

Gradient Flows and Diffusion Semigroups in Metric Spaces under Lower Curvature Bounds

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Abstract

We present some new results concerning well-posedness of gradient flows generated by λ -convex functionals in a wide class of metric spaces, including Alexandrov spaces satisfying a lower curvature bound and the corresponding L^2 -Wasserstein spaces. Applications to the gradient flow of Entropy functionals in metric-measure spaces with Ricci curvature bounded from below and to the corresponding diffusion semigroup are also considered. These results have been announced during the workshop on “Optimal Transport: theory and applications” held in Pisa, November 2006.

Let (X, d) be a complete and separable metric space. A (constant speed, minimal) *geodesic* is a curve $x : [0, 1] \rightarrow X$ such that $d(x_s, x_t) = |x| |s - t|$, $\forall s, t \in [0, 1]$, $|x|$ denoting its (constant) metric velocity.

Definition 1 (λ -convexity) *A functional $\phi : X \rightarrow (-\infty, +\infty]$ is λ -convex, $\lambda \in \mathbb{R}$, if every couple of points $x_0, x_1 \in D(\phi) := \{u \in X : \phi(u) < +\infty\}$ can be connected by a geodesic x such that*

$$\phi(x_t) \leq (1-t)\phi(x_0) + t\phi(x_1) - \frac{1}{2}\lambda t(1-t)d^2(x_0, x_1) \quad \forall t \in [0, 1]. \quad (1)$$

In contrast with the well known case when X is an Hilbert space [3], in arbitrary metric spaces λ -convexity is generally not sufficient to obtain the existence of a λ -contracting gradient flow, and it is a common belief that some “Riemannian-like” structure for X should also be required. When X is a *non positively curved* (NPC) Alexandrov space (i.e., the squared distance map $u \mapsto \frac{1}{2}d^2(u, v)$ is 1-convex, see e.g. [4]), then a generation result reproducing the celebrated CRANDALL-LIGGET argument has been proved by [7] and it has been refined in various directions in [1]. In this note we consider the case of spaces satisfying (in a suitable synthetic way) only a lower bound on the curvature. Besides Alexandrov spaces (considered by a completely different method in the unpublished [9] and, when X is compact and positively curved, in the recent [8]), our approach covers more general situations, as the Wasserstein space $\mathcal{P}_2(X)$, when the Riemannian manifold X has points with negative sectional curvature. In particular our conditions are preserved by the Wasserstein construction and avoid compactness of the sublevels of ϕ .

Let us recall the metric definition of gradient flow for a λ -convex functional (see [1, Chap. 4]).

Definition 2 (Gradient flow) *Let $\phi : X \rightarrow (-\infty, +\infty]$ be proper, l.s.c., and λ -convex. The gradient flow of ϕ with initial value $u_0 \in \overline{D(\phi)}$ is a locally Lipschitz curve $u : t \in (0, +\infty) \mapsto u_t \in D(\phi)$ such that*

$$\frac{d}{dt} \frac{1}{2} d^2(u_t, v) + \frac{\lambda}{2} d^2(u_t, v) \leq \phi(v) - \phi(u_t) \quad \text{for a.e. } t \in (0, +\infty), \quad \forall v \in D(\phi); \quad \lim_{t \downarrow 0} u_t = u_0. \quad (2)$$

Existence of gradient flows will be proved by the so called *Minimizing Movements* variational scheme.

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Definition 3 (The “Minimizing Movements” approximation scheme) A recursive minimizing sequence $\{U_\tau^n\}_{n \in \mathbb{N}}$ with step $\tau > 0$ and initial datum $U^0 \in X$ is any solution of the family of problems

$$U_\tau^0 := U^0, \quad U_\tau^n \in \operatorname{argmin}_V \left(\frac{1}{2\tau} d^2(U_\tau^{n-1}, V) + \phi(V) \right) \quad n = 1, 2, \dots \quad (3)$$

A discrete solution $\bar{U}_\tau : [0, +\infty) \rightarrow X$ is defined by setting $\bar{U}_\tau(t) \equiv U_\tau^n$ if $t \in ((n-1)\tau, n\tau]$. The variational scheme is generically solvable if there exists a minimizing sequence $\{U_\tau^n\}_{n \in \mathbb{N}}$ for every U^0 in a dense subset of $D(\phi)$ and for a vanishing sequence of time steps τ (depending on U^0).

