

# Issue III: Homotopy Type Theory

Maxim Sokhatsky <sup>1</sup>

<sup>1</sup> National Technical University of Ukraine  
Igor Sikorsky Kyiv Polytechnical Institute  
August 22, 2018

## **Abstract**

We present here main distinctive point of Homotopy Type Theory as an extension of Martin-Löf Type Theory up to higher inductive types which we will give in the next issue.

**Keywords:** Homotopy Type Theory

## **Contents**

# 1 Homotopy Type Theory

Homotopy type theory to classical homotopy theory is like Euclidian syntethic geometry (points, lines, axioms and deduction rules) to analytical geometry with cartesian coordinates on  $\mathbb{R}^n$  (geometric and algebraic) <sup>1</sup>

## 1.1 Homotopies

The first higher equality we meet in homotopy theory is a notion of homotopy, where we compare two functions or two path spaces (which is sort of dependent families). The homotopy interval  $\mathbf{I} = [0, 1]$  is the perfect foundation for definition of homotopy.

**Definition 1.** (Interval). Compact interval.

```
data I = i0
      | i1
      | seg <i> [(i=0) -> i0 ,
                (i=1) -> i1]
```

You can think of  $\mathbf{I}$  as isomorphism of equality type, disregarding carriers on the edges. By mapping  $i0, i1 : \mathbf{I}$  to  $x, y : A$  one can obtain identity or equality type from classic type theory.

**Definition 2.** (Interval Split). The conversion function from  $\mathbf{I}$  to a type of comparison is a direct eliminator of interval. The interval is also known as one of primitive higher inductive types which will be given in the next **Issue IV: Higher Inductive Types**.

```
pathToHtpy (A: U) (x y: A) (p: Path A x y): I -> A
  = split { i0 -> x; i1 -> y; seg @ i -> p @ i }
```

**Definition 3.** (Homotopy). The homotopy between two function  $f, g : X \rightarrow Y$  is a continuous map of cylinder  $H : X \times \mathbf{I} \rightarrow Y$  such that

$$\begin{cases} H(x, 0) = f(x), \\ H(x, 1) = g(x). \end{cases}$$

```
homotopy (X Y: U) (f g: X -> Y)
  (p: (x: X) -> Path Y (f x) (g x))
  (x: X): I -> Y = pathToHtpy Y (f x) (g x) (p x)
```

---

<sup>1</sup>We will denote geometric, type theoretical and homotopy constants bold font  $\mathbf{R}$  while analitical will be denoted with double lined letters  $\mathbb{R}$ .

## 1.2 Groupoid Interpretation

The first text about groupoid interpretation of type theory can be found in Francois Lamarche: A proposal about Foundations<sup>2</sup>. Then Martin Hofmann and Thomas Streicher wrote the initial document on groupoid interpretation of type theory<sup>3</sup>.

Equality	Homotopy	$\infty$ -Groupoid
reflexivity	constant path	identity morphism
symmetry	inversion of path	inverse morphism
transitivity	concatenation of paths	composition of morphisms

There is a deep connection between higher-dimensional groupoids in category theory and spaces in homotopy theory, equipped with some topology. The category or groupoid could be built where the objects are particular spaces or types, and morphisms are path types between these types, composition operation is a path concatenation. We can write this groupoid here recalling that it should be category with inverted morphisms.

```

cat : U = (A : U) * (A -> A -> U)
groupoid : U = (X : cat) * isCatGroupoid X
PathCat (X : U) : cat = (X, \ (x y : X) -> Path X x y)

isCatGroupoid (C : cat) : U
= (id : (x : C.1) -> C.2 x x)
* (c : (x y z : C.1) -> C.2 x y -> C.2 y z -> C.2 x z)
* (inv : (x y : C.1) -> C.2 x y -> C.2 y x)
* (inv_left : (x y : C.1) (p : C.2 x y) ->
  Path (C.2 x x) (c x y x p (inv x y p)) (id x))
* (inv_right : (x y : C.1) (p : C.2 x y) ->
  Path (C.2 y y) (c y x y (inv x y p) p) (id y))
* (left : (x y : C.1) (f : C.2 x y) ->
  Path (C.2 x y) (c x x y (id x) f) f)
* (right : (x y : C.1) (f : C.2 x y) ->
  Path (C.2 x y) (c x y y f (id y)) f)
* ((x y z w : C.1) (f : C.2 x y) (g : C.2 y z) (h : C.2 z w) ->
  Path (C.2 x w) (c x z w (c x y z f g) h)
    (c x y w f (c y z w g h)))

```

<sup>2</sup><http://www.cse.chalmers.se/coquand/Proposal.pdf>

<sup>3</sup>Martin Hofmann and Thomas Streicher. The Groupoid Interpretation of Type Theory. 1996.

```

PathGrpd (X: U)
  : groupoid
  = ((Ob, Hom), id, c, sym X, compPathInv X, compInvPath X, L, R, Q) where
    Ob: U = X
    Hom (A B: Ob): U = Path X A B
    id (A: Ob): Path X A A = refl X A
    c (A B C: Ob) (f: Hom A B) (g: Hom B C): Hom A C
      = comp (<i> Path X A (g@i)) f []

```

From here should be clear what it meant to be groupoid interpretation of path type in type theory. In the same way we can construct categories of  $\prod$  and  $\sum$  types. In **Issue VIII: Topos Theory** such categories will be given.

### 1.3 Functional Extensionality

### 1.4 Fibration

### 1.5 Loop Spaces

### 1.6 Equivalence

### 1.7 Homotopy Type

### 1.8 Univalence