

# Open-Source Cortex-M Development and Debugging



May 20, 2015  
Gareth McMullin

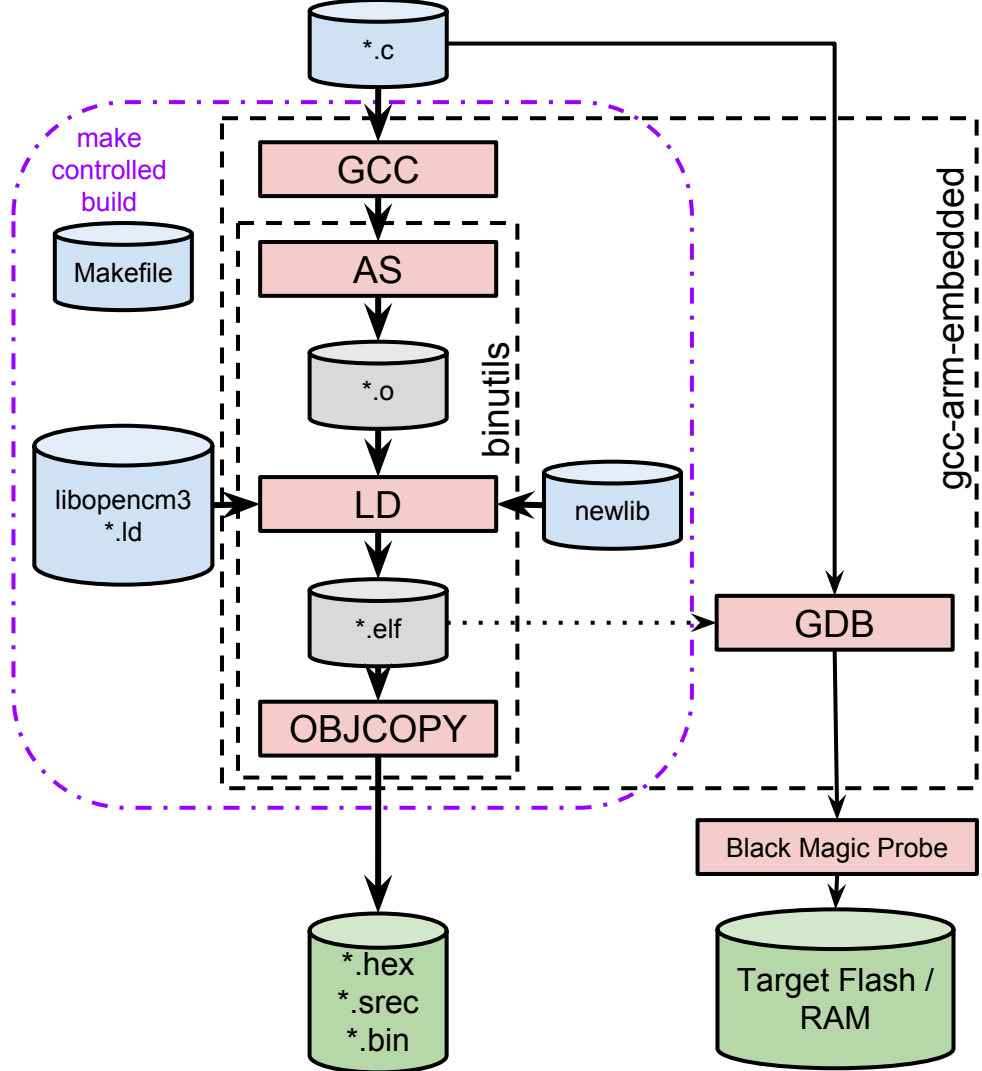


# Overview

- Introduction to open-source bare-metal ARM stack
- Highlight differences between Unix and embedded
- Introduction to remote debugging with GDB
- Demonstrate complete workflow with an example using Newlib's `<stdio.h>`
- Some simple techniques for reducing binary size

