Weekly report 12

What was done this week?

* Development and testing of mapping and pathing systems.
* Final tweaks of some of the hardware components.
* Writing of test cases.
* Development of algorithms.
* Improvement of hardware related python classes and implementation of multiprocessing.
* Soldering.

What issues/risks/blockers do you have?

* Currently, we don’t have any issues.

What is the goal for next week?

* Keep developing and testing the room mapping system.
* Connect a remote controller.
* Connect computer vision system to the robot.

What is the overall status?

* Green.