Weekly report 7

What was done this week?

* Tested driving functionality of the robot’s tracks.
* Finished printing robot’s body parts.
* Working on camera depth vision.
* Testing of the software.
* Research.
* Writing a weekly report 😊

What issues/risks/blockers do you have?

* Currently, we don’t have any issues.

What is the goal for next week?

* Solder the required electronic connections.
* Connect the electronic parts together.
* Make a driving version of a robot which detects and avoids objects in its way.

What is the overall status?

* Green.