



Flange Bolt Looseness Prediction with Smart Touch Using Stress Wave Analysis and Machine Learning

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Problem Statement and Approach

- Manual inspection methods for ensuring the appropriate tightness of flange bolts are labor-intensive, prone to human error, and may overlook gradual loosening between checks, posing risks of equipment failure and downtime.
- Need to develop smart touch based non-destructive testing solution using PZT sensor to predict The flange bolt looseness.
- Explore the advance signal processing technique and machine learning algorithm.

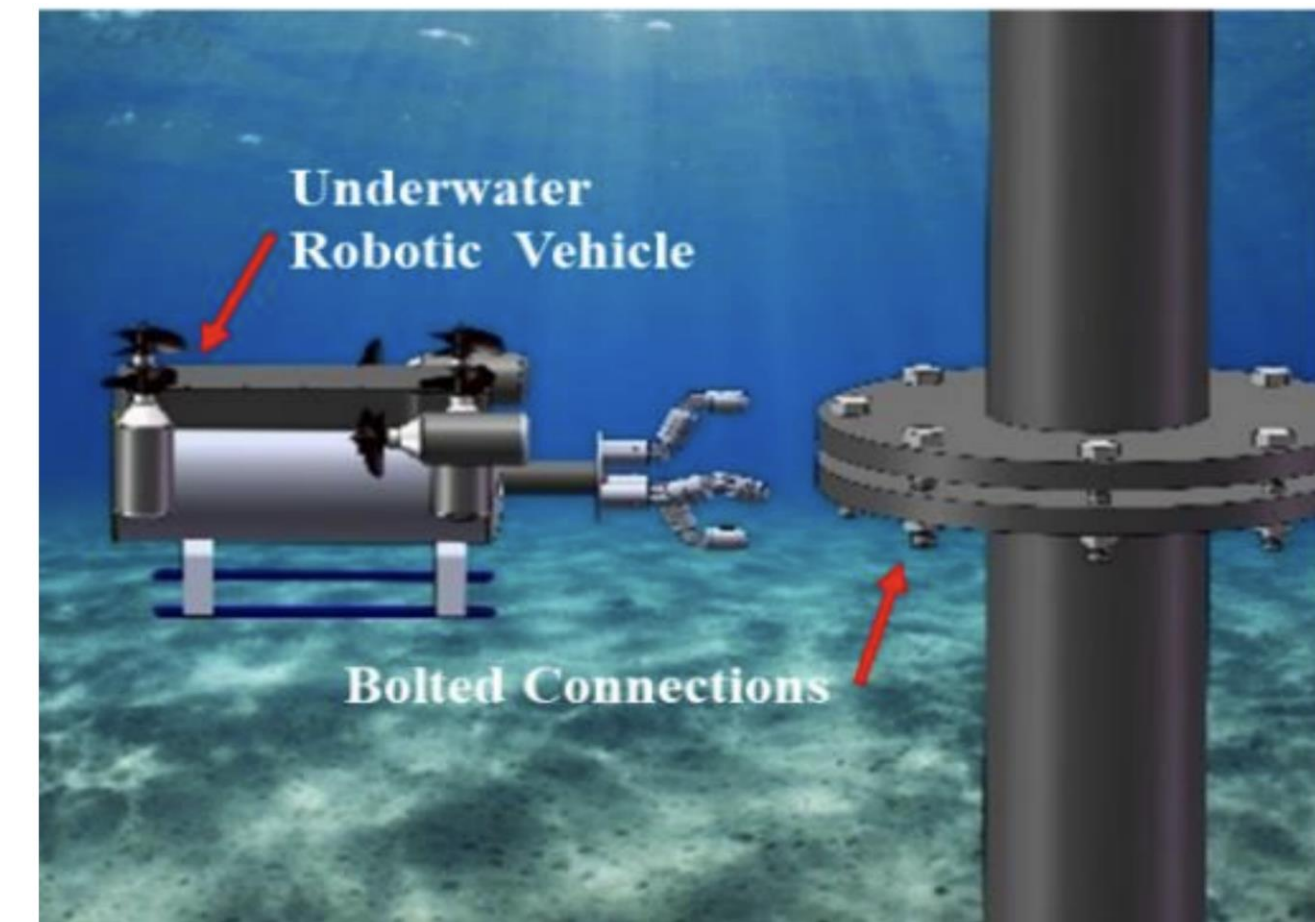


Fig.1: Proposed ROV solution
Source: Jiang and Jinwei [1]

