

Sürekli Zamanlı Periyodik İşaretler için Fourier Serisi gösterilimi

Özfonksiyonlar

LZD sistemin

$$x(t) = e^{st}$$

girişine cevabını bulalım.

Sistem çıkışı

$$\begin{aligned} y(t) &= \int_{-\infty}^{+\infty} h(\tau)x(t-\tau) d\tau \\ &= \int_{-\infty}^{+\infty} h(\tau)e^{s(t-\tau)} d\tau. \end{aligned}$$

$$y(t) = e^{st} \int_{-\infty}^{+\infty} h(\tau)e^{-s\tau} d\tau.$$

$$y(t) = H(s)e^{st},$$

$$H(s) = \int_{-\infty}^{+\infty} h(\tau)e^{-s\tau} d\tau.$$

Benzer şekilde

$$x(t) = a_1 e^{s_1 t} + a_2 e^{s_2 t} + a_3 e^{s_3 t}.$$

Şeklinde verilen giriş işareti için sistem çıkışı

$$a_1 e^{s_1 t} \longrightarrow a_1 H(s_1) e^{s_1 t},$$

$$a_2 e^{s_2 t} \longrightarrow a_2 H(s_2) e^{s_2 t},$$

$$a_3 e^{s_3 t} \longrightarrow a_3 H(s_3) e^{s_3 t},$$

$$y(t) = a_1 H(s_1) e^{s_1 t} + a_2 H(s_2) e^{s_2 t} + a_3 H(s_3) e^{s_3 t}.$$

Sonuç olarak,

$$x(t) = \sum_k a_k e^{s_k t},$$

şeklinde modellenen işaret için sistemin cevabı

$$y(t) = \sum_k a_k H(s_k) e^{s_k t}.$$

Fourier serisi gösterilimi

$$x(t) = x(t + T)$$

koşulu tüm T değerleri için sağlayan işaret T (koşulu sağlayan en küçük T) ile periyodiktir.

Temel açısal frekans

$$\omega_0 = 2\pi/T$$

Fourier serisi gösterilimi

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$$

Örnek:

$$x(t) = \sum_{k=-3}^{+3} a_k e^{jk2\pi t},$$

$$a_0 = 1,$$

$$a_1 = a_{-1} = \frac{1}{4},$$

$$a_2 = a_{-2} = \frac{1}{2},$$

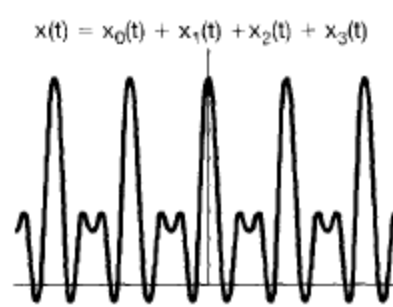
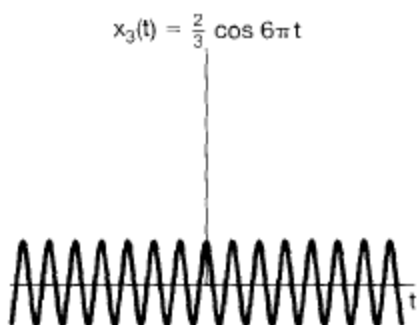
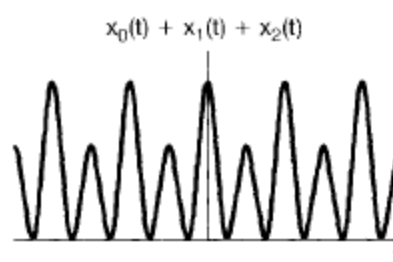
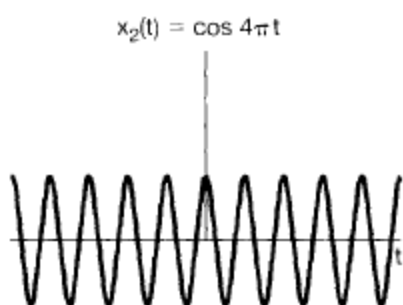
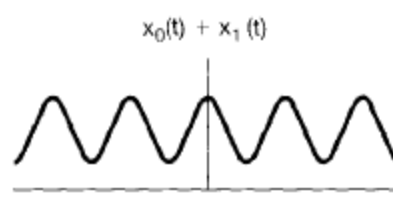
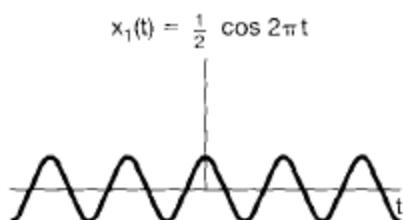
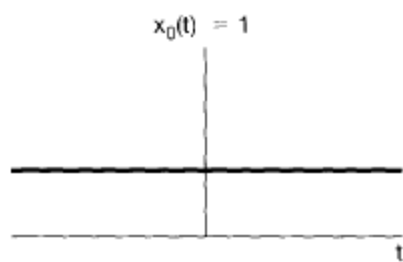
$$a_3 = a_{-3} = \frac{1}{3}.$$

