

# Problem Set on Convex Sets

Let's recall some definitions.

**Definition 1.** A **closed half-space** in  $\mathbf{R}^n$  is a set of points  $[p \geq \alpha] = \{x : p \cdot x \geq \alpha\}$  or  $[p \leq \alpha] = \{x : p \cdot x \leq \alpha\}$  for some  $p \in \mathbf{R}^n$  and  $\alpha \in \mathbf{R}$ .

A **half-space** is just the set of points one side or the other of a hyperplane  $[p = \alpha] = \{x : p \cdot x = \alpha\}$ . If the half-space includes the hyperplane, it is closed. If it contains no points in the hyperplane, it is open.

**Definition 2.** A hyperplane  $[p = \alpha]$  **separates** convex sets  $A$  and  $B$  iff for all  $x \in A$  and  $y \in B$ ,  $p \cdot x \leq \alpha$  and  $p \cdot y \geq \alpha$  (or vice versa). That is,  $A \subset [p \leq \alpha]$  and  $B \subset [p \geq \alpha]$  (or vice versa). The separation is **proper** iff there is some  $x \in A$  and  $y \in B$  for which  $p \cdot x \neq p \cdot y$ .

**Proper** just means that the two convex sets do not lie in the hyperplane.

**Definition 3.** Two convex sets  $A$  and  $B$  are **strongly separated** by  $p$  iff there is an  $\epsilon > 0$  and  $\alpha$  such that  $A \subset [p \leq \alpha]$  and  $B \subset [p \geq \alpha + \epsilon]$  (or vice versa).

The key result for us is

**Theorem 1** (Strong Separating Hyperplane Theorem). *If  $K$  and  $C$  are non-empty disjoint convex subsets of  $\mathbf{R}^n$  with  $K$  compact and  $C$  closed, then there is a  $p \neq 0$  which strongly separates  $K$  and  $C$ .*

**Strong separation** means that there is a separating hyperplane containing neither set.

There are two ways to describe a closed convex set  $C$ . The **primal** description of  $C$  is the list of elements in  $C$ . The **dual** description of  $C$  is the set of closed half-spaces containing  $C$ . Proving this, which we briefly discussed in class, is problem 1 below.

1. Use the strong separating hyperplane theorem to show that if  $C$  is a closed convex set, then  $C$  is the intersection of the half-spaces containing it.
2. For  $p \in \mathbf{R}^n$ , define  $e_C(p) = \inf\{p \cdot x, x \in C\}$ .  $e_C(p)$  is called the **concave support function** of  $C$ .
  - (a) Show that  $e(p)$  is concave.
  - (b) Show that  $e(p)$  is homogeneous of degree 1.
  - (c) What does it mean if  $e(p) = -\infty$ ? You can explain with a picture.
  - (d) Show that  $[p \geq \alpha]$  ( $[-p \leq -\alpha]$ ) contains  $C$  iff  $\alpha \leq e(p)$ .
3. Show that a function  $f : \mathbf{R}^n \rightarrow \mathbf{R}$  is concave iff  $\{(x, y) \in \mathbf{R}^n \times \mathbf{R} : y \leq f(x)\}$  is convex. This set is called the **subgraph** or **hypograph** of  $f$ .
4. Give an example of two closed convex sets that cannot be strongly separated.
5. Prove *Gordan's Lemma*: Either  $Ax = 0, x > 0$  has a solution or  $yA \ll 0$  has a solution. Hint: This follows from Farkas' lemma.

For notation in problem 5 (and throughout the course),  $x \geq 0$  means  $x \in \mathbf{R}_+^n$ .  $x > 0$  means that  $x \geq 0$  and  $x \neq 0$ . Such vectors are called *semi-positive*.  $x \gg 0$  means that each component of  $x$  is strictly positive. Similarly for the less-than relationships.