

## **Group board meeting: The Sand·E Group**

Minutes for 2016-01-13

**Present:** A. Goodsell (Chair), M. Fry (Board member), L. Foglianti Spadini, A. Hyslop, A. Kallaivannan, R. Kent, C. Lau, A. Rutley, S. Searles-Bryant, S. Wright, L. Yeo

### **Announcements**

1. The assessment criteria for the peer-assessment component of the module have been chosen:

**Communication** “Exchanging ideas and updating others on progress/feedback.”

**Productivity** “Maximising your contribution within a given time frame.”

**Participation** “Willingness to engage in, and contribute to, the project.”

**Quality** “Clear work which significantly furthers the progress of the project.”

**Cooperation** “Prioritising effectively towards a common goal.”

**Reliability** “Do what you say you’re going to do; be trustworthy.”

Scores should be between 1 and 3 (less than expected; expected; exceeds expectations). These must be sent weekly to MF before 17.00 each Monday, starting Monday, January 25.

### **Allocation of roles**

1. AG will chair meeting and act as the team leader.
2. SSB will take minutes and act as the contact person for MF and the course coordinator.
3. RK will collate the peer-assessment scores and send to SSB to forward to MF each week.
4. CL will act as the group treasurer.

## **Project brief (MF)**

“The challenge is to develop a robot which can draw artwork on sandy beaches.”

1. The final product should be small enough to fit in a rucksack/suitcase. It should be manageable on public transport.
2. Examples of sand art at <https://www.flickr.com/photos/martinartman>.
3. The product can draw large-scale on a beach, or small-scale in a table-top sandpit.
4. The robot should be named
5. The specifics of what sorts of images the robot should draw are left for us to decide; the purpose and motivations for the project have not been specified.

## **Resources**

1. The project budget is £200.
2. A case can be made to the course coordinator to obtain extra funding (MF advises probably only up to £50).
3. The robot designed for this course a few years ago is available for parts. MF advises that the motors (value c. £100) are particularly useful.

**Next Meeting:** Tuesday, January 19, at 11:15 in MPEB 3.14a

## **Actions**

- > Discuss skills and divide responsibilities among team members (*all*)
- > Decide upon purpose and motivations for the product (*all*)

## **Group board meeting: The Sand·E Group**

Minutes for 2016-01-19

**Present:** A. Goodsell (Chair), M. Fry (Board member), L. Foglianti Spadini, A. Hyslop, A. Kallaivannan, R. Kent, C. Lau, A. Rutley, S. Searles-Bryant, S. Wright, L. Yeo

### **Old business**

1. The minutes of the previous meeting were approved.

### **Announcements & progress**

1. We now have bench space in Lab 3. No access 1300–1400 every day and 1400–1630 on Wednesdays. A 3d printer is available; a sketch must be made and shown to the technician. (RK)
2. Final report has been started on Overleaf. Team can edit at [www.overleaf.com/4075528rppsqb](http://www.overleaf.com/4075528rppsqb).

### ***Aims and motivations***

3. Motivation is to build a robot for education. The robot should be programmable by children; they set start/end points and waypoints and whether or not to draw in between. This teaches algorithmic thinking (*e.g.* age 6–9).

### ***Group structure and roles***

4. Roles which have been allocated.

(AR, AH) Art review: Looking into history of sand art; choose type of thing to draw.

(SW, AK) Robotics review: Look at movement/digging mech, materials, and history.

(SSB) Education review: Case for teaching children algorithmic thinking; existing ways in which this is achieved.

(AG, AH) Website: Project website.

5. Design outline: Areas of design which should be decided upon this week.

- Movement (SW, AK)
- Interface
- Guidance (LFS, CL)
- Construction materials (SW, AK)
- Digging mechanism (SW, AK)
- Electronics platform (CL, SSB)

### *Preliminary research*

6. Art review. (AR, AH)

Began as protest of commercialization of art in US. Motivations behind recent works are to bring attention to the environment.

There are many large scale sculptures using rakes, trowels. Smaller sand patterns use ropes; precise measurement is not emphasized. New movement of small-scale ‘sand-stories’ involving light projection.

7. History of robotics review (incl. preliminary survey of methods of movement and digging mechanisms). (SW, AK)

- (a) Drawing mechanics: most viable options are rakes/teeth and rollers.
- (b) Locomotion: problems include purchase on sand and not ruining the drawing. Tracks ruin previous drawing; best option looks like SandBot: three wheels.
- (c) Brief summary of history of robotics
- (d) Materials: waterproof/sandproof towels exist, could be used to protect sensitive components.

