

Statistics for grp-bork/reCOGnise

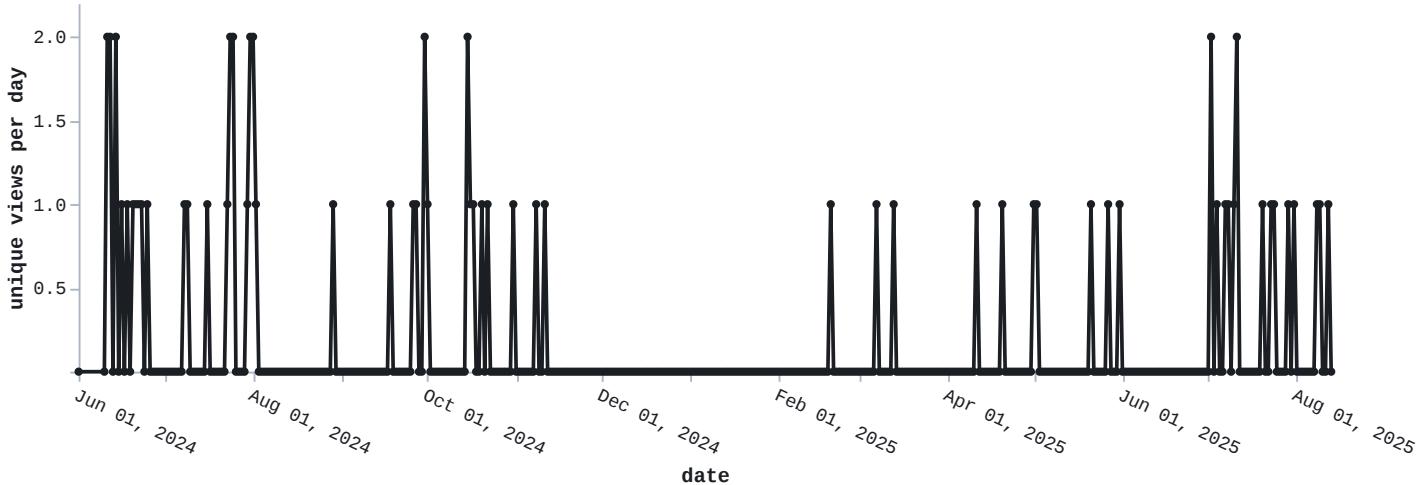
Generated for [grp-bork/reCOGnise](#) with [jgehrcke/github-repo-stats](#) at 2025-08-16 23:02 UTC.

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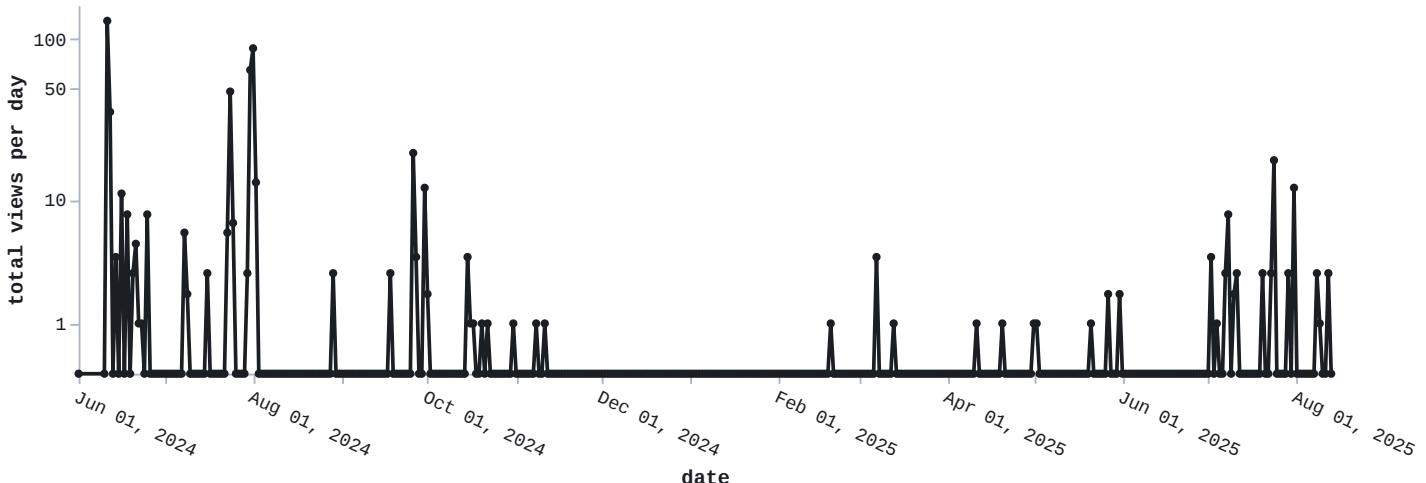
Views

