Weekly report 8

What was done this week?

* Making a version of the robot that drives around the room and avoids obstacles.
* Soldering electronic components.
* Working on camera depth vision.
* Programming classes with python.
* Testing.
* Writing a weekly report 😊.

What issues/risks/blockers do you have?

* Issues with one camera.

What is the goal for next week?

* Fix issue with robot’s camera.
* Keep working on object detection / computer vision.
* Start developing a room mapping system.

What is the overall status?

* Green.Gro