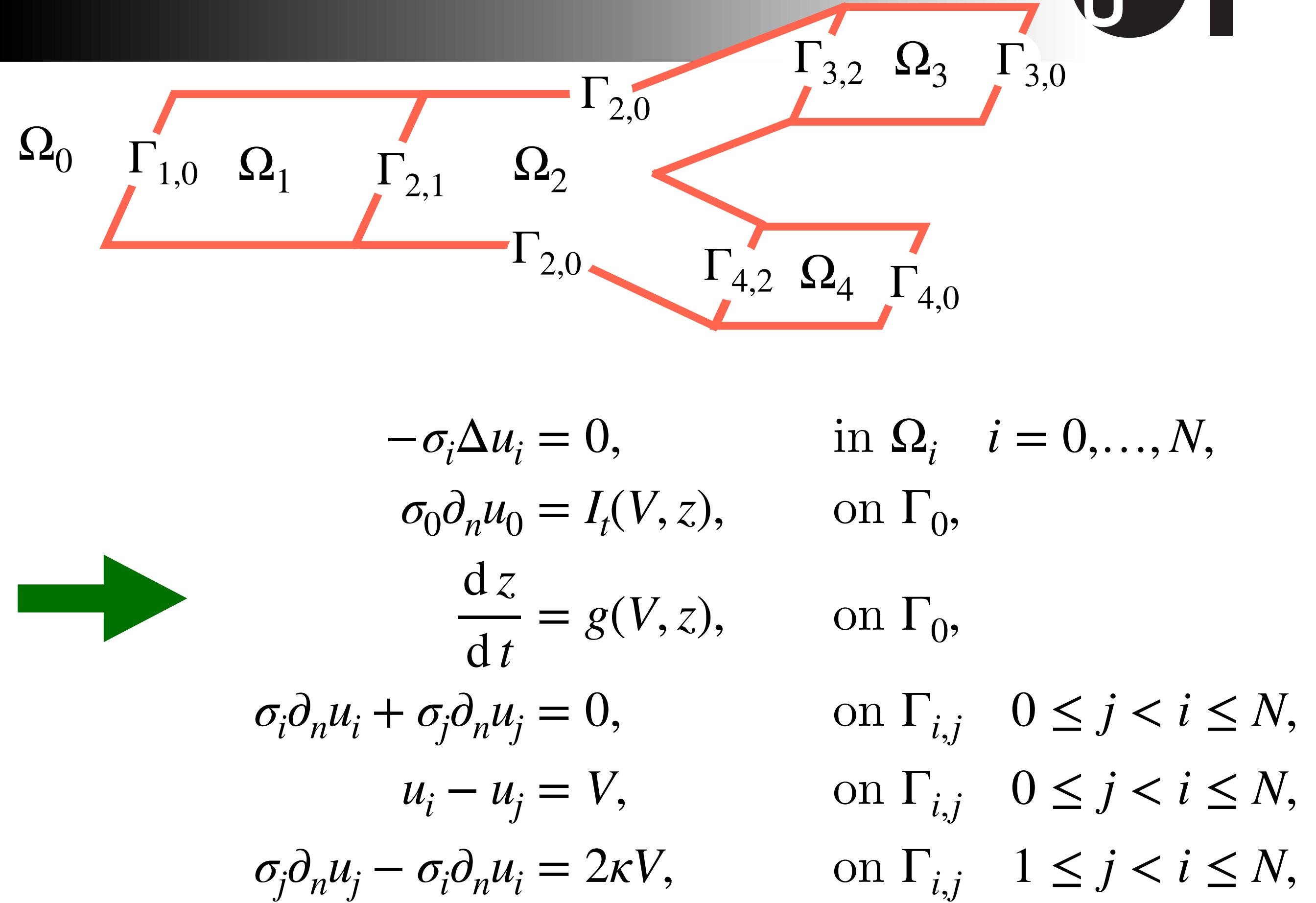
Fun facts:

- P_S is symmetric,
- For  and  it is singular
- For  $P_S \mathbf{e} = 0$, $\mathbf{e} = (1, \dots, 1)^\top$.
- For  it is invertible due to decaying conditions, which fix the constant.

Model reformulation

Consider a problem with N cells Ω_i , $i = 1, \dots, N$ and *unbounded* extracellular matrix Ω_0 with boundary Γ_0 :

$$\begin{aligned} -\sigma_i \Delta u_i &= 0, & \text{in } \Omega_i \quad i = 0, \dots, N, \\ -\sigma_i \partial_n u_i &= I_t(V_m, z), & \text{on } \Gamma_{i,0} \quad i = 1, \dots, N, \\ -\sigma_0 \partial_n u_0 &= -I_t(V_m, z), & \text{on } \Gamma_0, \\ u_i - u_0 &= V_m, & \text{on } \Gamma_{i,0} \quad i = 1, \dots, N, \\ \frac{dz}{dt} &= g(V_m, z), & \text{on } \Gamma_0, \\ -\sigma_i \partial_n u_i &= \kappa(u_i - u_j), & \text{on } \Gamma_{i,j} \quad 1 \leq j, i \leq N, \end{aligned}$$



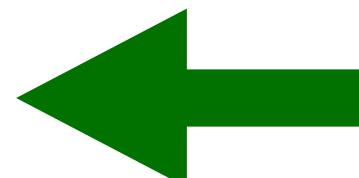
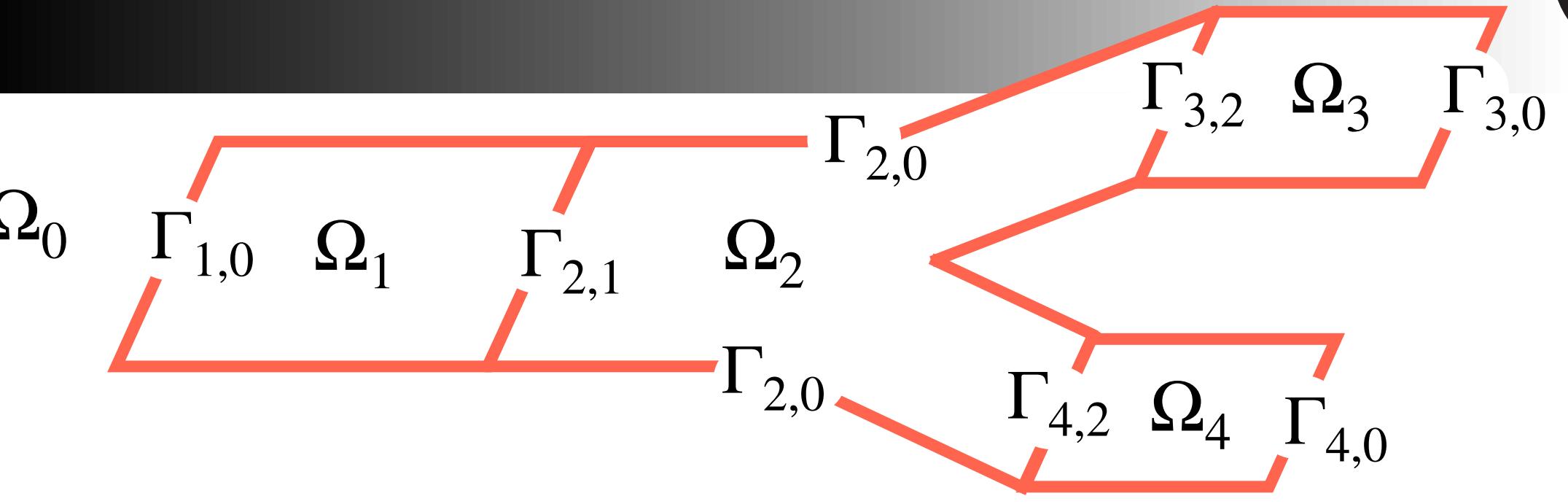
with $I_t(V_m, z) = C_m \frac{dV_m}{dt} + I_{\text{ion}}(V_m, z)$.

Model discretisation

Discretize the skeleton Γ with M points.
 Every domain's boundary $\Gamma_i = \partial\Omega_i$ has M_i points.

Recall: $\partial_n u \rightarrow P_S \mathbf{u}$, $u \rightarrow \mathbf{u}$.

$$\begin{aligned} & \emptyset && \text{in } \Omega_i \quad i = 0, \dots, N, \\ & \sigma_0 P_{S,0} \mathbf{u}_0 = I_t(\mathbf{V}, \mathbf{z}), && \text{on } \Gamma_0, \\ & \frac{d \mathbf{z}}{dt} = g(\mathbf{V}, \mathbf{z}), && \text{on } \Gamma_0, \\ & \sigma_i P_{S,i} \mathbf{u}_i + \sigma_j P_{S,j} \mathbf{u}_j = 0, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\ & \mathbf{u}_i - \mathbf{u}_j = \mathbf{V}, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\ & \sigma_j P_{S,j} \mathbf{u}_j - \sigma_i P_{S,i} \mathbf{u}_i = 2\kappa \mathbf{V}, && \text{on } \Gamma_{i,j} \quad 1 \leq j < i \leq N, \end{aligned}$$

