

# Multinomial and Gaussian Naïve Bayes

Slides from Tom Mitchell

# Naïve Bayes in a Nutshell

Bayes rule:

$$P(Y = y_k | X_1 \dots X_n) = \frac{P(Y = y_k) P(X_1 \dots X_n | Y = y_k)}{\sum_j P(Y = y_j) P(X_1 \dots X_n | Y = y_j)}$$

Assuming conditional independence among  $X_i$ 's:

$$P(Y = y_k | X_1 \dots X_n) = \frac{P(Y = y_k) \prod_i P(X_i | Y = y_k)}{\sum_j P(Y = y_j) \prod_i P(X_i | Y = y_j)}$$

So, classification rule for  $X^{new} = \langle X_1, \dots, X_n \rangle$  is:

$$Y^{new} \leftarrow \arg \max_{y_k} P(Y = y_k) \prod_i P(X_i^{new} | Y = y_k)$$

Another way to view Naïve Bayes (Boolean Y):  
Decision rule: is this quantity greater or less than 1?

$$\frac{P(Y = 1|X_1 \dots X_n)}{P(Y = 0|X_1 \dots X_n)} = \frac{P(Y = 1) \prod_i P(X_i|Y = 1)}{P(Y = 0) \prod_i P(X_i|Y = 0)}$$

# Naïve Bayes: classifying text documents

- Classify which emails are spam?
- Classify which emails promise an attachment?

I am pleased to announce that Bob Frederking of the Language Technologies Institute is our new Associate Dean for Graduate Programs. In this role, he oversees the many issues that arise with our multiple masters and PhD programs. Bob brings to this position considerable experience with the masters and PhD programs in the LTI.

I would like to thank Frank Pfenning, who has served ably in this role for the past two years.

\*\*\*\*\*  
Randal E. Bryant  
Dean and University Professor

How shall we represent text documents for Naïve Bayes?

## Learning to classify documents: $P(Y|X)$

- $Y$  discrete valued.
  - e.g., Spam or not
- $X = \langle X_1, X_2, \dots, X_n \rangle = \text{document}$

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- $X_i$  is a random variable describing...

## Learning to classify document: $P(Y|X)$ the “Bag of Words” model

- $Y$  discrete valued. e.g., Spam or not
- $X = \langle X_1, X_2, \dots, X_n \rangle =$  document
- $X_i$  are iid random variables. Each represents the word at its position  $i$  in the document
- Generating a document according to this distribution = rolling a 50,000 sided die, once for each word position in the document
- The observed counts for each word follow a ??? distribution

# Multinomial Distribution

- $P(\theta)$  and  $P(\theta | D)$  have the same form

**Eg. 2** Dice roll problem (6 outcomes instead of 2)

Likelihood is  $\sim \text{Multinomial}(\theta = \{\theta_1, \theta_2, \dots, \theta_k\})$

$$P(\mathcal{D} | \theta) = \theta_1^{\alpha_1} \theta_2^{\alpha_2} \dots \theta_k^{\alpha_k}$$

If prior is Dirichlet distribution,

$$P(\theta) = \frac{\prod_{i=1}^k \theta_i^{\beta_i - 1}}{B(\beta_1, \dots, \beta_k)} \sim \text{Dirichlet}(\beta_1, \dots, \beta_k)$$

Then posterior is Dirichlet distribution

$$P(\theta | D) \sim \text{Dirichlet}(\beta_1 + \alpha_1, \dots, \beta_k + \alpha_k)$$

**For Multinomial, conjugate prior is Dirichlet distribution.**



# Bag of Words Approach

the world of

**TOTAL**



**all about the company**

Our energy exploration, production, and distribution operations span the globe, with activities in more than 100 countries.

At TOTAL, we draw our greatest strength from our fast-growing oil and gas reserves. Our strategic emphasis on natural gas provides a strong position in a rapidly expanding market.

Our expanding refining and marketing operations in Asia and the Mediterranean Rim complement already solid positions in Europe, Africa, and the U.S.

