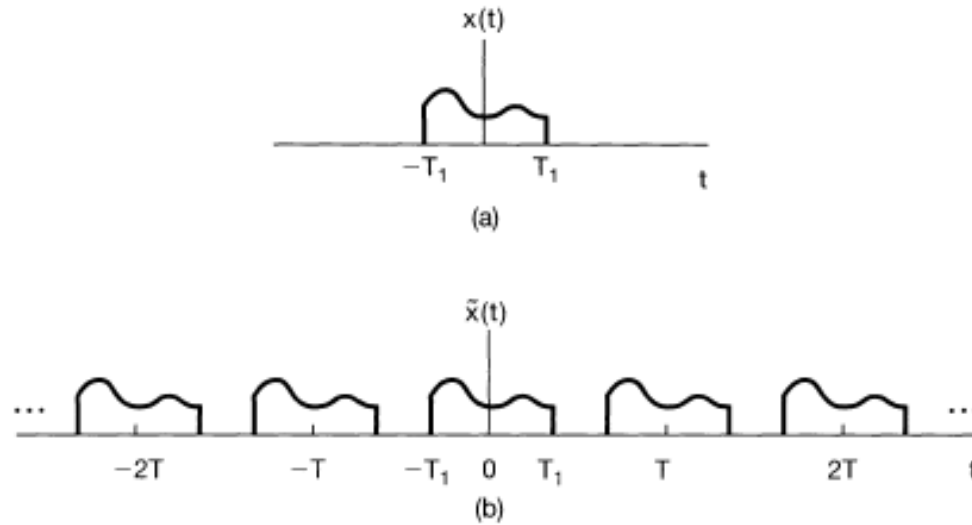




# Sürekli Zamanlı Fourier Dönüşümü

Ref: Oppenheim and Willsky, "Signals and Systems"

## Sürekli Zamanlı Fourier Dönüşümü



a) Aperi-yodik iřaret, b) periyodik iřaret

Periyodik iřareti Fourier Serisine açarsak, Fourier serisi gösterilimi ve Fourier serisi katsayılarının ařağıdaki gibi yazılabileceğini önceki derslerimizde görmüřtük.

$-T/2 \leq t \leq T/2$ , we have

$$\tilde{x}(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t},$$

$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t) e^{-jk\omega_0 t} dt,$$

$$\omega_0 = 2\pi/T.$$

Temel periyod için, her iki iřaret birbirine eřit olduğundan

$$\tilde{x}(t) = x(t) \text{ for } |t| < T/2$$

Fourier serisi katsayısı  
için

$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_{-\infty}^{+\infty} x(t) e^{-jk\omega_0 t} dt.$$

yazılabilir

$$X(j\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt,$$

Tanımını yapalım. Bu  
durumda

$$a_k = \frac{1}{T} X(jk\omega_0).$$

yazılabilir. Periyodik işaret Fourier serisi gösterilimi  
ile

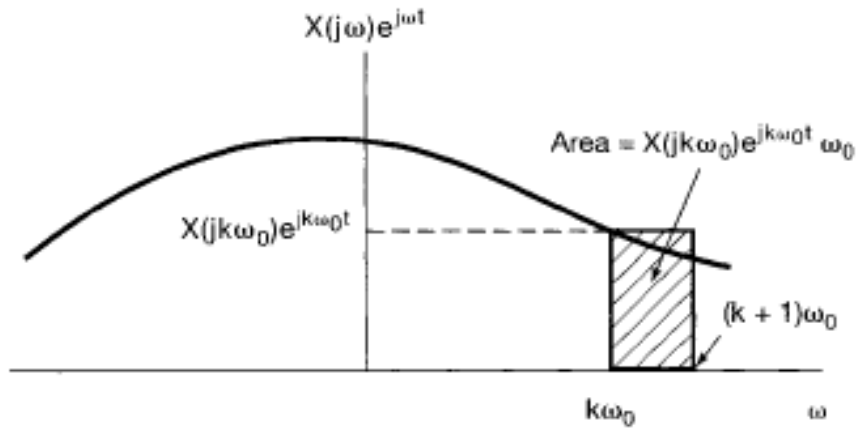
$$\tilde{x}(t) = \sum_{k=-\infty}^{+\infty} \frac{1}{T} X(jk\omega_0) e^{jk\omega_0 t},$$

şeklinde ifade  
edilebilir

$$2\pi/T = \omega_0, \text{ olduğunda}$$

n

$$\tilde{x}(t) = \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jk\omega_0) e^{jk\omega_0 t} \omega_0.$$



$\omega_0 \rightarrow 0$  as  $T \rightarrow \infty$ , içi  
n

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$X(j\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt.$$

Sonlu sayıda maksimum ve minimum noktası içermeli

Sonlu sayıda süreksizlik olmalı ve süreksizliklerde sonlu değer almalı

$$\int_{-\infty}^{+\infty} |x(t)| dt < \infty.$$

### Örnek :

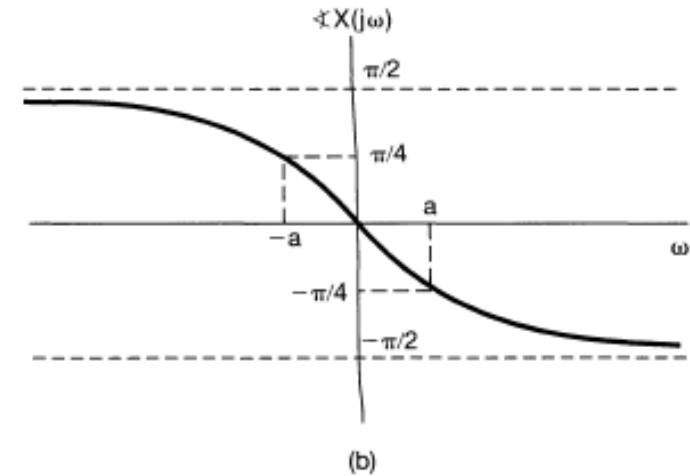
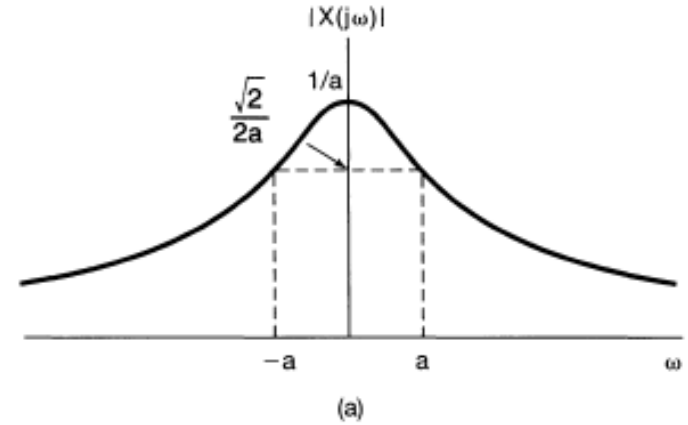
$x(t) = e^{-at} u(t)$   $a > 0$ . şeklinde verilen işaret için Fourier dönüşümü

$$X(j\omega) = \int_0^{\infty} e^{-at} e^{-j\omega t} dt = -\frac{1}{a + j\omega} e^{-(a + j\omega)t} \Bigg|_0^{\infty}.$$

$$X(j\omega) = \frac{1}{a + j\omega}, \quad a > 0.$$

Genlik ve faz

$$|X(j\omega)| = \frac{1}{\sqrt{a^2 + \omega^2}}, \quad \angle X(j\omega) = -\tan^{-1}\left(\frac{\omega}{a}\right).$$