# ARM Toolchain

- Your fav text editor
- make
- gcc-arm-embedded
  - gcc
  - binutils (as, ld, objcopy, ...)
  - newlib
  - gdb
- libopenm3
- Black Magic Probe



# ARM Toolchain Links

- gcc-arm-embedded

<https://launchpad.net/gcc-arm-embedded/>

- libopencm3

<https://github.com/libopencm3/libopencm3>

- Black Magic Probe

<https://github.com/blacksphere/blackmagic>

# Unix Demo Program

Github: [tree](#)

```
/* demo.c */
#include <stdio.h>

int main(void)
{
    int counter = 0;
    while (1) {
        int a, b;
        printf("Iteration %d\n", ++counter);
        printf("Give me two numbers to add.\n");
        scanf("%d %d", &a, &b);
        printf("%d + %d = %d\n\n", a, b, a + b);
    }
    return 0;
}
```

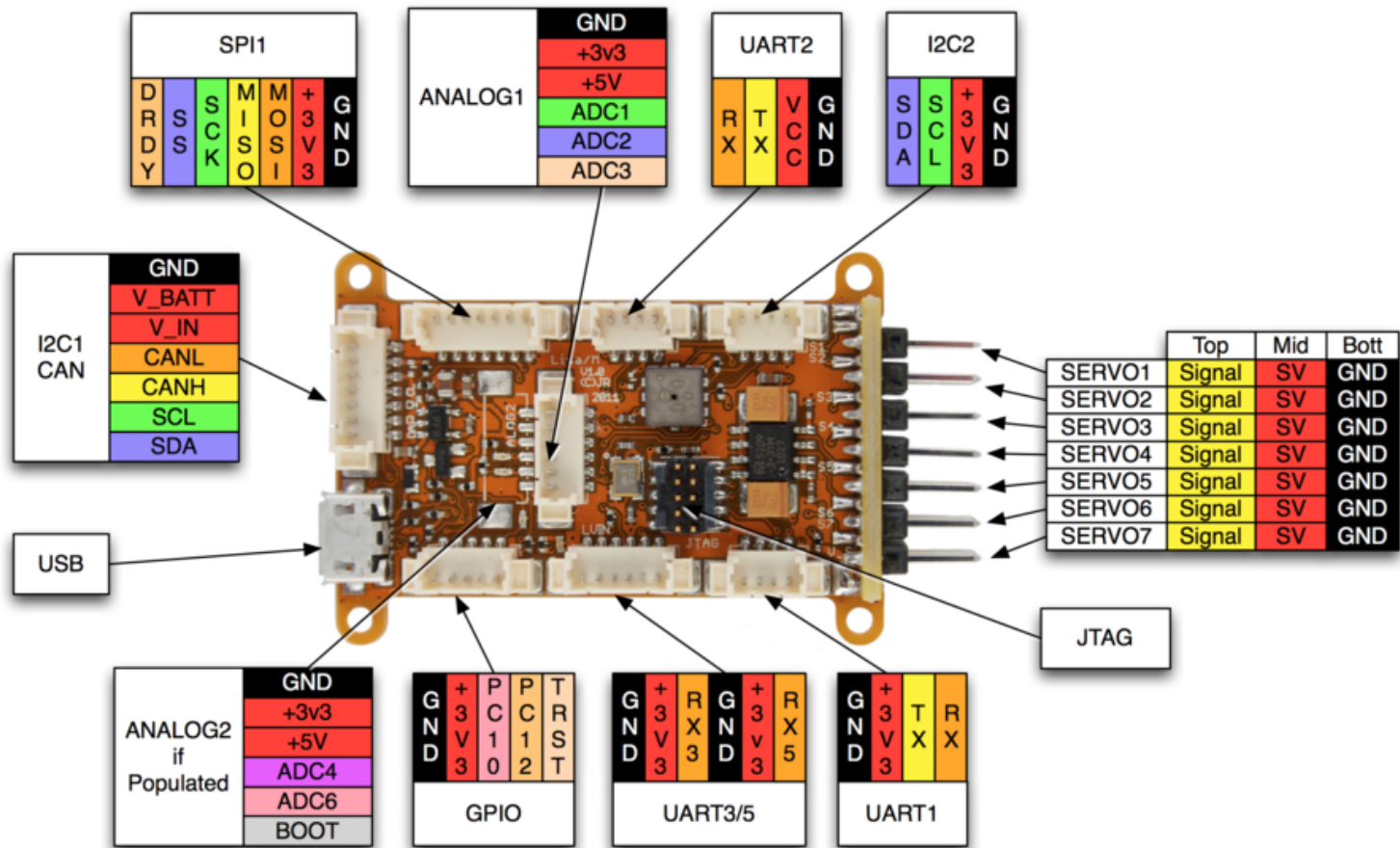
```
# Makefile
CFLAGS = -Wall -Wextra -g3 -O0 -MD

CSRC = demo.c
OBJ = $(CSRC:.c=.o)

demo: $(OBJ)
    $(CC) $(LDFLAGS) -o $@ $(OBJ) $(LDLIBS)

.PHONY: clean
clean:
    -rm -rf *.o demo

-include *.d
```



