Python 2.7.14 (v2.7.14:84471935ed, Sep 16 2017, 20:19:30) [MSC v.1500 32 bit (Intel)] on win32
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>>>
=== RESTART: C:\Users\mahrog\Desktop\P5\smartcab-master\smartcab\agent.py ===
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Training trial 1
\
Simulating trial
epsilon = 0.9950; alpha = 0.5000
/
Step 0 Results
\
Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving left through a red light with traffic and cause a major accident. (rewarded 39.72)
97% of time remaining to reach destination.
/
Step 1 Results
\
Agent previous state: ('left', 'red', 'forward', None)

Agent attempted driving left through a red light. (rewarded -9.12)
94% of time remaining to reach destination.
/
Step 2 Results
\
Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving left through a red light. (rewarded -9.95)
91% of time remaining to reach destination.
/
Step 3 Results
\
Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving left through a red light. (rewarded -10.87)
89% of time remaining to reach destination.
/
Step 4 Results
\
Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving forward through a red light. (rewarded -10.96)

/
Step 5 Results
\
Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving forward through a red light. (rewarded -10.13)
83% of time remaining to reach destination.
/
Step 6 Results
\
Agent previous state: ('left', 'green', 'forward', 'forward')
Agent drove forward instead of left. (rewarded 0.67)
80% of time remaining to reach destination.
/
Step 7 Results
\
Agent previous state: ('left', 'green', 'left', None)
Agent drove forward instead of left. (rewarded 1.33)
77% of time remaining to reach destination.

86% of time remaining to reach destination.

/
Step 8 Results
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Agent previous state: ('left', 'green', 'left', 'right')
Agent drove right instead of left. (rewarded 0.95)
74% of time remaining to reach destination.
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Step 9 Results
\
Agent previous state: ('forward', 'green', None, None)
Agent drove right instead of forward. (rewarded 1.91)
71% of time remaining to reach destination.
/
Step 10 Results
\
Agent previous state: ('left', 'green', 'left', 'forward')
Agent drove right instead of left. (rewarded 1.19)
69% of time remaining to reach destination.

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Step 11 Results	
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Agent previous state: ('forward', 'red', None, 'right')	
Agent properly idled at a red light. (rewarded 1.24)	
66% of time remaining to reach destination.	
/	
Step 12 Results	
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Agent previous state: ('forward', 'red', None, 'right')	
Agent attempted driving left through a red light. (rewarded -9.	80)
63% of time remaining to reach destination.	
/	
Step 13 Results	
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Agent previous state: ('forward', 'green', None, None)	
Agent drove left instead of forward. (rewarded 1.67)	
60% of time remaining to reach destination.	
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Step 14 Results
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Agent previous state: ('right', 'red', None, None)
Agent properly idled at a red light. (rewarded 1.81)
57% of time remaining to reach destination.
/
Step 15 Results
\
Agent previous state: ('right', 'red', None, None)
Agent attempted driving forward through a red light. (rewarded -10.40)
54% of time remaining to reach destination.
/
Step 16 Results
\
Agent previous state: ('right', 'green', None, None)
Agent followed the waypoint right. (rewarded 1.60)
51% of time remaining to reach destination.
/
Step 17 Results

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Agent previous state: ('forward', 'red', None, None)
Agent properly idled at a red light. (rewarded 2.60)
49% of time remaining to reach destination.
/
Step 18 Results
\
Agent previous state: ('forward', 'red', None, None)
Agent properly idled at a red light. (rewarded 1.24)
46% of time remaining to reach destination.
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Step 19 Results
\
Agent previous state: ('forward', 'green', None, None)
Agent drove left instead of forward. (rewarded 1.19)
43% of time remaining to reach destination.
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Step 20 Results
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Agent previous state: ('right', 'green', None, 'left')
Agent drove forward instead of right. (rewarded 0.98)
40% of time remaining to reach destination.
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Step 21 Results
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Agent previous state: ('right', 'red', None, 'left')
Agent followed the waypoint right. (rewarded 0.79)
37% of time remaining to reach destination.
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/   Step 22 Results
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Step 22 Results
Step 22 Results
Step 22 Results
Step 22 Results \  Agent previous state: ('forward', 'green', None, None)
Step 22 Results  \  Agent previous state: ('forward', 'green', None, None)  Agent drove right instead of forward. (rewarded 0.94)
Step 22 Results  \  Agent previous state: ('forward', 'green', None, None)  Agent drove right instead of forward. (rewarded 0.94)
Step 22 Results  \  Agent previous state: ('forward', 'green', None, None)  Agent drove right instead of forward. (rewarded 0.94)  34% of time remaining to reach destination.

Agent previous state: ('left', 'red', None, None)
Agent drove right instead of left. (rewarded 1.40)
31% of time remaining to reach destination.
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Step 24 Results
\
Agent previous state: ('right', 'green', None, None)
Agent drove left instead of right. (rewarded 1.00)
29% of time remaining to reach destination.
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Step 25 Results
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Agent previous state: ('left', 'red', None, None)
Agent attempted driving forward through a red light with traffic and cause a major accident. (rewarded 39.29)
26% of time remaining to reach destination.
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Step 26 Results
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Agent previous state: ('left', 'red', 'forward', 'forward')

Agent attempted driving right through traffic and cause a minor accident. (rewarded -19.96)
23% of time remaining to reach destination.
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Step 27 Results
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Agent previous state: ('left', 'red', 'forward', None)
Agent attempted driving forward through a red light. (rewarded -10.07)
20% of time remaining to reach destination.
/
Step 28 Results
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Agent previous state: ('left', 'green', 'forward', None)
Agent attempted driving left through traffic and cause a minor accident. (rewarded -20.87)
17% of time remaining to reach destination.
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Step 29 Results
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Agent previous state: ('left', 'green', None, None)
Agent followed the waypoint left. (rewarded 1.12)

14% of time remaining to reach destination.
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Step 30 Results
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Agent previous state: ('forward', 'red', None, None)
Agent attempted driving left through a red light. (rewarded -10.71)
11% of time remaining to reach destination.
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Step 31 Results
\
Agent previous state: ('forward', 'red', None, None)
Agent attempted driving left through a red light. (rewarded -9.77)
9% of time remaining to reach destination.
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Step 32 Results
\
Agent previous state: ('forward', 'red', 'right', None)
Agent attempted driving left through a red light with traffic and cause a major accident. (rewarded 39.63)
6% of time remaining to reach destination.

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Step 33 Results
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Agent previous state: ('forward', 'green', 'forward', None)
Agent drove right instead of forward. (rewarded -0.32)
3% of time remaining to reach destination.
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Step 34 Results
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