8. Education review. (SSB)

Turtles have been used for education since 1960s. Drawing robots exist based on the Logo language; ink-and-paper equivalents of what we aim to build are very popular in primary schools.

The idea of teaching computation in primary schools has received enormous interest recently.

## 9. Electronics and guidance mechanisms (LFS, CL)

- (a) GPS and compass: compass necessary to determine direction of robot. Cost would be c. £50. Not sure if precision is adequate for our needs.
- (b) Laser grids: prebuilt modules are too expensive; should look into building our own. Ultrasound equivalent is too short-range.
- (c) Tethering: requires child to follow the robot.
- (d) Remote control (bluetooth): can use a mobile phone; range of 30 feet. Software exists for Arduino.

## 10. Electronics platform (SSB)

- (a) Arduino: best option for embedded systems; large community online for support. Cost < £50.
- (b) NETduino: similar to Arduino but uses .NET framework. Possibly easier to program (several team members know .NET languages).
- (c) Raspberry Pi: more a computer than for embedded systems. Used a lot for education.
- (d) Micro-controller: Requires all supporting circuitry to be built by us; more difficult to program. Possible but would require a lot of time.
- (e) A systems engineer role should be appointed to ensure compatibility of all components (software and hardware). LFS points out that power supplies will be an issue that needs some attention.

## **New Business**

### 1. Resources and examples (MF)

- (a) Rake: adjustable tines. Too large for our project but mechanism may be of interest
- (b) “Ed-bot”: small line-following robot built by MF’s son.

- (c) USB shield for Arduino: includes dongle for cordless Playstation controller
  - (d) Assorted servo motors.
- 2. Time management plan and Gantt chart. (AG)
  - (a) SSB thinks more troubleshooting/testing time should be added. AG says build phases include time for testing.
  - (b) First software task needs to be a tool to allow hardware to be tested manually.
  - (c) A second Gantt chart should be produced once the design has been completed and detailed development processes are known.
- 3. Discussion of material to be posted on the website. (AG)
  - (a) Demonstration of website.
  - (b) Mirrors report in sections with summaries of each part.
  - (c) In future will have photos and a video of the robot.
- 4. Peer-assessment scores need to be collected

**Next Meeting:** Tuesday, January 26, at 11:15 in MPEB 3.14a

### **Actions**

- > Add research to the report on Overleaf (*all*)
- > Investigate building our own LiDAR system for guidance. (*SSB*)
- > Collect peer assessment scores (*RK*)

## **Group board meeting: The Sand·E Group**

Minutes for 2016-01-26

**Present:** A. Goodsell (Chair), M. Fry (Board member), L. Foglianti Spadini, A. Hyslop, A. Kallaivannan, R. Kent, C. Lau, A. Rutley, S. Searles-Bryant, S. Wright, L. Yeo

### **Old business**

1. The minutes of the previous meeting were approved.
2. The report is now available to view in Dropbox at <https://goo.gl/1CujQq> or to view and edit in Overleaf at [www.overleaf.com/4075528rppsqb](http://www.overleaf.com/4075528rppsqb). These will be updated and kept synced with SSB's local copy roughly daily.
3. Peer assessment form has been filled out for this week

### **Announcements & progress**

1. We do not have access to our space in Lab 3 on Tuesdays unless we make special arrangements. We also only have half a bench.
2. Servos: We have 7 in the lab, MF may have more. Plan is to use 3 for the rakes.
3. Motors: 148:1 gear ratio. We have 4 in the lab from the stair-climbing project.
4. The code for the Physics study room (top floor of Physics Bldg) is 0921.

### ***Electronics platform (SSB, SW, AH)***

5. The electronics platform outline. Discussion of exact requirements.
  - (a) We believe that we need the following for the project (from Adafruit in the US):
    - Arduino board: Arduino Uno (\$24.95)  
<https://www.adafruit.com/products/50>

- Motor control shield (\$19.95)  
<https://www.adafruit.com/products/1438>
  - GPS shield (\$49.95)  
<https://www.adafruit.com/products/1272>
  - Servo control shield (\$17.50)  
<https://www.adafruit.com/products/1411>
  - Compass breakout board (\$19.95)  
<https://www.adafruit.com/products/1746>
- (b) The GPS could be a breakout (<https://www.adafruit.com/products/746>) instead of a shield at a saving of \$15.
  - (c) The servo control board is unnecessary if only 2 servos are used since the motor shield board can handle these.
  - (d) The motors and servos should be powered separately from the control board. 2 PP3 (9V) batteries should be sufficient.
  - (e) The total cost for all of the components is a little over \$128, or £90, plus shipping.
  - (f) We would also need a few other components (bypass capacitors; cables; battery connectors) which could be sourced in the UK (*e.g.* Maplin).
  - (g) The Arduino (Genuino) 101 has built in accelerometer. This would be very useful for navigation and making the positioning more precise.