Lisa/M v1.0 Autopilot from [https://wiki.paparazziuav.org/wiki/Lisa/M\\_v1.0](https://wiki.paparazziuav.org/wiki/Lisa/M_v1.0)

# Makefile for cross-compile

Github: [tree](#) / [diff](#)

```
+CROSS_COMPILE = arm-none-eabi-  
+CC = $(CROSS_COMPILE)gcc  
+CPUFLAGS = -mcpu=cortex-m3 -mthumb  
-CFLAGS = -Wall -Wextra -g3 -O0 -MD  
+CFLAGS = -Wall -Wextra -g3 -O0 -MD $(CPUFLAGS)  
+LDFLAGS = $(CPUFLAGS)  
+LDLIBS = -lc -lnosys
```

CPUFLAGS from [gcc-arm-embedded readme.txt](#)

# Newlib libc and Unix syscalls

- <https://sourceware.org/newlib/libc.html#sprintf>
- <https://sourceware.org/newlib/libc.html#Syscalls>

(Nice PDF documentation included with gcc-arm-embedded)

- Newlib provides dummy syscalls in libnosys:

**LDLIBS** = -lc -lnosys



# Generating Hex files

```
OBJCOPY = $(CROSS_COMPILE)objcopy
```

```
%.hex: %.elf  
    $(OBJCOPY) -O ihex $< $@
```

```
%.srec: %.elf  
    $(OBJCOPY) -O srec $< $@
```

# What's still missing?

We have a binary using ARM instructions, but no OS loader:

```
$ arm-none-eabi-nm demo.elf | sort | head -n 3  
00008000 T _init  
00008010 T exit  
00008030 t register_fini
```

- Code at arbitrary addresses
- No interrupt vector table

# Introducing libopencm3

- **Newlib** provides a device independent C library.
- **libopencm3** provides device dependent support.
  - Peripheral MMIO register definitions
  - Interrupt vector table definition
  - Convenience routines for peripheral access
  - Linker scripts

# Git Submodule: libopencm3

Github: [tree](#) / [diff](#)

```
$ git submodule add https://github.com/libopencm3/libopencm3.git
```

```
+ .PHONY: libopencm3
+ libopencm3:
+   if [ ! -f libopencm3/Makefile ]; then \
+       git submodule init; \
+       git submodule update; \
+   fi
+   $(MAKE) -C libopencm3 lib/stm32/f1
+
+ .PHONY: clean
+ clean:
+   -$(MAKE) -C libopencm3 clean
```

[Documentation on Git Submodules](#)

