

Weekly report 12

What was done this week?

- Development and testing of mapping and pathing systems.
- Final tweaks of some of the hardware components.
- Writing of test cases.
- Development of algorithms.
- Improvement of hardware related python classes and implementation of multiprocessing.
- Soldering.

What issues/risks/blockers do you have?

- Currently, we don't have any issues.

What is the goal for next week?

- Keep developing and testing the room mapping system.
- Connect a remote controller.
- Connect computer vision system to the robot.

What is the overall status?

- **Green.**