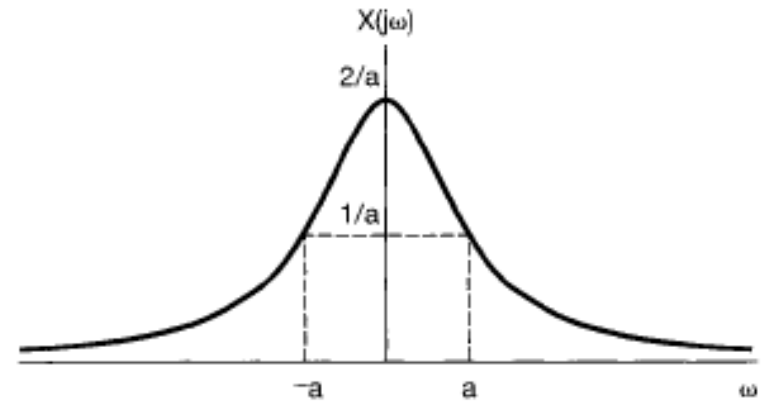
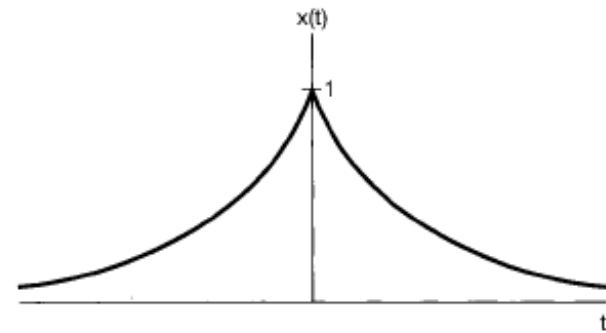


a) Genlik, b) faz  
cevabı

### Örnek :

$x(t) = e^{-a|t|}$ ,  $a > 0$ , şeklinde verilen işaretin Fourier dönüşümü

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{+\infty} e^{-a|t|} e^{-j\omega t} dt = \int_{-\infty}^0 e^{at} e^{-j\omega t} dt + \int_0^{\infty} e^{-at} e^{-j\omega t} dt \\ &= \frac{1}{a - j\omega} + \frac{1}{a + j\omega} \\ &= \frac{2a}{a^2 + \omega^2} \end{aligned}$$



İşaret ve fourier  
dönüşümü

### Örnek :

$x(t) = \delta(t)$ , şeklinde verilen işaretin Fourier dönüşümü

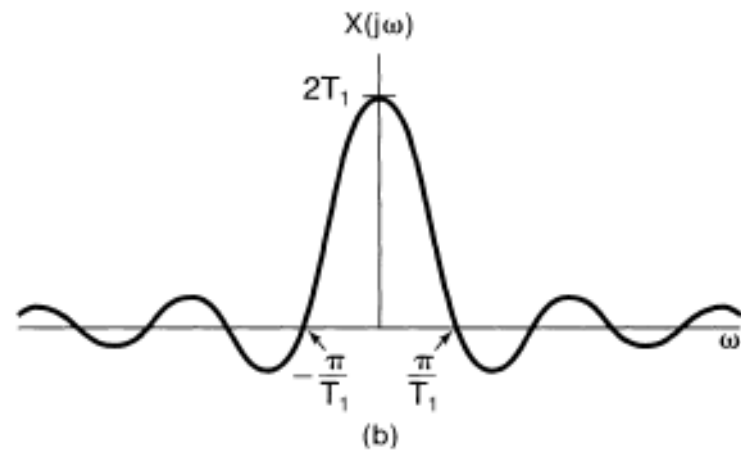
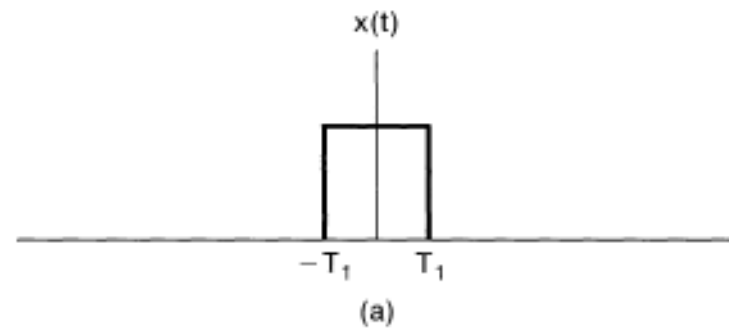
$$X(j\omega) = \int_{-\infty}^{+\infty} \delta(t) e^{-j\omega t} dt = 1.$$

### Örnek :

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases},$$

şeklinde verilen işaretin Fourier dönüşümü

$$X(j\omega) = \int_{-T_1}^{T_1} e^{-j\omega t} dt = 2 \frac{\sin \omega T_1}{\omega}$$

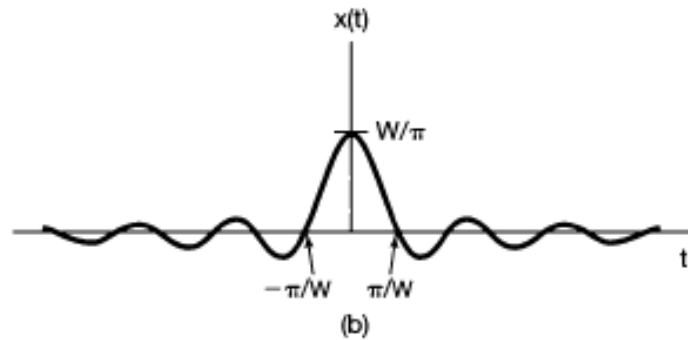
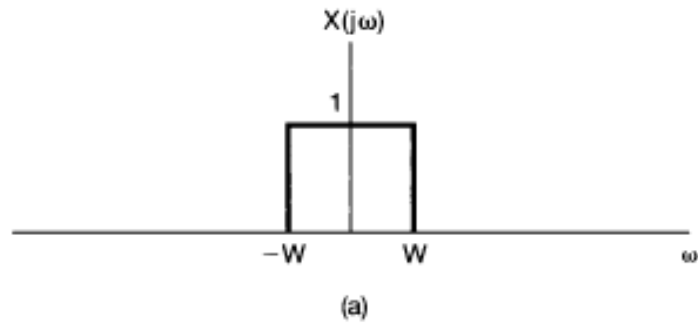


a) İşaret, b) Fourier dönüşümü

**Örnek :**

$$X(j\omega) = \begin{cases} 1, & |\omega| < W \\ 0, & |\omega| > W \end{cases}$$

şeklinde verilen Fourier dönüşümüne karşı gelen zaman domeni işareti bulunuz.