# The linking stage

Github: [tree](#) / [diff](#)

```
/* lisa-m.ld - Linker script for Lisa-M */

/* Define memory regions. */
MEMORY
{
    rom (rx) : ORIGIN = 0x08000000,
               LENGTH = 128K
    ram (rwx) : ORIGIN = 0x20000000,
               LENGTH = 20K
}

/* Include the common ld script. */
INCLUDE libopencm3_stm32f1.ld

-CFLAGS = -Wall -Wextra -g3 -O0 -MD $(CPUFLAGS)
+CFLAGS = -Wall -Wextra -g3 -O0 -MD $(CPUFLAGS) \
+      -DSTM32F1 -Ilibopencm3/include
-LDFLAGS = $(CPUFLAGS)
+LDLAGS = $(CPUFLAGS) -nostartfiles \
+      -Llibopencm3/lib -Wl,-T,lisa-m.ld
-LDLIBS = -lc -lnosys
+LDLIBS = -lopencm3_stm32f1 -lc -lnosys
```

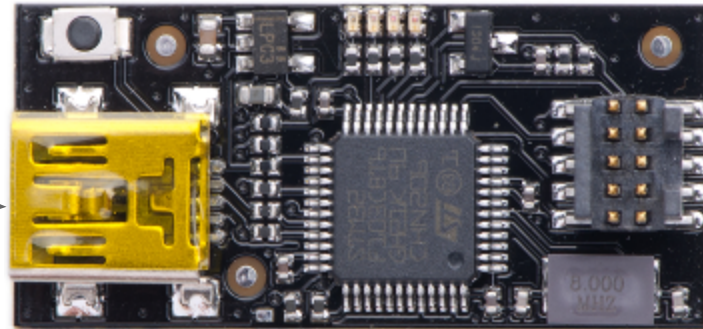
# Remote Debugging with GDB

- GDB offers remote debugging using a serial protocol over TCP, pipes, serial ports, etc.  
<https://sourceware.org/gdb/current/onlinedocs/gdb/Remote-Protocol.html#Remote-Protocol>
- Remote server implementations:
  - gdbserver
  - gdb-stubs
  - kgdb
  - Black Magic Probe
  - OpenOCD / texane/stlink / PyOCD / Segger J-Link GDB server
- Connect with `target extended-remote ...`
- Send commands to server with `monitor ...`

DFU Request Switch

**Composite USB:**  
CDC/ACM (GDB server)  
CDC/ACM (UART)  
DFU

**LEDS:**  
Power  
Error indicator  
Debug state  
UART TX/RX



**Cortex Debug**  
JTAG / SWD



**UART**  
3.3V CMOS

Black Magic Probe (Mini)

# Demo with Black Magic Probe

(gdb) target extended-remote /dev/ttyACM0

Remote debugging using /dev/ttyACM0

(gdb) monitor swdp\_scan

Target voltage: 3.4V

Available Targets:

No. Att Driver

1 STM32, High density.

(gdb) attach 1

Attaching to program: /home/gareth/Projects/embedded-demo/demo.elf, Remote target  
reset\_handler () at ../../cm3/vector.c:67

(gdb) load

Loading section .text, size 0xc5d8 lma 0x8000000

Loading section .ARM.exidx, size 0x8 lma 0x800c5d8

Loading section .data, size 0x8c8 lma 0x800c5e0

Start address 0x80001a8, load size 52904

Transfer rate: 18 KB/sec, 944 bytes/write.

(gdb) start

Temporary breakpoint 1 at 0x8000156: file demo.c, line 5.

Starting program: /home/gareth/Projects/embedded-demo/demo.elf

Note: automatically using hardware breakpoints for read-only addresses.

Temporary breakpoint 1, main () at demo.c:5

5 int counter = 0;

For OS X: /dev/cu.usbmodem\*1

For Windows: COM?