Definition 4 (Semi-concavity of the squared distance function) We say that X is a K-SC (SemiConcave) space, $K \geq 1$, if for every geodesic x and any $y \in X$

$$d^2(x_t, y) \geq (1-t)d^2(x_0, y) + td^2(x_1, y) - Kt(1-t)d^2(x_0, x_1) \quad \forall t \in [0, 1]. \quad (4)$$

Examples

- PC SPACES: X is *Positively Curved* (PC) in the sense of ALEXANDROV iff it is K-SC with $K = 1$.
- ALEXANDROV SPACES: if X is an Alexandrov space whose curvature is bounded from below by a negative constant $-\kappa$ and $D = \operatorname{diam}(X) < +\infty$, then X is K-SC with $K = D\sqrt{\kappa}/\tanh(D\sqrt{\kappa})$. This class includes all bounded and complete Riemannian manifolds whose sectional curvature is bounded from below.
- PRODUCT AND L^2 SPACES: if (X_i, d_i) is a (even countable) collection of K-SC spaces, then $\mathbf{X} := \prod_i X_i$ with the usual product distance is K-SC. If μ is a finite measure on some separable measure space Ω then $\mathcal{X} := L_\mu^2(\Omega; X)$ endowed with the distance $d_{\mathcal{X}}^2(x, y) := \int_\Omega d^2(x(\omega), y(\omega)) d\mu(\omega)$
- WASSERSTEIN SPACE: $\mathcal{P}_2(X)$ is the set of all Borel probability measures μ on X with $\int_X d^2(x, x_0) d\mu < +\infty$ for some $x_0 \in X$, endowed with the L^2 -Wasserstein distance [11, 1]. $\mathcal{P}_2(X)$ is K-SC iff X is K-SC.

Definition 5 ((Upper) angles) Let x^1, x^2 be two geodesics emanating from the same initial point $x_0 := x_0^1 = x_0^2$. Their upper angle $\angle_u(x^1, x^2) \in [0, \pi]$ is defined by

$$\cos(\angle_u(x^1, x^2)) := \liminf_{s, t \downarrow 0} \frac{d^2(x_0, x_s^1) + d^2(x_0, x_t^2) - d^2(x_s^1, x_t^2)}{2d(x_0, x_s^1)d(x_0, x_t^2)}. \quad (5)$$

Definition 6 (Local Angle Condition (LAC)) X satisfies the local angle condition (LAC) if for any triple of geodesics $x^i, i = 1, 2, 3$, emanating from the same initial point x_0 the corresponding angles $\theta^{ij} := \angle_u(x^i, x^j) \in [0, \pi]$ satisfy one of the following equivalent conditions:

1. $\theta^{12} + \theta^{23} + \theta^{31} \leq 2\pi$.
2. There exists an Hilbert space H and vectors $w^i \in H$ such that $\langle w^i, w^j \rangle_H = \cos(\theta^{ij}) \quad 1 \leq i, j \leq 3$.
3. For every choice of $\xi_1, \xi_2, \xi_3 \geq 0$ one has $\sum_{i,j=1}^3 \cos(\theta^{ij}) \xi_i \xi_j \geq 0$.

Examples

- A BANACH SPACE X satisfies (LAC) iff X is a HILBERT SPACE.
- RIEMANNIAN MANIFOLDS AND ALEXANDROV SPACES with curvature bounded below satisfy (LAC).
- PRODUCT SPACES: $\mathbf{X} := \prod_i X_i$ satisfies (LAC) iff each (X_i, d_i) does satisfy it.
- L^2 SPACES: The space $L_\mu^2(\Omega; X)$ satisfies (LAC) iff X satisfies it.
- WASSERSTEIN SPACE: The L^2 -Wasserstein space $\mathcal{P}_2(X)$ satisfies (LAC) iff X does.
- Let (e_i) be an orthonormal basis of \mathbb{R}^4 and let X be the cone $\{\sum_{i=1}^4 x_i e_i : x_i \geq 0\} \subset \mathbb{R}^4$ with the distance $d^2(x, y) := |x|^2 + |y|^2 - 2|x||y|\cos(\frac{1}{3}\sqrt{2}\pi|\frac{x}{|x|} - \frac{y}{|y|}|)$. The geodesics $x_t^e := te, e \in X, t \in [0, 1]$, emanating from the origin satisfy (LAC) since $\angle_u(x^e, x^f) \leq 2\pi/3$ but X is not an Alexandrov space since $\sum_{i,j=1}^4 \cos(\angle_u(x^{e_i}, x^{e_j})) = -2 < 0$.

Main results

Let us recall that the *Metric Slope* of ϕ at $u \in D(\phi)$ is $|\partial\phi|u := \limsup_{v \rightarrow u} (\phi(u) - \phi(v))^+ / d(u, v)$.