katsayıları verilsin. Temel açısal frekans ω_0 olmak üzere, $x(t)$ işaretini bulunuz.

$$\begin{aligned} x(t) = 1 + \frac{1}{4}(e^{j2\pi t} + e^{-j2\pi t}) + \frac{1}{2}(e^{j4\pi t} + e^{-j4\pi t}) \\ + \frac{1}{3}(e^{j6\pi t} + e^{-j6\pi t}). \end{aligned}$$

Euler bağıntısından yararlanarak,

$$x(t) = 1 + \frac{1}{2} \cos 2\pi t + \cos 4\pi t + \frac{2}{3} \cos 6\pi t.$$



Fourier serisi gösterilimi (Fourier Series representation)

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} a_k e^{jk(2\pi/T)t},$$

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_T x(t) e^{-jk(2\pi/T)t} dt,$$

$$a_0 = \frac{1}{T} \int_T x(t) dt,$$

Örnek:

$$x(t) = \sin \omega_0 t,$$

şeklinde verilen işaretin Fourier serisi katsayılarını bulalım. (temel açısal frekans ω_0)

$$\sin \omega_0 t = \frac{1}{2j} e^{j\omega_0 t} - \frac{1}{2j} e^{-j\omega_0 t},$$

$$a_1 = \frac{1}{2j}, \quad a_{-1} = -\frac{1}{2j},$$

$$a_k = 0, \quad k \neq +1 \text{ or } -1.$$

Örnek:

$$x(t) = 1 + \sin \omega_0 t + 2 \cos \omega_0 t + \cos \left(2\omega_0 t + \frac{\pi}{4} \right),$$

şeklinde verilen işaretin Fourier serisi katsayılarını bulalım. (temel açısal frekans ω_0)

$$x(t) = 1 + \frac{1}{2j} [e^{j\omega_0 t} - e^{-j\omega_0 t}] + [e^{j\omega_0 t} + e^{-j\omega_0 t}] + \frac{1}{2} [e^{j(2\omega_0 t + \pi/4)} + e^{-j(2\omega_0 t + \pi/4)}].$$

$$x(t) = 1 + \left(1 + \frac{1}{2j} \right) e^{j\omega_0 t} + \left(1 - \frac{1}{2j} \right) e^{-j\omega_0 t} + \left(\frac{1}{2} e^{j(\pi/4)} \right) e^{j2\omega_0 t} + \left(\frac{1}{2} e^{-j(\pi/4)} \right) e^{-j2\omega_0 t}.$$

Fourier Serisi katsayıları

$$a_0 = 1,$$

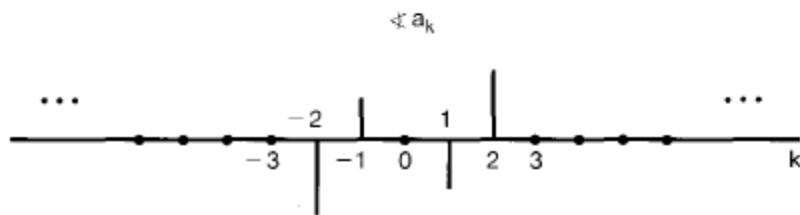
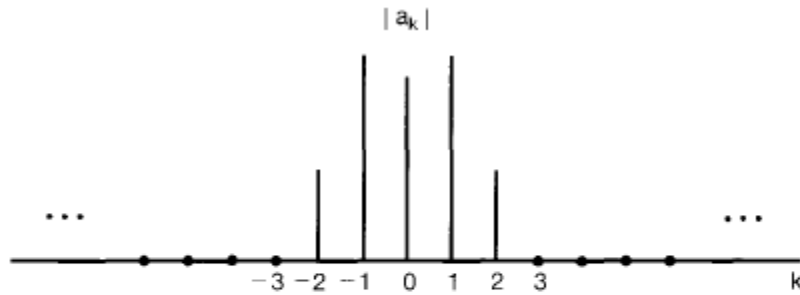
$$a_1 = \left(1 + \frac{1}{2j}\right) = 1 - \frac{1}{2}j,$$

