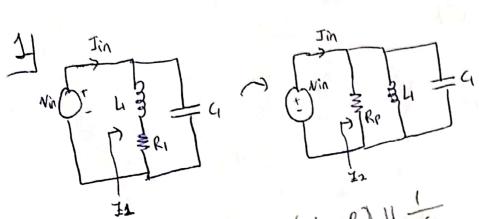
EHB 336E HW#7

Serden Sait Franil 040190025 S. S. your



$$\frac{1}{2}(s) = (sL_1 + R_1) | \frac{1}{sC_1} = \frac{sL_1 + R_1}{sC_1} =$$

$$\frac{1}{2}(s) = (sL_1 + R_1) \left(\frac{1}{sC_1} + \frac{1}{sC_1} +$$

$$\frac{\left(1-\omega^{2}L(\zeta)+\dot{s}\omega\zeta(R)\right)}{\left(1-\omega^{2}L(\zeta)-\dot{s}\omega\zeta(R)\right)} = \frac{\left(1-\omega^{2}L(\zeta)+\dot{s}\omega\zeta(R)\right)}{\left(1-\omega^{2}L(\zeta)-\dot{s}\omega\zeta(R)\right)} = \frac{\left(1-\omega^{2}L(\zeta)+\dot{s}\omega\zeta(R)\right)}{\left(1-\omega^{2}L(\zeta)-\dot{s}\omega\zeta(R)\right)} = \frac{1}{8}\left(1-\omega^{2}L(\zeta)-\dot{s}\omega\zeta(R)\right)$$

$$\frac{1}{(sw)} = \frac{1}{(1-w^2h(1)+swc_1R_1)} + \frac{1}{swc_1R_1} = \frac{1}{(1-w^2h(1)-swc_1R_1)} = \frac{1}{(1-w^2h(1)-swh(1)-$$

$$Also, calculate = \frac{1}{5}(s) = \frac{1}{5}(s)$$

-> By equating real and imaginary parts we can find a solution or by simply

By equating real and imaginary pects we have
$$\frac{1}{R_1 + \hat{s}wL_1} = \frac{1}{R_p} + \frac{1}{\hat{s}wL_1} = \frac{1}{R_p} + \frac{1}{\hat{s}wL_1} + \frac{1}{\hat{s}wL_1} = \frac{1}{\hat{s}wL_1 + \hat{s}wL_1} = \frac{1}{\hat{s}wL_1 + \hat{s}wL_1}$$

$$\frac{1}{R_1 + \dot{s}wL_1} + \dot{s}wL_1 + \dot{s}wL_1 + \dot{s}wL_1 + \dot{s}wL_1 = \frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

$$\frac{1}{R_1 + \dot{s}wL_1} + \dot{s}wL_1 = \frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

$$\frac{1}{R_1 + \dot{s}wL_1} + \frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

$$\frac{1}{R_1 + \dot{s}wL_1} + \frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

$$\frac{1}{R_1 + \dot{s}wL_1} + \frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

$$\frac{1}{\dot{s}wL_1 + \dot{k}\rho}$$

Julike = juliki + ReR, -w2Li2 + julike by equating these impedances RPRI = - JWLIKI + W2Li2

$$RPR_1 = -3\omega L_1 R_1 + \omega^2 L_1^2$$

$$RP = -3\omega L_1 + \frac{\omega^2 L_1^2}{R_1}$$

· Break the loop at note Y.

Tret
$$(\hat{s}\omega) = 1$$

Tret

 $1_{\text{tot}} = 1_{\text{tot}} = 1_{\text{tot}}$
 $1_{\text{tot}} = 1_{\text{$

$$T_{ret} = gm\Omega_{\overline{1}} = -gm\Omega_{x} = -gmT_{1}Z_{1} ; Z_{1} = \frac{1}{Y_{Q_{1}} + Y_{C_{2}} + Y_{RL}} = \frac{1}{gm+SC_{2}+1|RL}$$

$$I_{ret} = -gm \frac{1}{gm + SC_2 + 1|R_L}$$

$$I_1 = -I_{lest} \cdot \frac{1}{1} + SL + \frac{1}{2}I$$

$$I_{ret} = -gm \frac{1}{gm + SC_2 + 1|R_L} \left(-I_{lest} + \frac{1}{3C_1} + SL + \frac{1}{gm + SC_2 + 1|R_L}\right)$$

$$gm \downarrow S$$

$$gm \downarrow S$$

$$gm \downarrow S$$

$$\frac{Int}{Itest} = \frac{gmLs}{\left(gm+SC_2+(1)R_L\right)\left(\frac{1}{sc_1}+sL\right)+1}$$

$$\frac{1}{\text{ret}} = -gm \frac{2}{gm + SC_2 + 11RL} \left(\frac{1}{3C_1} + \frac{1}{3C_1$$

at
$$\frac{3wgmL}{3wgmL} = 1$$

The only want this term to be left so that swymi = 1 Therefore, imaginary and real parts in the denominator should be zero.