Theorem 7 (Generation result for gradient flows) *Let X be a K -SC space satisfying (LAC) and let $\phi : X \mapsto (-\infty, +\infty]$ be proper, l.s.c., and λ -convex. If (3) is generically solvable, then*

λ -contractive semigroup. *For every $u_0 \in \overline{D(\phi)}$ there exists a unique gradient flow $u := S[u_0]$ according to definition 2. The map $u_0 \mapsto S_t[u_0]$ is a λ -contracting continuous semigroup on $\overline{D(\phi)}$, i.e.*

$$S_{t+h}[u_0] = S_h[S_t[u_0]], \quad d(S[u_0](t), S[v_0](t)) \leq e^{-\lambda t} d(u_0, v_0) \quad \forall u_0, v_0 \in \overline{D(\phi)}. \quad (6)$$

Uniform error estimate. *For every time interval $[0, T]$ there exists a “universal” constant $C_{K, \lambda, T}$ (only depending on K, λ, T) such that for every discrete solution \bar{U}_τ , $\tau \in (0, \frac{1}{2\lambda})$,*

$$\sup_{t \in [0, T]} d^2(u_t, \bar{U}_\tau(t)) \leq \begin{cases} C_{K, \lambda, T} (\phi(u_0) - \inf_X \phi) \cdot \sqrt{\tau} & \text{if } u_0 = U_\tau^0 \in D(\phi), \\ C_{K, \lambda, T} |\partial\phi|^2(u_0) \cdot \tau & \text{if } u_0 = U_\tau^0 \in D(|\partial\phi|). \end{cases} \quad (7)$$

Regularizing effect. *S_t maps $\overline{D(\phi)}$ into $D(|\partial\phi|) \subset D(\phi)$ for every $t > 0$, $t \mapsto e^{\lambda t} |\partial\phi|(u_t)$ is nonincreasing, $t \mapsto \phi(u_t)$ is (locally semi-, if $\lambda < 0$) convex, and, when $\lambda \geq 0$,*

$$\phi(u_t) \leq \phi(v) + \frac{1}{2t} d^2(u_0, v), \quad |\partial\phi|^2(u_t) \leq |\partial\phi|^2(v) + \frac{1}{t^2} d^2(u_0, v) \quad \forall v \in X. \quad (8)$$

Energy identity. *The right limits $|\dot{u}_{t+}| := \lim_{h \downarrow 0} \frac{d(u_t, u_{t+h})}{h}$ and $\frac{d}{dt+} \phi(u_t) := \lim_{h \downarrow 0} \frac{\phi(u_{t+h}) - \phi(u_t)}{h}$ exist for every $t \geq 0$, are finite if $t > 0$, and coincide with the corresponding left ones for $t \in (0, +\infty) \setminus \mathcal{C}$, \mathcal{C} being at most countable. They satisfy the differential energy identity*

$$\frac{d}{dt+} \phi(u_t) = -|\dot{u}_{t+}|^2 = -|\partial\phi|^2(u_t) \quad \forall t \geq 0. \quad (9)$$

Asymptotic behavior. *If $\lambda > 0$, then ϕ admits a unique minimum point \bar{u} and for $t \geq t_0 \geq 0$ we have*

$$\frac{\lambda}{2} d^2(u_t, \bar{u}) \leq \phi(u_t) - \phi(\bar{u}) \leq \frac{1}{2\lambda} |\partial\phi|^2(u_t), \quad d^2(u_t, \bar{u}) \leq d^2(u_{t_0}, \bar{u}) e^{-\lambda(t-t_0)}, \quad (10a)$$

$$\phi(u_t) - \phi(\bar{u}) \leq (\phi(u_{t_0}) - \phi(\bar{u})) e^{-2\lambda(t-t_0)}, \quad |\partial\phi|(u_t) \leq |\partial\phi|(u_{t_0}) e^{-\lambda(t-t_0)}. \quad (10b)$$

Applications to metric-measure spaces. Let (X, d, γ) be a metric-measure space with $\gamma \in \mathcal{P}(X)$. On the Wasserstein space $\mathcal{X} = \mathcal{P}_2(X)$ we consider the Relative Entropy functional $\phi(\mu) = \text{Ent}(\mu|\gamma) := \int_X \rho \log \rho d\gamma$ if $\mu = \rho \cdot \gamma \ll \gamma$, $\phi(\mu) := +\infty$ otherwise. According to [10, 6], X satisfies the **lower Ricci curvature bound** $\underline{\text{Curv}}(X, d, \gamma) \geq \lambda$ iff the functional $\phi = \text{Ent}(\cdot|\gamma)$ is λ -geodesically convex in $\mathcal{P}_2(X)$. X is *non-branching* if two geodesics x, y with $x_0 = y_0$ and $x_{\bar{t}} = y_{\bar{t}}$ for some $\bar{t} \in (0, 1)$ must coincide.