Our growing specialty chemicals sector adds balance and profit to the core energy business.

► All About The Company

- Global Activities
- Corporate Structure
- TOTAL's Story
- Upstream Strategy
- Downstream Strategy
- Chemicals Strategy
- TOTAL Foundation
- Homepage

aardvark	0
about	2
all	2
Africa	1
apple	0
anxious	0
...	
gas	1
...	
oil	1
...	
Zaire	0



# MAP estimates for bag of words

## Map estimate for multinomial

$$\theta_i = \frac{\alpha_i + \beta_i - 1}{\sum_{m=1}^k \alpha_m + \sum_{m=1}^k (\beta_m - 1)}$$

$$\theta_{aardvark} = P(X_i = \text{aardvark}) = \frac{\# \text{ observed 'aardvark'} + \# \text{ hallucinated 'aardvark'} - 1}{\# \text{ observed words} + \# \text{ hallucinated words} - k}$$

What  $\beta$ 's should we choose?

## Naïve Bayes Algorithm – discrete $X_i$

- Train Naïve Bayes (examples)

for each value  $y_k$

estimate  $\pi_k \equiv P(Y = y_k)$

for each value  $x_{ij}$  of each attribute  $X_i$

estimate  $\theta_{ijk} \equiv P(X_i = x_{ij} | Y = y_k)$

prob that word  $x_{ij}$  appears  
in position  $i$ , given  $Y=y_k$

- Classify ( $X^{new}$ )

$$Y^{new} \leftarrow \arg \max_{y_k} P(Y = y_k) \prod_i P(X_i^{new} | Y = y_k)$$

$$Y^{new} \leftarrow \arg \max_{y_k} \pi_k \prod_i \theta_{ijk}$$

- Additional assumption: word probabilities are position independent

$$\theta_{ijk} = \theta_{mjk} \text{ for } i \neq m$$

## Twenty NewsGroups

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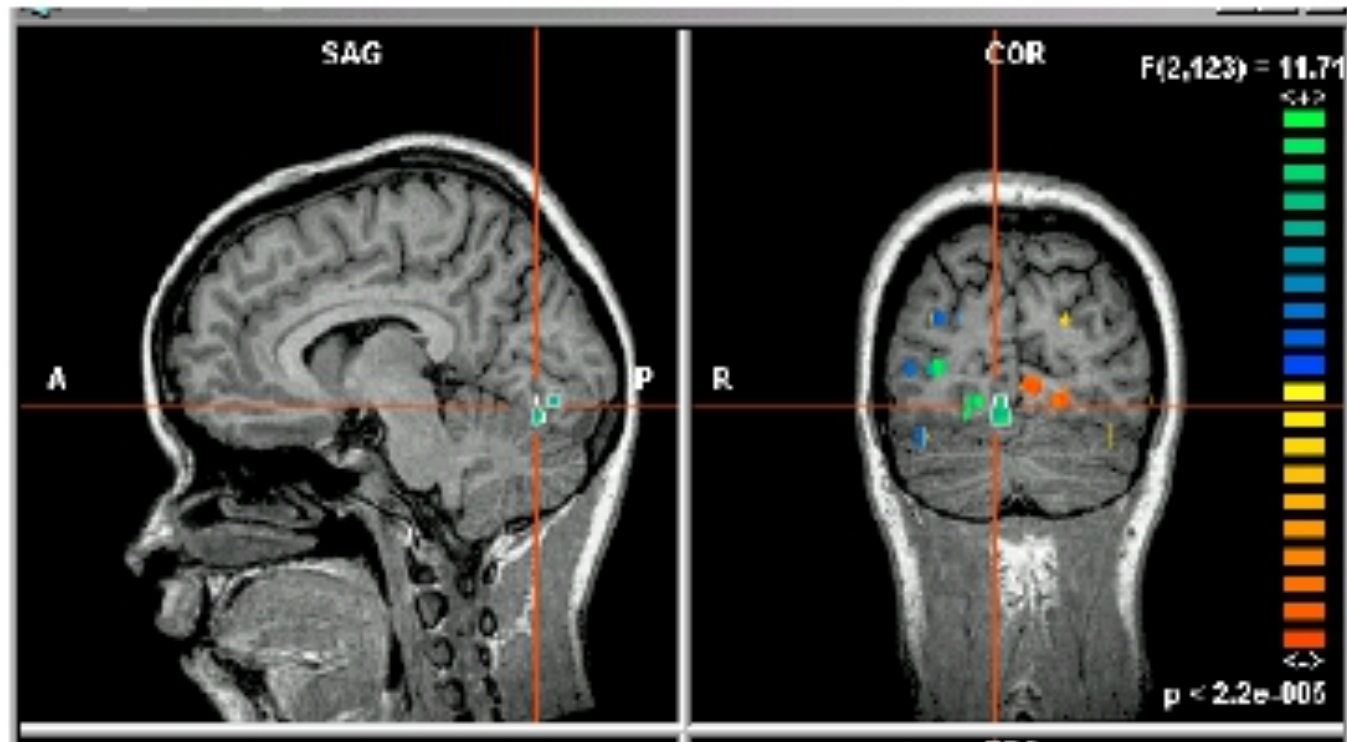
Given 1000 training documents from each group  
Learn to classify new documents according to  
which newsgroup it came from

