

Elec 405 - Homework 1

```
In [5]: using LinearAlgebra
        using Plots
```

8. Affine Approximation

$$a(\mathbf{x}) = f(\mathbf{x}_0) + \nabla f(\mathbf{x}_0)^T (\mathbf{x} - \mathbf{x}_0) \quad (7)$$

is an affine approximation of $f(\mathbf{x})$ around \mathbf{x}_0 .

Note that this affine function defines an hyperplane in \mathbb{R}^{n+1} in the standard form

$$\begin{bmatrix} \nabla f(\mathbf{x}_0) \\ -1 \end{bmatrix}^T \left(\begin{bmatrix} \mathbf{x} \\ a(\mathbf{x}) \end{bmatrix} - \begin{bmatrix} \mathbf{x}_0 \\ f(\mathbf{x}_0) \end{bmatrix} \right) = 0. \quad (8)$$

Now consider the function

$$f(\mathbf{x}) = \mathbf{x}^T \mathbf{A} \mathbf{x} \quad (9)$$

defined over \mathbb{R}^2 , where

$$\mathbf{A} = \begin{bmatrix} 0.01 & 0.001 \\ 0.001 & 0.01 \end{bmatrix}. \quad (10)$$

```
In [6]: A = [0.01 0.001; 0.001 0.01]
        A
```

```
Out[6]: 2x2 Array{Float64,2}:
 0.01  0.001
 0.001 0.01
```

```
In [7]: function draw_hyperplane_3D_modified(a, b, camera=(60, 45))

#   pyplot()
x=range(-50, stop=50, length=100)
y=range(-50, stop=50, length=100)
g(x, y) = (dot(a, b) - dot(a[1: 2], [x; y]))/a[3]
plot!(x, y, g,
      label="$a' (x-$b)=0",
      xlabel="x_1", ylabel="x_2", zlabel="x_3",
      st=:surface, camera=camera)

# # plot the normal vector, since b is on the plane plot the vector b to b+a
a_x1 = range(b[1], stop=(b[1]+15*a[1]), length=100)
a_x2 = range(b[2], stop=(b[2]+15*a[2]), length=100)
a_x3 = range(b[3], stop=(b[3]+15*a[3]), length=100)
plot!(a_x1, a_x2, a_x3, label="a")
end

function draw_hyperplane_3D(a, b, p, camera=(60, 45))
pyplot()
x=range(-2, stop=2, length=100)
y=range(-2, stop=2, length=100)
g(x, y) = (dot(a, b) - dot(a[1: 2], [x; y]))/a[3]
p= plot(x, y, g,
      title="Hyperplane in 3D",
      label="$a' (x-$b)=0",
      xlabel="x_1", ylabel="x_2", zlabel="x_3",
      xlims= (-2, 2), ylims=(-2, 2), zlims=(-2, 2),
      st=:surface, camera=camera)

# plot the normal vector, since b is on the plane plot the vector b to b+a
a_x1 = range(b[1], stop=(b[1]+a[1]), length=100)
a_x2 = range(b[2], stop=(b[2]+a[2]), length=100)
a_x3 = range(b[3], stop=(b[3]+a[3]), length=100)
plot!(a_x1, a_x2, a_x3, label="a")
end
```

