A Manufacturer-Agnostic Automation Framework for SPM

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Outline

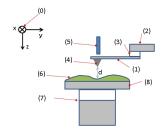
1 Justification

2 Introduction to afspm

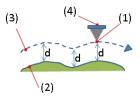
3 Design Particulars

SPM Basics

- An atomically-sharp tip is scanned above a surface measuring properties.
 - Allows spatial imaging, spectroscopic analysis, sample manipulation.
- Usable on various surfaces, only require relatively flat sample ($\sim 5 \mu m$).



Typical AFM Configuration, Tom Toyosaki, Wikimedia Commons



Schematics of AFM topographic image forming, Tom Toyosaki, Wikimedia Commons.

Challenges and Automation

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Challenges for Wider Adoption

- Preparing, running, and analyzing requires significant domain knowledge.
- 2 Running an experiment requires constant user attention.
- **3 Statistical** understanding is **limited** by the researcher's **decisions**.

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Automation Prior Art.

- Conditioning of the tip for proper surface characterization.
- Structure classification, for where to scan next.
- Bayesian/Active Learning for statistical decision making.

A Remaining Limitation

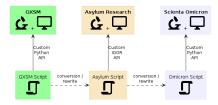
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- Scripts written for a **specific** SPM system **cannot be re-used** on others.
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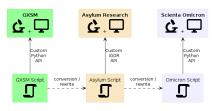
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Goals

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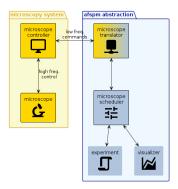
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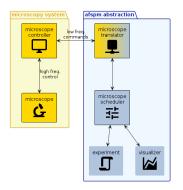
Design Characteristics

- Standalone components that each 'do one thing and do it well' (nodes).
- They communicate over 'pipes' via generic schemas.
- It is easy to **split up** components among **different** computing **devices**.

Principal Components



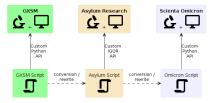
Principal Components



Any experiment must contain:

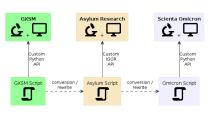
- Microscope Translator: translates between afspm-generic and microscope-specific.
- Microscope Scheduler: mediates control between components and translator and caches data.

Scripting with / without afspm

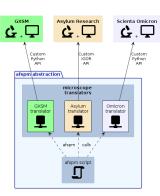


Code Reuse in SPM Scripting

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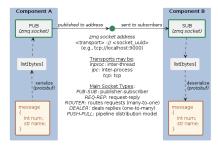


Code Reuse in SPM Scripting



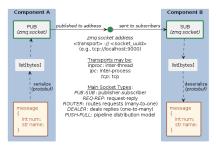
Approach Taken by afspm

Communication Protocol



Generic schemas sent between network sockets held by components.

Communication Protocol



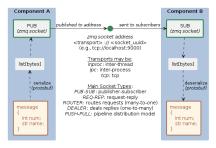
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Serialization / Deserialization

Translates data structures into a format that can be stored/communicated.

Google Protocol Buffers: avoids schema violations, extra error handling.

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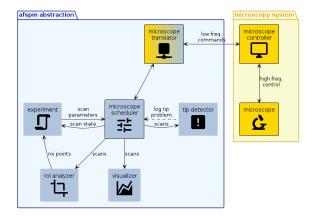
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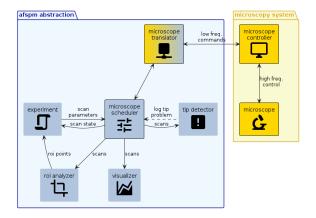
Data Transmission Protocol

Handles sending of data between 'sockets' via common 'nodes'. ZeroMQ: abstracts away transports used, handles common roadblocks.

Example



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- ROI Analyzer reviews scans for interesting regions.
- **Experiment** switches between scanning a large region or a suggested ROI.
- **Tip Detector** evaluates the state of the tip, logs problem if deemed poor.
- Visualizer visualizes what is being scanned.

Our publisher-subscriber, control-request world

We subscribe to events published by the SPM and request actions of it.

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- The SPM **publishes** messages types when its 'state' changes.
- Components may **subscribe** to only messages of interest.
- Messages may be **cached** by the Scheduler, to send to new components.