comp.graphics	misc.forsale
comp.os.ms-windows.misc	rec.autos
comp.sys.ibm.pc.hardware	rec.motorcycles
comp.sys.mac.hardware	rec.sport.baseball
comp.windows.x	rec.sport.hockey
alt.atheism	sci.space
soc.religion.christian	sci.crypt
talk.religion.misc	sci.electronics
talk.politics.mideast	sci.med
talk.politics.misc	
talk.politics.guns	

Naive Bayes: 89% classification accuracy

## What if we have continuous $X_i$ ?

Eg., image classification:  $X_i$  is real-valued  $i_{\text{th}}$  pixel



## What if we have continuous $X_i$ ?

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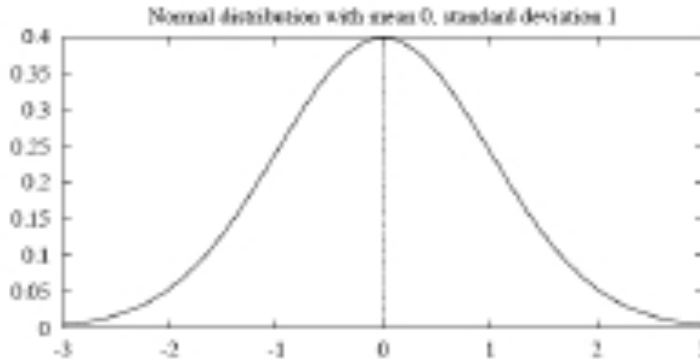
Naïve Bayes requires  $P(X_i | Y=y_k)$ , but  $X_i$  is real (continuous)

$$P(Y = y_k | X_1 \dots X_n) = \frac{P(Y = y_k) \prod_i P(X_i | Y = y_k)}{\sum_j P(Y = y_j) \prod_i P(X_i | Y = y_j)}$$

Common approach: assume  $P(X_i | Y=y_k)$  follows a Normal (Gaussian) distribution

# Gaussian Distribution (also called “Normal”)

$p(x)$  is a *probability density function*,  
whose  
integral (not sum) is 1



$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

The probability that  $X$  will fall into the interval  $(a, b)$  is given by

$$\int_a^b p(x) dx$$

- Expected, or mean value of  $X$ ,  $E[X]$ , is

$$E[X] = \mu$$

- Variance of  $X$  is

$$Var(X) = \sigma^2$$

- Standard deviation of  $X$ ,  $\sigma_X$ , is

$$\sigma_X = \sigma$$

## What if we have continuous $X_i$ ?

Gaussian Naïve Bayes (GNB): assume

$$p(X_i = x | Y = y_k) = \frac{1}{\sqrt{2\pi\sigma_{ik}^2}} e^{-\frac{1}{2}\left(\frac{x-\mu_{ik}}{\sigma_{ik}}\right)^2}$$