Literature Review

- Jiang et al. [1] propose a touch-based method using PZT transducers to inspect subsea bolted connections. Spectrograms and wavelet packet transformation analysis validate the approach.
- Ning Li [2] presents a 3D electromechanical FEA approach for monitoring bolt looseness through active sensing. Confirming the efficacy of fractal contact theory, the study establishes a link between signal peak amplitude and preload
- Wang and Song [3] introduce a novel Vibro-Acoustic Modulation (VAM) method for detecting multi-bolt connection looseness, surpassing traditional single-bolt joint approaches. Their method, utilizing linear swept sine waves and the Gnome entropy (gEn).

Experimental Setup and Collection of Data

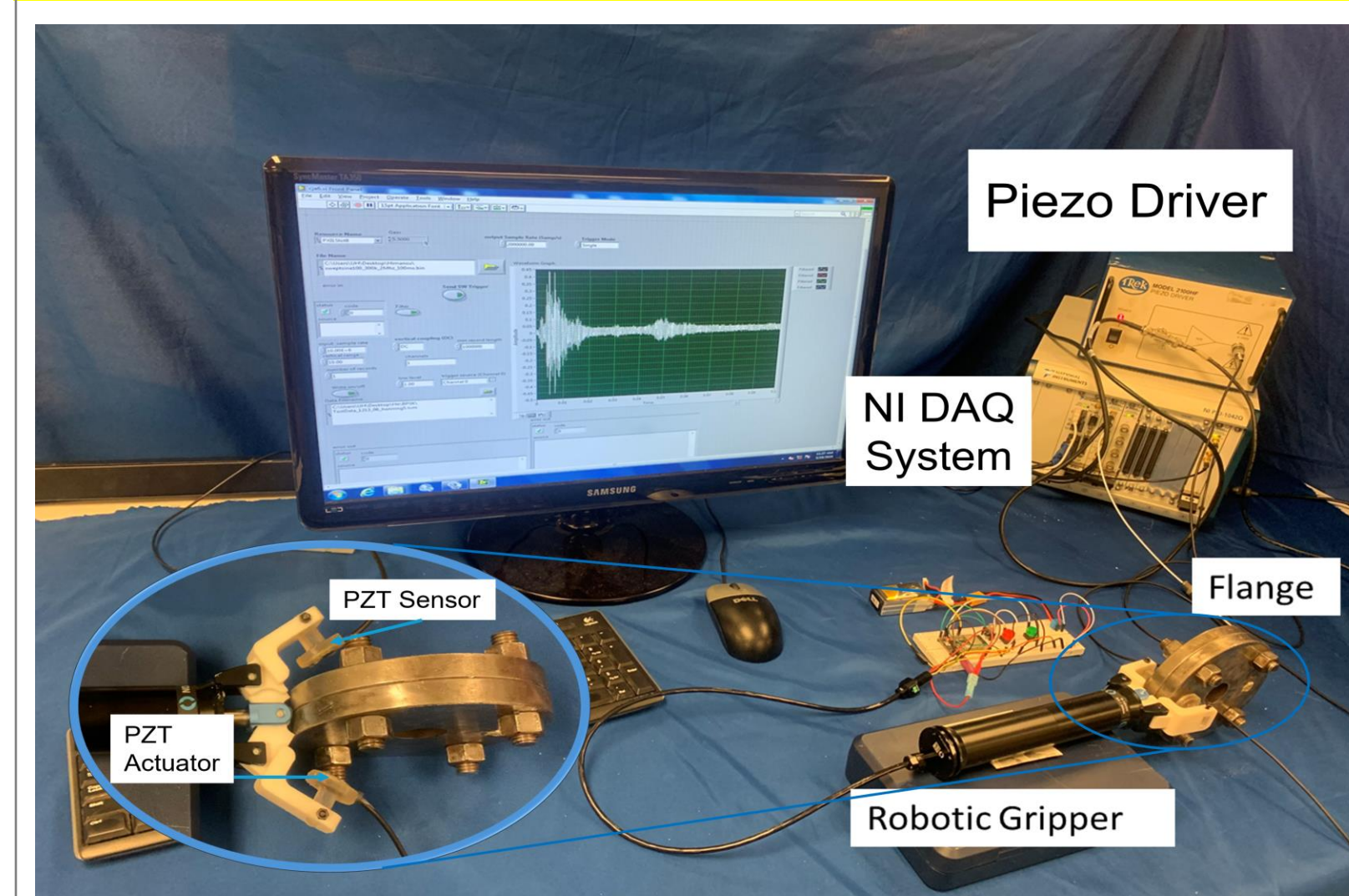


Fig.2: Experimental Setup

- A PZT sensor, located opposite the actuator on the flange plate, captures stress waves from a chirp signal. Sampling at 10 MHz ensures accurate wave recording.
- STFT plot was generated from the time series information

