· Metrix Lie groups Today: · Lie algebres · Representations Next time . symmetries in QM · role of representation theory Lie Groups, Lie Algebres, and Representations Good reference: Brien C. Hall

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Def: A metrix Lie group is a closed subgroup G ≤ GL(n, C) for some n∈N
 (closed w.r.t. the topology induced from Mn(a)) using operator norm
                                                      ||A|| = Sup { ||A x || | x & C | {0}}
 GL(U, C) = {A & Mn (C) | det A # 0 5
                                                   or use the norm from Cuz
                 nxn metrices
examples
 · GL (n, C) general linear group over C
 · SL (h, C) = {A ∈ GL(h, C) | det A = 1} special linear group over C
 · GL (n, IR) = {A & GL(n, C) | A - A = o} general linear group over IR
  · SL(n, IR) = { A ∈ GL(n, IR) | det A = 1 } special linear group over IR
 · O(h) = { A & GL (h, IR) | AtA = 11 } orthogonal group
 · SO(n) = {A & O(n) | det A = 1} special orthogonal group
 • U(n) = \{A \in GL(n, C) \mid A^*A = 11\} unitary group
                                                           red Lie groups
 · Su(n) = {A \in U(n) | det A = 1} special unitary group | despite having complex
 Some familier examples:
 · U(1) = { z ∈ C \ {0} | 1212 = 1} circle group
 . SO(2) = \left\{ \begin{pmatrix} GS\theta & Sin\theta \\ -5in\theta & GS\theta \end{pmatrix} \middle| \theta \in [0, 2\pi) \right\} 2D rotation group
              SAEM2(IR) At A=1, set A=1}
                      (eb) | A-bc=1 (ec) (ea)=(1)
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Def: A real or complex Lie algebre is a vector space V over IR or C with
 on operation [.,.]: V x V > V (Lie brocket) satisfying
     [xx+By, 2] = x[x,2]+B[y,2] (cmplibility
    [2, xx+ By] = x [2, x] + B [2, y]
  · [y, x] = - [x, y]
  · [x, [y, 2]] + [y, [z,x]] + [z, [x,y]] = 0 Je66: identy
     Prototype: Mn (4) with [x,y] = xy + yx
     Note: [., .] not assistive
                                Motorx Lie Group
Def: Let G < GL(4, a) be a MLG. The associated Lie algebra is
the set Lie(G) = { x & Mn (C) | exeG Y & & IR} with Lie brecket
                  [x,y] = xy-yx
Note: Lie(G) is usually denoted by (g) > you on use 3
 prost con be found in "extre" folder on google drive
 Q(u) = SO(n)
                          \underline{o}(n) = \{ \times \in M_n(n) \mid \times^{\top} = - \times \}
                          SO(n) = \left\{ \times \in \mathcal{Q}(n) \mid tr \times = 0 \right\}
                                    xT=-x => {r x =0
  O(n) \neq So(n)
                                              tr xt = tr X
 but their Lie algebras are the same
                                              tv (-x) = - tv X
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Some more notions about MLGs:
. G = GL (h, C) is called compact if it is closed and bounded (w.r.t. to Mn (a))
     > O(n), so(n), u(n), su(n) are compact
                             Hene-Borel theorem
· G connected if for every g & G there is a continuous path connecting it
  to the identity (\gamma: [0,1] \rightarrow G with \gamma(0)=e, \gamma(1)=g)
        > So(h) is Gueckel, o(h) is not
· G simply connected if connected and every loop (x: to,1) > G with x(0)=x(1)
  can be shrunk to a point ("no holes")

> U(1) is not simply connected

(ex) = ex
· if X & Lie (G) then { EX | E & | R} is a one-peremeter subgroup of G.
 In fact, every (smooth) one-parameter subgroup of G is of this form.
  > × generates the subgroup {ex| E eIR}
  if G is connected, every group element 8 EG can be written as
  8= ex exz - ex with x; eLie(G)
   > G is generated by Lie (G)
         o(h) is not convected but so(h) < o(h) is
                                    so(n) generales So(n) / 2(n) generales So(n)
· MLG homomorphism: antihuous group homomorphism Q: G > H
· MLG isomorphism: group isomorphism Q: G → H with Pend P-1 antimous
          Q: Z \in U(1) \rightarrow \begin{pmatrix} Re(Z) & Im(Z) \\ -Im(Z) & Re(Z) \end{pmatrix} \in SO(Z) isomorphism
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