

FitB 206- Uygulama 2

Uğurhan Yıldırım

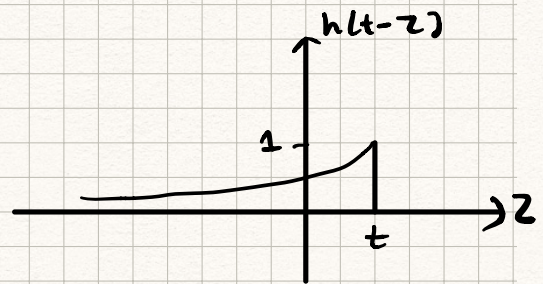
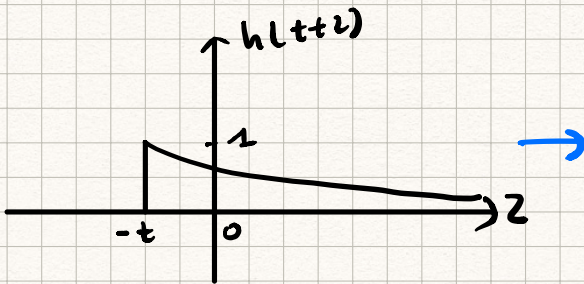
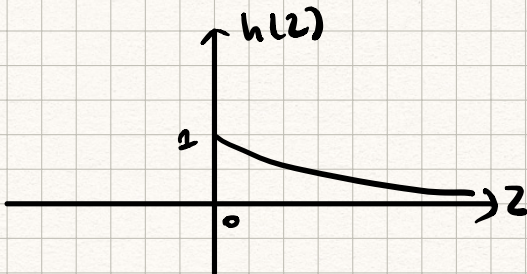
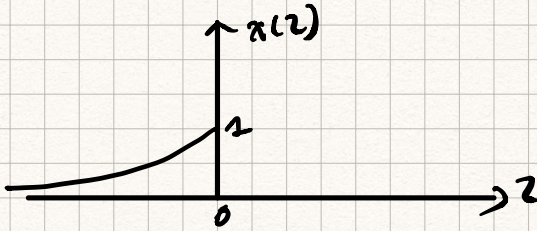
1

$h(t)$ dürtü yanıtına sahip DİD bir sistemin girişine $x(t)$ uygulanmaktadır. Bu girişe karşı çıkan $y(t)$ çıkışını bulunuz.

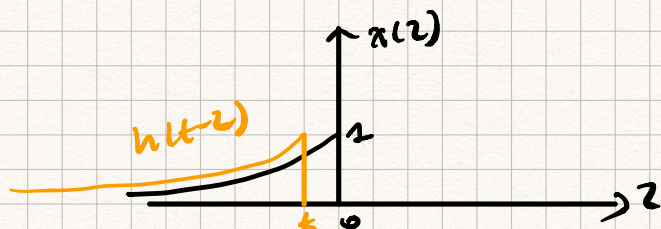
$$h(t) = e^{-at} \cdot u(t),$$

$$x(t) = e^{at} \cdot u(-t), \quad a > 0.$$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$



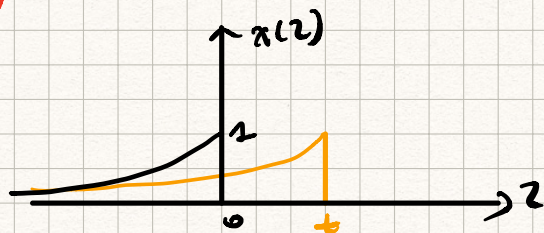
④ $t < 0$



$$y(t) = \int_{-\infty}^t e^{az} e^{-a(t-z)} dz = e^{-at} \int_{-\infty}^t e^{2az} dz = \frac{e^{-at}}{2a} \left(e^{2az} \Big|_{-\infty}^t \right)$$

$$= \frac{e^{-at}}{2a} (e^{2at} - 0) = \frac{e^{at}}{2a}$$

⑤ $t \geq 0$

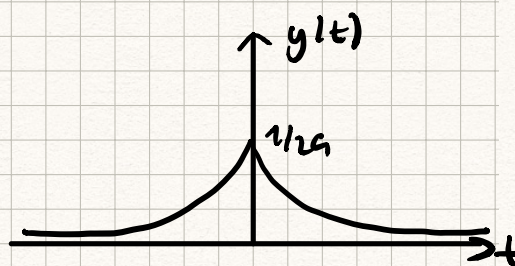


$$y(t) = \int_{-\infty}^0 e^{az} e^{-a(t-z)} dz = e^{-at} \int_{-\infty}^0 e^{2az} dz$$

$$= \frac{e^{-at}}{2a} (1 - 0) = \frac{e^{-at}}{2a}$$

⑥

$$y(t) = \begin{cases} e^{at}/2a, & t < 0 \\ e^{-at}/2a, & t \geq 0 \end{cases}$$