For JTAG, use monitor jtag\_scan



# GDB Host I/O and ARM Semihosting

- ARM defines a host system call interface:  
[http://infocenter.arm.com/help/topic/com.arm.doc.dui0471c/DUI0471C\\_developing\\_for\\_arm\\_processors.pdf](http://infocenter.arm.com/help/topic/com.arm.doc.dui0471c/DUI0471C_developing_for_arm_processors.pdf) (Chapter 8)
- GDB provides a host system call interface:  
[https://sourceware.org/gdb/current/onlinedocs/gdb/File\\_002dl\\_002fO-Remote-Protocol-Extension.html](https://sourceware.org/gdb/current/onlinedocs/gdb/File_002dl_002fO-Remote-Protocol-Extension.html)
- Unfortunately these don't match. Black Magic Probe provides the translation.
- Newlib provides ARM compliant semihosting syscalls enabled with linker command line argument `--specs=rdimon.specs`.
- Must initialise file descriptors with `initialise_monitor_handles()`.

# Newlib's semihosting syscalls

Github: [tree](#) / [diff](#)

```
-DSTM32F1 -Ilibopencm3
LD_FLAGS = $(CPU_FLAGS) -nostartfiles \
          -Llibopencm3/lib -Wl,-T,lisa-m.ld
-LDLIBS = -lopencm3_stm32f1 -lc -lnosys
+LDLIBS = -lopencm3_stm32f1 \
+        --specs=rdimon.specs

CSRC = demo.c
OBJ = $(CSRC:.c=.o)
```

```
int main(void)
{
    int counter = 0;
+
+    void initialise_monitor_handles(void);
+    initialise_monitor_handles();
+
    while (1) {
        int a, b;
        printf("Iteration %d\n",
```

**Note:** Semihosting calls use BKPT instructions for communication with the debugger. If no debugger is connected these will trigger faults.

# STM32 USART with libopencm3

Github: [tree](#) / [diff](#)

```
int _read(int file, char *ptr, int len)
{
    int i;

    if (file != STDIN_FILENO) {
        errno = EIO;
        return -1;
    }

    for (i = 0; i < len; i++) {
        ptr[i] = usart_recv_blocking(USART2);
        usart_send_blocking(USART2, ptr[i]);
        if (ptr[i] == '\r') {
            ptr[i] = '\n';
            usart_send_blocking(USART2, ptr[i]);
            return i + 1;
        }
    }
    return i;
}
```

```
int _write(int file, const char *ptr, int len)
{
    int i;

    if (file != STDOUT_FILENO) {
        errno = EIO;
        return -1;
    }

    for (i = 0; i < len; i++) {
        if (ptr[i] == '\n')
            usart_send_blocking(USART2, '\r');
        usart_send_blocking(USART2, ptr[i]);
    }

    return i;
}
```

[libopencm3 API reference](#)

# Why is the binary so big?

Github: [tree](#) / [diff](#)

Binary size before:

```
$ arm-none-eabi-size demo.elf
```

text	data	bss	dec	hex	filename
54880	2260	72	57212	df7c	demo.elf

Some low-hanging fruit:

```
CFLAGS += -Os
```

```
LDFLAGS += --specs=nano.specs
```

```
CFLAGS += -ffunction-sections -fdata-sections
```

```
LDFLAGS += -Wl,--gc-sections
```

After:

```
$ arm-none-eabi-size demo.elf
```

text	data	bss	dec	hex	filename
8820	116	16	8952	22f8	demo.elf

# More examples

- libopencm3 Examples repository:  
<https://github.com/libopencm3/libopencm3-examples.git>
- Black Magic Probe firmware:  
<https://github.com/blacksphere/blackmagic.git>
- Swift Navigation Piksi firmware:  
[https://github.com/swift-nav/piksi\\_firmware.git](https://github.com/swift-nav/piksi_firmware.git)
- Projects based on libopencm3:  
[http://libopencm3.org/wiki/Projects\\_based\\_on\\_libopencm3](http://libopencm3.org/wiki/Projects_based_on_libopencm3)

# Further discussion

- The pub afterwards?
- libopencm3 on [Gitter](#) or #libopencm3 on irc.freenode.net
- Black Magic Probe on [Gitter](#)