**Decisions** Procure Genuino 101 from Arduino in Italy. All shields and the compass breakout from Adafruit. RK will order through Lab 3. SSB will forward details to RK and CL.

### ***Robot design (AR, RK)***

6. CAD design made.
7. Use acrylic to manufacture (easy to work with; won't rust)
8. Could have an acrylic box over top for protection
9. Dimensions TBC
10. Discussion of whether two driven wheels should be at the front or the back



11. AG has a friend who will design a pretty box for us to be 3d-rpinted.
12. Suggestion from MF: consider using only 1 rake up/down to keep simple
13. Consider how much we can achieve this year; don't be over ambitious and perhaps leave some development for a further project.
14. We could recycle wheels from previous project (cable spools).
15. Safety regulations are extensive.

### ***Software (AG, LFS, LY)***

16. Started looking at Arduino boards but handed that off to electronics subgroup because it made more sense for them to do it.
17. LY has investigated generating images (fractal-type diagrams) without using GPS. It is feasible to draw images without a positioning system even with possible turning and moving errors accounted for (computer simulations). This would be a good avenue to pursue if GPS and current plans fail. (MF: minimum goal should be to have a spiral-drawing robot tethered to a centre-point.)
18. LY has found a website for simulating Arduino output for some code (<https://123d.circuits.io/>). We can also connect simulated circuits, readings *etc.* for simulation of the whole system. We should start a project on this website to simulate our code.

### **New Business**

1. Jobs to be assigned in group general meeting tomorrow.

**Next Meeting:** Tuesday, February 2, at 11:15 in MPEB 3.14a

### **Actions**

- > Written work to be sent to SSB for compilation (*all*)
- > Aims and Motivations sections to be written up (*AG*)

- > Investigate procurements options for shields (***SSB, AH, SW***)
- > Buy Arduino controller board (***RK, SSB***)
- > Buy other electronics (***RK, SSB***)

## **Group board meeting: The Sand·E Group**

Minutes for 2016-02-02

**Present:** A. Goodsell (Chair), M. Fry (Board member), L. Foglianti Spadini, A. Hyslop, R. Kent, C. Lau, A. Rutley, S. Searles-Bryant, S. Wright, L. Yeo

**Absent:** A. Kallaivannan (*apologies*)

### **Old business & announcements**

1. The minutes of the previous meeting were approved.
2. The robot has been officially named Sand·E (Sand Education, or Sand Art ‘n’ Design Experiment).
3. The components discussed last week have been ordered from RS.

### **Progress**

#### ***Modelling and robot chassis***

1. Cardboard models of the robot and the electronics have been built. (discussion)
  - (a) motors are on underside of chassis
  - (b) on this model the large, driven wheels are at the front.
  - (c) a more robust, moving prototype will be built this week.
  - (d) the electronics box can be bought (see below)

**Decisions** The two driven wheels should be on the front; the drawing mechanism on the back with the single caster wheel. This will avoid “trolley syndrome”, where the leading caster wheel will lead the rear wheels astray.

2. SSB has found a suitable box and on/off switch. Would require:
  - “Hammond Project Box Light Grey 125x100x90mm” £6.29 from Maplin (N26HG)
  - “Miniature 6A AC 230V Rocker Switch DPDT” £2.09 (YX65V)
  - 2× “Maplin Cable Exit Gland 15mm with Sleeve” £3.89 (JZ43W)

### ***Software***

3. AG, LFS, LY have got motors running in the online simulator.

### ***Website***

4. There is some content on the website, but it is not yet live.

### **New Business**

1. LFS, RK, and LY have not yet contributed to the report. Now we have finished a lot of the initial design SSB would like to get those sections finished.

### ***Feedback from MF***

2. There seems to be an imbalance in the contributions from different members of the team (4 people seem to be contributing more than others). AG confirms that our team meetings on Wednesdays are very different, and everybody is contributing fairly.

**Next Meeting:** Tuesday, February 9, at 11:15 in MPEB 3.14a

### **Actions**

- > Contribute research to report (***LFS, RK, LY***)
- > Write up design work (***all***)
- > Build a second prototype (***RK, CL, AK, AR***)
- > Calculate how long a PP3 will last driving the motors and investigate other battery options (***SSB***)
- > Find out how to recoup expenses for components (***SSB, AG***)
- > Download some of Martin Artman's photos for the website & report (***SSB***)