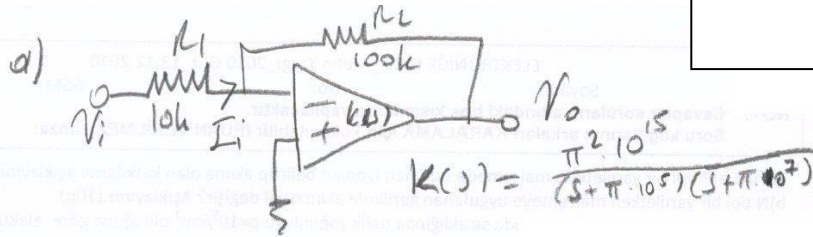
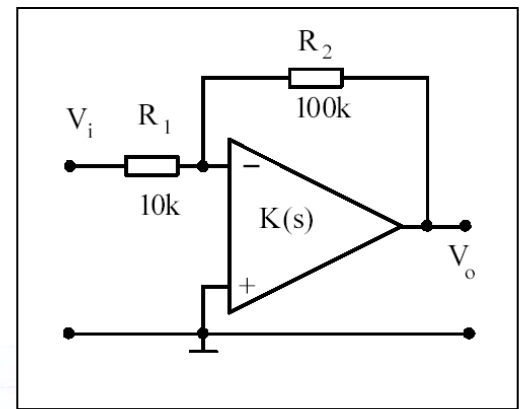


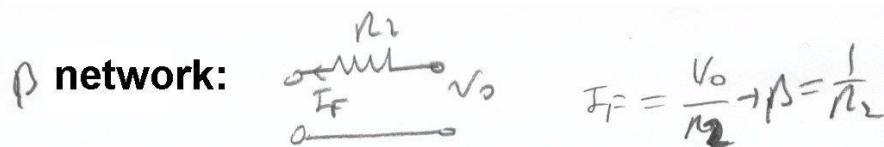
For the amplifier in the circuit;
 $r_{Ki}=100k\Omega$, $C_{Ki}=100pF$, $r_{Ko}\approx 0$, $C_{Ko}\approx 0$,
 $K(s)=\pi^2 10^{15}/(s+\pi 10^5)(s+\pi 10^7)$

a) Find v_o/v_i in s domain ($A_f(s)=?$).

b) Investigate the stability of the circuit and find the gain margin.



Feedback type: input current, output voltage



open loop case including,
the loading effect of β

$$(V_o = -I_t \cdot Z_i \cdot K(s))$$

$$Z_m = \frac{V_o}{I_t} = -K(s) Z_i(s)$$

$$Z_i(s) = \frac{50k \rightarrow (R_{L1} || R_{L2})}{s \cdot 10^{-10} \cdot 5 \cdot 10^4 + 1} = \frac{10^{10}}{s + 200k} \quad \text{Cik } 100pF$$

Feedback

$$Z_{MF} = \frac{Z_m}{1 - \beta Z_m} = \frac{-K(s) Z_i(s)}{1 + \beta K(s) Z_i(s)} = V_o / I_i$$

$$I_i = \frac{V_i}{R_1 + Z_{if}}$$

$$Z_{if} = \frac{Z_i}{1 - \beta Z_m}$$

feedback type
input current

$$\frac{V_o}{I_i} = \frac{V_o}{\frac{V_i}{R_1 + Z_{if}}} \rightarrow \frac{V_o}{V_i} = \frac{1}{R_1 + Z_{if}} \cdot \frac{Z_m}{1 - \beta Z_m}$$

transimpedance

voltage gain

$$= \frac{1}{R_1 + \frac{Z_i(s)}{1 + \beta K(s) Z_i(s)}} \cdot \frac{-K(s) Z_i(s)}{1 + \beta K(s) Z_i(s)}$$