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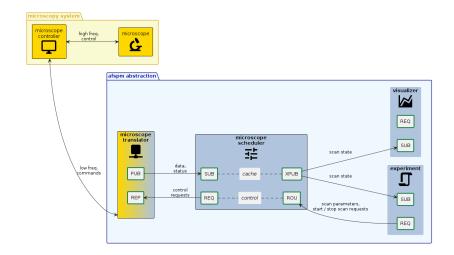
Publisher-Subscriber Path

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Control Path

- Components send **requests** to the SPM and receive **responses**.
- The Scheduler routes control to the SPM (one component at a time).
- Components not in control may flag **problems** control is dropped.
 - A user may manually fix a problem and unflag the problem.
 - A component that **fixes** a flagged problem can grab control.

afspm: Detailed View



Publisher-Subscriber Path

```
message DataAspects {
   optional Size2u shape = 1;
   optional string units = 2;
}

message SpatialAspects {
   optional Rect2d roi = 1;
   optional string units = 2;
}

message ScanParameters2d {
   optional SpatialAspects spatial = 1;
   optional DataAspects data = 2;
}
```

2D Scan Parameters Schema

```
message Scan2d {
  optional ScanParameters2d params = 1;
  optional google.protobuf.Timestamp timestamp = 2;
  optional string channel = 3;
  optional string filename = 5;
  repeated double values = 4;
}
```

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2D Scan Schema

2D Scan Parameters Schema

Frame 1 'Scan2d'

Frame 2 Scan2d Data

Envelope
Serialized Data Structure

Message Format

Control Path

Control Request Schema

Control Response Schema

Control Path

Control Request Schema

```
enum ExperimentProblem {
   EP_NONE = 0;
   EP_TIP_SHAPE_CHANGED = 1;
   EP_DEVICE_MALFUNCTION = 2;
   EP_FEEDBACK_NON_OPTIMAL = 3;
}
```

Experiment Problem Schema

Control Response Schema

```
enum ControlMode {
  CM_UNDEFINED = 0;
  CM_MANUAL = 1;
  CM_AUTOMATED = 2;
  CM_PROBLEM = 3;
}
```

Control Mode Schema

Control Path

Control Request Schema

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}
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Experiment Problem Schema

```
Frame 1 REQ_REQUEST_CTRL

Frame 2 EP_TIP_SHAPE_CHANGED
```

Control Response Schema

```
enum ControlMode {
   CM_UNDEFINED = 0;
   CM_MANUAL = 1;
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}
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Control Mode Schema

```
Command Request Enum
Serialized Data Structure(s)
```

Message Format

Spawning, Monitoring, and the Config File

An experiment defined via a **config** file, with components **spawned** as needed.

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Spawning

- Each component is instantiated as a child process (independent memory).
 - One crashed component does not crash all.
- We can spawn different components on different computers.
 - The 'spawn' command allows indication of which components to spawn.

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Monitoring

- The parent process monitors spawned components for heartbeats.
- If a process has not 'beat' in a timeframe, it is killed and respawned.
- Then the caching logic chosen is important must be able to run.

Sample Config File

```
# --- URLs --- #
pub_url = "tcp://127.0.0.1:9000"
psc_url = "tcp://127.0.0.1:9001"

server_url = "tcp://127.0.0.1:6666"
router_url = "tcp://127.0.0.1:6667"
# [...]
exp_scan_res = [256, 256]
# [...]
```

```
f ..... PubSub ..... f
[translator_pub]
class = 'afspm.io.pubsub.publisher.Publisher'
url = 'pub_url'
f [...]
[experiment_sub]
class = 'afspm.io.pubsub.subscriber.Subscriber'
sub_url = 'psc_url'
f [...]
```

General Variables

Intermediary Classes

```
[translator]
component = true
class = 'afspm.components.microscope.translators.gxsm.translator.GxsmTranslator'
publisher = 'translator_pub'
control_server = 'translator_server'
# [...]
```

Config Components

We defined a 'basis' set of schemas we believe are standard. But this is quite arbitrary! Here are ways you can expand upon them.

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- Defined as an SPM config describing cantilever control during a scan.
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- Can send these by providing action id and <key:value> params map.

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Custom Messages

■ Any user may create custom messages or expand existing ones.

The End

Let us know what you think and help us make it better.

afspm on github