Unique visitors



Cumulative: 69

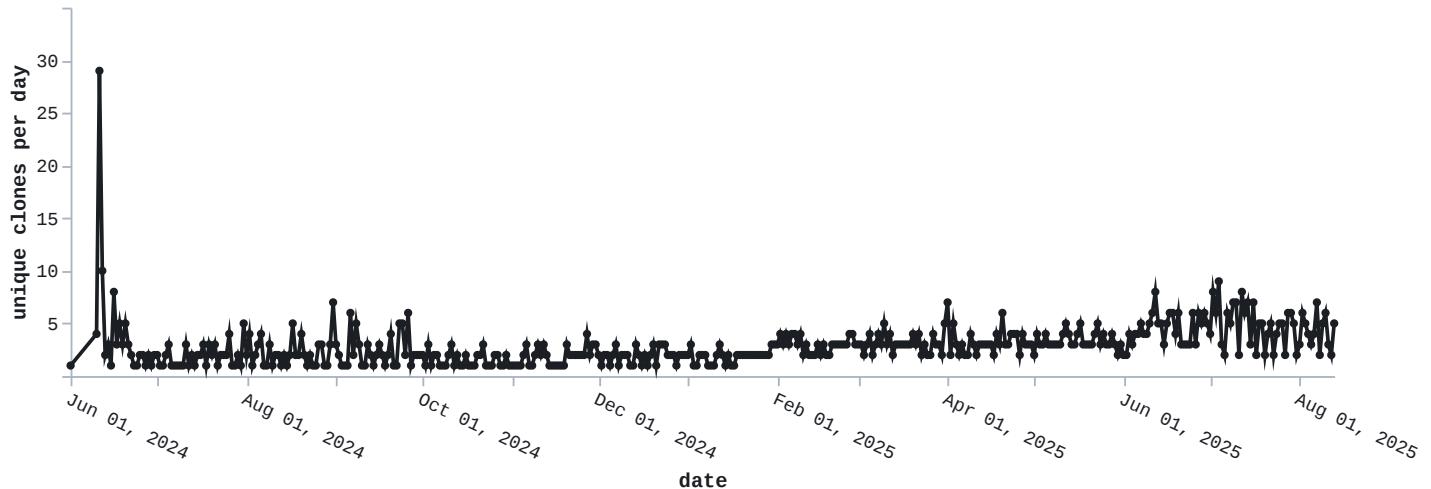
Total views



Cumulative: 584

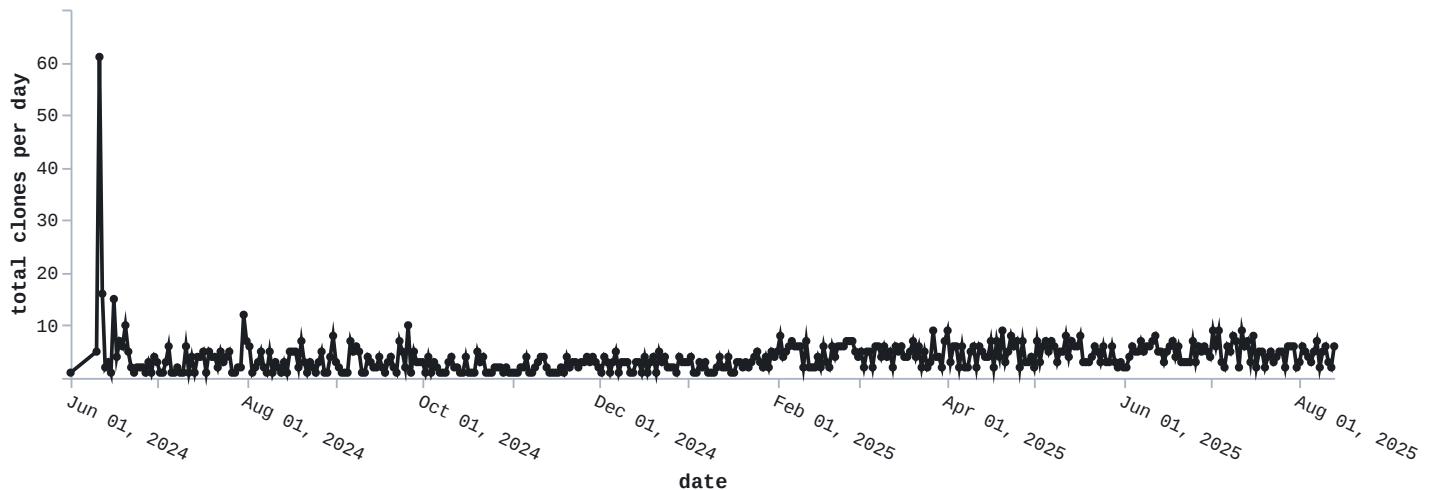
Clones

Unique cloners



Cumulative: 1235

Total clones



Cumulative: 1672

Stargazers

This repository has no stars yet.