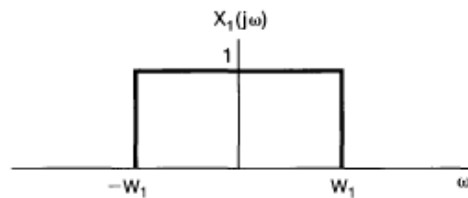
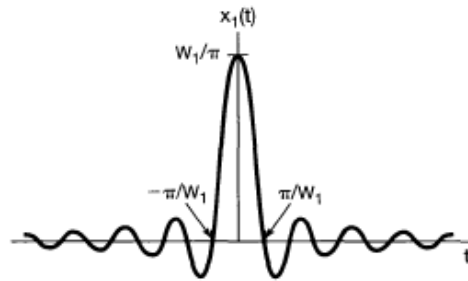
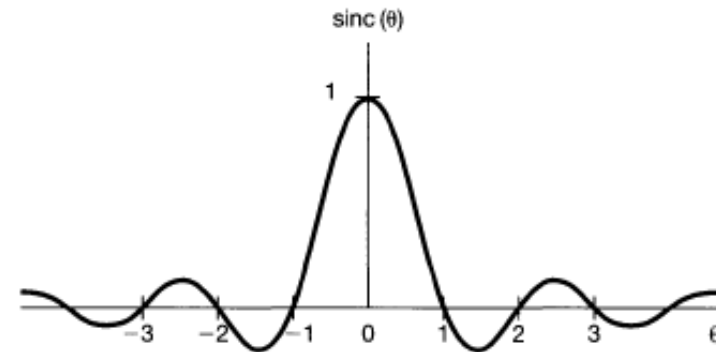
$$x(t) = \frac{1}{2\pi} \int_{-W}^W e^{j\omega t} d\omega = \frac{\sin Wt}{\pi t},$$

Sinc  
işareti:  $\text{sinc}(\theta) = \frac{\sin \pi\theta}{\pi\theta}$ , şeklinde tanımlanır.

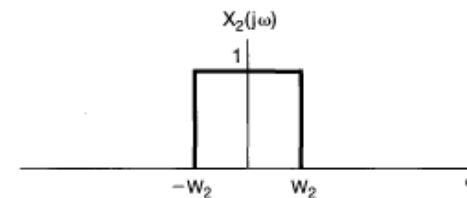
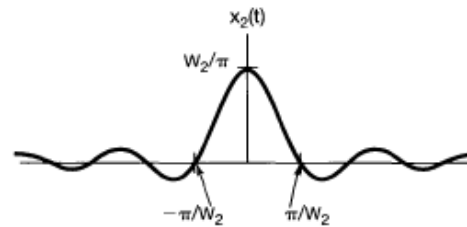


$$\frac{2 \sin \omega T_1}{\omega} = 2T_1 \operatorname{sinc}\left(\frac{\omega T_1}{\pi}\right)$$

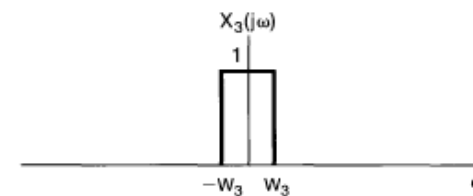
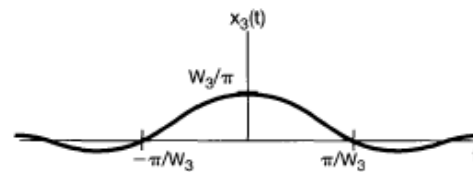
$$\frac{\sin Wt}{\pi t} = \frac{W}{\pi} \operatorname{sinc}\left(\frac{Wt}{\pi}\right).$$



(a)



(b)



(c)

W değerine bağlı olarak elde edilen Fourier dönüşüm çiftleri

## Fourier Dönüşümünün Özellikleri :

### Fourier dönüşüm çifti

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$X(j\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt.$$

### Lineerlik (Doğrusallık) :

$$x(t) \xleftrightarrow{\mathcal{F}} X(j\omega)$$

$$y(t) \xleftrightarrow{\mathcal{F}} Y(j\omega),$$

$$ax(t) + by(t) \xleftrightarrow{\mathcal{F}} aX(j\omega) + bY(j\omega).$$

### Zamanda Öteleme :

$$x(t) \xleftrightarrow{\mathcal{F}} X(j\omega),$$

$$x(t - t_0) \xleftrightarrow{\mathcal{F}} e^{-j\omega t_0} X(j\omega).$$

İspat :  $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega.$

$t$  yerin  $t - t_0$  koyara

$$\begin{aligned} x(t - t_0) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega(t-t_0)} d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} (e^{-j\omega t_0} X(j\omega)) e^{j\omega t} d\omega. \end{aligned}$$

$$\mathcal{F}\{x(t - t_0)\} = e^{-j\omega t_0} X(j\omega).$$

Zamanda öteleme özelliği genlik spektrumunu

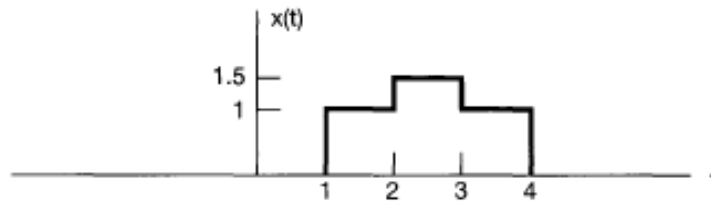
$$\mathcal{F}\{x(t)\} = X(j\omega) = |X(j\omega)| e^{j\angle X(j\omega)},$$

$$\mathcal{F}\{x(t - t_0)\} = e^{-j\omega t_0} X(j\omega) = |X(j\omega)| e^{j[\angle X(j\omega) - \omega t_0]}.$$

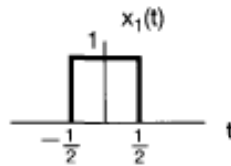
**Örnek :**

$$x(t) = \frac{1}{2}x_1(t - 2.5) + x_2(t - 2.5),$$

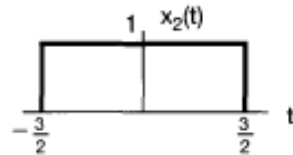
şeklinde verilen işaretin Fourier dönüşümünü bulunuz.



