2021 Final Solutions for 2024 Students

Patrick Ferguson

December 13, 2024

Note that this was a take-home exam (due to Covid).

Exercise 1.

(a) False. Let $f, g : \mathbb{R} \to \mathbb{R}$ be given by

$$f(x) := \mathbf{1}\{x \geqslant 0\} \cdot (-x)$$

and

$$g(x) := \mathbf{1}\{x \leqslant 0\} \cdot x$$

Then (f+g)(x) = -|x|, which is not quasi-convex.

- (b) False. $e^x \cdot e^{-x} = e^0 = 1$.
- (c) True. See Section 4 Exercise 2.
- (d) False. See 2023 Midterm 2 Q1(iii).
- (e) False. f is continuous at 0. If $x_n \to 0$ then for each $n \in \mathbb{N}$, $f(x_n) = x_n$ or $f(x_n) = 0$. In both cases $f(x_n) \to 0$.

Exercise 2.

(a) F is clearly C^1 . We want to show that $\partial F/\partial y \neq 0$ at (0,0.5,0.5).

$$\frac{\partial F(0, 0.5, 0.5)}{\partial y} = 1 - x_1 x_2 e^{x_1 x_2 y} \Big|_{(0, 0.5, 0.5)} = 1 \neq 0$$

We then have

$$Dh = -\left[\frac{\partial F}{\partial y}\right]^{-1} D_x F$$

$$= -\frac{1}{1 - x_1 x_2 e^{x_1 x_2 y}} \left[1 - x_2 y e^{x_1 x_2 y} \quad 1 - x_1 y e^{x_1 x_2 y}\right]$$

(b) Again, F is clearly C^1 . We have

$$DF_y(2, -1, 2, 1) = \begin{bmatrix} -3y_1^2 & 2y_2 \\ -4y_1 & 12y_2^3 \end{bmatrix} \Big|_{(2, -1, 2, 1)}$$
$$= \begin{bmatrix} -12 & 2 \\ -8 & 12 \end{bmatrix}$$

which has determinant $-144 + 16 = 128 \neq 0$.

$$Dh = -[D_y F]^{-1} D_x F$$

$$= -\begin{bmatrix} -3y_1^2 & 2y_2 \\ -4y_1 & 12y_2^3 \end{bmatrix}^{-1} \begin{bmatrix} 2x_1 & -2x_2 \\ 2x_2 & 2x_1 + 2x_2 \end{bmatrix}$$

$$= -\frac{1}{-36y_1^2 y_2^3 + 8y_1 y_2} \begin{bmatrix} 12y_2^3 & -2y_2 \\ 4y_1 & -3y_1^2 \end{bmatrix} \begin{bmatrix} 2x_1 & -2x_2 \\ 2x_2 & 2x_1 + 2x_2 \end{bmatrix}$$

 $\it Exercise$ 3. Compare Module 5 "Differentiation" Exercise 18.

Exercise 4.

(a) Continuous differentiability implies continuity, so π is continuous. Because the domain, [0,100] is compact, we know that π attains a maximum. $\pi'(q) = p(q) + qp'(q) - c'(q) + s$ and so $\pi''(q) = p'(q) + qp''(q) + p'(q) - c''(q)$. We know that p'(q) < 0, $q \ge 0$, $p''(q) \le 0$, and $c''(q) \ge 0$. It follows that $\pi''(q) < 0$, so that profit is strictly concave in output. This implies that the maximum attained is unique. The FOC is

$$0 \equiv \pi'(q) = p(q) + qp'(q) - c'(q) + s$$

We can therefore write

$$F(q,s) := p(q) + qp'(q) - c'(q) + s$$

We know that $\pi''(q) < 0$, so the conditions of the implicit function theorem are met. We then have

$$\frac{dq}{ds} = -\left[\frac{\partial F}{\partial q}\right]^{-1} \frac{\partial F}{\partial s}$$
$$= -\left[\pi''(q)\right]^{-1} (1)$$
$$> 0$$

(b) We still have a continuous objective function on a compact domain, so we know that a solution exists. We cannot say that it is unique. We have

$$\frac{\partial^2 \pi}{\partial s \partial q} = \frac{\partial}{\partial s} \left[p(q) + q p'(q) - c'(q) + s \right]$$

$$= 1$$

$$> 0$$

so that π has increasing differences in (q, s). Clearly, $\pi(\cdot, s)$ is supermodular in q (because $q \in \mathbb{R}$, which is totally ordered). By the Theorem of Milgrom and Shannon, the solution set $Q^*(s) := \arg\max_{q \in [0,100]} \pi(q, s)$ is monotone increasing in s, in the strong set order.

Exercise 5.

(a)

$$\frac{\partial^2 \pi}{\partial p \partial \alpha} = \frac{\partial}{\partial p} \left[-\alpha p^{-\alpha} \log(p) \cdot (p - c) \right]$$

$$= -\alpha \left[-\alpha p^{-\alpha - 1} \log(p) \cdot (p - c) + p^{-\alpha} \cdot \frac{1}{p} \cdot (p - c) + p^{-\alpha} \log(p) \right]$$

$$= -\alpha p^{-\alpha - 1} \left[-\alpha \log(p) \cdot (p - c) + p - c + p \log(p) \right]$$

The term outside the brackets is negative. For fixed $p < \infty$, as $\alpha \to 0$, the term inside the brackets approaches $p - c + p \log p$. If $p > \max\{c, 1\}$, this expression is positive; if $p < \min\{c, 1\}$, this expression is negative. Therefore, $\partial^2 \pi / \partial p \partial \alpha$ takes both positive and negative values over \mathbb{R}^2_{++} .

- (b) $(\log \circ \pi)(p, \alpha) = -\alpha \log(p) + \log(p c)$. This has cross derivative -1/p < 0.
- (c) By the Theorem of Milgrom and Shannon, $-p^*(\alpha)$ is monotone increasing in α . It follows that $p^*(\alpha)$ is monotone decreasing. It follows, in turn, that $D(p^*, \alpha) := (p^*)^{-\alpha}$ is monotone increasing in α .
- (d) It suffices to show that $\log D(p,\alpha)$ has increasing differences. We are given that elasticity,

$$\frac{\partial \log D(p,\alpha)}{\partial p}$$

is increasing in α . Then

$$\frac{\partial^2 \log D(p, \alpha)}{\partial \alpha \partial p} \geqslant 0$$

as required.

Exercise 6. This exercise uses dynamic programming, which we did not cover in 2024.

Exercise 7.

Note that what Suraj calls the "single-crossing property", we call "single-crossing differences".

- (a) From the definitions.
- (b) Module 7 "Comparative Statics" Exercise 7.
- (c) Any function f(x,t) that does not satisfy increasing differences but such that g(t) := f(x',t) f(x,t), does not cross or intersect with the t-axis for all x' > x will work. For example, if $f: \mathbb{R}^2_{++} \to \mathbb{R}$ is defined by f(x,t) = x/t, then

$$\frac{\partial^2 f}{\partial x \partial t} = -\frac{1}{t^2} < 0$$

but if x' > x

$$f(x',t) - f(x,t) = \frac{x'-x}{t} > 0$$

Therefore, f(x',t') > f(x,t') for all t' and all x' > x, so single-crossing differences is satisfied.