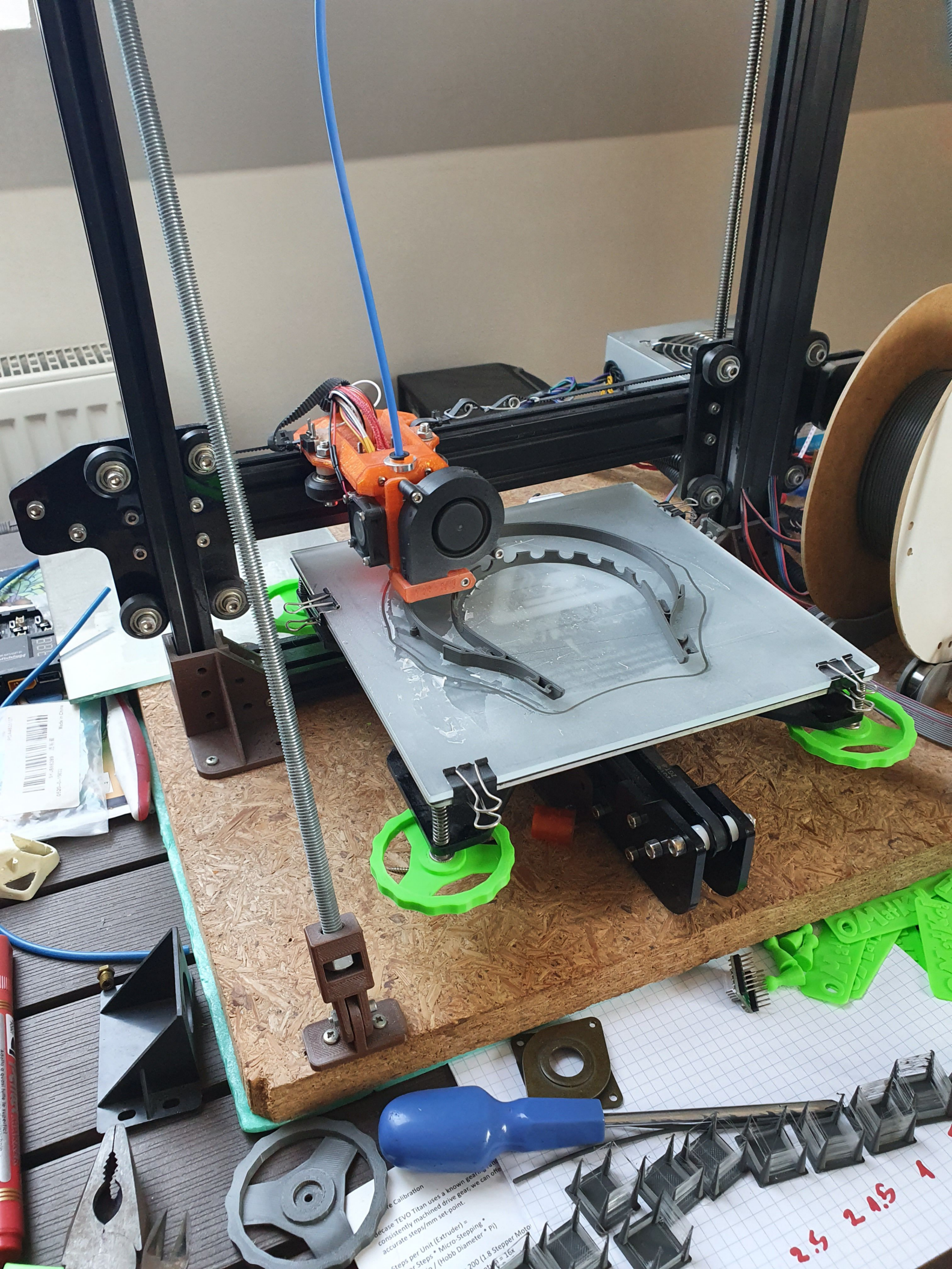
Calibration
consistently machined drive gear, we can ofte
accurate steps/mm set-point.
Steps per Unit (Extruder) =
Steps * Micro-Stepping *
(Hobb Diameter * Pi)
200 (1.8 Stepper Moto
= 16x
2.5
2.5
1

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