- Experimental setup combines PXI-1042 National Instruments (NI) hardware system with robotic gripper equipped with piezoelectric (PZT) sensors and actuators.
- LabVIEW system produces chirp signal sweeping from 100 Hz to 300 kHz over 0.1 second duration.

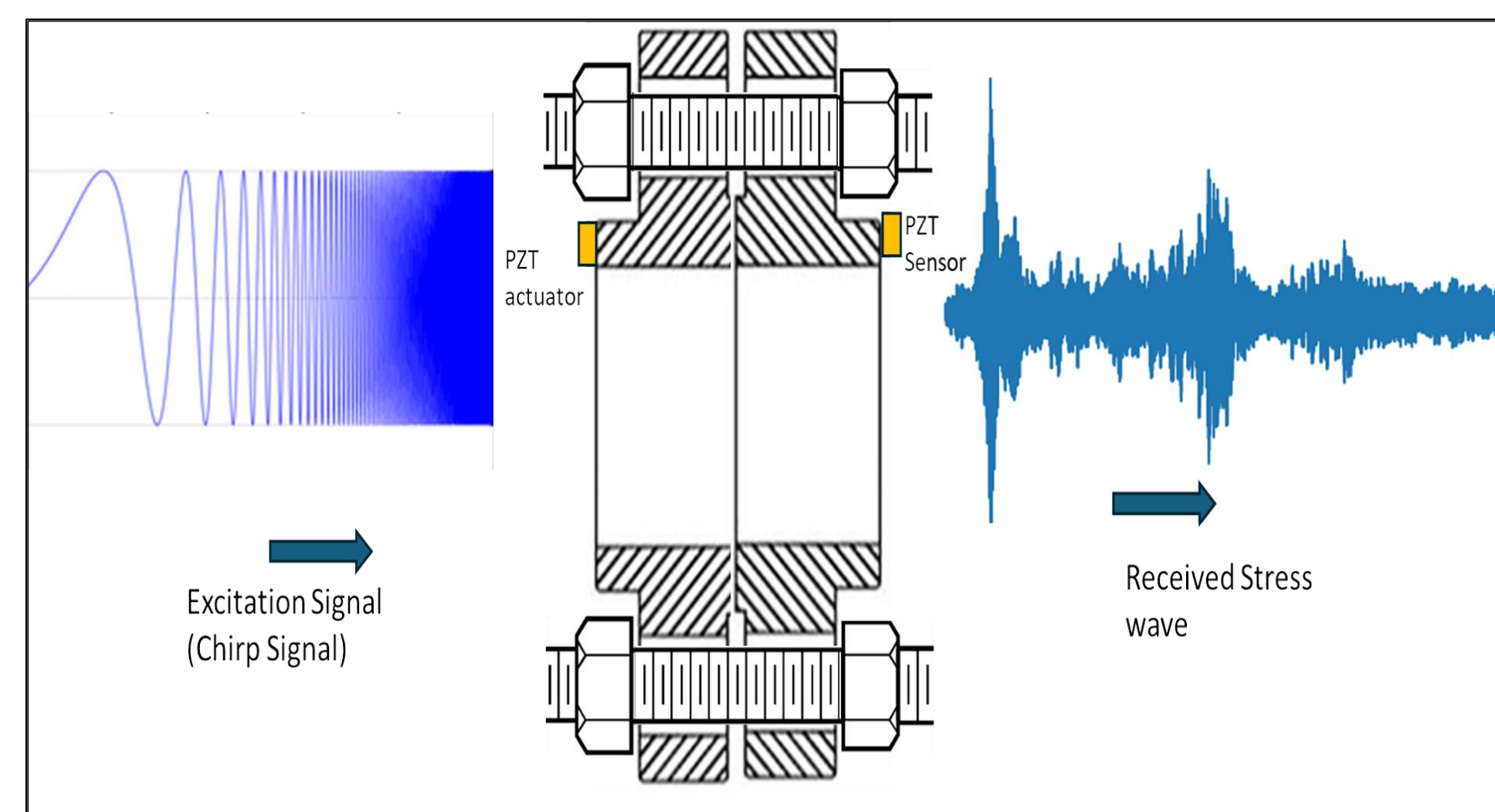


Fig.3: Schematic Diagram of Stress Wave Propagation

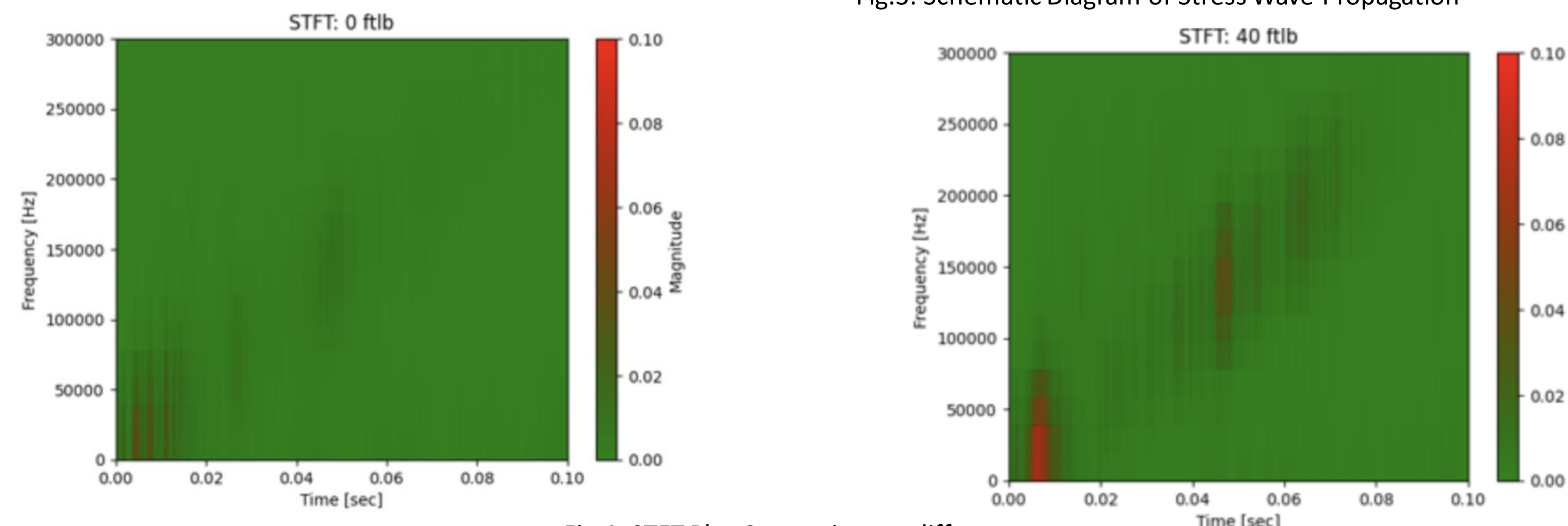


Fig.4: STFT Plot Comparison at different torque

Methods

- STFT computed with a window length of 256 points and an overlap of 128 points.
- The STFT plot was average pooled to reduced the dimension by 20 times and flatten to an 1D matrix
- Dataset comprised 500 samples with five torque labels (0,10,20,30,40 ft-lb), evenly split for training and independent verification.
- SVM model used Radial Basis Function (RBF) kernel, fine-tuned with C parameter set to 2.5 for regularization strength.
- 'Scale' option utilized for gamma parameter to adapt to dataset characteristics.