(a)



(b)



(c)

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases}, \quad \text{için}$$

$$X(j\omega) = \int_{-T_1}^{T_1} e^{-j\omega t} dt = 2 \frac{\sin \omega T_1}{\omega},$$

şeklinde

hesaplanmıştı.

$$X_1(j\omega) = \frac{2 \sin(\omega/2)}{\omega} \quad \text{and} \quad X_2(j\omega) = \frac{2 \sin(3\omega/2)}{\omega}.$$

şeklinde doğrudan

vazırlarak,

$$X(j\omega) = e^{-j5\omega/2} \left\{ \frac{\sin(\omega/2) + 2 \sin(3\omega/2)}{\omega} \right\}$$

### Eşlenik :

$$x(t) \xleftrightarrow{\mathcal{F}} X(j\omega),$$

$$x^*(t) \xleftrightarrow{\mathcal{F}} X^*(-j\omega).$$

### İspat :

$$\begin{aligned} X^*(j\omega) &= \left[ \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt \right]^* \\ &= \int_{-\infty}^{+\infty} x^*(t) e^{j\omega t} dt. \end{aligned}$$

$\omega$  by  $-\omega$ .

$$X^*(-j\omega) = \int_{-\infty}^{+\infty} x^*(t) e^{-j\omega t} dt.$$

Reel  $x(t)$

için,

$$X^*(-j\omega) = \int_{-\infty}^{+\infty} x(t) e^{j\omega t} dt = X(j\omega),$$

### Örnek :

$$x(t) = e^{-at} u(t),$$

$$X(j\omega) = \frac{1}{a + j\omega}$$

$$X(-j\omega) = \frac{1}{a - j\omega} = X^*(j\omega).$$

### Türev ve integral Alma :

$$\frac{dx(t)}{dt} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} j\omega X(j\omega) e^{j\omega t} d\omega.$$

$$\frac{dx(t)}{dt} \xleftrightarrow{\mathcal{F}} j\omega X(j\omega).$$

$$\int_{-\infty}^t x(\tau) d\tau \xleftrightarrow{\mathcal{F}} \frac{1}{j\omega} X(j\omega) + \pi X(0) \delta(\omega).$$

### Örnek :

$x(t) = u(t)$  işaretinin Fourier dönüşümünü bulalım

$$g(t) = \delta(t) \xleftrightarrow{\mathcal{F}} G(j\omega) = 1.$$

$$x(t) = \int_{-\infty}^t g(\tau) d\tau$$

$$X(j\omega) = \frac{G(j\omega)}{j\omega} + \pi G(0)\delta(\omega),$$

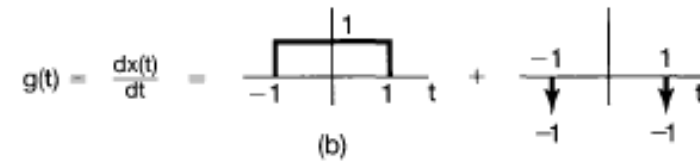
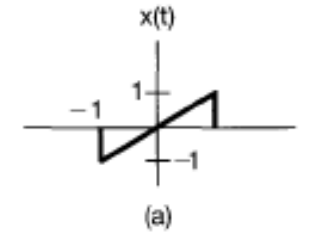
$$G(j\omega) = 1$$

$$X(j\omega) = \frac{1}{j\omega} + \pi\delta(\omega).$$

$$\delta(t) = \frac{du(t)}{dt} \xleftrightarrow{\mathcal{F}} j\omega \left[ \frac{1}{j\omega} + \pi\delta(\omega) \right] = 1$$

### Örnek :

$$g(t) = \frac{d}{dt}x(t).$$



$$G(j\omega) = \left( \frac{2 \sin \omega}{\omega} \right) - e^{j\omega} - e^{-j\omega}$$

$$G(0) = 0.$$

$$X(j\omega) = \frac{G(j\omega)}{j\omega} + \pi G(0)\delta(\omega) \quad \text{integrasyon özelliği}$$

kullanılarak,

$$X(j\omega) = \frac{2 \sin \omega}{j\omega^2} - \frac{2 \cos \omega}{j\omega}$$

## Zaman ve frekans Ölçekleme :

$$x(t) \xleftrightarrow{\mathcal{F}} X(j\omega),$$

$$x(at) \xleftrightarrow{\mathcal{F}} \frac{1}{|a|} X\left(\frac{j\omega}{a}\right),$$

### İspat :

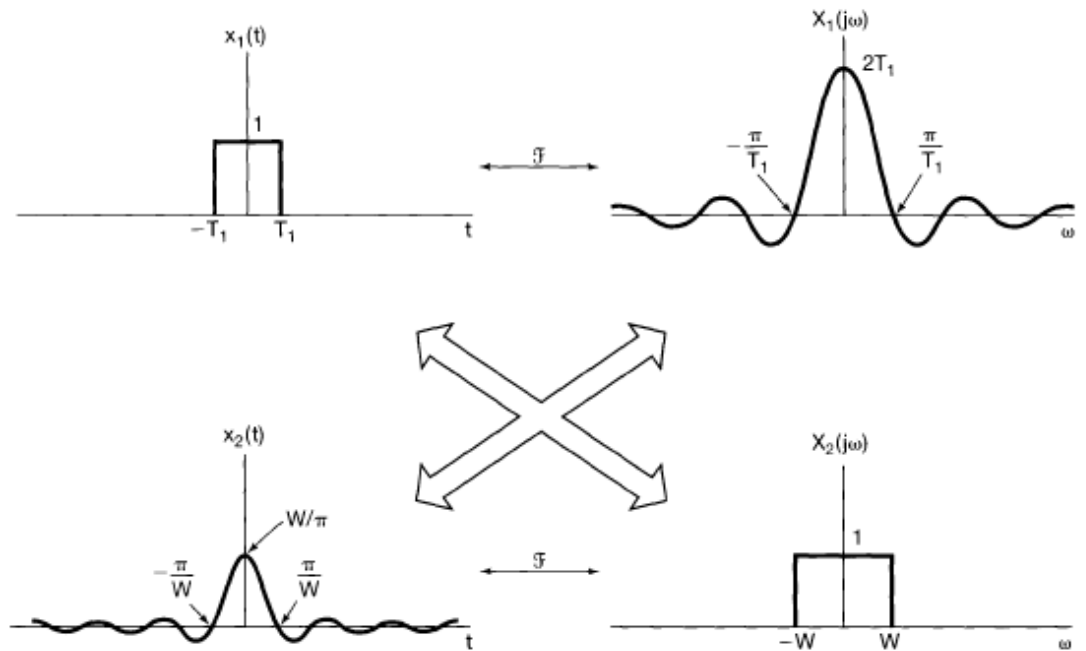
$$\mathcal{F}\{x(at)\} = \int_{-\infty}^{+\infty} x(at) e^{-j\omega t} dt.$$

$$\mathcal{F}\{x(at)\} = \begin{cases} \frac{1}{|a|} \int_{-\infty}^{+\infty} x(\tau) e^{-j(\omega/a)\tau} d\tau, & a > 0 \\ -\frac{1}{|a|} \int_{-\infty}^{+\infty} x(\tau) e^{-j(\omega/a)\tau} d\tau, & a < 0 \end{cases}$$

## Dualite :

$$x_1(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases} \xleftrightarrow{\mathcal{F}} X_1(j\omega) = \frac{2 \sin \omega T_1}{\omega}, \quad \text{dönüşüm çifti}$$

$$x_2(t) = \frac{\sin Wt}{\pi t} \xleftrightarrow{\mathcal{F}} X_2(j\omega) = \begin{cases} 1, & |\omega| < W \\ 0, & |\omega| > W \end{cases} \quad \text{İlşkisi görülmüştü.}$$



### Örnek :

$$g(t) = \frac{2}{1+t^2}.$$

şeklinde verilen işaretin Fourier dönüşümünü dualite özelliğinden yararlanarak hesaplayalım.