$$a_{-1} = \left(1 - \frac{1}{2j}\right) = 1 + \frac{1}{2}j,$$

$$a_2 = \frac{1}{2}e^{j(\pi/4)} = \frac{\sqrt{2}}{4}(1 + j),$$

$$a_{-2} = \frac{1}{2}e^{-j(\pi/4)} = \frac{\sqrt{2}}{4}(1 - j),$$

$$a_k = 0, |k| > 2.$$

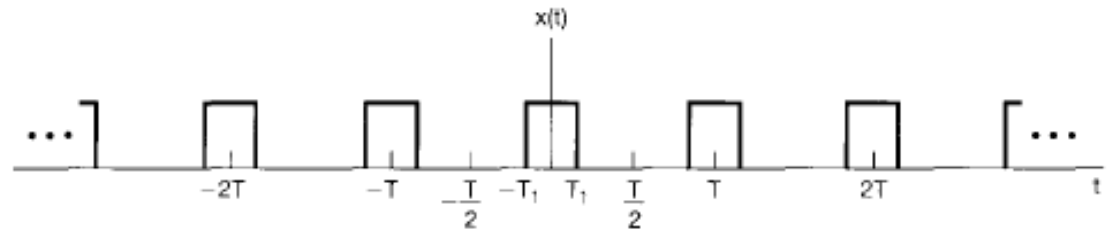


Genlik ve faz spektrumları

Örnek:

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & T_1 < |t| < T/2 \end{cases},$$

$$\omega_0 = 2\pi/T.$$



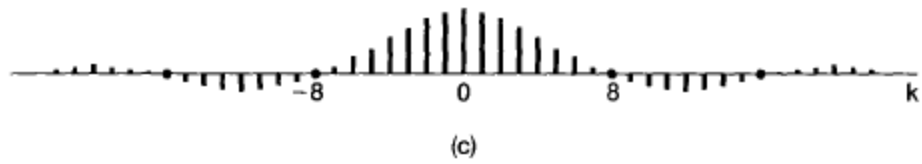
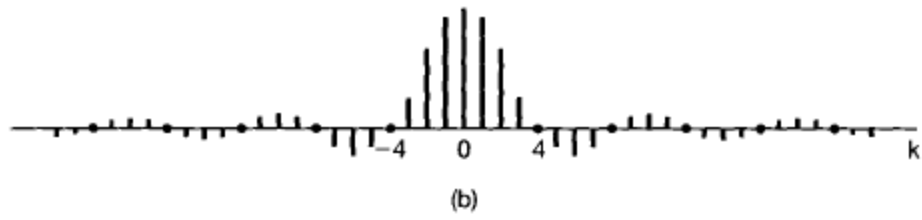
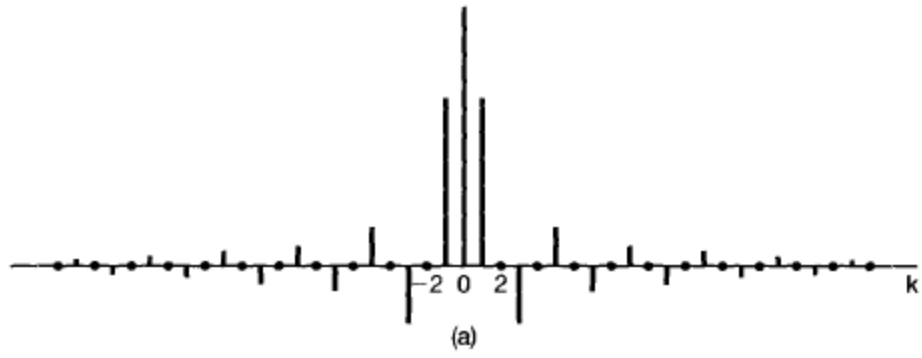
$$a_0 = \frac{1}{T} \int_{-T_1}^{T_1} dt = \frac{2T_1}{T}.$$