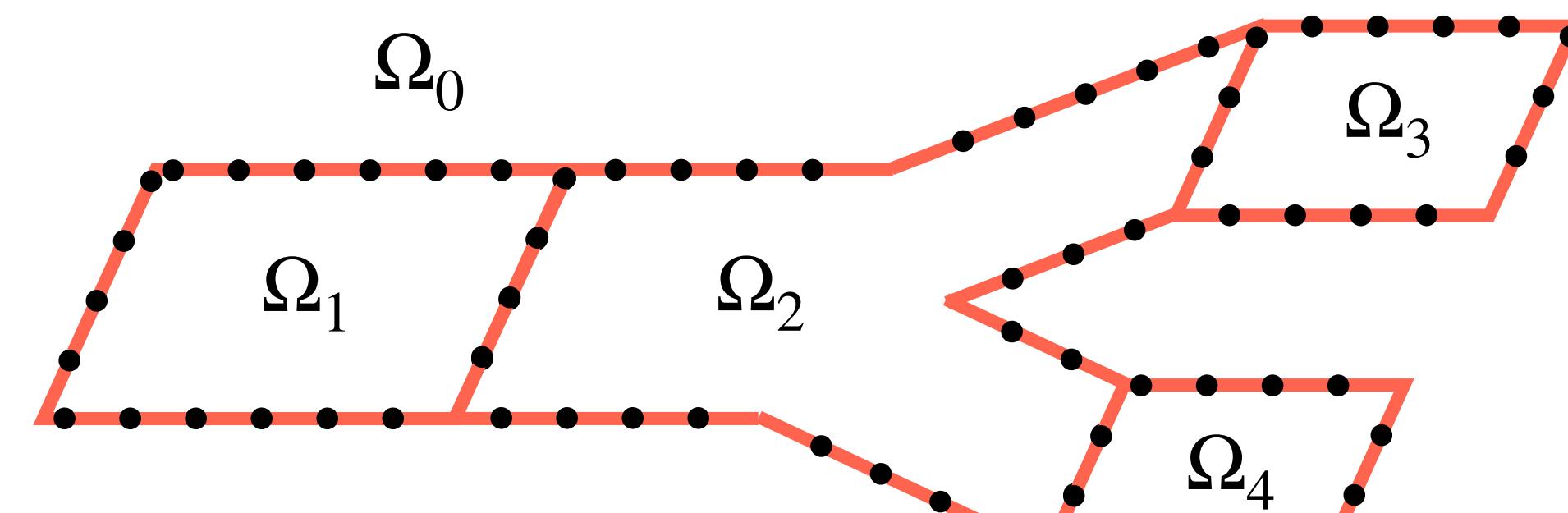


$$\begin{aligned} & -\sigma_i \Delta u_i = 0, && \text{in } \Omega_i \quad i = 0, \dots, N, \\ & \sigma_0 \partial_n u_0 = I_t(V, z), && \text{on } \Gamma_0, \\ & \frac{dz}{dt} = g(V, z), && \text{on } \Gamma_0, \\ & \sigma_i \partial_n u_i + \sigma_j \partial_n u_j = 0, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\ & u_i - u_j = V, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\ & \sigma_j \partial_n u_j - \sigma_i \partial_n u_i = 2\kappa V, && \text{on } \Gamma_{i,j} \quad 1 \leq j < i \leq N, \end{aligned}$$

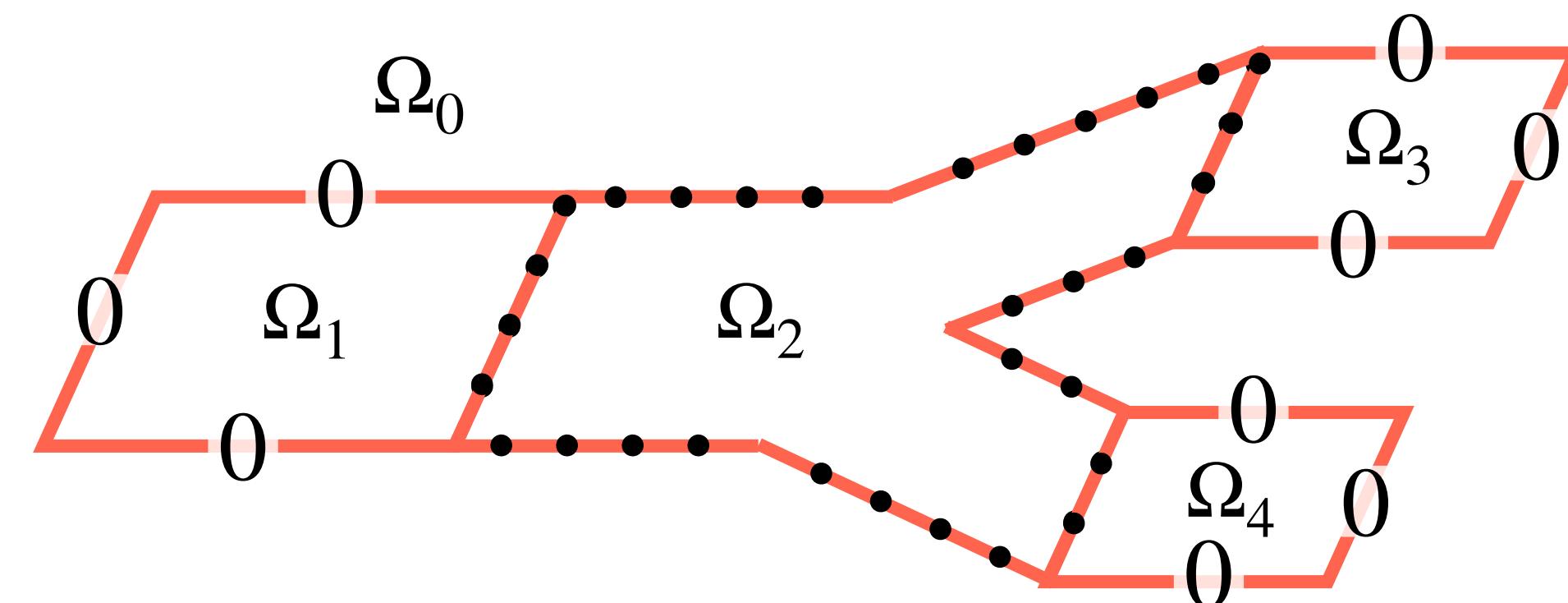
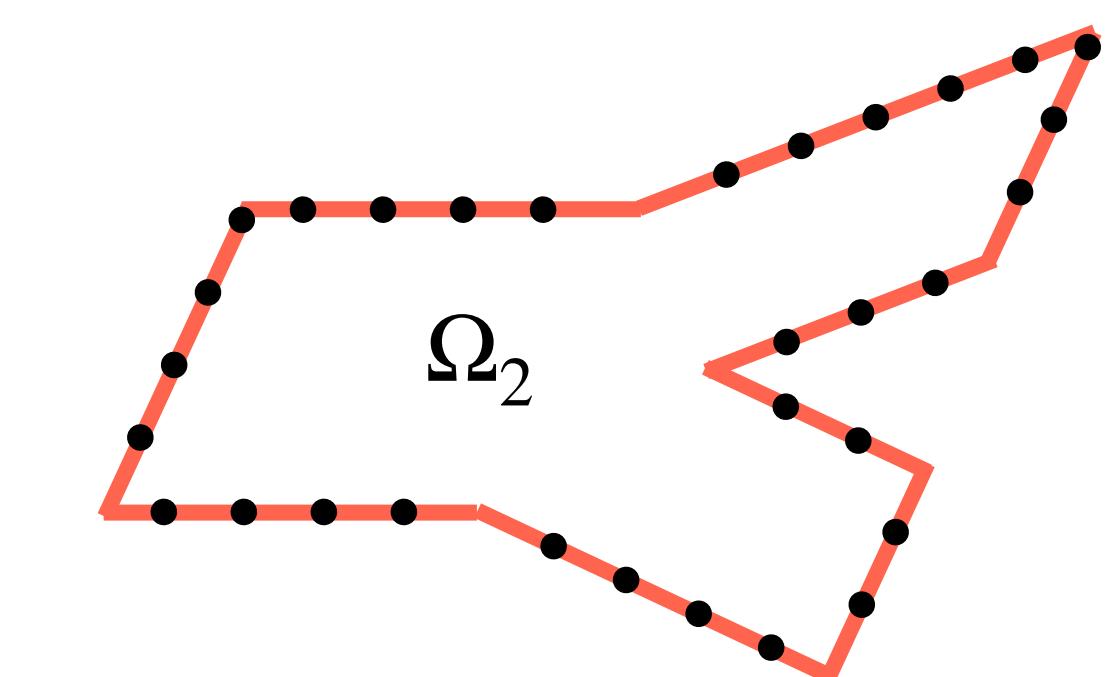
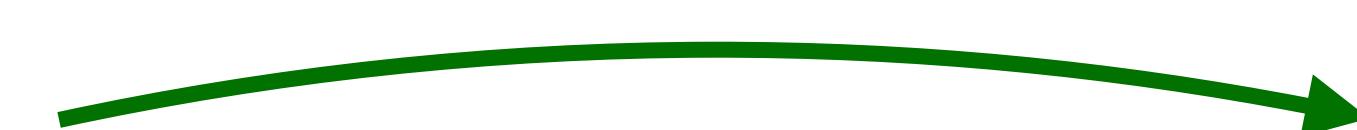
Now, we need to define some restriction $\Gamma \rightarrow \Gamma_i$ and extension $\Gamma_i \rightarrow \Gamma$ operators.