$$X(j\omega) = \frac{2}{1+\omega^2}.$$

işaretini düşünelim

$$x(t) = e^{-|t|} \xleftrightarrow{\mathcal{F}} X(j\omega) = \frac{2}{1+\omega^2}.$$

$$e^{-|t|} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left( \frac{2}{1+\omega^2} \right) e^{j\omega t} d\omega.$$

Multiplying this equation by  $2\pi$  and replacing  $t$  by  $-\omega$ , we obtain

$$2\pi e^{-|\omega|} = \int_{-\infty}^{\infty} \left( \frac{2}{1+\omega^2} \right) e^{-j\omega t} d\omega.$$

$$2\pi e^{-|\omega|} = \int_{-\infty}^{\infty} \left( \frac{2}{1+t^2} \right) e^{-j\omega t} dt.$$

$$\mathcal{F} \left\{ \frac{2}{1+t^2} \right\} = 2\pi e^{-|\omega|}$$

### Parseval Bağıntısı :

$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega.$$

### İspat :

$$\begin{aligned} \int_{-\infty}^{+\infty} |x(t)|^2 dt &= \int_{-\infty}^{+\infty} x(t) x^*(t) dt \\ &= \int_{-\infty}^{+\infty} x(t) \left[ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X^*(j\omega) e^{-j\omega t} d\omega \right] dt. \end{aligned}$$

$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X^*(j\omega) \left[ \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt \right] d\omega.$$

$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega.$$

## Konvolüsyon Özelliği :

$$y(t) = h(t) * x(t) \xleftrightarrow{\mathcal{F}} Y(j\omega) = H(j\omega)X(j\omega).$$

İspat :

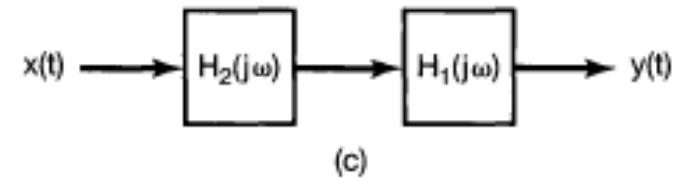
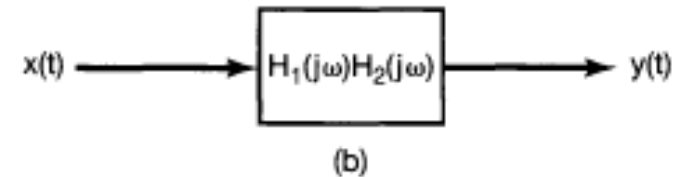
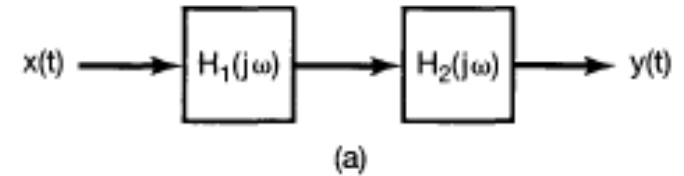
$$y(t) = \int_{-\infty}^{+\infty} x(\tau)h(t - \tau)d\tau.$$

$$Y(j\omega) = \int_{-\infty}^{+\infty} x(\tau) \left[ \int_{-\infty}^{+\infty} h(t - \tau)e^{-j\omega t}dt \right] d\tau.$$

$$Y(j\omega) = \mathcal{F}\{y(t)\} = \int_{-\infty}^{+\infty} \left[ \int_{-\infty}^{+\infty} x(\tau)h(t - \tau)d\tau \right] e^{-j\omega t}dt.$$

$$Y(j\omega) = \int_{-\infty}^{+\infty} x(\tau)e^{-j\omega\tau}H(j\omega)d\tau = H(j\omega) \int_{-\infty}^{+\infty} x(\tau)e^{-j\omega\tau}d\tau.$$

$$Y(j\omega) = H(j\omega)X(j\omega).$$



Şekildeki 3 sistem de eşdeğerdir.

$\int_{-\infty}^{+\infty} |h(t)|dt < \infty$ , koşulunun sağlanması durumunda (Kararlı sistem) sistemin frekans cevabı  $H(j\omega)$  tanımlıdır



### Örnek :

$$h(t) = \delta(t - t_0).$$

şeklinde impuls cevabı verilen sistemin frekans

$H(j\omega) = e^{-j\omega t_0}$ , olarak bulunur. Sistemin

$$\begin{aligned} Y(j\omega) &= H(j\omega)X(j\omega) \\ &= e^{-j\omega t_0}X(j\omega), \end{aligned}$$

$$y(t) = x(t - t_0).$$

### Örnek :

$y(t) = \frac{dx(t)}{dt}$ , işareti için türev özelliği  
kullanılarak Fourier dönüşümü

$$Y(j\omega) = j\omega X(j\omega).$$

$$H(j\omega) = j\omega.$$

türev alıcı sistemin frekans cevabı bulunmuş  
olur.

### Örnek :

$$y(t) = \int_{-\infty}^t x(\tau) d\tau.$$

şeklinde verilen sistemin impuls cevabının birim basamak işareti  $u(t)$   
olduğu görülebilir. Bu durumda integral alıcı sistemin frekans cevabı

$$H(j\omega) = \frac{1}{j\omega} + \pi\delta(\omega).$$

Örnekte verilen işaretin Fourier dönüşümü olarak  
bulunur.

$$\begin{aligned} Y(j\omega) &= H(j\omega)X(j\omega) \\ &= \frac{1}{j\omega}X(j\omega) + \pi X(j\omega)\delta(\omega) \\ &= \frac{1}{j\omega}X(j\omega) + \pi X(0)\delta(\omega), \end{aligned}$$

### Örnek :

$$h(t) = e^{-at}u(t), \quad a > 0,$$

içi

$$x(t) = e^{-bt}u(t), \quad b > 0.$$

n

$y(t) = x(t) * h(t)$  şeklinde tanımlanan çıkış işaretini

$$X(j\omega) = \frac{1}{b + j\omega}$$

$$H(j\omega) = \frac{1}{a + j\omega}.$$

$$Y(j\omega) = \frac{1}{(a + j\omega)(b + j\omega)}$$

$$Y(j\omega) = \frac{A}{a + j\omega} + \frac{B}{b + j\omega},$$

$$Y(j\omega) = \frac{1}{b - a} \left[ \frac{1}{a + j\omega} - \frac{1}{b + j\omega} \right]$$

Ters Fourier dönüşümü alınarak

$$y(t) = \frac{1}{b - a} [e^{-at}u(t) - e^{-bt}u(t)].$$

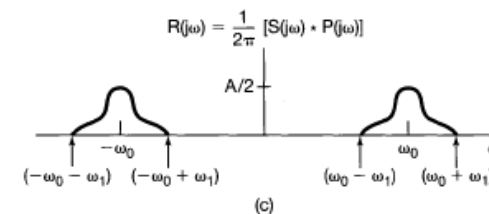
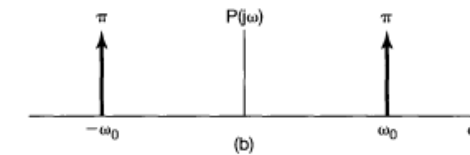
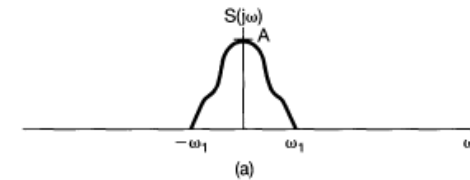
### Çarpım Özelliği :

$$r(t) = s(t)p(t) \longleftrightarrow R(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S(j\theta)P(j(\omega - \theta))d\theta$$

