Intro to Bayes

Upcoming

Bayesian programming Error Propagation Forecasting competition 1!

Things to keep in mind:

Be thinking about a forecasting project. (more details to come)

I am going to look over your lab 4 and get you feedback this week

Intro to Bayes

Forecasting time:

- ~ 5% to build model make mean prediction.
- ~ 95% to fully quantify and propagate sources of uncertainty.

Why Bayes?

The era of raging debate between Bayesians and frequentists has mostly ended....

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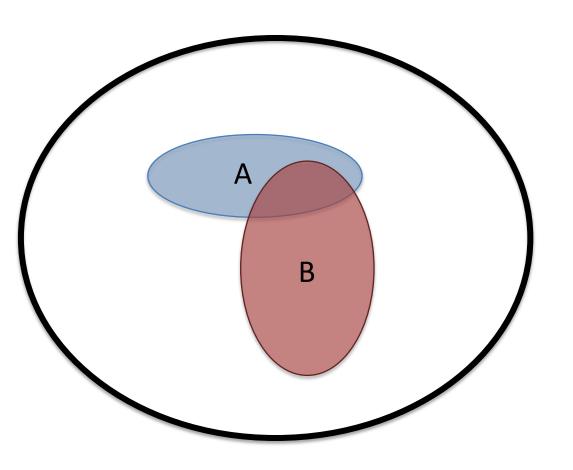
- 1. Well developed theoretical basis
- 2. Explicit quantification of probability (impossible with frequentist or ML)
- 3. Easy to partition uncertainty into different sources (difficult with frequentist or ML).
- 4. Easily handles missing data or uncertainty in data
- 5. Prior-posterior updating given new data allows for updating forecasts based on new data.

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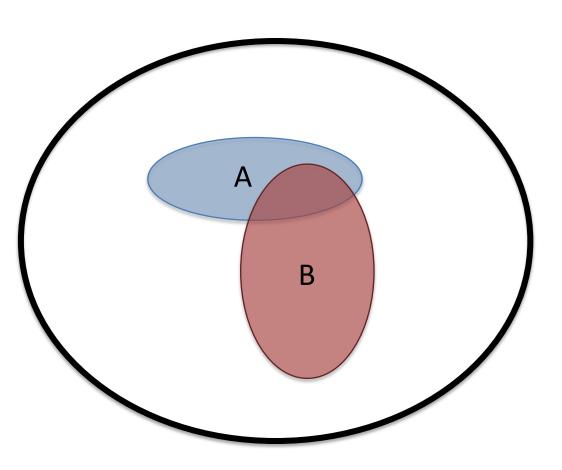
This doesn't mean that frequentist or ML approaches can't make valid and useful forecasts, Bayesian approaches just have a number of distinct advantages.



Marginal Probability

$$P(A) = Area \ of \ A$$

$$P(B) = Area \ of \ B$$



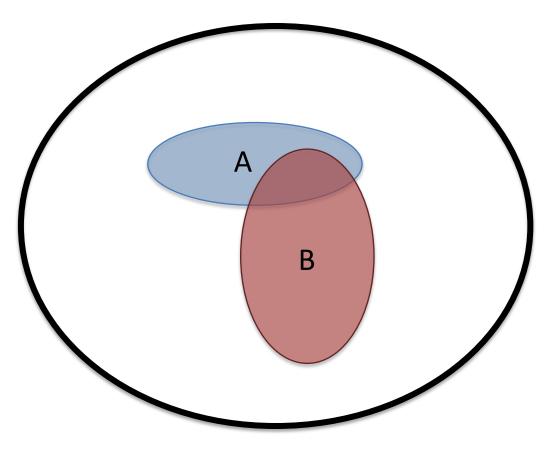
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P(A,B) = Shared Area of A & B



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Joint Probability

$$P(A,B) = Shared Area of A \& B$$

Conditional Probability

$$P(B|A) = \frac{Shared Area of A \& B}{Area of A}$$

$$P(B|A) = \frac{P(A,B)}{P(A)}$$

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Algebraic
rearrangement
$$P(A|B) = \frac{P(A,B)}{P(B)}$$

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The goal is to "learn" about parameters given observed data

Parameters Data
$$[\theta|y] = \frac{[\theta,y]}{[v]} \qquad [\theta,y] = [y|\theta] [\theta]$$

$$[\theta|y] = \frac{[y|\theta][\theta]}{[y]}$$

Notation: P(A) is the same as [A]

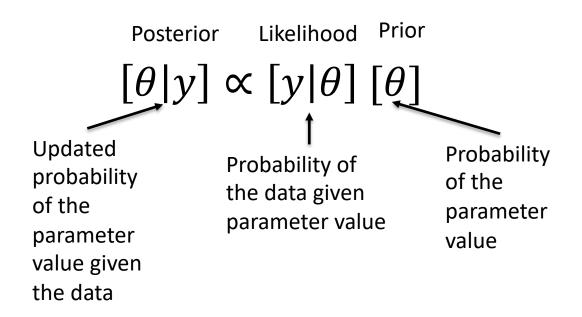
The goal is to "learn" about parameters given observed data