Global to local operators

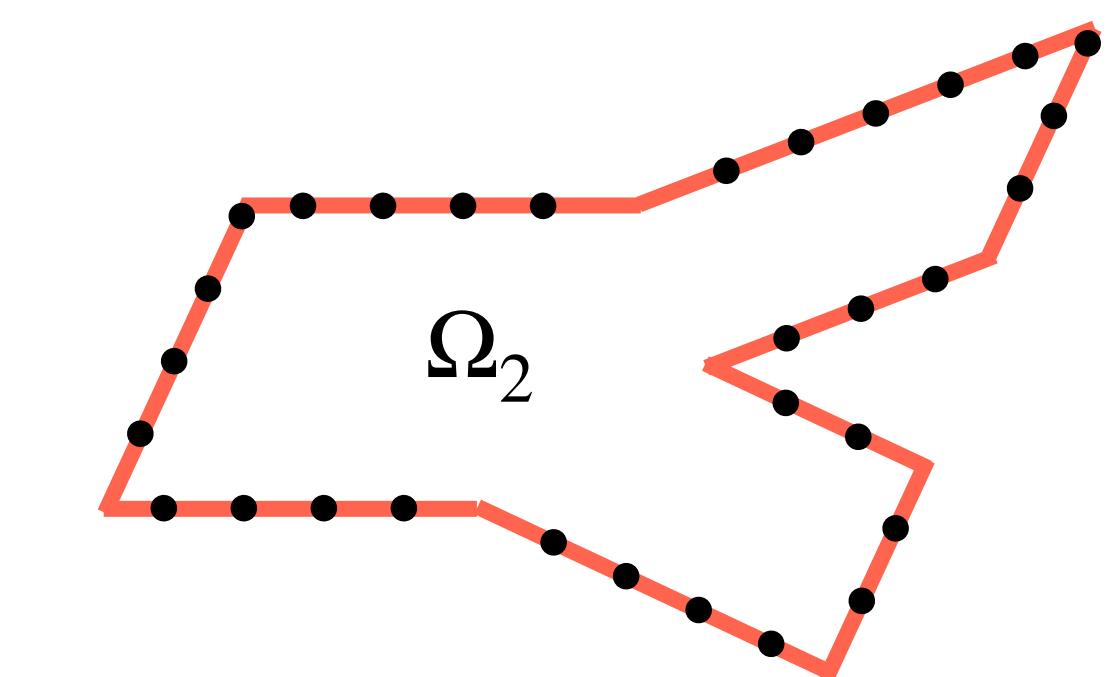
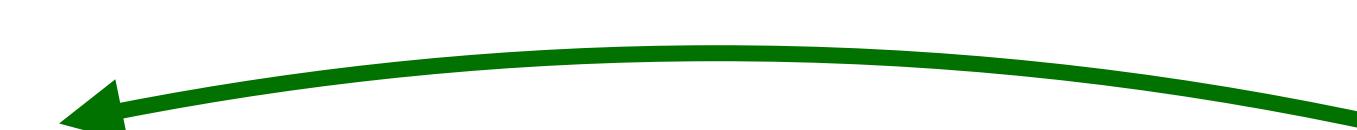
The boolean connectivity matrix $A_i : \mathbb{R}^M \rightarrow \mathbb{R}^{M_i}$ maps a global vector on Γ to a local vector on Γ_i . The transpose A_i^\top maps local to global.



$$A_2$$

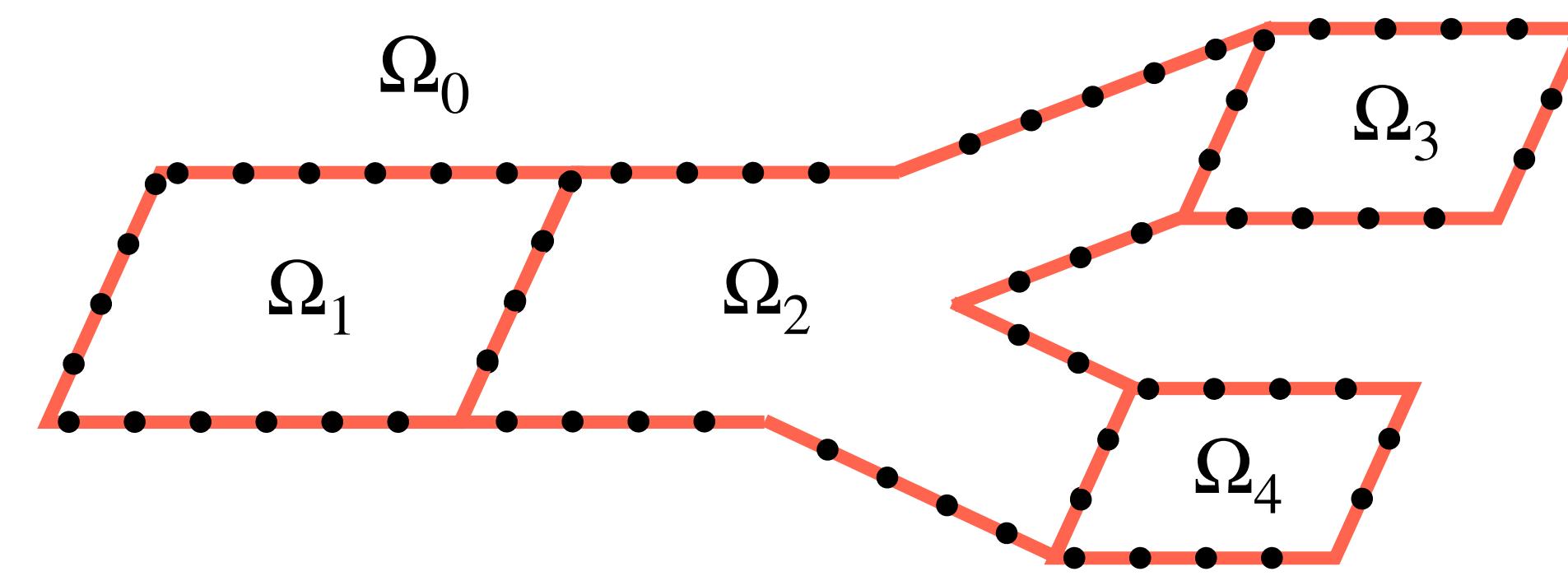


$$A_2^\top$$

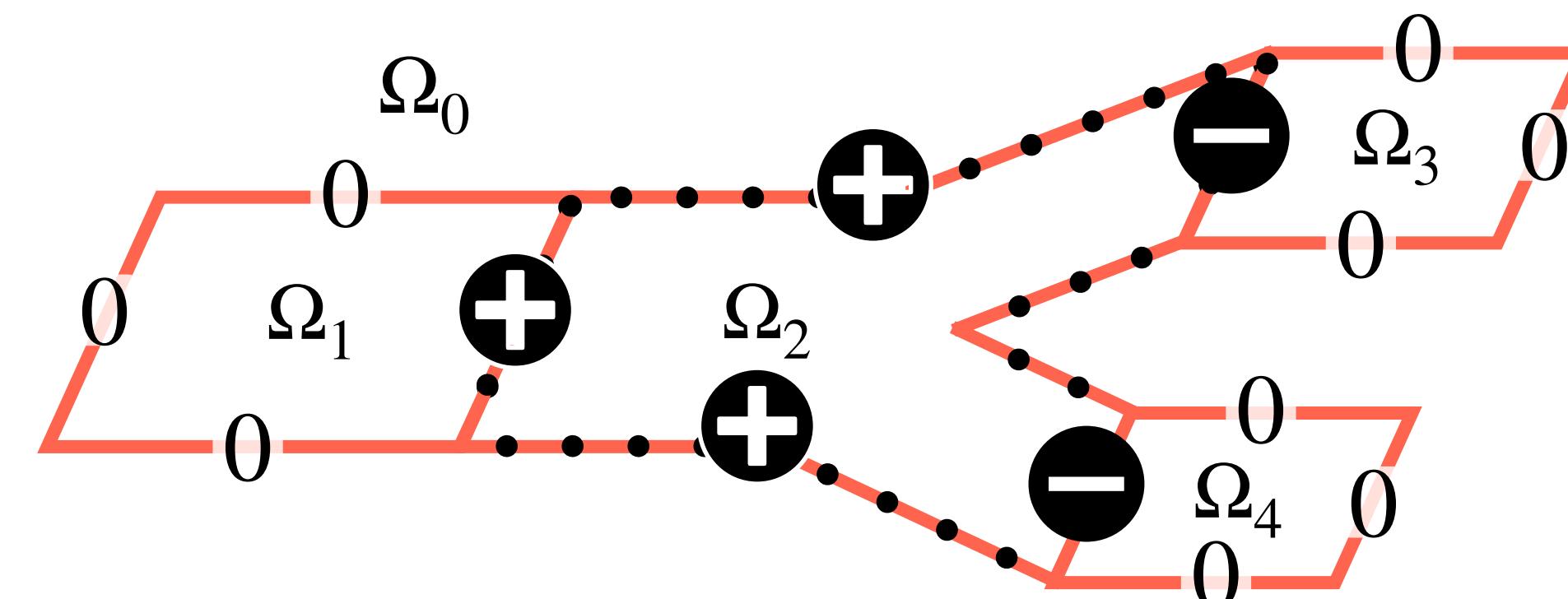
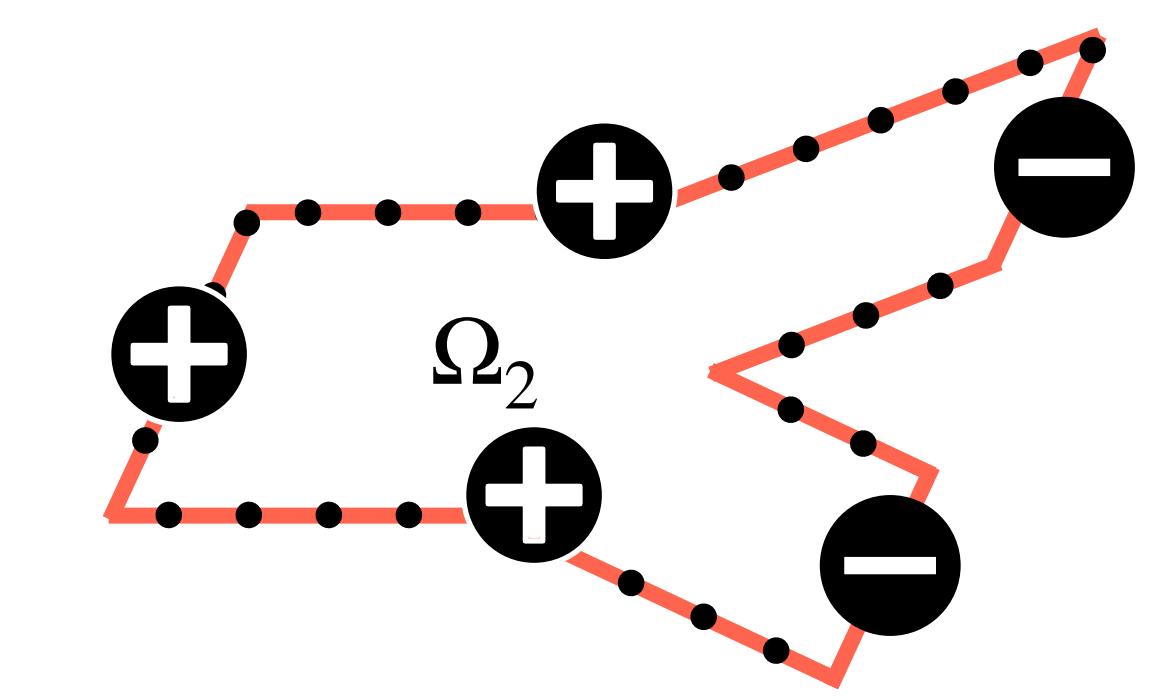
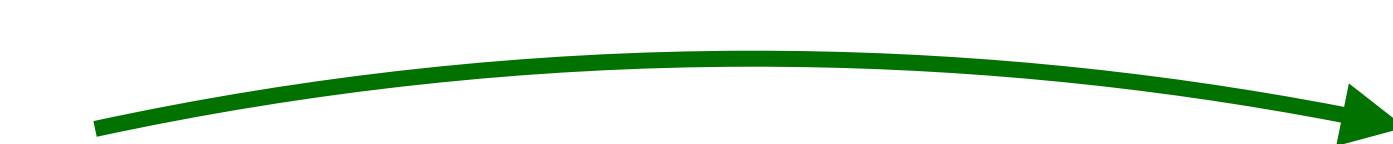