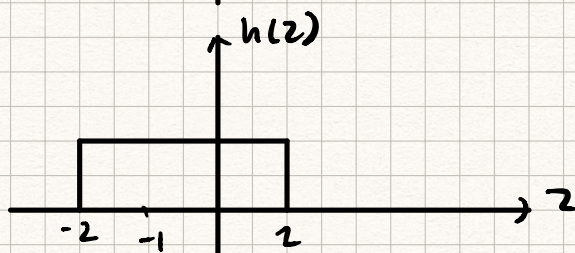
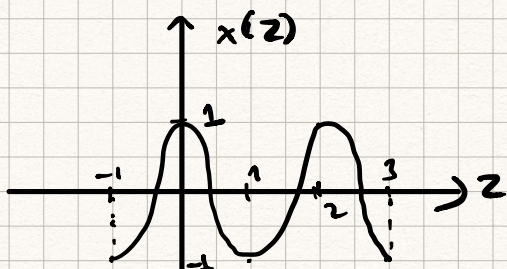
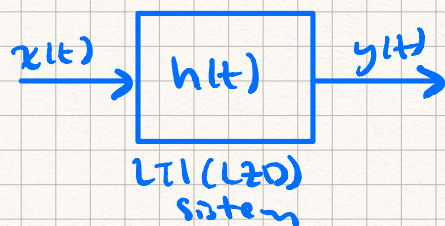
2

$$x(t) = \cos(\pi t) [u(t+1) - u(t-3)] \text{ ve}$$

$$h(t) = u(t+2) - u(t-1) \text{ olmak üzere,}$$

$$y(t) = x(t) * h(t) \text{ yi bulunuz.}$$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(z) h(t-z) dz$$

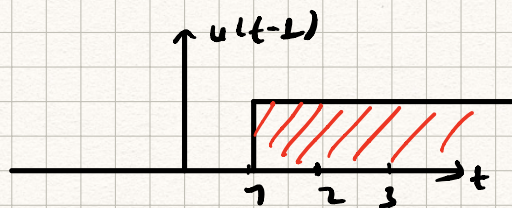
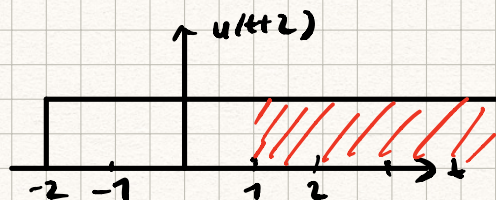