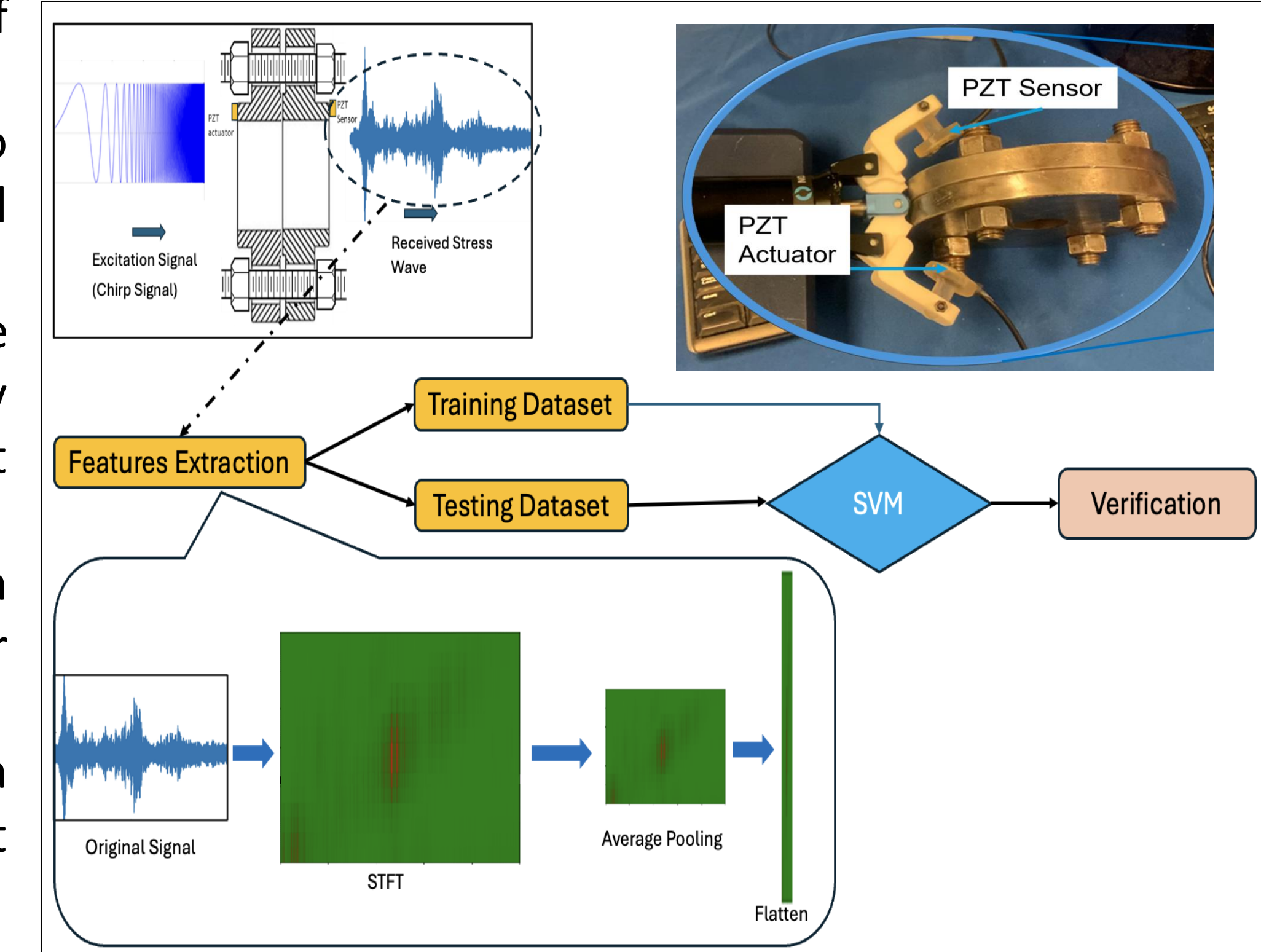


Fig.5: Flow Diagram of The Proposed Method

Results, Analysis and Discussion

- SVM model trained on 500 samples with a 50:50 split for training and testing.
- Model achieved an accuracy of 93.2% in this configuration, focusing solely on STFT data.
- Confusion matrix in Fig. 6 illustrated model performance in the independent validation test.
- Capturing subtle variations in bolt tightness levels using frequency-domain features.
- Challenges include managing computational complexity and reliance on singular feature type, suggesting room for optimization.

True Label	0 ftlb	10 ftlb	20 ftlb	30 ftlb	40 ftlb
0 ftlb	50	0	0	0	0
10 ftlb	2	47	0	1	0
20 ftlb	1	1	45	1	2
30 ftlb	3	0	0	46	1
40 ftlb	1	1	1	2	45
	0 ftlb	10 ftlb	20 ftlb	30 ftlb	40 ftlb

Fig.6: Confusion Matrix of The Independent Validation

Conclusion

- The research achieves a high accuracy of 93.2% in predicting flange bolt looseness using stress wave analysis and machine learning.
- Leveraging frequency-domain features proves effective for classification despite challenges like computational complexity and feature dependency.
- Future work in this project will focus on adopting advanced deep learning models, particularly Convolutional Neural Net-

Acknowledgements

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