Global to local operators with sign change

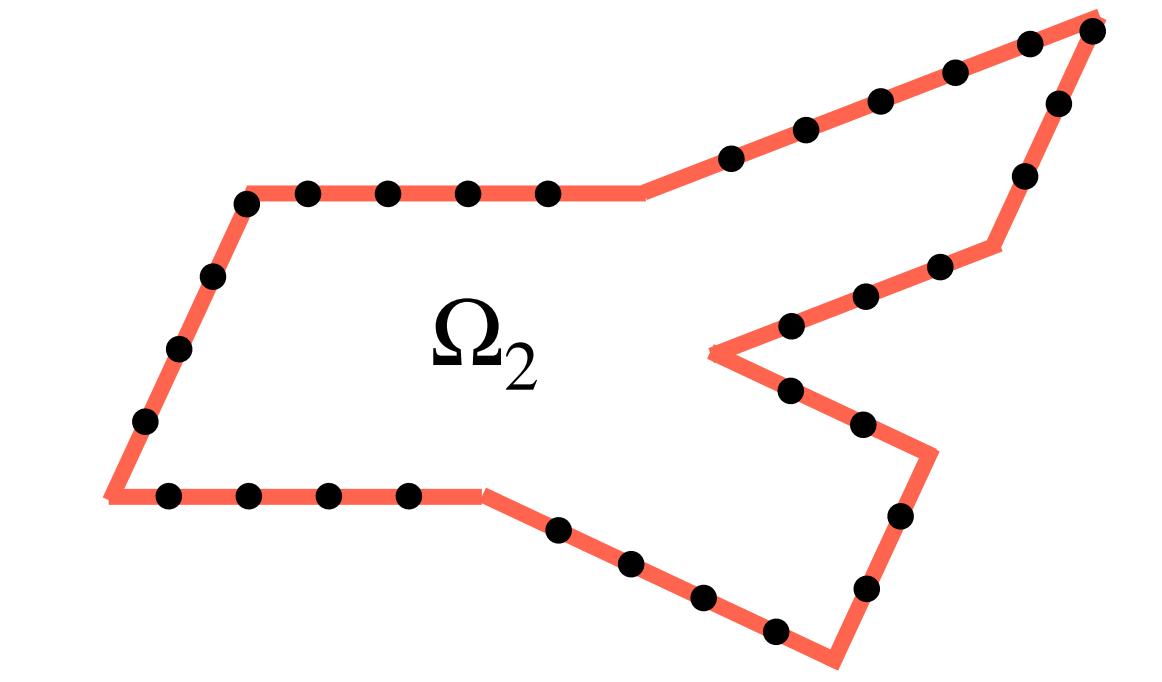
The signed boolean connectivity matrix $B_i : \mathbb{R}^M \rightarrow \mathbb{R}^{M_i}$ maps a global vector on Γ to a local vector on Γ_i . A sign change occurs if the neighbouring domain has higher index.



B_2

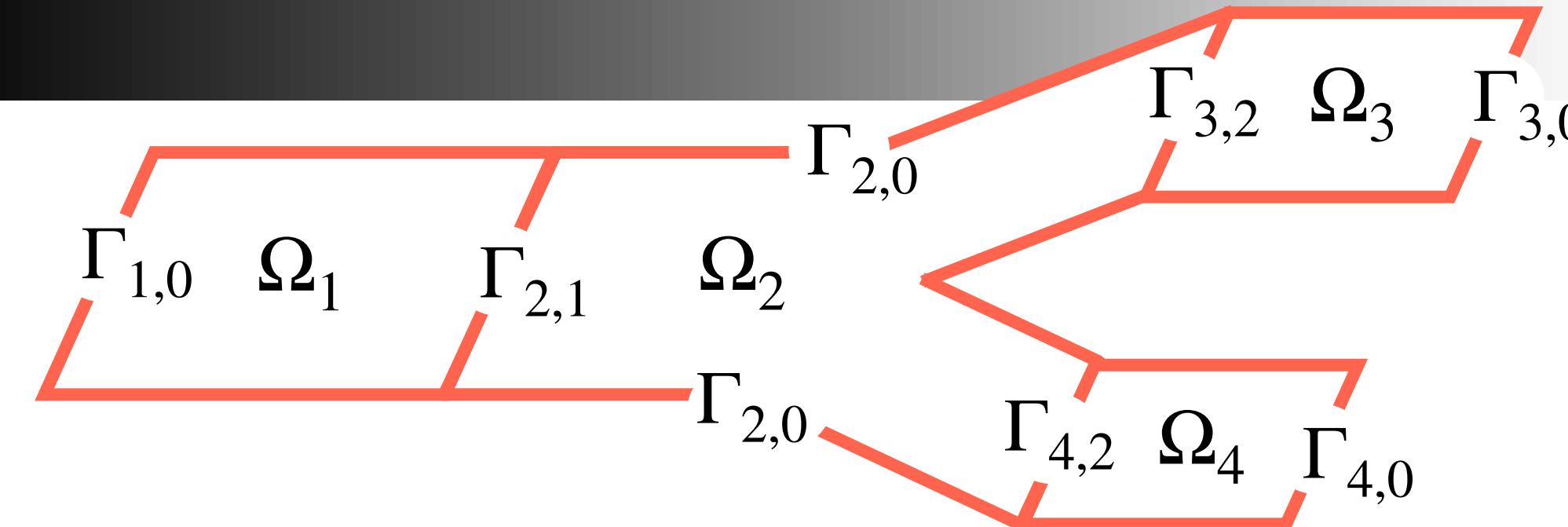


B_2^\top



Model discretisation

We transpose the equations below, living on $\Gamma_{i,j}$ and Γ_0 , to the global domain Γ .



$$\begin{aligned}
 & \emptyset && \text{in } \Omega_i \quad i = 0, \dots, N, \\
 & \sigma_0 P_{S,0} \mathbf{u}_0 = I_t(\mathbf{V}, \mathbf{z}), && \text{on } \Gamma_0, \\
 & \frac{d\mathbf{z}}{dt} = g(\mathbf{V}, \mathbf{z}), && \text{on } \Gamma_0, \\
 & \sigma_i P_{S,i} \mathbf{u}_i + \sigma_j P_{S,j} \mathbf{u}_j = 0, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\
 & \mathbf{u}_i - \mathbf{u}_j = \mathbf{V}, && \text{on } \Gamma_{i,j} \quad 0 \leq j < i \leq N, \\
 & \sigma_j P_{S,j} \mathbf{u}_j - \sigma_i P_{S,i} \mathbf{u}_i = 2\kappa \mathbf{V}, && \text{on } \Gamma_{i,j} \quad 1 \leq j < i \leq N,
 \end{aligned}$$

With A_g the operator from Γ to the gap junctions.