Out[7]: draw_hyperplane_3D (generic function with 2 methods)

```
In [8]: function affine_approx(x, f, f_der, x_0)
      return f(x_0) + dot(f_der(x_0), (x-x_0))
end

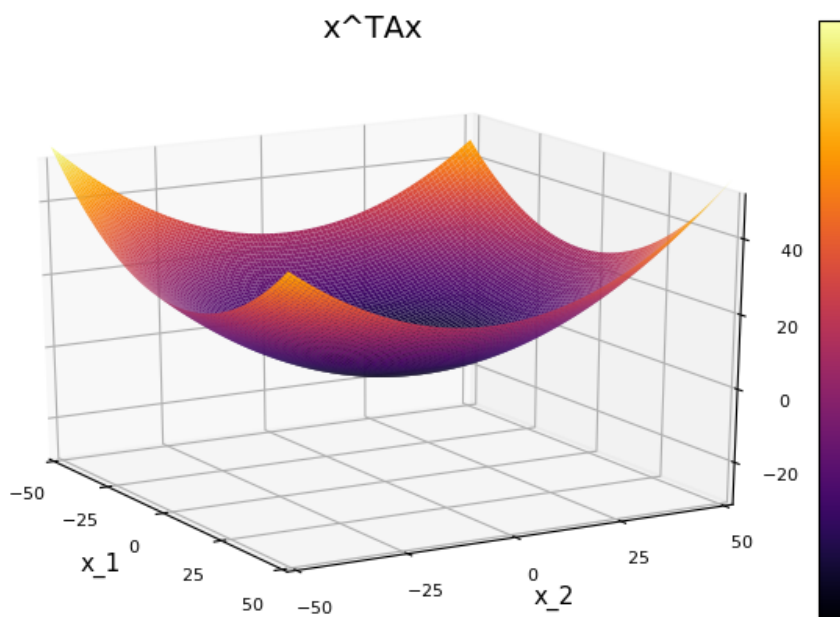
function f(x)
      return x' * A * x
end

function nabla_f(x)
      return (A+A')x
end
```

Out[8]: nabla_f (generic function with 1 method)

```
In [11]: camera=(60, 20)
# draw_hyperplane_3D()
pyplot()
x=range(-50, stop=50, length=100)
y=range(-50, stop=50, length=100)
g(x, y) = ([x y] * A * [x; y])[1]
p= plot(x, y, g,
        title="x^TAx",
        label="x^TAx",
        xlabel="x_1", ylabel="x_2",
        zlims=(-30,50),
        st=:surface, camera=camera)
```

Out[11]:



```

In [12]: camera=(30, -10)

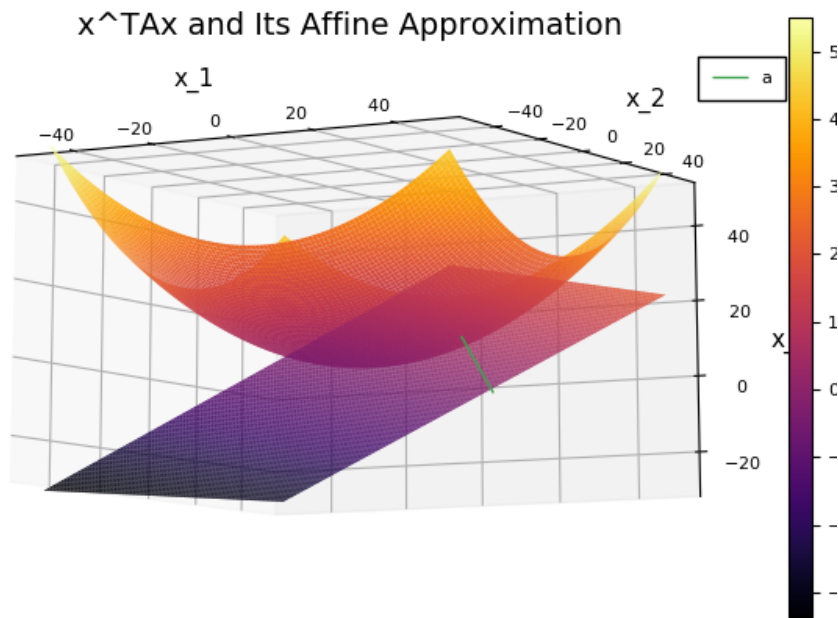
pyplot()
x=range(-50, stop=50, length=100)
y=range(-50, stop=50, length=100)
g(x, y) = ([x y] * A * [x; y])[1]
p= plot(x, y, g,
        title="x^TAx and Its Affine Approximation",
        label="x^TAx",
        xlabel="x_1", ylabel="x_2",
        zlims=(-30,50),
        st=:surface, camera=camera)

x_0 = [25; 0]
a = [nabla_f(x_0); -1]
b = [x_0; f(x_0)]

draw_hyperplane_3D_modified(a, b, camera)

```

Out[12]:



In []: