

Team Minutes for [Team #7]

Delete the instructions in black italics and replace them with your team's information. Add new information after each meeting and save the document with the current date after the document name. This will create one long document that includes the minutes of all team meetings. You will have the old versions saved under document names with the previous dates in case they are needed.

Team Members' Names

Name: Brendan Roberts

Name: Noah Henderson

Name: Logan Lindeman

Name: Bradley Dobbins

Meeting Agenda Template

Meeting Date: <i>Put date here</i>	Start Time: <i>Record time meeting started</i> End Time: <i>Record meeting end time</i> Summary of Meeting
1. Attendance	<i>Record members present (if absent, include reasons and whether teammates were notified in advance).</i>
2. Purpose of Meeting	
3. Discuss work completed since last meeting.	<i>Team members report on what has been accomplished. Record notes of those reports here.</i>
4. Summarize work completed during meeting	<i>Summarize discussion and work accomplished.</i>
5. Review action items to be completed after meeting	<i>Who will do what by when?</i>
6. Schedule next meeting	<i>Note time, place, and purpose.</i>
7. Recording secretary	<i>Note who took the meeting minutes and the date that meeting minutes were circulated by e-mail.</i>

Final Demo Meeting

Meeting Date: 11/25/2024	Start Time: 1:00pm End Time: 1:50pm Summary of Meeting
1. Attendance	<i>All Present</i>
2. Purpose of Meeting	<i>To test the final robot and tune speed.</i>
3. Discuss work completed since last meeting.	<i>Team member: Brendan. Worked on color threshold and orientation of robot.</i>
	<i>Team member: Noah. Worked on marker distance threshold and Pi Queue logic.</i>
	<i>Team member: Logan. Worked on PID controller and alignment to marker drift.</i>
	<i>Team member: Bradley. Worked on motor misalignment and adjusting turn percentages after marker detection</i>
4. Summarize work completed during meeting	<i>Gimpy the robot successfully scans in a circle, finds the marker and moves towards it. It stops a foot away and turns correctly. Then it also sees the next marker and repeats. Final demo should be good if the hardware doesn't crap out again.</i>
5. Review action items to be completed after meeting	<i>Team member: All. Continue final course testing and delay between state machines steps. The color shading of the green and red are a little dim. Need slight color correction.</i>
6. Schedule next meeting	<i>12/2/2024</i>
7. Recording secretary	<i>Bradley Dobbins</i>

<https://github.com/grustlersdotcom/SEEDLab/tree/main/Demo2>