$$\begin{aligned}
 & \sigma_0 P_{S,0} \mathbf{u}_0 = I_t(A_0 \mathbf{V}, \mathbf{z}) && \in \mathbb{R}^{M_0} = \Gamma_0 \\
 & \frac{d\mathbf{z}}{dt} = g(A_0 \mathbf{V}, \mathbf{z}) && \in \mathbb{R}^{M_0} = \Gamma_0 \\
 & \sum_{i=0}^N \sigma_i A_i^\top P_{S,i} \mathbf{u}_i = 0 && \in \mathbb{R}^M = \Gamma \\
 & \sum_{i=0}^N B_i^T \mathbf{u}_i = \mathbf{V} && \in \mathbb{R}^M = \Gamma \\
 & \sum_{i=0}^N \sigma_i A_g B_i^\top P_{S,i} \mathbf{u}_i = -2\kappa A_g \mathbf{V} && \in \mathbb{R}^{M_g} = \Gamma_g
 \end{aligned}$$

Reduction to a DAE system

$$\sigma_0 P_{S,0} \mathbf{u}_0 = I_t(A_0 \mathbf{V}, \mathbf{z}) \quad \in \mathbb{R}^{M_0} = \Gamma_0$$

$$\frac{d \mathbf{z}}{d t} = g(A_0 \mathbf{V}, \mathbf{z}) \quad \in \mathbb{R}^{M_0} = \Gamma_0$$

$$\sum_{i=0}^N \sigma_i A_i^\top P_{S,i} \mathbf{u}_i = 0 \quad \in \mathbb{R}^M = \Gamma$$

$$\sum_{i=0}^N B_i^T \mathbf{u}_i = \mathbf{V} \quad \in \mathbb{R}^M = \Gamma$$

$$\sum_{i=0}^N \sigma_i A_g B_i^\top P_{S,i} \mathbf{u}_i = -2\kappa A_g \mathbf{V} \quad \in \mathbb{R}^{M_g} = \Gamma_g$$

Goal: Find maps

$$\psi_i : \Gamma \rightarrow \Gamma_i : V \mapsto \sigma_i P_{S,i} \mathbf{u}_i,$$

where \mathbf{u}_i satisfies

$$\sum_{i=0}^N \sigma_i A_i^\top P_{S,i} \mathbf{u}_i = 0, \quad \sum_{i=0}^N B_i^T \mathbf{u}_i = \mathbf{V}.$$

We obtain the DAE:

$$\psi_0(\mathbf{V}) = I_t(A_0 \mathbf{V}, \mathbf{z}) \quad \text{on } \Gamma_0,$$

$$\frac{d \mathbf{z}}{d t} = g(A_0 \mathbf{V}, \mathbf{z}) \quad \text{on } \Gamma_0,$$

$$\sum_{i=0}^N A_g B_i^\top \psi_i(\mathbf{V}) = -2\kappa A_g \mathbf{V} \quad \text{on } \Gamma_g.$$

Reduction to a DAE system

Theorem: computing ψ_i

The linear maps $\psi_i(\mathbf{V}) = \sigma_i P_{S,i} \mathbf{u}_i$ satisfy

$$\psi_i(\mathbf{V}) = -B_i \lambda$$

with $\lambda \in \mathbb{R}^M$ and $\beta \in \mathbb{R}^N$ solutions to

$$\begin{pmatrix} F & G \\ G^\top & 0 \end{pmatrix} \begin{pmatrix} \lambda \\ \beta \end{pmatrix} = \begin{pmatrix} \mathbf{V} \\ \mathbf{0} \end{pmatrix}.$$

Where

$$F = -\sum_{i=0}^N \sigma_i^{-1} B_i^\top (P_{S,i}^+)^{-1} B_i, \quad G = (B_1^\top \mathbf{e}_1, \dots, B_N^\top \mathbf{e}_N),$$

$$P_{S,i}^+ = P_{S,i} + \alpha_i \mathbf{e}_i \mathbf{e}_i^\top, \quad \mathbf{e}_i = (1, \dots, 1)^\top \in \mathbb{R}^{M_i}, \quad \alpha_i > 0.$$

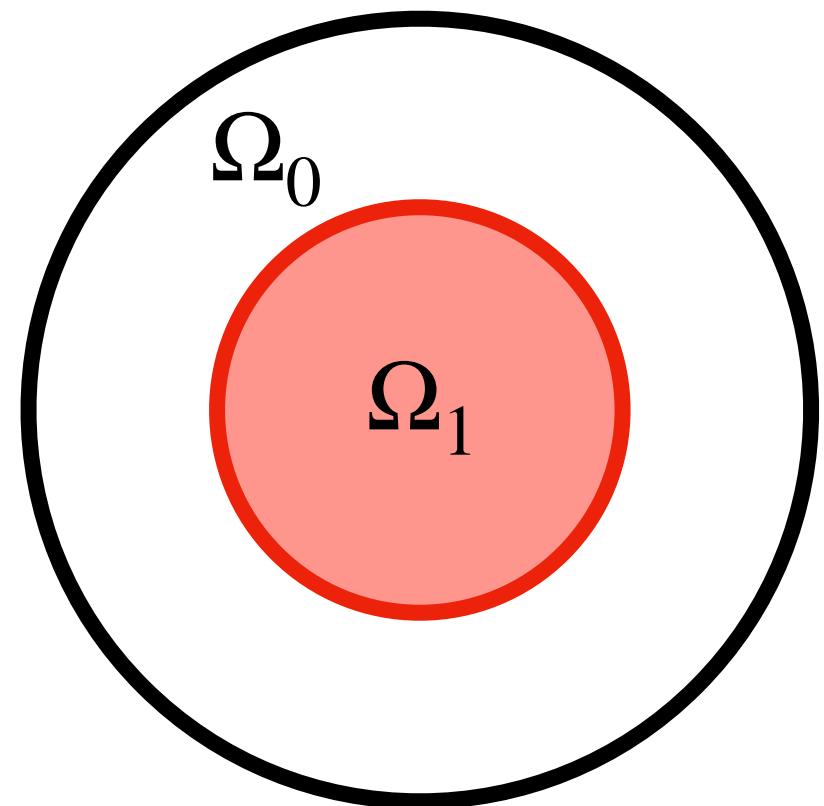
The boundary data \mathbf{u}_i can be computed with

$$\mathbf{u}_i = -\sigma_i^{-1} (P_{S,i}^+)^{-1} B_i \lambda + \beta_i \mathbf{e}_i,$$

where β_0 is free.

Checking correctness of $\psi_i(\mathbf{V}) = \sigma_i P_{S,i} \mathbf{u}_i \approx \sigma_i \partial_{\mathbf{n}} u$

Consider two harmonic functions u_0, u_1 satisfying flux continuity.

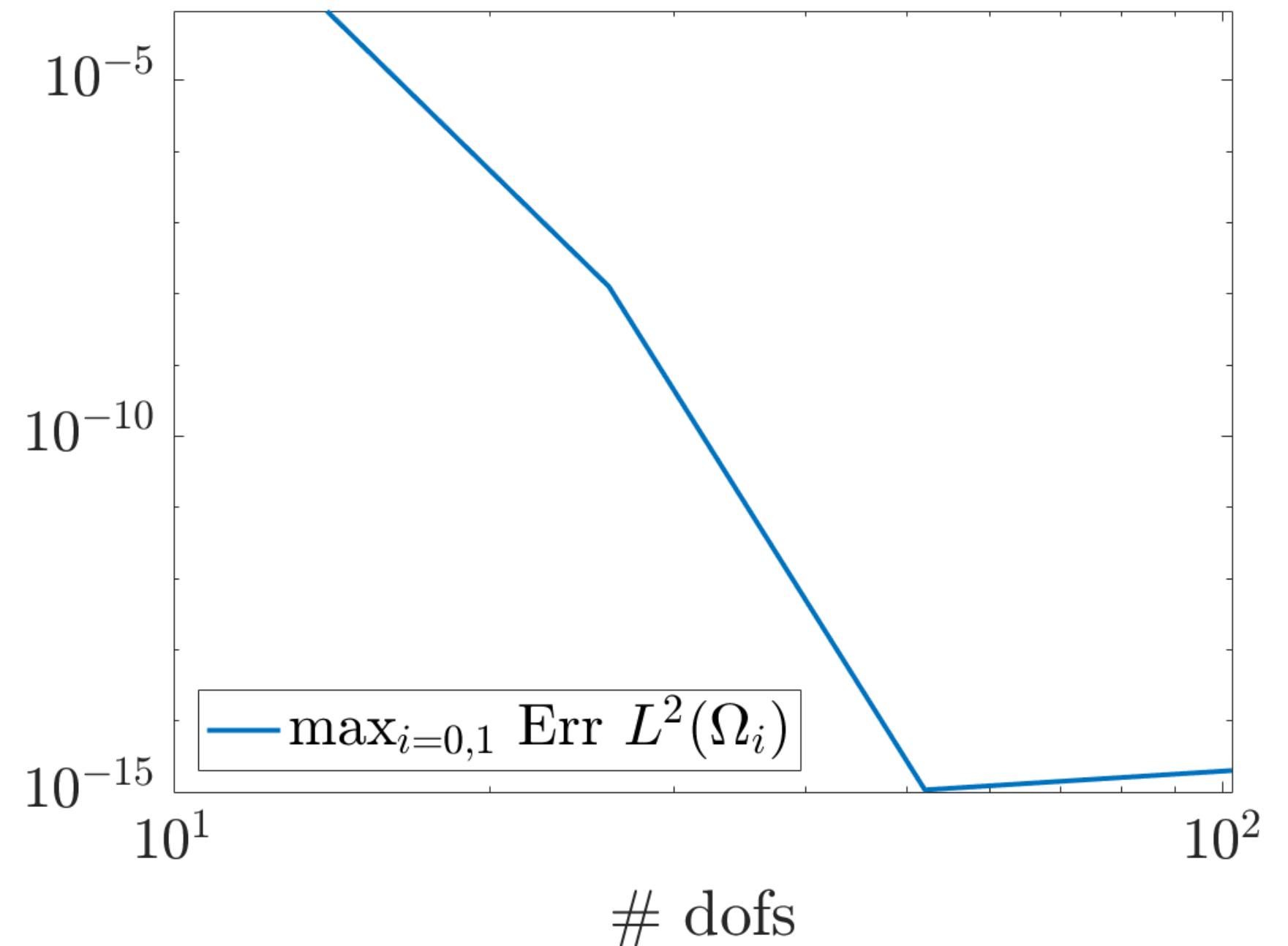


Define $\mathbf{V} = u_i - u_j$, we recover the fluxes and traces as:

- $\sigma_i P_{S,i} \mathbf{u}_i = \psi_i(\mathbf{V})$,
- $\mathbf{u}_i = -\sigma_i^{-1} (P_{S,i}^+)^{-1} B_i \lambda + \beta_i \mathbf{e}_i$.