### Örnek :

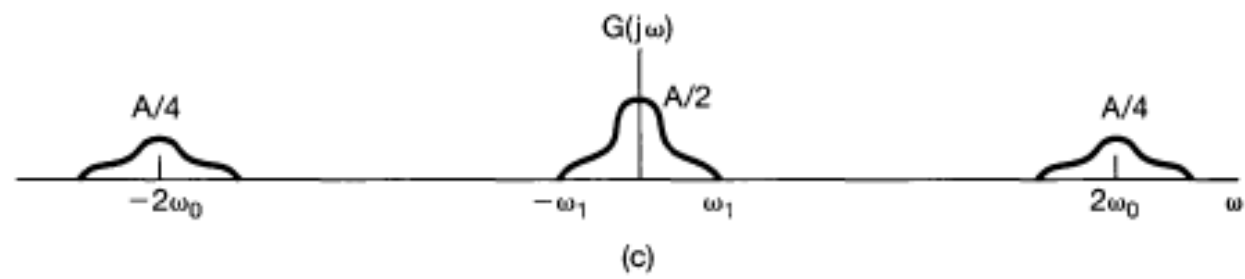
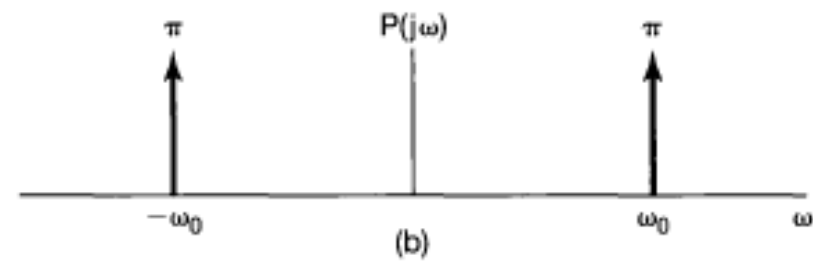
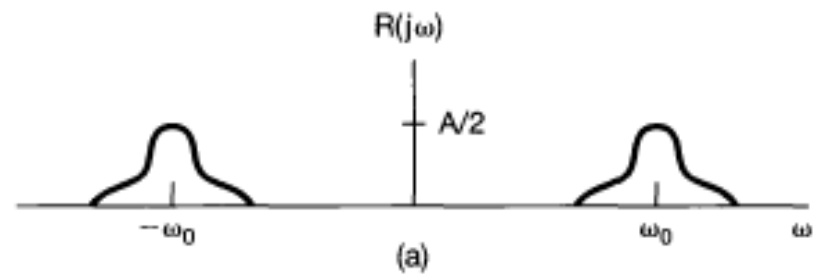
$$p(t) = \cos \omega_0 t.$$

$$P(j\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0),$$



$$R(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S(j\theta)P(j(\omega - \theta))d\theta$$

$$= \frac{1}{2}S(j(\omega - \omega_0)) + \frac{1}{2}S(j(\omega + \omega_0)),$$

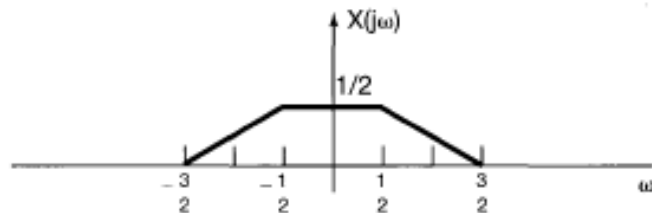


### Örnek :

$$x(t) = \frac{\sin(t) \sin(t/2)}{\pi t^2}$$

$$x(t) = \pi \left( \frac{\sin(t)}{\pi t} \right) \left( \frac{\sin(t/2)}{\pi t} \right)$$

$$X(j\omega) = \frac{1}{2} \mathcal{F} \left\{ \frac{\sin(t)}{\pi t} \right\} * \mathcal{F} \left\{ \frac{\sin(t/2)}{\pi t} \right\}$$



Property	Aperiodic signal	Fourier transform
	$x(t)$ $y(t)$	$X(j\omega)$ $Y(j\omega)$
Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0} X(j\omega)$
Frequency Shifting	$e^{j\omega_0 t} x(t)$	$X(j(\omega - \omega_0))$
Conjugation	$x^*(t)$	$X^*(-j\omega)$
Time Reversal	$x(-t)$	$X(-j\omega)$
Time and Frequency Scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$
Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
Multiplication	$x(t)y(t)$	$\frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\theta)Y(j(\omega - \theta))d\theta$
Differentiation in Time	$\frac{d}{dt} x(t)$	$j\omega X(j\omega)$
Integration	$\int_{-\infty}^t x(t)dt$	$\frac{1}{j\omega} X(j\omega) + \pi X(0)\delta(\omega)$
Differentiation in Frequency	$tx(t)$	$j \frac{d}{d\omega} X(j\omega)$
Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \Re\{X(j\omega)\} = \Re\{X(-j\omega)\} \\ \Im\{X(j\omega)\} = -\Im\{X(-j\omega)\} \\  X(j\omega)  =  X(-j\omega)  \\ \angle X(j\omega) = -\angle X(-j\omega) \end{cases}$
Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
Even-Odd Decomposition for Real Signals	$x_e(t) = \mathcal{E}\{x(t)\}$ [ $x(t)$ real] $x_o(t) = \mathcal{O}\{x(t)\}$ [ $x(t)$ real]	$\Re\{X(j\omega)\}$ $j\Im\{X(j\omega)\}$
Parseval's Relation for Aperiodic Signals		
$\int_{-\infty}^{+\infty}  x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty}  X(j\omega) ^2 d\omega$		

