MTH 451/EGR 551 - Homework 9

Due Monday April 26, 2021 at 5 p.m.

Please submit all computer codes you developed to solve these problems.

In this assignment you are required to implement the classical 4-order explicit Runge-Kutta method, which can be described as follows.

Input: $f(y,t), N > 0, h = (t_f - t_i)/N, t_i, y_i$ Output: $y^{(k)}, k = 0, 1, 2, \dots, N$ 1: $t^{(0)} = t_i, y^{(0)} = y_i$ 2: **for** $k = 0, 1, \dots, N - 1$ **do** $k_1 = f(y^{(k)}, t^{(k)})$ $y_2 = y^{(k)} + \frac{1}{2}hk_1$ $\tau_2 = t^{(k)} + \frac{1}{2}h$ $k_2 = f(y_2, \tau_2)$ $y_3 = y^{(k)} + \frac{1}{2}hk_2$ $\tau_3 = t^{(k)} + \frac{1}{2}h$ 8: $k_3 = f(y_3, \tau_3)$ 9: $y_4 = y^{(k)} + hk_3$ 10: $\tau_4 = t^{(k)} + h$ 11: $k_4 = f(y_4, \tau_4)$ $y^{(k+1)} = y^{(k)} + h(\frac{1}{6}k_1 + \frac{1}{3}k_2 + \frac{1}{3}k_3 + \frac{1}{6}k_4)$ 12: 13:

 $t^{(k+1)} = t^{(k)} + h$

14:

15: end for

- 1. Apply the explicit Euler method, the implicit Euler method and the classical 4-th order Runge-Kutta method to the following problems.
 - (a) $\dot{x} = -0.1x + 1$, x(0) = 0, and 0 < t < 1.

(b)
$$\dot{x}_1 = x_2$$
, $\dot{x}_2 = -2\xi\omega_n x_2 - \omega_n^2 x_1$, $x_1(0) = 1$, $x_2(0) = 0$, $0 \le t \le 1$, $\xi = 0.1$, and $\omega_n = 2\pi$.

For each of the numerical methods use the following step sizes; $h = 10^{-1}$, 10^{-2} , 10^{-3} , 10^{-4} . Compare the numerical solutions with the exact solution in each case. Plot the solution.

For part (b) the exact solution for $x_1(t)$ is

$$x_1(t) = x_1(0)e^{-\xi\omega_n t} \left(\cos\omega_d t + \frac{\xi}{\sqrt{1-\xi^2}}\sin\omega_d t\right) + \frac{x_2(0)}{\omega_d}e^{-\xi\omega_n t}\sin\omega_d t,$$

where $\omega_d = \omega_n \sqrt{1 - \xi^2}$. Also, $x_2(t) = \dot{x}_1(t) = \frac{dx_1}{dt}$.

2. Use the classical 4-th order Runge-Kutta method to solve the differential equation

$$\dot{y}_1 = y_2,$$

 $\dot{y}_2 = \mu(1 - y_1^2)y_2 - y_1,$

with initial conditions $y(0) = [2, 4]^T$. Solve this problem for the case $\mu = 1$ and final time t = 20. Plot (i) $(t, y_1(t))$, (ii) $(t, y_2(t))$, and (iii) $(y_1(t), y_2(t))$.

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