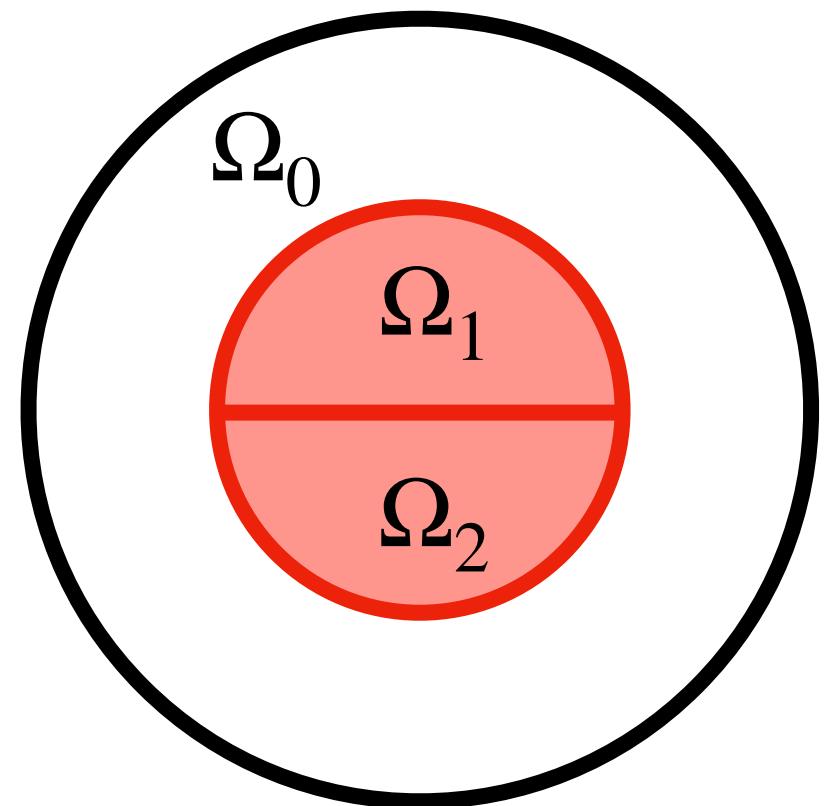
Given flux and trace, we compute u_0, u_1, u_2 inside Ω_i using the Green representation formula.

$$u(x) = \int_{\Gamma} G(x, y) \partial_n u(y) ds_y - \int_{\Gamma} \partial_n G(x, y) u(y) ds_y$$



Checking correctness of $\psi_i(\mathbf{V}) = \sigma_i P_{S,i} \mathbf{u}_i \approx \sigma_i \partial_{\mathbf{n}} u$

Consider three harmonic functions u_0, u_1, u_2 satisfying flux continuity ($u_1 = u_2$)

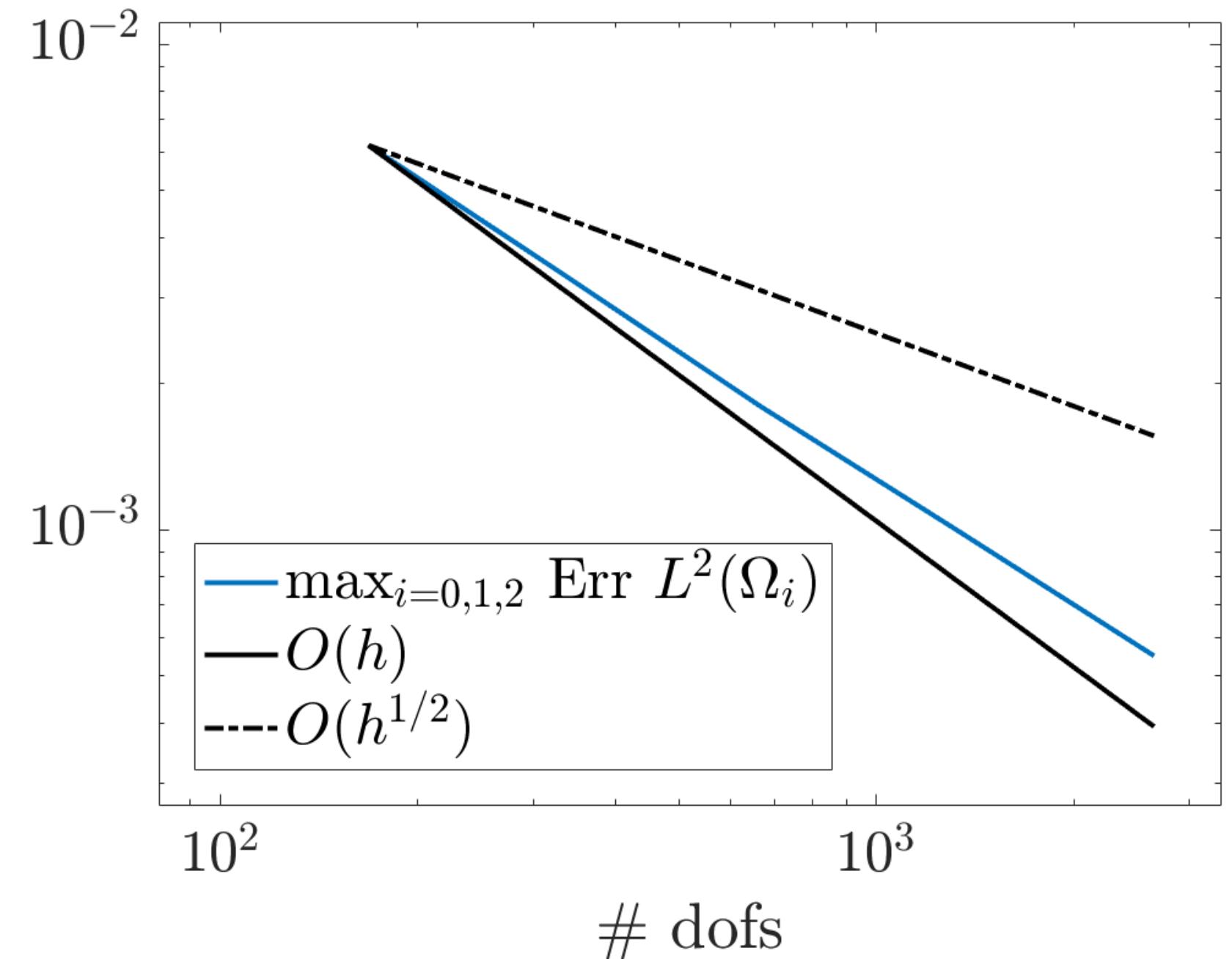


Define $V = u_i - u_j$, we recover the fluxes and traces as:

- $\sigma_i P_{S,i} \mathbf{u}_i = \psi_i(\mathbf{V})$,
- $\mathbf{u}_i = -\sigma_i^{-1} (P_{S,i}^+)^{-1} B_i \lambda + \beta_i \mathbf{e}_i$.

Given flux and trace, we compute u_0, u_1, u_2 inside Ω_i using the Green representation formula.

$$u(x) = \int_{\Gamma} G(x, y) \partial_n u(y) ds_y - \int_{\Gamma} \partial_n G(x, y) u(y) ds_y$$



Reduction to an ODE system

Recall that we want to solve

$$\psi_0(\mathbf{V}) = I_t(A_0 \mathbf{V}, \mathbf{z}) \quad \text{on } \Gamma_0,$$

$$\frac{d\mathbf{z}}{dt} = g(A_0 \mathbf{V}, \mathbf{z}) \quad \text{on } \Gamma_0,$$

$$\sum_{i=0}^N A_g B_i^\top \psi_i(\mathbf{V}) = -2\kappa A_g \mathbf{V} \quad \text{on } \Gamma_g.$$

Using $\psi_i(\mathbf{V}) = -B_i\lambda$ yields

$$\sum_{i=0}^N A_g B_i^\top B_i \lambda = 2\kappa A_g \mathbf{V},$$

$$A_g \lambda = \kappa A_g \mathbf{V}.$$

With this information we can dispose of the equations on Γ_g .