$$\begin{aligned} \frac{V_o}{V_i} &= \frac{-K(s) \cdot Z_1(s)}{R_1 [1 + \beta K(s) H(s)] + Z_1(s)} \\ &= \frac{\frac{-\pi^2 \cdot 10^{15}}{(s + \pi \cdot 10^5)(s + \pi \cdot 10^7)} \cdot \frac{10^{10}}{s + 200k}}{10k + \frac{10k}{100k} \cdot \frac{+\pi^2 \cdot 10^{15}}{(s + \pi \cdot 10^5)(s + \pi \cdot 10^7)} \cdot \frac{10^{10}}{s + 200k} + \frac{10^{10}}{s + 200k}} \\ &= \frac{-\pi^2 \cdot 10^{21}}{(s + \pi \cdot 10^5)(s + \pi \cdot 10^7)(s + 200k) + \pi^2 \cdot 10^{20} + 10^6(s + \pi \cdot 10^5)(s + \pi \cdot 10^7)} \end{aligned}$$

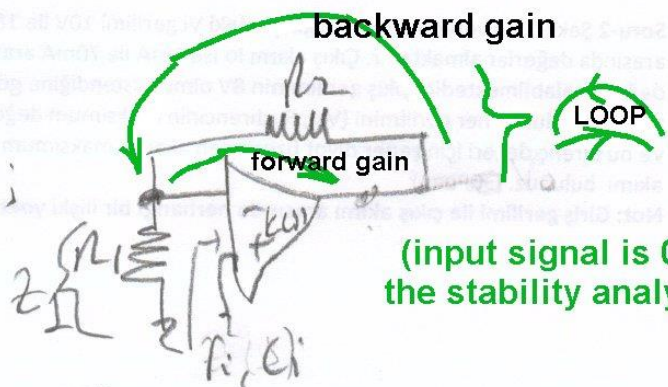
b) For stability analysis;

$$R_1 \parallel R_i \approx 9k$$

$$Z_1 = \frac{9k}{s \cdot 10^{10} \cdot 9k + 1} \approx \frac{10^{10}}{s + 1/1 \cdot 10^6}$$

$$\beta(s) = \frac{Z_1}{R_2 + Z_1} = \frac{10^{10}}{(s + 1/1 \cdot 10^6) \cdot 100k + 10^{10}} \approx \frac{10^5}{s + 1/2 \cdot 10^6}$$

$$A(s) = K(s) \quad (r_o = 0, A_v = \infty)$$



(input signal is 0 for the stability analysis.)

$$B(s)A(s) = \frac{10^5}{s+1,2 \cdot 10^6} \cdot \frac{-\pi^2 \cdot 10^{15}}{(s+\pi \cdot 10^5)(s+\pi \cdot 10^7)} \quad |5|$$

$$\downarrow$$

$$= \frac{-\pi^2 \cdot 10^{20}}{(s+1,2 \cdot 10^6)(s+\pi \cdot 10^5)(s+\pi \cdot 10^7)}$$

denominator $= s^3 + s^2 \cdot 33 \cdot 10^6 + s \cdot 479 \cdot 10^{11} + 1,2 \cdot 10^9$

$$s \rightarrow j\omega = -j\omega^3 - \omega^2 \cdot 33 \cdot 10^6 + j\omega \cdot 479 \cdot 10^{11} + 1,2 \cdot 10^9$$

If the imaginal part of the denominator is zero, the phase of the loop gain is zero.
 Since, for this condition, denominator becomes real and negative,
 the loop gain becomes real and positive.

$$- \omega^3 + \omega \cdot 479 \cdot 10^{11} = 0 \rightarrow \omega \approx 6,9 \cdot 10^6$$

\downarrow the phase is zero

at $\omega_0 = 6,9 \cdot 10^6$

$$B \cdot A = \frac{-\pi^2 \cdot 10^{20}}{-(479 \cdot 10^{11} \cdot 33 \cdot 10^6 + 1,2 \cdot 10^9)} \approx \frac{-9,9 \cdot 10^{20}}{-1,57 \cdot 10^{21}} = 0,63$$

$$B \cdot A \Big|_{\omega_0 = 6,9 \cdot 10^6} = 0,63 < 1$$

loop gain is less than 1 when
 the loop phase becomes 0.
 Thus, the circuit is stable.

$$\text{Gain Margin} = 4 \text{ dB} = -20 \cdot \log 0,63$$

Note that in this analysis, ω_0 is not the natural frequency.