$$a_k = \frac{1}{T} \int_{-T_1}^{T_1} e^{-jk\omega_0 t} dt = -\frac{1}{jk\omega_0 T} e^{-jk\omega_0 t} \Big|_{-T_1}^{T_1},$$

$$a_k = \frac{2}{k\omega_0 T} \left[\frac{e^{jk\omega_0 T_1} - e^{-jk\omega_0 T_1}}{2j} \right].$$

$$a_k = \frac{2 \sin(k\omega_0 T_1)}{k\omega_0 T} = \frac{\sin(k\omega_0 T_1)}{k\pi}, \quad k \neq 0,$$

$$\omega_0 T = 2\pi.$$



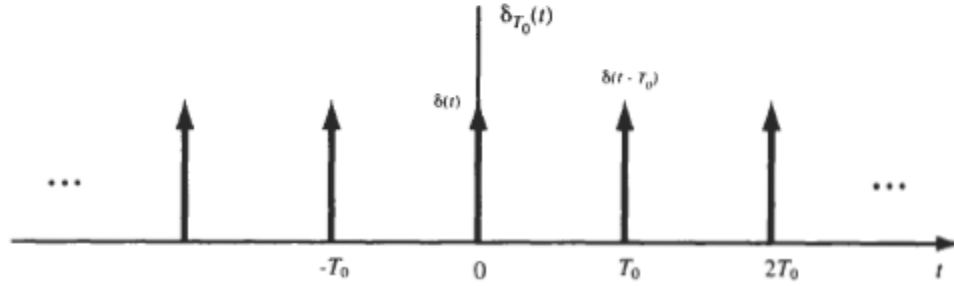
Farklı darbe genişlikleri için katsayıların değişimi

(a) $T = 4T_1$;

(b) $T = 8T_1$; (c) $T = 16T_1$.

Örnek: Periyodik impuls dizisi (impuls katarı) için Fourier Serisi katsayılarını bulalım.

$$\delta_{T_0}(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT_0)$$



$$x(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT);$$

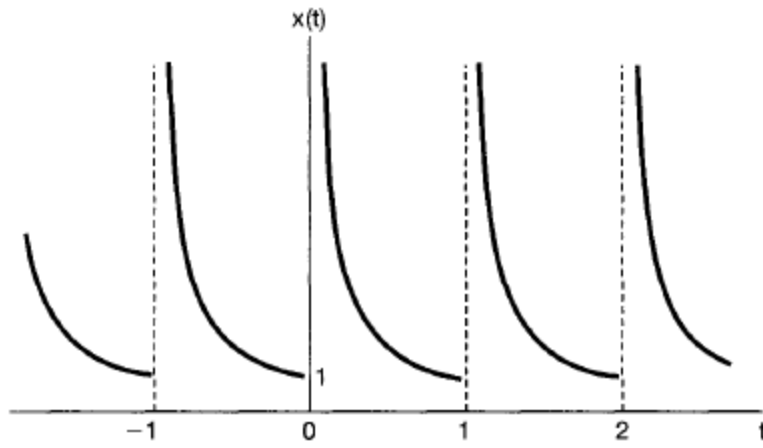
$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} \delta(t) e^{-jk2\pi t/T} dt = \frac{1}{T}.$$

Fourier Serilerinin yakınsama koşulu (Dirichlet Koşulları)

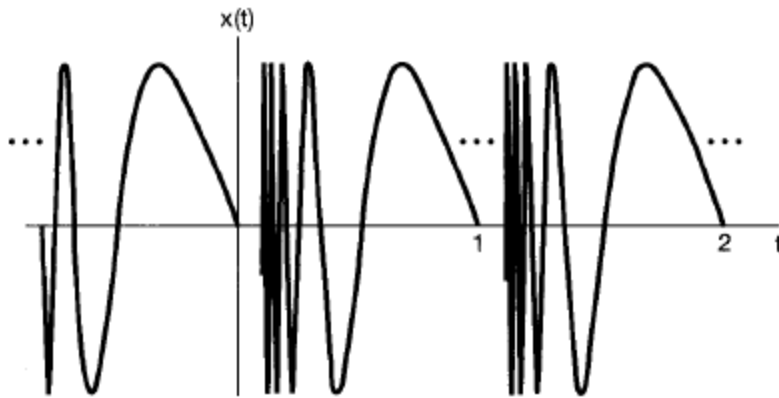
1. İşaret ana periyotta integre edilebilir olmalı

$$\int_T |x(t)| dt < \infty.$$

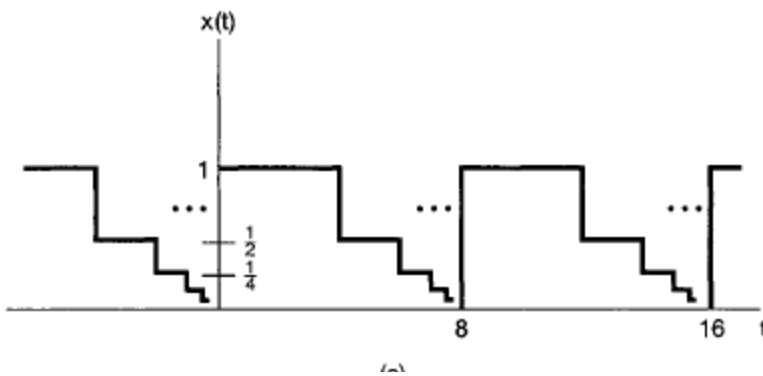
2. Sonlu sayıda maksimum ve minimum olmalı
3. Sonlu sayıda süreksizlik göstermeli ve bu süreksizliklerde sonlu değer almalı



(a)



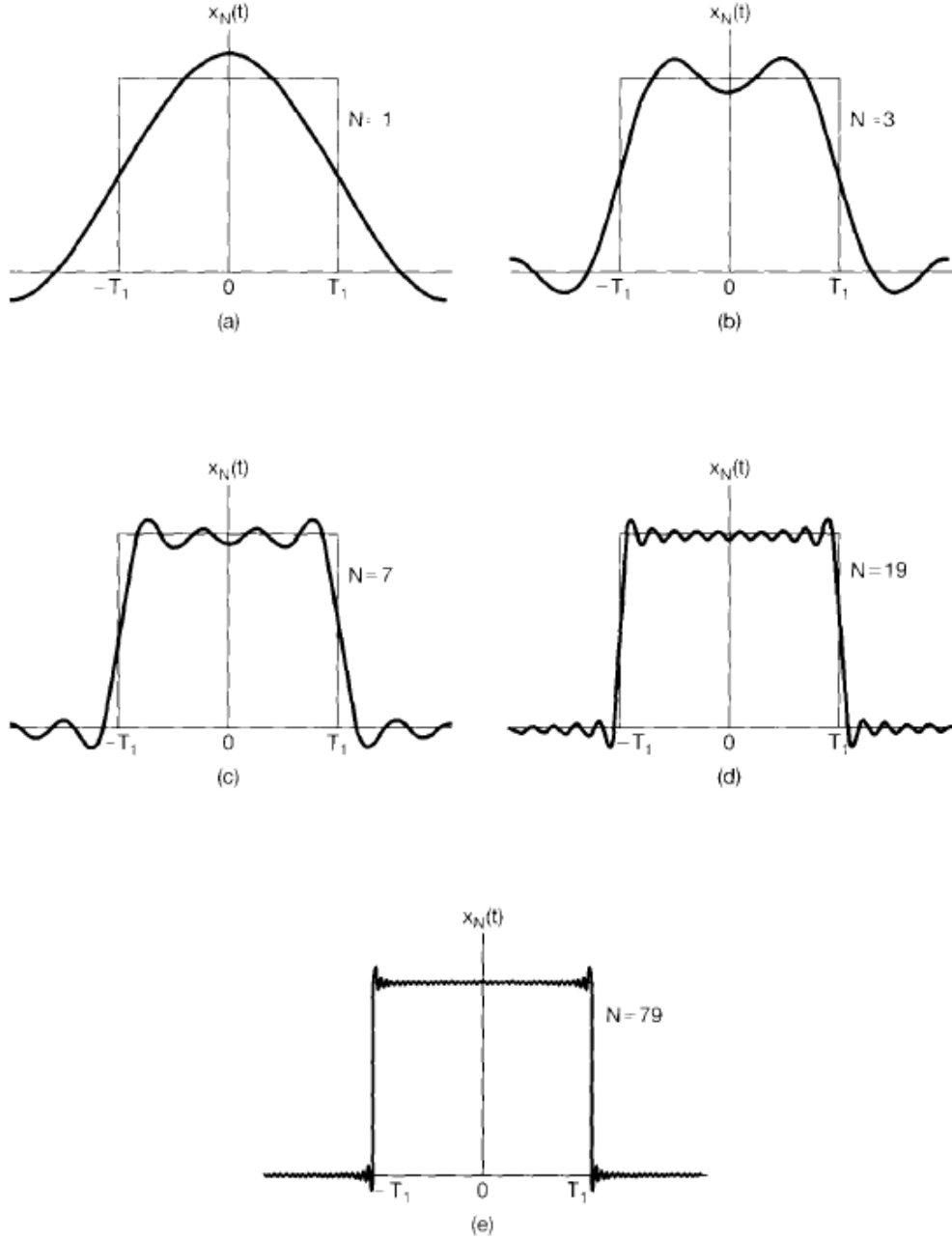
(b)