Multiply first line of

$$\begin{pmatrix} F & G \\ G^\top & 0 \end{pmatrix} \begin{pmatrix} \lambda \\ \beta \end{pmatrix} = \begin{pmatrix} \mathbf{V} \\ \mathbf{0} \end{pmatrix}.$$

with A_0 or A_g , use $A_g \lambda = \kappa A_g \mathbf{V}$ and get

$$\begin{pmatrix} F_{00} & F_{0g} & A_0 G \\ F_{g0} & F_{gg} - \kappa^{-1} I & A_g G \\ G^\top A_0^\top & G^\top A_g^\top & 0 \end{pmatrix} \begin{pmatrix} \lambda_m \\ \lambda_g \\ \beta \end{pmatrix} = \begin{pmatrix} \mathbf{V}_m \\ \mathbf{0} \\ \mathbf{0} \end{pmatrix}.$$

With $\lambda_m = A_0 \lambda$, $\lambda_g = A_g \lambda$, $\mathbf{V}_m = A_0 \mathbf{V}$. Thus

$$\psi_0(\mathbf{V}) = -B_0 \lambda = A_0 \lambda = \lambda_m$$

and $\psi_0(\mathbf{V})$ is replaced with $\psi(\mathbf{V}_m) = \lambda_m$.

Reduction to an ODE system

Recall that: $I_t(\mathbf{V}_m, \mathbf{z}) = C_m \frac{d\mathbf{V}_m}{dt} + I_{\text{ion}}(\mathbf{V}_m, \mathbf{z})$.

Theorem: the ODE system.

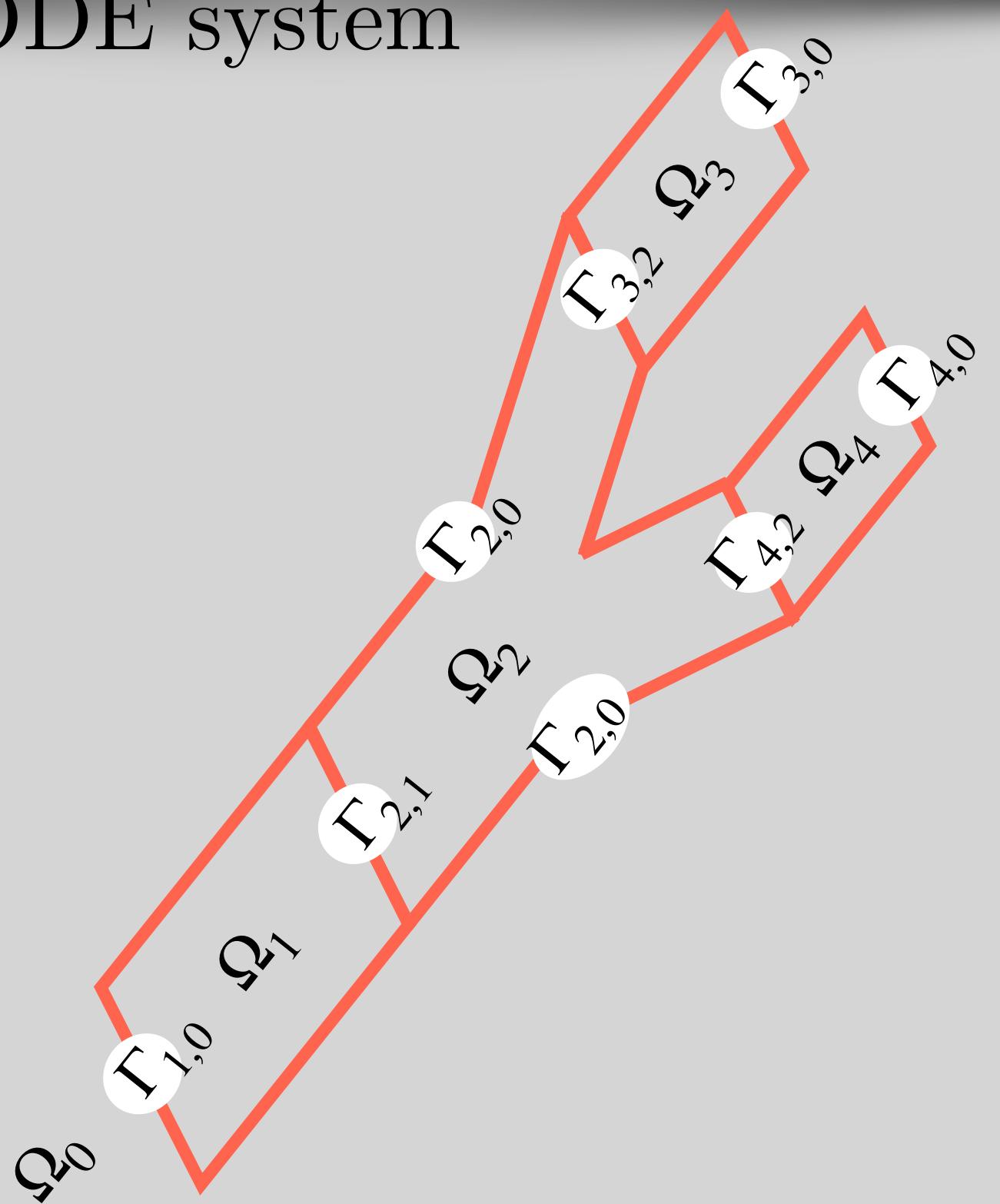
$$\begin{aligned} -\sigma_i \Delta u_i &= 0, & \text{in } \Omega_i \quad i = 0, \dots, N, \\ -\sigma_i \partial_n u_i &= I_t(V_m, z), & \text{on } \Gamma_{i,0} \quad i = 1, \dots, N, \\ -\sigma_0 \partial_n u_0 &= -I_t(V_m, z), & \text{on } \Gamma_0, \\ u_i - u_0 &= V_m, & \text{on } \Gamma_{i,0} \quad i = 1, \dots, N, \\ \frac{dz}{dt} &= g(V_m, z), & \text{on } \Gamma_0, \\ -\sigma_i \partial_n u_i &= \kappa(u_i - u_j), & \text{on } \Gamma_{i,j} \quad 1 \leq j, i \leq N, \end{aligned}$$

The spatially discretized Cell-by-Cell model is equivalent to the ODE system

$$\begin{aligned} \psi(\mathbf{V}_m) &= C_m \frac{d\mathbf{V}_m}{dt} + I_{\text{ion}}(\mathbf{V}_m, \mathbf{z}) & \text{on } \Gamma_0, \\ \frac{d\mathbf{z}}{dt} &= g(\mathbf{V}_m, \mathbf{z}) & \text{on } \Gamma_0, \end{aligned}$$

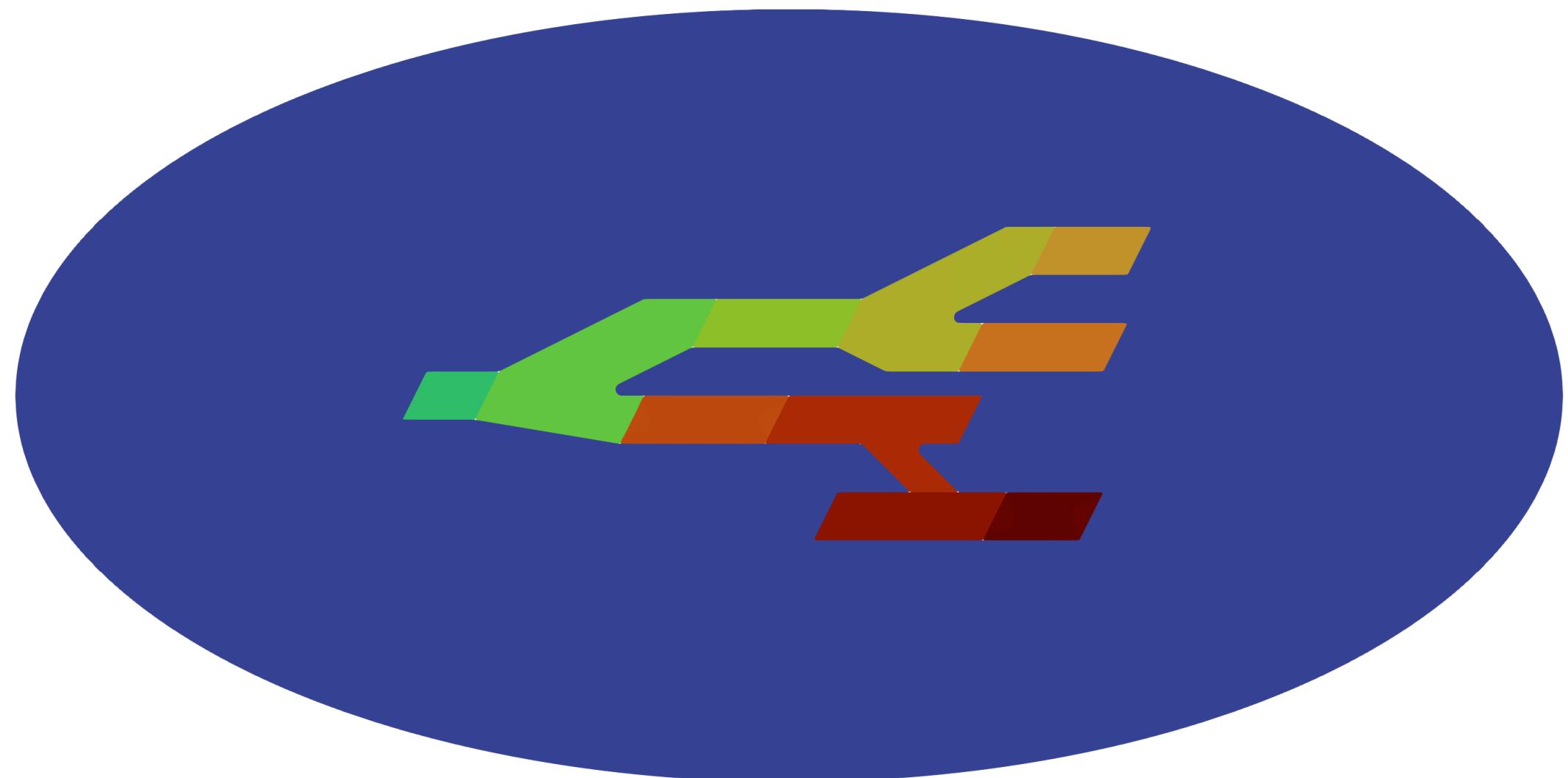
with $\psi(\mathbf{V}_m) = \lambda_m$ solution to

$$\begin{pmatrix} F_{00} & F_{0g} & A_0 G \\ F_{g0} & F_{gg} - \kappa^{-1} I & A_g G \\ G^\top A_0^\top & G^\top A_g^\top & 0 \end{pmatrix} \begin{pmatrix} \lambda_m \\ \lambda_g \\ \beta \end{pmatrix} = \begin{pmatrix} \mathbf{V}_m \\ \mathbf{0} \\ \mathbf{0} \end{pmatrix}.$$