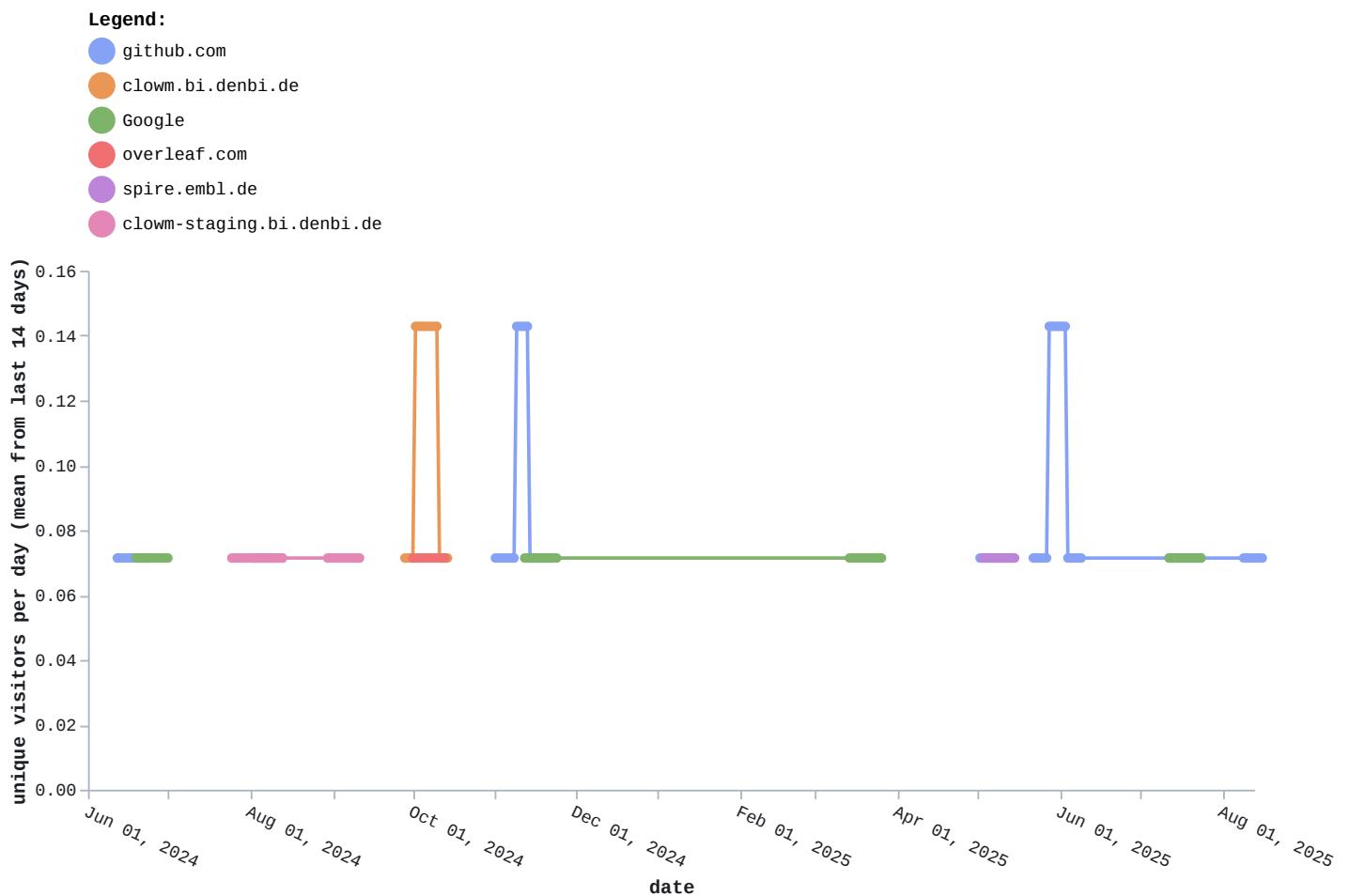
Forks

This repository has no forks yet.

Top referrers and paths

Note: Each data point in the plots shown below is influenced by the 14 days leading up to it. Each data point is the arithmetic mean of the “unique visitors per day” metric, built from a time window of 14 days width, and plotted at the right edge of that very time window. That is, these plots respond slowly to change (narrow peaks are smoothed out).