Posterior
$$[\theta | y] = \frac{[y|\theta][\theta]}{[y]}$$
Normalizing Constant

The goal is to "learn" about parameters given observed data

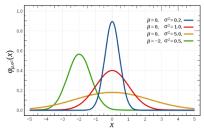
Posterior Likelihood Prior
$$[\theta|y] \propto [y|\theta] [\theta]$$

The goal is to "learn" about parameters given observed data



<u>Continuous</u> <u>Discrete</u>

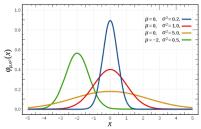
Normal: Any value from -Inf to Inf, Mean is independent of variance



Daily carbon flux

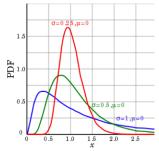
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Daily carbon flux

Log Normal: Any value from >0 to Inf, Variance scales with mean

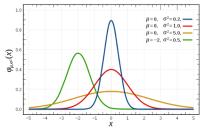


Population Density

Continuous

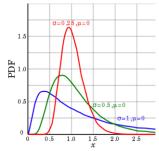
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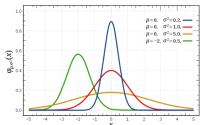
Beta: Any value from >0 to <1, Variance scales with mean



Survival Prob.

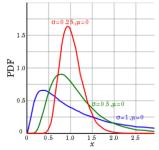
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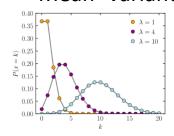
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Survival Prob.

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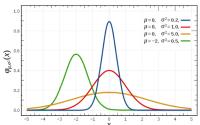
Poisson: Any value from 0 to Inf, Mean=Variance



Population Counts

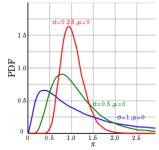
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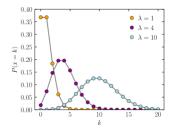
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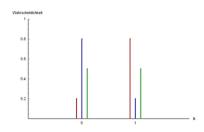
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Population Counts

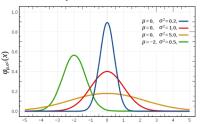
Bernoulli: 0 or 1, Single parameter Prob. That event will occur



Individual Survival

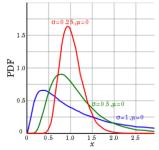
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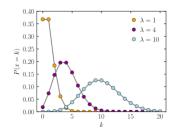
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Survival Prob.

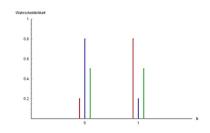
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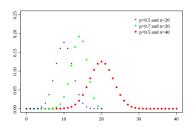
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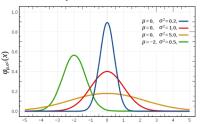
Binomial: 0 to Inf., Outcome of multiple Bernoulli events



Deaths in a population

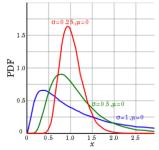
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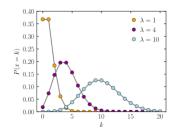
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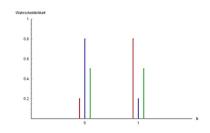
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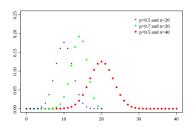
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Individual Survival

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Deaths in a population

Likelihood should match the data and data generating process.

Picking a likelihood Likelihood should match the data and data generating process. What matters is the conditional distribution not the raw data distribution.

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Questions to ask:

Are the data continuous or discrete?

What are the range of possible values that data can take?

How does the variance change as a function of the mean?

Likelihood should match the data and data generating process.

 $Normal(\mu, \sigma^2)$

Poisson (λ)

Likelihood should match the data and data generating process.

$Normal(\mu, \sigma^2)$

- Continuous
- Values from –Inf to Inf
- Variance constant and independent of mean
- No Skew

Poisson (λ)

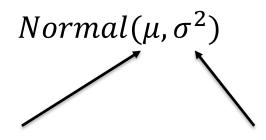
- Discrete
- Values from 0 to Inf
- Variance=mean
- Skewed at low values

Priors represent existing belief or knowledge about a parameter.

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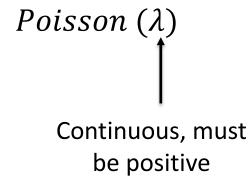
What range can a parameter take mathematically?
What values are biologically realistic given our current understanding?
Is there an appropriate conjugate prior?

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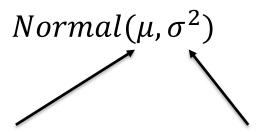


Continuous, Can take on any value.

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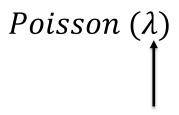


Continuous, Can take on any value.

 $Normal(\mu_p, \sigma_p^2)$

Continuous, must be positive

 $Gamma(a_p, b_p)$



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Priors represent existing belief or knowledge about a parameter.

When do priors need to be informative? When can they be uninformative?

