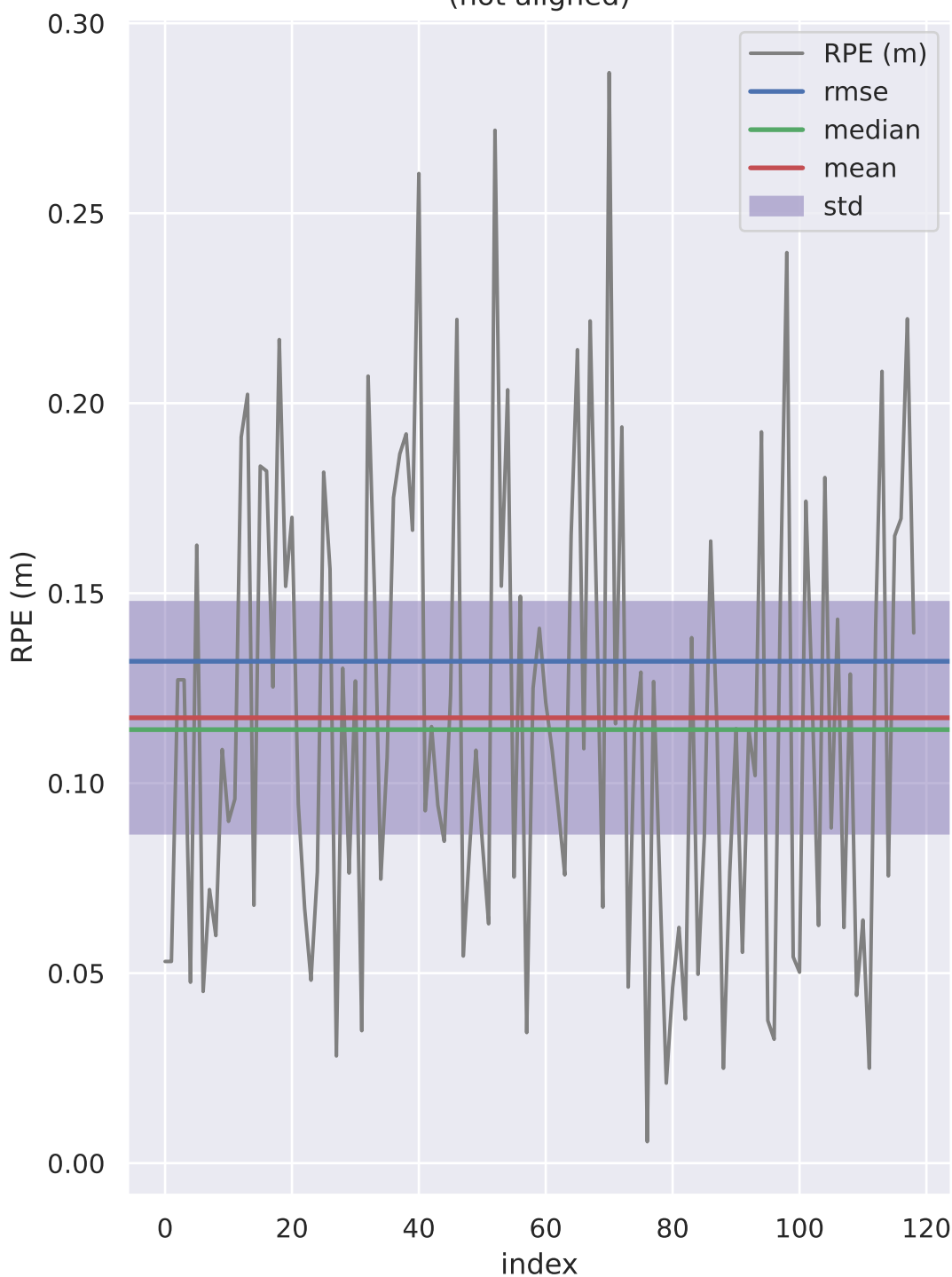


RPE w.r.t. translation part (m)  
for  $\delta = 1$  (frames) using consecutive pairs  
(not aligned)



Error mapped onto trajectory

