Weekly report 8

What was done this week?

- Making a version of the robot that drives around the room and avoids obstacles.
- Soldering electronic components.
- Working on camera depth vision.
- Programming classes with python.
- Testing.
- Writing a weekly report ⍰.

What issues/risks/blockers do you have?

- Issues with one camera.

What is the goal for next week?

- Fix issue with robot's camera.
- Keep working on object detection / computer vision.
- Start developing a room mapping system.

What is the overall status?

- Green.Gro