Numerical experiment

We consider the extracellular matrix and 10 cells:



And solve

$$\psi(\mathbf{V}_m) = C_m \frac{d\mathbf{V}_m}{dt} + I_{\text{ion}}(\mathbf{V}_m, \mathbf{z}) \quad \text{on } \Gamma_0,$$

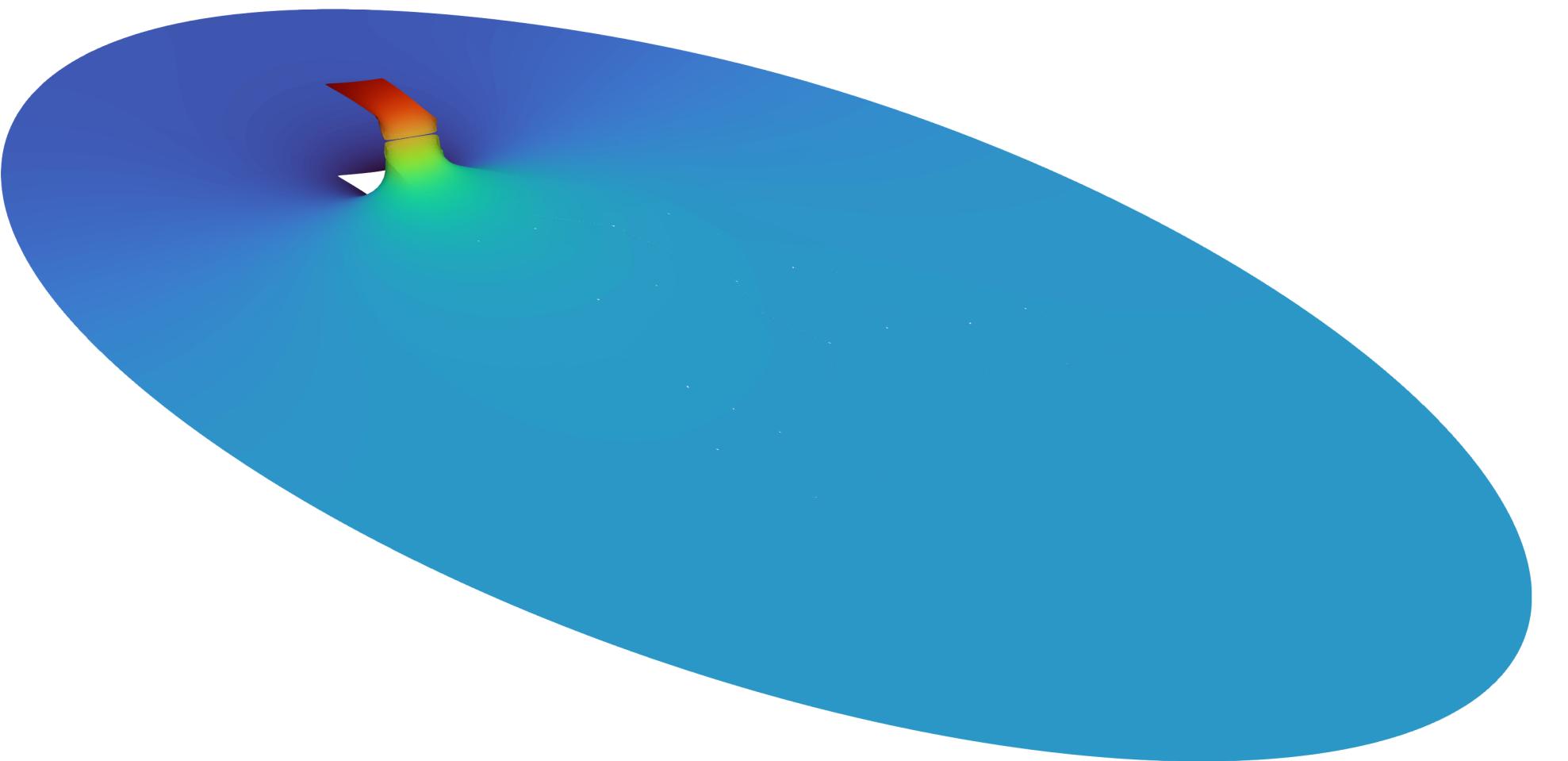
$$\frac{d\mathbf{z}}{dt} = g(\mathbf{V}_m, \mathbf{z}) \quad \text{on } \Gamma_0.$$

With ionic model

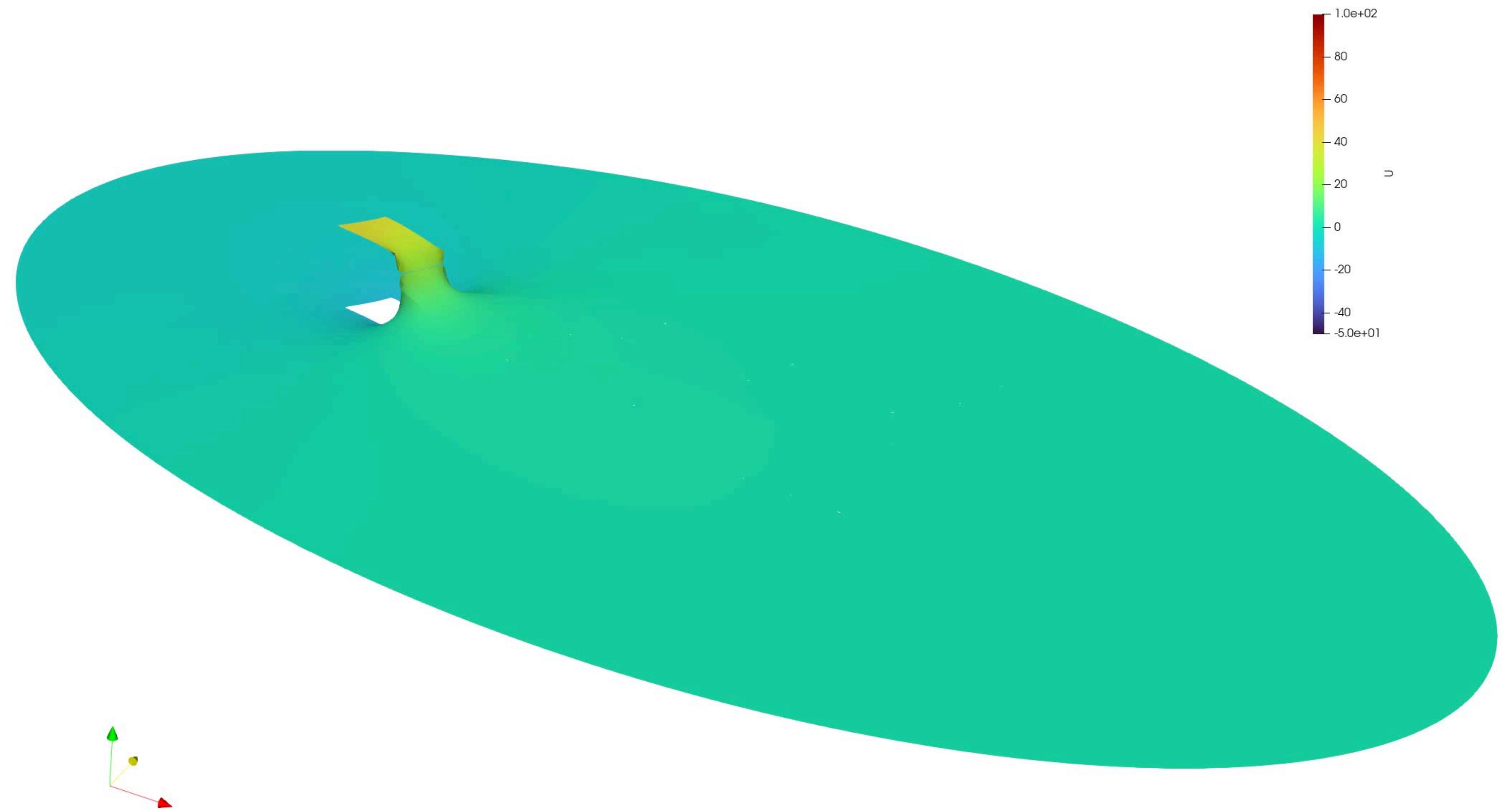
$$I_{\text{ion}}(V) = \eta_0 V(1 - V/V_{th})(1 - V/V_p),$$

without gating variables.

We stimulate the first cell:



Numerical experiment



The End

Thank you!

Funding: This project has received funding from the European High-Performance Computing Joint Undertaking (JU) under grant agreement No 955495 (MICROCARD). The JU receives support from the European Union's Horizon 2020 research and innovation programme and Belgium, France, Germany, Switzerland.