Top referrers

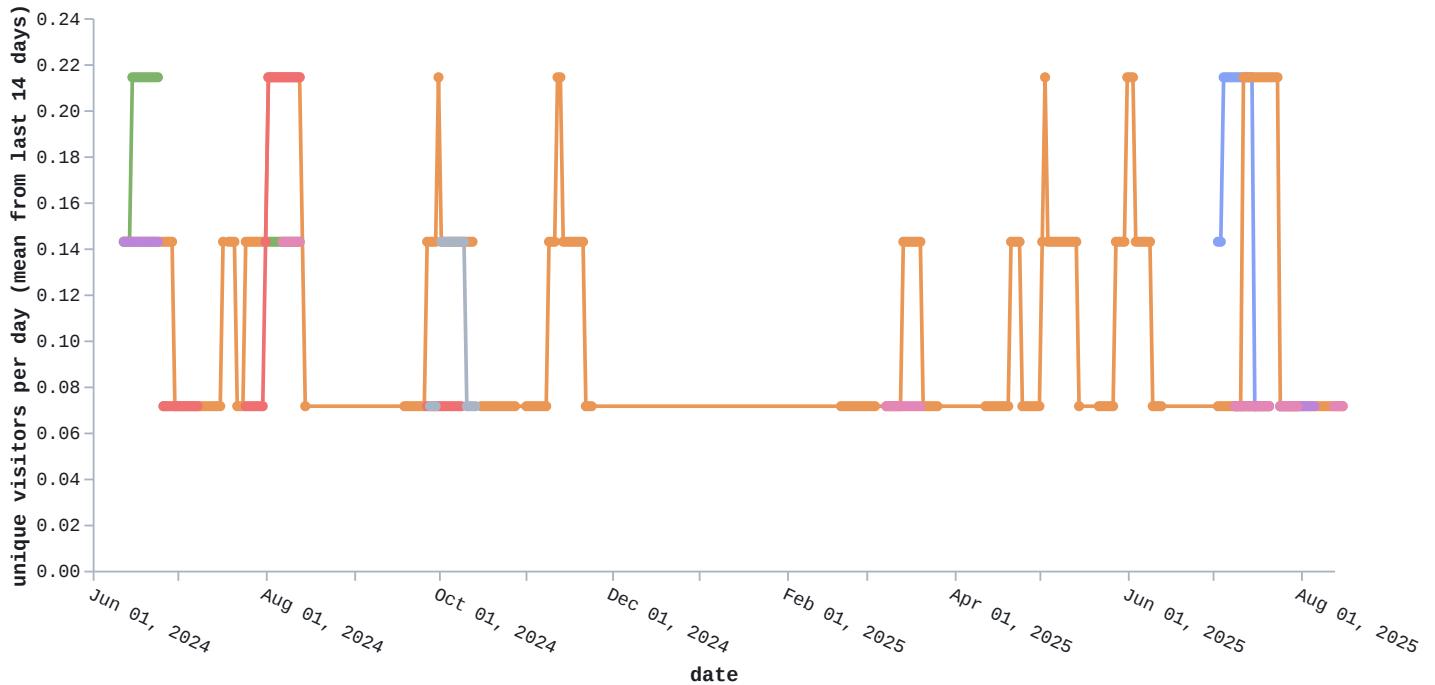


Top 15 referrers: 01: [github.com](#) , 02: [clowm.bi.denbi.de](#) , 03: [Google](#) , 04: [overleaf.com](#) , 05: [spire.embl.de](#) , 06: [clowm-staging.bi.denbi.de](#)

Top paths

Legend:

- grp-bork/reCOGnise/blob/m...
- grp-bork/reCOGnise
- grp-bork/reCOGnise/blob/m...
- grp-bork/reCOGnise/blob/m...
- grp-bork/reCOGnise/actions
- grp-bork/reCOGnise/blob/m...
- grp-bork/reCOGnise/blob/3...



Top 15 paths: 01: grp-bork/reCOGnise/blob/main/.github/workflows/docker-publish.yml , 02: grp-bork/reCOGnise , 03: grp-bork/reCOGnise/blob/main/main.nf , 04: grp-bork/reCOGnise/blob/main/nextflow.config , 05: grp-bork/reCOGnise/actions , 06: grp-bork/reCOGnise/blob/main/modules/recognise.nf , 07: grp-bork/reCOGnise/blob/3e7143dfc83e35bf756abd9549db89668fe713f3/nextflow_schema.json , 08: grp-bork/reCOGnise/tree/main/modules , 09: grp-bork/reCOGnise/blob/main/recognise/__main__.py , 10: grp-bork/reCOGnise/commits/main , 11: grp-bork/reCOGnise/blob/main/nextflow_schema.json , 12: grp-bork/reCOGnise/branches , 13: grp-bork/reCOGnise/tree/3e7143dfc83e35bf756abd9549db89668fe713f3 , 14: cschu/reCOGnise/blob/main/.github/workflows/singularity.yml , 15: grp-bork/reCOGnise/tree/main