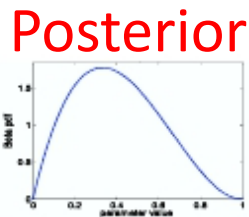
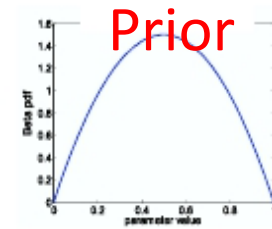
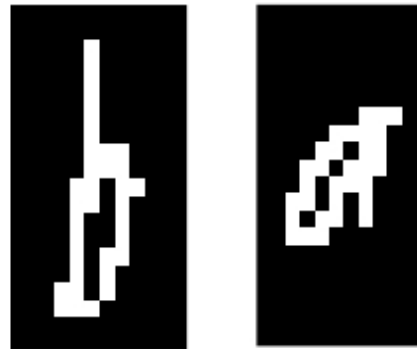
Sometimes assume variance

- is independent of  $Y$  (i.e.,  $\sigma_i$ ),
- or independent of  $X_i$  (i.e.,  $\sigma_k$ )
- or both (i.e.,  $\sigma$ )

# Bayesian Learning

## What if Features are Continuous?

Eg., Character Recognition:  
 $X_i$  is  $i$ th pixel



$$P(Y \mid \mathbf{X}) \propto P(\mathbf{X} \mid Y) P(Y)$$



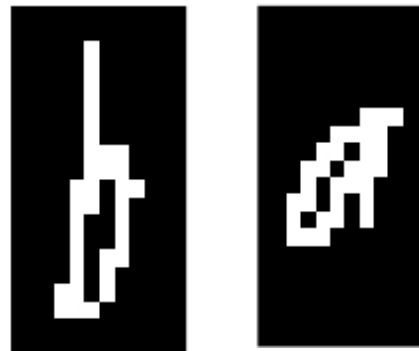
Data Likelihood



# Bayesian Learning

## What if Features are Continuous?

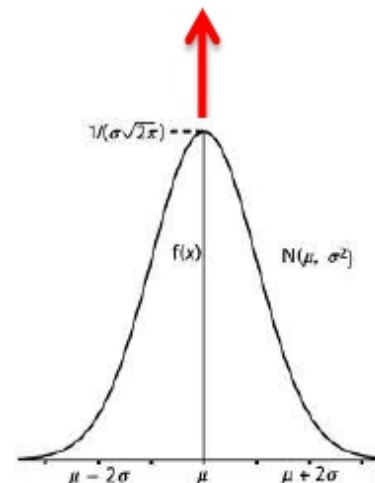
Eg., Character Recognition:  
 $X_i$  is  $i$ th pixel



$$P(Y \mid \mathbf{X}) \propto P(\mathbf{X} \mid Y) P(Y)$$

$$P(X_i = x \mid Y = y_k) = N(\mu_{ik}, \sigma_{ik})$$

$$N(\mu_{ik}, \sigma_{ik}) = \frac{1}{\sigma_{ik} \sqrt{2\pi}} e^{-\frac{(x - \mu_{ik})^2}{2\sigma_{ik}^2}}$$



# Gaussian Naïve Bayes

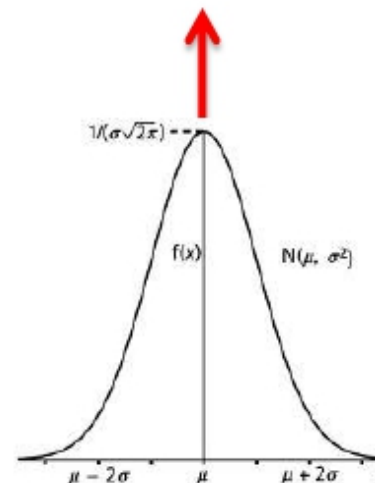
## Sometimes Assume Variance

- is independent of  $Y$  (i.e.,  $\sigma_i$ ),
- or independent of  $X_i$  (i.e.,  $\sigma_k$ )
- or both (i.e.,  $\sigma$ )

$$P(Y \mid \mathbf{X}) \propto P(\mathbf{X} \mid Y) P(Y)$$

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# Learning Gaussian Parameters

## Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{MLE} = \frac{1}{N} \sum_{i=1}^N x_i$$

- Variance:

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

# Learning Gaussian Parameters

## Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{ik} = \frac{1}{\sum_j \delta(Y^j = y_k)} \sum_j X_i^j \delta(Y^j = y_k)$$

jth training  
example

- Variance:

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

$\delta(x)=1$  if x true,  
else 0

# Learning Gaussian Parameters

## Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{ik} = \frac{1}{\sum_j \delta(Y^j = y_k)} \sum_j X_i^j \delta(Y^j = y_k)$$

- Variance:

$$\hat{\sigma}_{ik}^2 = \frac{1}{\sum_j \delta(Y^j = y_k) - 1} \sum_j (X_i^j - \hat{\mu}_{ik})^2 \delta(Y^j = y_k)$$

## Gaussian Naïve Bayes Algorithm – continuous $X_i$ (but still discrete $Y$ )

- Train Naïve Bayes (examples)

for each value  $y_k$

estimate\*  $\pi_k \equiv P(Y = y_k)$

for each attribute  $X_i$  estimate  $P(X_i|Y = y_k)$

- class conditional mean  $\mu_{ik}$ , variance  $\sigma_{ik}$

- Classify ( $X^{new}$ )

$$Y^{new} \leftarrow \arg \max_{y_k} P(Y = y_k) \prod_i P(X_i^{new}|Y = y_k)$$

$$Y^{new} \leftarrow \arg \max_{y_k} \pi_k \prod_i \mathcal{N}(X_i^{new}; \mu_{ik}, \sigma_{ik})$$

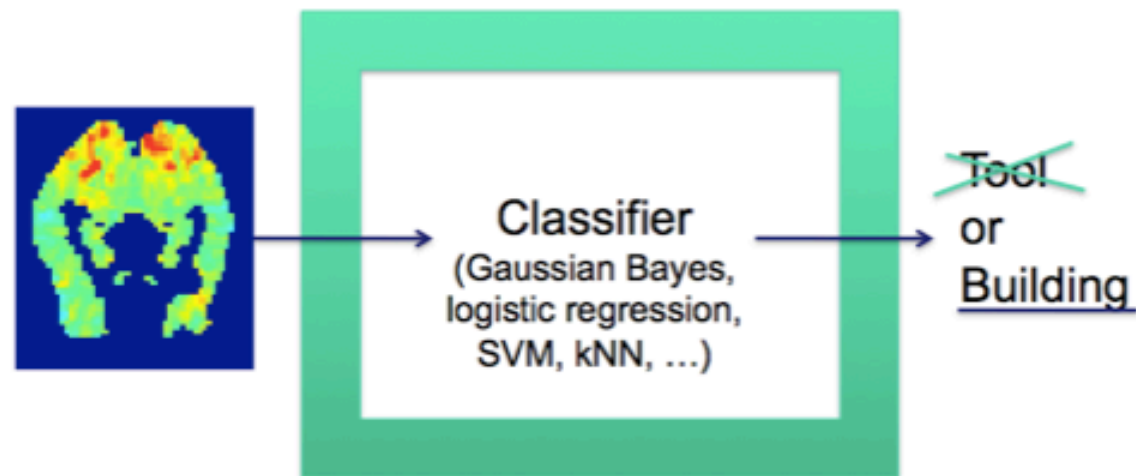
\* probabilities must sum to 1, so need estimate only n-1 parameters...