Some parameters can almost reliably estimated by data. E.g.:

Regression parameters

Some parameters will rarely ever be indefinable without prior information. E.g.: Observation Error

Priors represent existing belief or knowledge about a parameter.

When do priors need to be informative? When can they be uninformative?

In practice, selecting priors can be part of the model development process.

Start with vague priors. If a parameter is not identifiable, additional data may be needed.

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P(Disease | Positive)= (P(Positive | Disease)*P(Disease))/P(Positive)

(.95*.01)/0.07=.135

Only 13.5% of people that test positive have the disease!

Posterior Calculations

If prior is conjugate, we can calculate the posterior analytically.

Conjugate: Posterior distribution is the same as prior with parameters updated based on data

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Likelihood
$$\mathbf{y} \sim Poisson(\lambda)$$

Prior
$$\lambda \sim Gamma\ (a_{prior}, b_{prior})$$

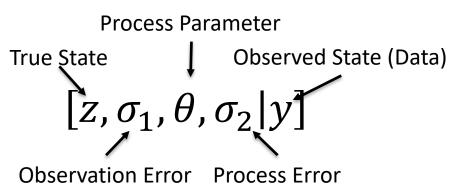
Posterior
$$\lambda |\mathbf{y} \sim Gamma \ (a_{prior} + \sum_{i=1}^{n} y_i \ , b_{prior} + n)$$

The mathematical calculations underlying this can be found online in a number of sources.

Complex problems

The power of Bayesian inference comes in modeling complex problems

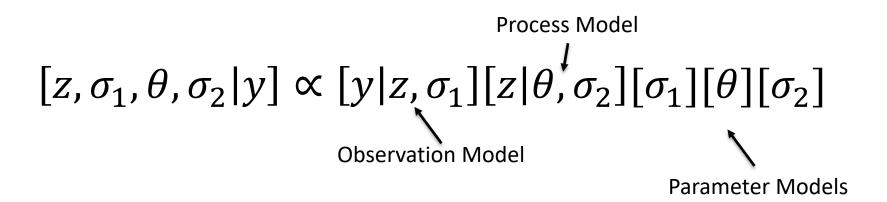
Examples of complex problems: Multiple datasets, unobserved (latent) states, autocorrelation, etc.



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Process Model
$$[z,\sigma_1,\theta,\sigma_2|y] \propto [y|z,\sigma_1][z|\theta,\sigma_2][\sigma_1][\theta][\sigma_2]$$
 Observation Model Parameter Models

This is an example of a hierarchical model

DAG (Directed Acyclic Graphs)

Thinking about and breaking down complex, hierarchical models

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 Observation Model Parameter Models

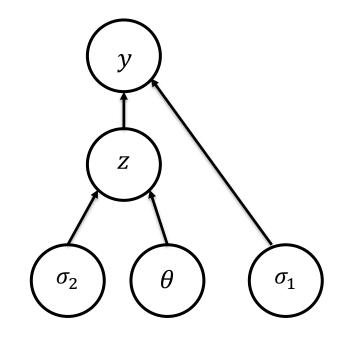
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Parameter Model

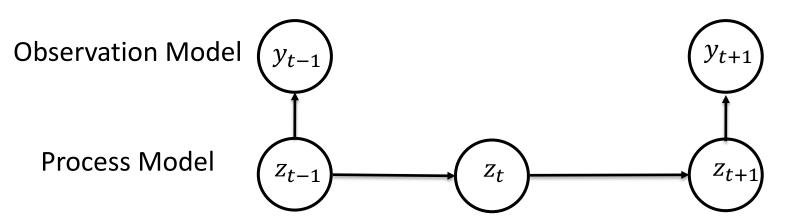


Process Model

$$[z, \sigma_1, \theta, \sigma_2 | y] \propto [y | z, \sigma_1] [z | \theta, \sigma_2] [\sigma_1] [\theta] [\sigma_2]$$
Observation Model

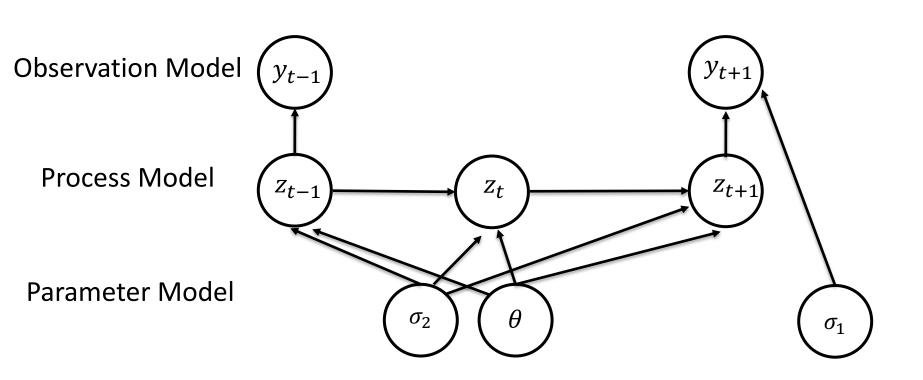
Parameter Models

Example 2: Missing data time series



Parameter Model

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Example 3: Making a forecast!