Dirichlet şartlarını sağlamayan işaretler (sırasıyla 1,2 ve 3. Koşullar sağlanmıyor)

Örnek: Gibbs Olayı

Periyodik dikdörtgen dalga işaretinin sonlu sayıda Fourier serisi katsayısı ile ifade edilmesi



Fourier Serilerinin özellikleri

Property	Section	Periodic Signal	Fourier Series Coefficients
		$\left. \begin{matrix} x(t) \\ y(t) \end{matrix} \right\}$ Periodic with period T and fundamental frequency $\omega_0 = 2\pi/T$	a_k b_k
Linearity	3.5.1	$Ax(t) + By(t)$	$Aa_k + Bb_k$
Time Shifting	3.5.2	$x(t - t_0)$	$a_k e^{-jk\omega_0 t_0} = a_k e^{-jk(2\pi/T)t_0}$
Frequency Shifting		$e^{jM\omega_0 t} = e^{jM(2\pi/T)t} x(t)$	a_{k-M}
Conjugation	3.5.6	$x^*(t)$	a_{-k}^*
Time Reversal	3.5.3	$x(-t)$	a_{-k}
Time Scaling	3.5.4	$x(\alpha t), \alpha > 0$ (periodic with period T/α)	a_k
Periodic Convolution		$\int_T x(\tau)y(t - \tau)d\tau$	$Ta_k b_k$
Multiplication	3.5.5	$x(t)y(t)$	$\sum_{l=-\infty}^{+\infty} a_l b_{k-l}$
Differentiation		$\frac{dx(t)}{dt}$	$jk\omega_0 a_k = jk\frac{2\pi}{T} a_k$
Integration		$\int_{-\infty}^t x(t) dt$ (finite valued and periodic only if $a_0 = 0$)	$\left(\frac{1}{jk\omega_0}\right)a_k = \left(\frac{1}{jk(2\pi/T)}\right)a_k$
Conjugate Symmetry for Real Signals	3.5.6	$x(t)$ real	$\begin{cases} a_k = a_{-k}^* \\ \Re\{a_k\} = \Re\{a_{-k}\} \\ \Im\{a_k\} = -\Im\{a_{-k}\} \\ a_k = a_{-k} \\ \angle a_k = -\angle a_{-k} \end{cases}$
Real and Even Signals	3.5.6	$x(t)$ real and even	a_k real and even
Real and Odd Signals	3.5.6	$x(t)$ real and odd	a_k purely imaginary and odd
Even-Odd Decomposition of Real Signals		$\begin{cases} x_e(t) = \mathcal{E}\{x(t)\} & [x(t) \text{ real}] \\ x_o(t) = \mathcal{O}\{x(t)\} & [x(t) \text{ real}] \end{cases}$	$\begin{cases} \Re\{a_k\} \\ j\Im\{a_k\} \end{cases}$