$$\Rightarrow \left(\frac{WL}{RL} - \frac{gm}{WC_1} - \frac{1}{WR_1C_1} = 0\right) \quad \beta \left(\frac{C_2}{C_1} + 1 - W^2C_2L = 0\right)$$

$$\int_{C_1}^{C_2} \frac{(2+1-w^2C_2L=0)}{(1+1-w^2C_2L=0)}$$

$$=) \frac{c_2}{c_1} + 1 = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\frac{c_1 + c_2}{c_1 + c_2} = \omega^2 c_2 L$$

$$\Rightarrow \frac{WL}{RL} = \frac{qm}{wc_1} - \frac{1}{wR_LC_1} = 0$$

$$\frac{WL}{RL} = \frac{qm}{wc_1} - \frac{1}{wR_L}$$

$$\frac{WL}{RL} = \frac{1}{wc_1} \left(qm + \frac{1}{RL} \right) \Rightarrow w^2Lc_1 = qmR_L + 1$$

$$\frac{c_1 + c_2}{gc_2 t} \neq 0$$

$$\frac{c_1}{gmR_L} = \frac{c_1}{c_2}$$

To ensure the oscillation
$$[gmk_L \ge \frac{1}{2}]$$
 we know sortwation voltages $L^{\dagger} = -L^{\dagger} = 10V$

We know sortwation voltages $L^{\dagger} = -L^{\dagger} = 10V$

We know sortwation voltages $L^{\dagger} = -L^{\dagger} = 10V$

and since this is an autoble multivibration, the arrange of the autoble multivibration voltage is $M_{\star} = L^{\dagger} = \frac{2}{3}L^{\dagger}$
 $C_{\star} = 0.01$
 $C_{\star} = 0.01$

Let's take the natural logorithm of
$$\frac{2}{3}t^2 = \frac{1}{3}t^2 = \frac{1}{5}t^4 = \frac{1}{5$$

let's toke the natural logarithm of
$$\frac{1}{3}k^2 = \frac{3}{3}k^2 = \frac{105}{3}k^2 =$$

let's sold
$$\ln (e^{-t/RC}) = -\ln 5$$
 \Rightarrow $t/RC = \frac{t}{\ln 5}$ $\Rightarrow \frac{10^{-3}}{\ln 5} = R_x = 0.621 \text{ ms}$
 $t = \frac{1}{2} = \frac{1}{2 \text{ for}} = \frac{1}{2 \times 500} = \frac{10^{-3} \text{ s}}{2 \times$

$$t = \frac{1}{2} = \frac{1}{2 f_{ox}} = \frac{1}{2 \times 500} = \frac{10^{-3} \text{s}}{2 \times 500} = \frac{10^{-3} \text{s}}{62.1 \times 10^{-3}} = \frac{1}{62.1 \times 10^{-3}} = \frac{1}$$

 $N_{x}=L^{t}$. $\frac{10}{30}=\frac{1}{3}L^{t}=1$ $N_{x}=L^{t}-(L^{t}+\frac{1}{3}L^{t})e^{-\frac{1}{3}L^{t}}=L^{t}-\frac{1}{3}L^{t}e^{-\frac{1}{3}L^{t}}=L^{t}-\frac{$ b) Now, potentionelis is connected to node B.

$$N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$$

 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{30} = \frac{1}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{\dagger} \Rightarrow N_x = L^{-(L+3)}$
 $N_x = L^{\dagger} \cdot \frac{10}{3}L^{$

$$\frac{1}{R_{x}(x)} = -\ln 2 \implies t = -\ln 2(R_{x}(x)) = -\ln 2(R_{x}$$

Avial = 100 ; ri= 10062, ; ci= 50pf ro=SLQ, it by connected > AVII=70 f3-86 = 5062 5 100 \$ P. T. Cy $Av_1L = \frac{Vo^2}{Vg} = \frac{Vx}{Vg} \cdot \frac{Vy}{Vx} \cdot \frac{No^2}{Vy} = \frac{100k\Omega}{100k\Omega + 5k\Omega} \cdot \frac{Ry}{ky + 5k} = \frac{36}{ky + 5k}$ When Iy is connected $\Rightarrow \frac{Ry}{Ry+Sk} = \frac{1}{10} \cdot \frac{105}{100} = 0.735 \Rightarrow 0.735 Ry + 3675 = Ry$ 3675 = 0.265 87 Py = 3675 = 13.868 652 · Zin = Kin Cin = BOPF (1006 11562) $= 6 \times 10^{-11} \left(\frac{5 \times 10^8}{105 \times 10^3} \right) = 0.238 \text{ } \mu\text{s}$ • $f_{in} = \frac{1}{2\pi Z_{in}} = \frac{1}{2\pi (0.238 \mu s)} = 668.45 \text{ kHz}$ · Tout = Rout Cout = (13.868kn 11 Skn) (out =) (out = 7 (13 xbike 11 562) 1 = 501s => Zout = 3.183 µs (out = 866.41 QF We should compensate the output pole. By using the inductor formula given as; $L = \frac{RAR_{B}^{2}Cout}{2ri}; \quad RA = Rg+ri = 5kR+13.868kQ = 18.868kQ = 3.675k$ RB = R9 11 ri = 5102 11 13.868 LOZ = 3.675 LOZ $L = \frac{(19.868 \text{ kg})(3.675 \text{ kg})^2(866.11 \times 10^{-12})}{} = 7.957 \times 10^{-3} \text{ H}$ ¥ 7.96mH 2 (13.868/2)