Gabriel Alkuino Page 1 of 2

## Problem 5.21

A magnetostatic field is due entirely to a localized distribution of permanent magnetization.

(a) Show that

$$\int \mathbf{B} \cdot \mathbf{H} \, \mathrm{d}^3 x = 0$$

provided the integral is taken over all space.

(b) From the potential energy (5.72) of a dipole in an external field, show that for a continuous distribution of permanent magnetization the magnetostatic energy can be written as

$$W = \frac{\mu_0}{2} \int \mathbf{H} \cdot \mathbf{H} \, \mathrm{d}^3 x = -\frac{\mu_0}{2} \int \mathbf{M} \cdot \mathbf{H} \, \mathrm{d}^3 x$$

apart from an additive constant, which is independent of the orientation or position of the various constituent magnetized bodies.

Solution.

(a) Since there are no free currents, **H** is derivable from a potential. Using the product rule  $\nabla \cdot (f\mathbf{A}) = \nabla f \cdot \mathbf{A} + f \nabla \cdot \mathbf{A}$ , we get

$$\int \mathbf{B} \cdot \mathbf{H} \, \mathrm{d}^3 x = -\int \mathbf{B} \cdot \nabla \Phi_M \, \mathrm{d}^3 x$$
$$= -\int \left[ \nabla \cdot (\Phi_M \mathbf{B}) - \Phi_M \nabla \cdot \mathbf{B} \right] \mathrm{d}^3 x$$
$$= -\int \nabla \cdot (\Phi_M \mathbf{B}) \, \mathrm{d}^3 x ,$$

where we used the fact that  $\nabla \cdot \mathbf{B} = 0$ . Now, by the Divergence theorem

$$\int \nabla \cdot (\Phi_M \mathbf{B}) \, \mathrm{d}^3 x = \oint (\Phi_M \mathbf{B}) \, \mathrm{d} a.$$

Since the magnetostatic field is due entirely to a localized distribution, the magnetic induction  $\mathbf{B}$  vanishes at infinity. Therefore, the surface integral (at infinity) is zero. Thus,

$$\int \mathbf{B} \cdot \mathbf{H} \, \mathrm{d}^3 x = 0.$$

(b) We generalize Equation 5.72 to a continuous distribution of permanent magnetization. We take  $\delta U = -\delta \mathbf{M} \cdot \mathbf{B}$ . Provided that a linear relation exists between  $\mathbf{M}$  and  $\mathbf{B}$ , we get

$$U = -\frac{1}{2} \int \mathbf{M} \cdot \mathbf{B} \, d^3 x$$

$$= -\frac{\mu_0}{2} \int \mathbf{M} \cdot (\mathbf{H} + \mathbf{M}) \, d^3 x$$

$$= -\frac{\mu_0}{2} \int \mathbf{M} \cdot \mathbf{H} \, d^3 x - \frac{\mu_0}{2} \int \mathbf{M} \cdot \mathbf{M} \, d^3 x.$$

Gabriel Alkuino Page 2 of 2

Note that  $\mathbf{M} \cdot \mathbf{M}$  is a scalar, which is independent of the orientation—and whose integral is independent of the position of the various constituent magnetized bodies. Therefore, the second integral is constant, which we denote by  $\mathcal{M}$ . Thus,

$$U = -\frac{\mu_0}{2} \int \mathbf{M} \cdot \mathbf{H} \, \mathrm{d}^3 x + \mathcal{M} ,$$

$$= -\frac{\mu_0}{2} \int \left( \frac{1}{\mu_0} \mathbf{B} - \mathbf{H} \right) \cdot \mathbf{H} \, \mathrm{d}^3 x + \mathcal{M}$$

$$= -\frac{1}{2} \int \mathbf{B} \cdot \mathbf{H} \, \mathrm{d}^3 x + \frac{\mu_0}{2} \int \mathbf{H} \cdot \mathbf{H} \, \mathrm{d}^3 x + \mathcal{M}$$

$$= \frac{\mu_0}{2} \int \mathbf{H} \cdot \mathbf{H} \, \mathrm{d}^3 x + \mathcal{M} .$$