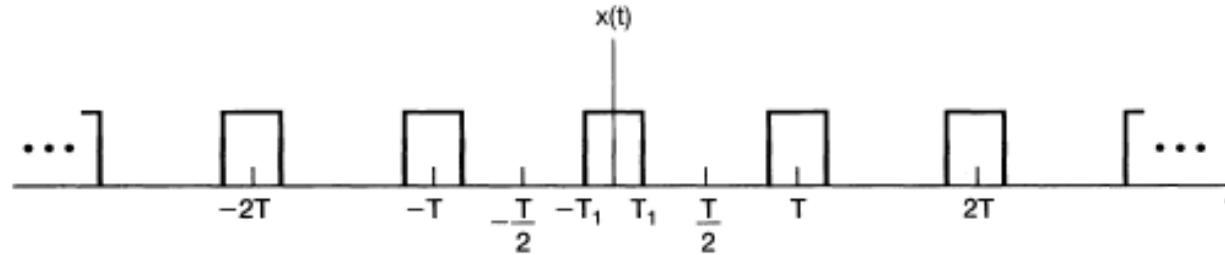
Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$	$a_k$
$e^{j\omega_0 t}$	$2\pi \delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0$ , otherwise
$\cos \omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0$ , otherwise
$\sin \omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0$ , otherwise
$x(t) = 1$	$2\pi \delta(\omega)$	$a_0 = 1$ , $a_k = 0$ , $k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$ )
Periodic square wave		
$x(t) = \begin{cases} 1, &  t  < T_1 \\ 0, & T_1 <  t  \leq \frac{T}{2} \end{cases}$ and $x(t+T) = x(t)$	$\sum_{k=-\infty}^{+\infty} \frac{2 \sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \operatorname{sinc}\left(\frac{k\omega_0 T_1}{\pi}\right) = \frac{\sin k\omega_0 T_1}{k\pi}$
$\sum_{n=-\infty}^{+\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all $k$
$x(t) \begin{cases} 1, &  t  < T_1 \\ 0, &  t  > T_1 \end{cases}$	$\frac{2 \sin \omega T_1}{\omega}$	—
$\frac{\sin Wt}{\pi t}$	$X(j\omega) = \begin{cases} 1, &  \omega  < W \\ 0, &  \omega  > W \end{cases}$	—
$\delta(t)$	1	—
$u(t)$	$\frac{1}{j\omega} + \pi \delta(\omega)$	—
$\delta(t - t_0)$	$e^{-j\omega t_0}$	—
$e^{-at} u(t), \operatorname{Re}\{a\} > 0$	$\frac{1}{a + j\omega}$	—
$te^{-at} u(t), \operatorname{Re}\{a\} > 0$	$\frac{1}{(a + j\omega)^2}$	—
$\frac{t^{n-1}}{(n-1)!} e^{-at} u(t),$ $\operatorname{Re}\{a\} > 0$	$\frac{1}{(a + j\omega)^n}$	—

## Periyodik işaretlerin Fourier dönüşümü ;

$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$ , şeklinde Fourier serisine açılan periyodik bir işaret için Fourier dönüşümü , 2 tarafın da dönüşümü alınarak

$X(j\omega) = \sum_{k=-\infty}^{+\infty} 2\pi a_k \delta(\omega - k\omega_0)$ , şeklinde tanımlanabilir.

### Örnek :



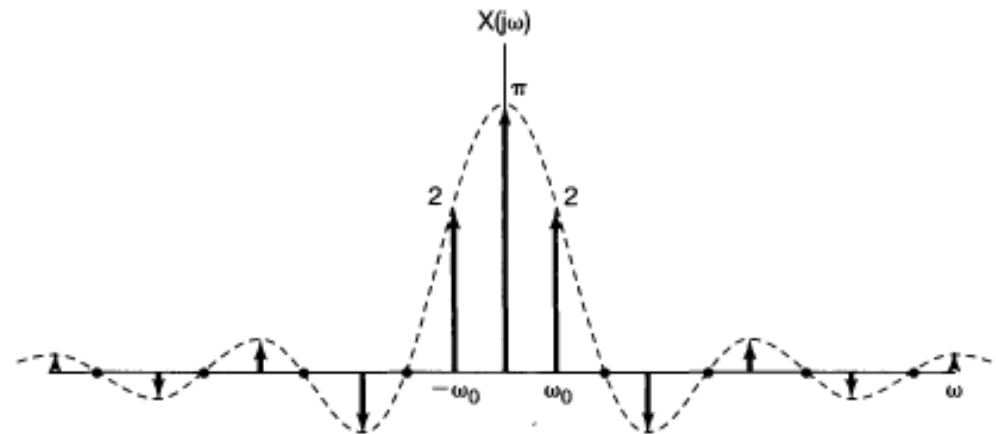
şeklinde verilen periyodik işaret  $x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & T_1 < |t| < T/2 \end{cases}$  ve Fourier serisi  $a_k = \frac{2 \sin(k\omega_0 T_1)}{k\omega_0 T}$ , için,   
şeklinde katsayıları

$T = 4T_1$  için

$a_k = \frac{\sin k\omega_0 T_1}{\pi k}$ , İşaretin Fourier dönüşümü

$$X(j\omega) = \sum_{k=-\infty}^{+\infty} \frac{2 \sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0),$$

yazılabilir



### Örnek :

$x(t) = \sin \omega_0 t$ , işareti için Fourier serisi

$$a_1 = \frac{1}{2j}, \quad \text{katsayıları}$$

$$a_{-1} = -\frac{1}{2j},$$

$$a_k = 0, \quad k \neq 1 \text{ or } -1.$$

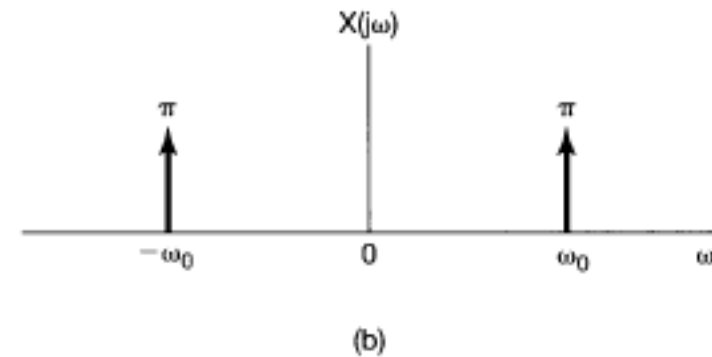
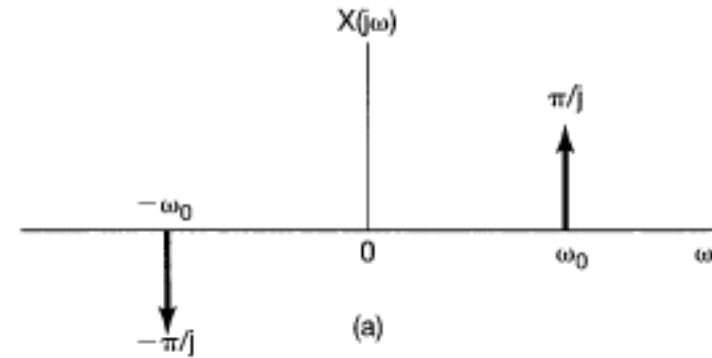
$x(t) = \cos \omega_0 t$ , işareti için Fourier serisi  
katsayıları

$$a_1 = a_{-1} = \frac{1}{2},$$

$$a_k = 0, \quad k \neq 1 \text{ or } -1.$$

bulunmuştu.

Karşı gelen Fourier  
dönüşümleri



(a)  $x(t) = \sin \omega_0 t$ ; (b)  $x(t) = \cos \omega_0 t$ .