Theorem 8 (Markov semigroup and diffusion kernels) *Let us suppose that X is K -SC, satisfies (LAC) and $\underline{\text{Curv}}(X, d, \gamma) \geq \lambda$. There exists a unique λ -contracting gradient flow S_t generated by $\phi = \text{Ent}(\cdot|\gamma)$ on $\mathcal{X}_\gamma := \{\mu \in \mathcal{P}_2(X) : \text{supp } \mu \subset \text{supp } \gamma\}$ as a limit of the (always solvable) Minimizing Movement scheme. S_t enjoys all the properties stated in Theorem 7 and, if X is non-branching, it satisfies the linearity condition*

$$S_t[\alpha\mu_0 + \beta\mu_1] = \alpha S_t[\mu_0] + \beta S_t[\mu_1] \quad \forall \mu_0, \mu_1 \in \mathcal{P}_2(X), \quad \alpha, \beta \geq 0, \quad \alpha + \beta = 1. \quad (11)$$

γ is an invariant measure and the kernels $\nu_{x,t} := S_t[\delta_x] \ll \gamma$ satisfy the Chapman-Kolmogorov equation

$$\nu_{x,t+s}(E) = \int_X \nu_{y,t}(E) d\nu_{x,s}(y) \quad \forall E \in \mathcal{B}(X), \quad x \in \text{supp } \gamma, \quad t, s > 0; \quad S_t[\mu] = \int_X \nu_{x,t} d\mu(x). \quad (12)$$

S_t can be uniquely extended to a Markov (i.e. linear, order preserving, strongly continuous, contraction) semigroup \mathcal{S}_t in $L^p(\gamma)$ such that $\mathcal{S}_t[\rho_0]\gamma = S_t[\rho_0\gamma]$ for every $\rho_0 \in L^p(\gamma)$ with $\rho_0\gamma \in \mathcal{P}_2(X)$.

Remark 9 When $X = \mathbb{R}^d = \text{supp } \gamma$, there exists a λ -convex potential $V : \mathbb{R}^d \rightarrow \mathbb{R}$ such that $\gamma = e^{-V} \mathcal{L}^d$ and the gradient flow $\mu_t = u_t \mathcal{L}^d$ generated by $\text{Ent}(\cdot | \gamma)$ satisfies the Fokker-Planck equation [5, 2]

$$\partial_t u_t - \nabla \cdot (\nabla u_t + u_t \nabla V) = 0 \quad \text{in } \mathbb{R}^d \times (0, +\infty). \quad (13)$$

Stability of gradient flows. Let now consider a sequence $(X^k, \mathbf{d}^k, \gamma^k)$, $\gamma^k \in \mathcal{P}_2(X^k)$, of metric measure spaces converging to (X, \mathbf{d}, γ) in the *measured* Gromov-Hausdorff distance. That means [10, 6] that a sequence of (separable and complete) coupling semidistances $\hat{\mathbf{d}}^k$ on the disjoint union $X^k \sqcup X$ exists s.t.

$$\lim_{k \rightarrow \infty} \hat{\mathbf{d}}_W^k(\gamma^k, \gamma) = 0, \quad \hat{\mathbf{d}}_W^k \text{ being the } L^2\text{-Wasserstein distance in } \mathcal{P}_2(X^k \sqcup X) \text{ induced by } \hat{\mathbf{d}}^k. \quad (14)$$

A sequence $\mu^k \in \mathcal{P}_2(X^k)$ converges to $\mu \in \mathcal{P}_2(X)$ if $\lim_{k \rightarrow \infty} \hat{\mathbf{d}}_W^k(\mu^k, \mu) = 0$.

Theorem 10 *Let us assume that each metric space X^k is K-SC, it satisfies (LAC) and the lower Ricci bound $\text{Curv}(X^k, \mathbf{d}^k, \gamma^k) \geq \lambda$ for suitable constants λ, K independent of k . If $\mu_0^k \in \mathcal{P}_2(X^k)$ is a sequence converging to $\mu_0 \in \mathcal{P}_2(X)$ with equibounded relative entropy $\sup_k \text{Ent}(\mu_0^k | \gamma^k) < +\infty$, then for every $t \geq 0$ the solution $\mu_t^k := S_t^k[\mu_0^k]$ of the “Entropy gradient flow” given by Theorem 8 converges to the measure $\mu_t = S_t[\mu_0] \in \mathcal{P}_2(X)$ which is the (unique) Entropy gradient flow in $\mathcal{P}_2(X)$ with initial datum μ_0 .*

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