Parseval's Relation for Periodic Signals

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2$$

Zamanda kaydırma (Time shifting)

$$y(t) = x(t - t_0)$$

$$b_k = \frac{1}{T} \int_T x(t - t_0) e^{-jk\omega_0 t} dt$$

$$\tau = t - t_0$$

$$\begin{aligned} \frac{1}{T} \int_T x(\tau) e^{-jk\omega_0(\tau+t_0)} d\tau &= e^{-jk\omega_0 t_0} \frac{1}{T} \int_T x(\tau) e^{-jk\omega_0 \tau} d\tau \\ &= e^{-jk\omega_0 t_0} a_k = e^{-jk(2\pi/T)t_0} a_k, \end{aligned}$$

$$x(t) \xleftrightarrow{\mathcal{FS}} a_k,$$

$$x(t - t_0) \xleftrightarrow{\mathcal{FS}} e^{-jk\omega_0 t_0} a_k = e^{-jk(2\pi/T)t_0} a_k.$$

Zamanda katlama (Time reversal)

$$y(t) = x(-t),$$

$$x(-t) = \sum_{k=-\infty}^{\infty} a_k e^{-jk2\pi t/T}.$$

$$k = -m.$$

$$y(t) = x(-t) = \sum_{m=-\infty}^{\infty} a_{-m} e^{jm2\pi t/T}.$$

$$b_k = a_{-k}.$$

$$x(t) \xleftrightarrow{\mathcal{FS}} a_k,$$

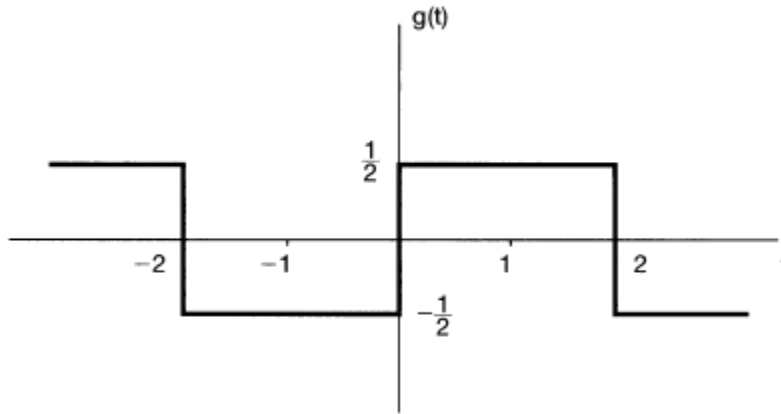
$$x(-t) \xleftrightarrow{\mathcal{FS}} a_{-k}.$$

Parseval Bağıntısı

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{+\infty} |a_k|^2,$$

$$\frac{1}{T} \int_T |a_k e^{jk\omega_0 t}|^2 dt = \frac{1}{T} \int_T |a_k|^2 dt = |a_k|^2,$$

Örnek:



işareti için Fourier Serisi katsayılarını önceki örnek (periyodik dikdörtgen darbe işareti) ve Fourier katsayılarının özelliklerinden yararlanarak bulalım.

Hatırlatma

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & T_1 < |t| < T/2 \end{cases}$$

$$a_k = \frac{2 \sin(k\omega_0 T_1)}{k\omega_0 T} = \frac{\sin(k\omega_0 T_1)}{k\pi}, \quad k \neq 0,$$

$$a_0 = \frac{1}{T} \int_{-T_1}^{T_1} dt = \frac{2T_1}{T}.$$

$$T = 4$$

$$T_1 = 1,$$

alınarak

$$g(t) = x(t - 1) - 1/2.$$

$$b_k = a_k e^{-jk\pi/2}.$$

ilişkisinden yararlanarak

$$d_k = \begin{cases} a_k e^{-jk\pi/2}, & \text{for } k \neq 0 \\ a_0 - \frac{1}{2}, & \text{for } k = 0 \end{cases},$$

$$d_k = \begin{cases} \frac{\sin(\pi k/2)}{k\pi} e^{-jk\pi/2}, & \text{for } k \neq 0 \\ 0, & \text{for } k = 0 \end{cases}.$$