### Örnek :

$$x(t) = \sum_{k=-\infty}^{+\infty} \delta(t - kT), \quad \text{işareti için Fourier serisi katsayıları} \quad a_k = \frac{1}{T} \int_{-T/2}^{+T/2} \delta(t) e^{-jk\omega_0 t} dt = \frac{1}{T}.$$

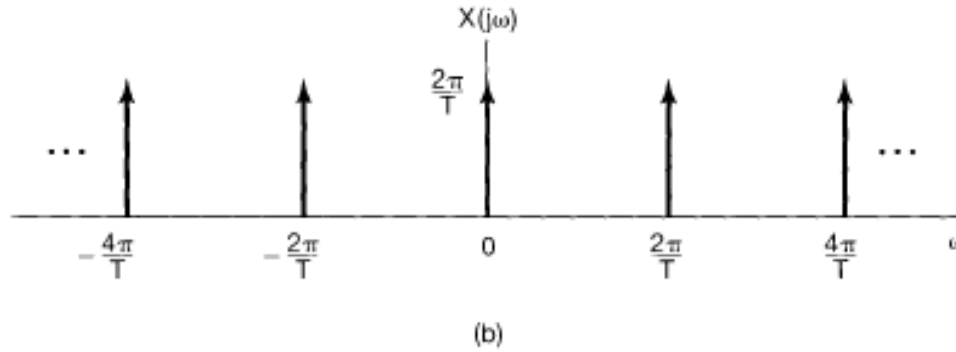
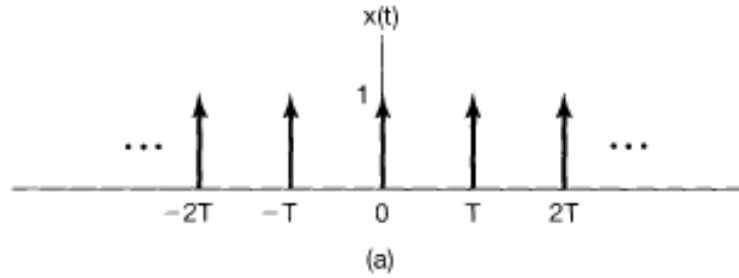
şeklinde  
edilmişti.

elde İşaretin  
dönüşümü

Fourie

$$X(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta\left(\omega - \frac{2\pi k}{T}\right).$$

bulunur.



a) İmpuls(dürtü katarı b) Fourier dönüşümü



## LZD sistemlerin frekans domeninde modellenmesi

Fourier dönüşümünün konvolusyon özelliği

$$Y(j\omega) = H(j\omega)X(j\omega),$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)},$$

şeklinde sistem çıkışının bulunabildiği gösterilmiştir. Benzer şekilde fark denklemleriyle modellenen sistemler

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k}.$$

2 tarafında Fourier dönüşümü

$$\mathcal{F}\left\{\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k}\right\} = \mathcal{F}\left\{\sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k}\right\}.$$

Lineerlik özelliğinden

$$\sum_{k=0}^N a_k \mathcal{F}\left\{\frac{d^k y(t)}{dt^k}\right\} = \sum_{k=0}^M b_k \mathcal{F}\left\{\frac{d^k x(t)}{dt^k}\right\},$$

$$\sum_{k=0}^N a_k (j\omega)^k Y(j\omega) = \sum_{k=0}^M b_k (j\omega)^k X(j\omega),$$

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^M b_k (j\omega)^k}{\sum_{k=0}^N a_k (j\omega)^k},$$

bulunur.

### Örnek :

$\frac{dy(t)}{dt} + ay(t) = x(t)$ , şeklinde giriş-çıkış ilişkisi tanımlanan sistem için frekans cevabı  $H(j\omega) = \frac{1}{j\omega + a}$ .

ve impuls  $h(t) = e^{-at}u(t)$ , olarak  
cevabı bulunur.

### Örnek :

Fark  $\frac{d^2y(t)}{dt^2} + 4\frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$ , şeklinde verilen LZD sistem için frekans  
denklemini cevabı

$H(j\omega) = \frac{(j\omega) + 2}{(j\omega)^2 + 4(j\omega) + 3}$ , bulunur. Sistemin impuls cevabı ters Fourier dönüşümü alınarak elde edilir

Frekans cevabını çarpanlarına  $H(j\omega) = \frac{j\omega + 2}{(j\omega + 1)(j\omega + 3)}$ ,  
ayırarak

Kısmi kesirlere ayırma (rezidü yöntemi)  $G(v) = \frac{A_{11}}{v + 1} + \frac{A_{21}}{v + 3}$ ,  
kullanılarak,

$$A_{11} = [(v + 1)G(v)]|_{v=-1} = \frac{-1 + 2}{-1 + 3} = \frac{1}{2},$$
$$A_{21} = [(v + 3)G(v)]|_{v=-3} = \frac{-3 + 2}{-3 + 1} = \frac{1}{2}.$$

$$H(j\omega) = \frac{\frac{1}{2}}{j\omega + 1} + \frac{\frac{1}{2}}{j\omega + 3}.$$

$$h(t) = \frac{1}{2}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t).$$

### Örnek :

$$x(t) = e^{-t}u(t).$$

$$Y(j\omega) = H(j\omega)X(j\omega) = \left[ \frac{j\omega + 2}{(j\omega + 1)(j\omega + 3)} \right] \left[ \frac{1}{j\omega + 1} \right] \\ = \frac{j\omega + 2}{(j\omega + 1)^2(j\omega + 3)}.$$

$$Y(j\omega) = \frac{A_{11}}{j\omega + 1} + \frac{A_{12}}{(j\omega + 1)^2} + \frac{A_{21}}{j\omega + 3},$$

$$G(v) = \frac{A_{11}}{v + 1} + \frac{A_{12}}{(v + 1)^2} + \frac{A_{21}}{v + 3},$$

$$A_{ik} = \frac{1}{(\sigma_i - k)!} \left[ \frac{d^{\sigma_i - k}}{dv^{\sigma_i - k}} [(v - \rho_i)^{\sigma_i} G(v)] \right] \Big|_{v=\rho_i}.$$

$$v = j\omega, G(v)$$

$$A_{11} = \frac{1}{(2 - 1)!} \frac{d}{dv} [(v + 1)^2 G(v)] \Big|_{v=-1} = \frac{1}{4},$$

$$A_{12} = [(v + 1)^2 G(v)] \Big|_{v=-1} = \frac{1}{2},$$

$$A_{21} = [(v + 3)G(v)] \Big|_{v=-3} = -\frac{1}{4}.$$

$$A_{11} = \frac{1}{4}, \quad A_{12} = \frac{1}{2}, \quad A_{21} = -\frac{1}{4},$$

bulunarak

$$Y(j\omega) = \frac{\frac{1}{4}}{j\omega + 1} + \frac{\frac{1}{2}}{(j\omega + 1)^2} - \frac{\frac{1}{4}}{j\omega + 3}.$$

yazılabilir

$$e^{-at}u(t), \operatorname{Re}\{a\} > 0 \quad \frac{1}{a + j\omega}$$

ve

$$te^{-at}u(t), \operatorname{Re}\{a\} > 0 \quad \frac{1}{(a + j\omega)^2}$$

dönüşüm çiftleri

kullanılarak

$$y(t) = \left[ \frac{1}{4}e^{-t} + \frac{1}{2}te^{-t} - \frac{1}{4}e^{-3t} \right] u(t).$$