shifting
 $h(t+2)$

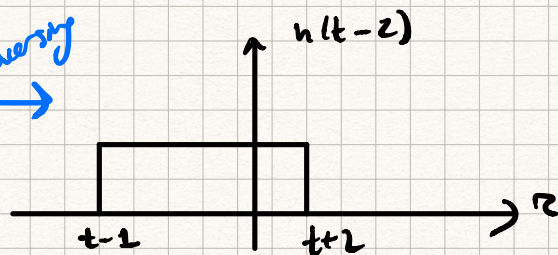


$$\cos(\pi t) = \cos(2\pi f t)$$

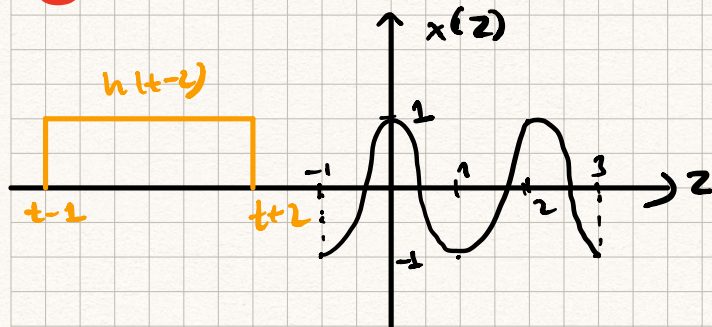
$$f_0 = 1/2, T_0 = \frac{1}{f_0} = 2$$



reversing

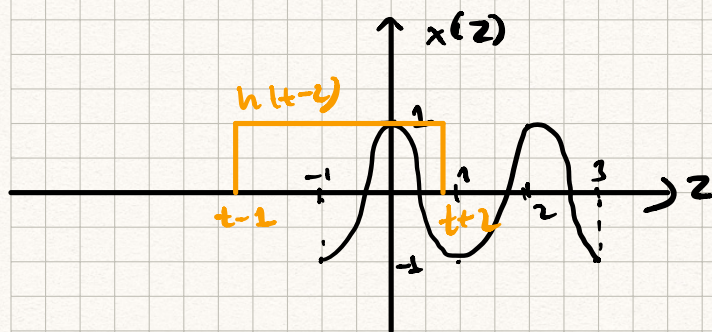


$$③ \quad t+2 < -1 \Rightarrow t < -3$$



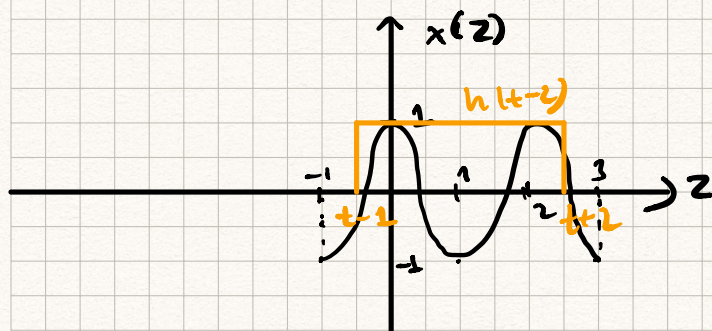
$$y(t) = 0$$

$$④ \quad t+2 > -1, \quad t-1 < -1 \Rightarrow -3 \leq t < 0$$



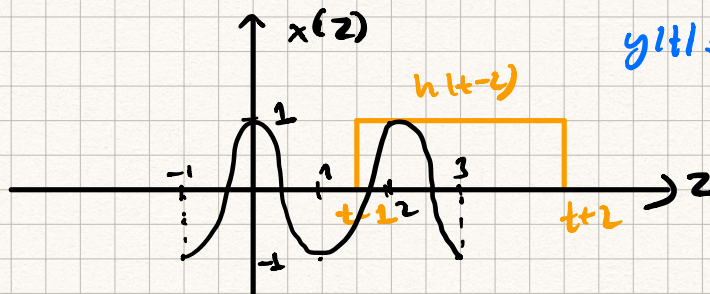
$$\begin{aligned} y(t) &= \int_{-1}^{t+2} \cos(\pi z) \cdot 1 \, dz \\ &= \frac{1}{\pi} \sin \pi z \Big|_{-1}^{t+2} \\ &= \frac{1}{\pi} \sin \pi(t+2) - \frac{1}{\pi} \sin(-\pi) \\ &= \frac{1}{\pi} \sin(\pi t), \quad -3 \leq t < 0 \end{aligned}$$

$$⑤ \quad t-1 > -1, \quad t+2 < 3 \Rightarrow 0 \leq t < 1$$



$$\begin{aligned} y(t) &= \int_{t-1}^{t+2} \cos(\pi z) \, dz \\ &= \frac{1}{\pi} \sin(\pi(t+2)) - \frac{1}{\pi} \sin(\pi(t-1)) \\ &= \frac{1}{\pi} \sin(\pi t) + \frac{1}{\pi} \sin(\pi t) = \frac{2}{\pi} \sin \pi t \end{aligned}$$

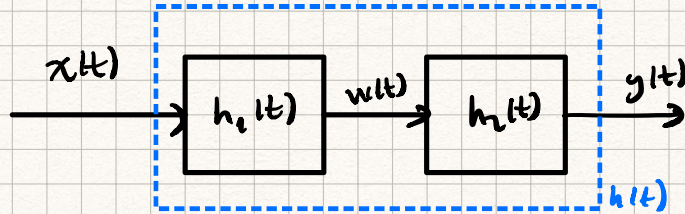
$$⑥ \quad t+2 > 3, \quad t-1 < 3 \Rightarrow 1 \leq t < 4$$



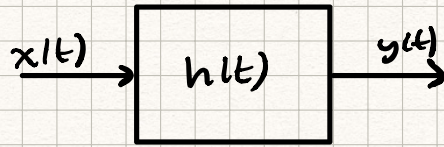
$$\begin{aligned} y(t) &= \int_{t-1}^3 \cos(\pi z) \, dz \\ &= \frac{1}{\pi} \sin(3\pi) - \frac{1}{\pi} \sin(\pi(t-1)) \\ &= \frac{1}{\pi} \sin(\pi t) \end{aligned}$$

$$y(t) = \begin{cases} 0 & , t < -3 \text{ ve } t > 4 \\ \frac{1}{\pi} \sin(\pi t) & , -3 \leq t < 0 \text{ ve } 1 \leq t < 4 \\ \frac{2}{\pi} \sin(\pi t) & , 0 \leq t < 1 \end{cases}$$

3)



Yukarıdaki kaskat DTD sistem için $h_1(t) = e^{-2t} u(t)$ ve $h_2(t) = 2e^{-t} u(t)$ olarak verilmiştir. Tüm sistemin dürtü yanıtı $h(t)$ 'yi bulunuz.



$$\left. \begin{aligned} w(t) &= x(t) * h_1(t) \\ y(t) &= w(t) * h_2(t) \end{aligned} \right\} y(t) = [x(t) * h_1(t)] * h_2(t)$$

$$y(t) = x(t) * \underbrace{[h_1(t) * h_2(t)]}_{h(t)}$$

Tüm sistemin dürtü yanıtı:

$$h(t) = h_1(t) * h_2(t)$$

$$h(t) = \int_{-\infty}^{\infty} h_1(z) h_2(t-z) dz = \int_{-\infty}^{\infty} e^{-2z} u(z) 2 e^{-(t-z)} u(t-z) dz$$

$$= 2 (e^{-t} - e^{-2t}) u(t)$$