How many parameters must we estimate for Gaussian Naïve Bayes if Y has k possible values,  $X = \langle X_1, \dots, X_n \rangle$ ?

$$p(X_i = x | Y = y_k) = \frac{1}{\sqrt{2\pi\sigma_{ik}^2}} e^{-\frac{1}{2}\left(\frac{x - \mu_{ik}}{\sigma_{ik}}\right)^2}$$

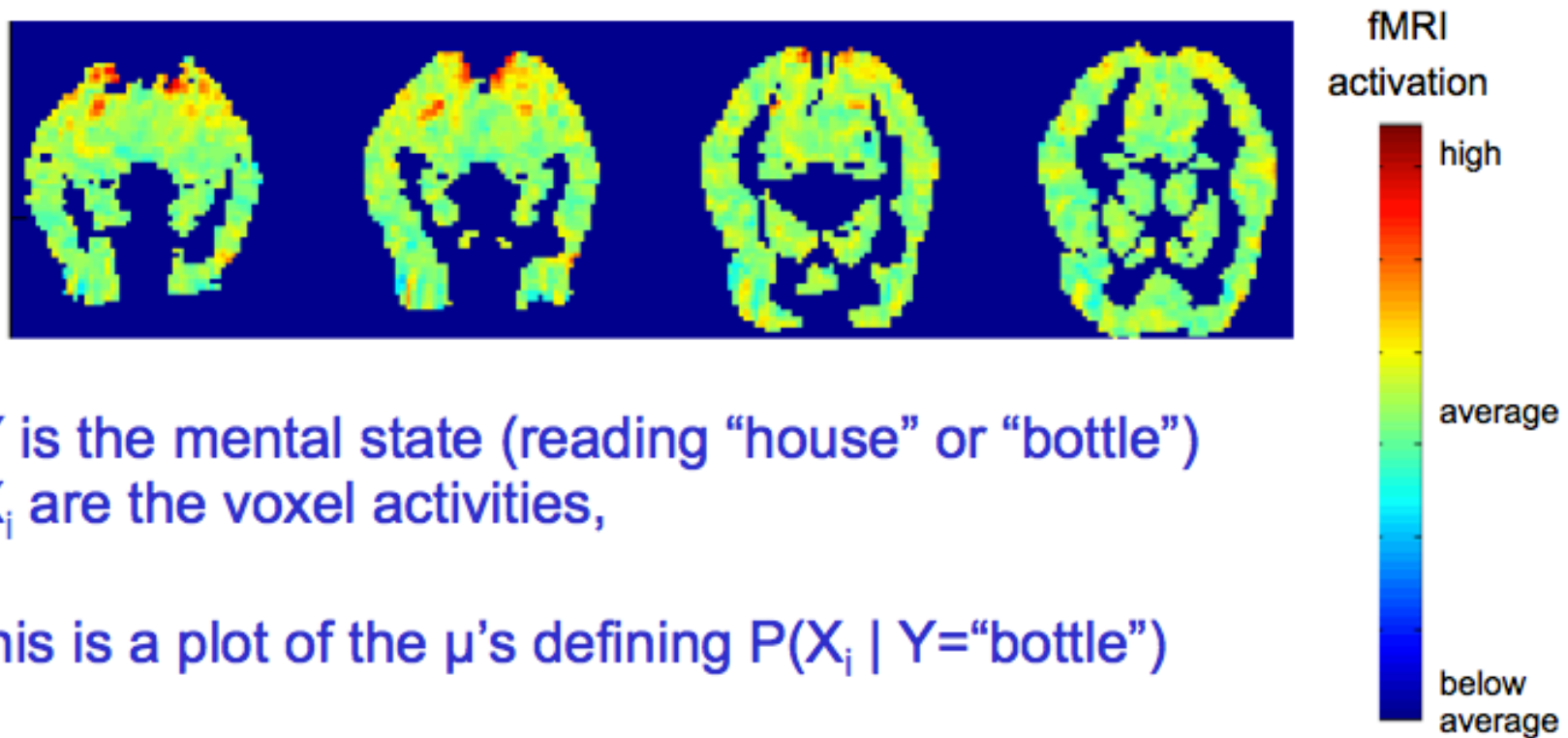
# GNB Example: Classify a person's cognitive state, based on brain image

- reading a sentence or viewing a picture?
- reading the word describing a “Tool” or “Building”?
- answering the question, or getting confused?





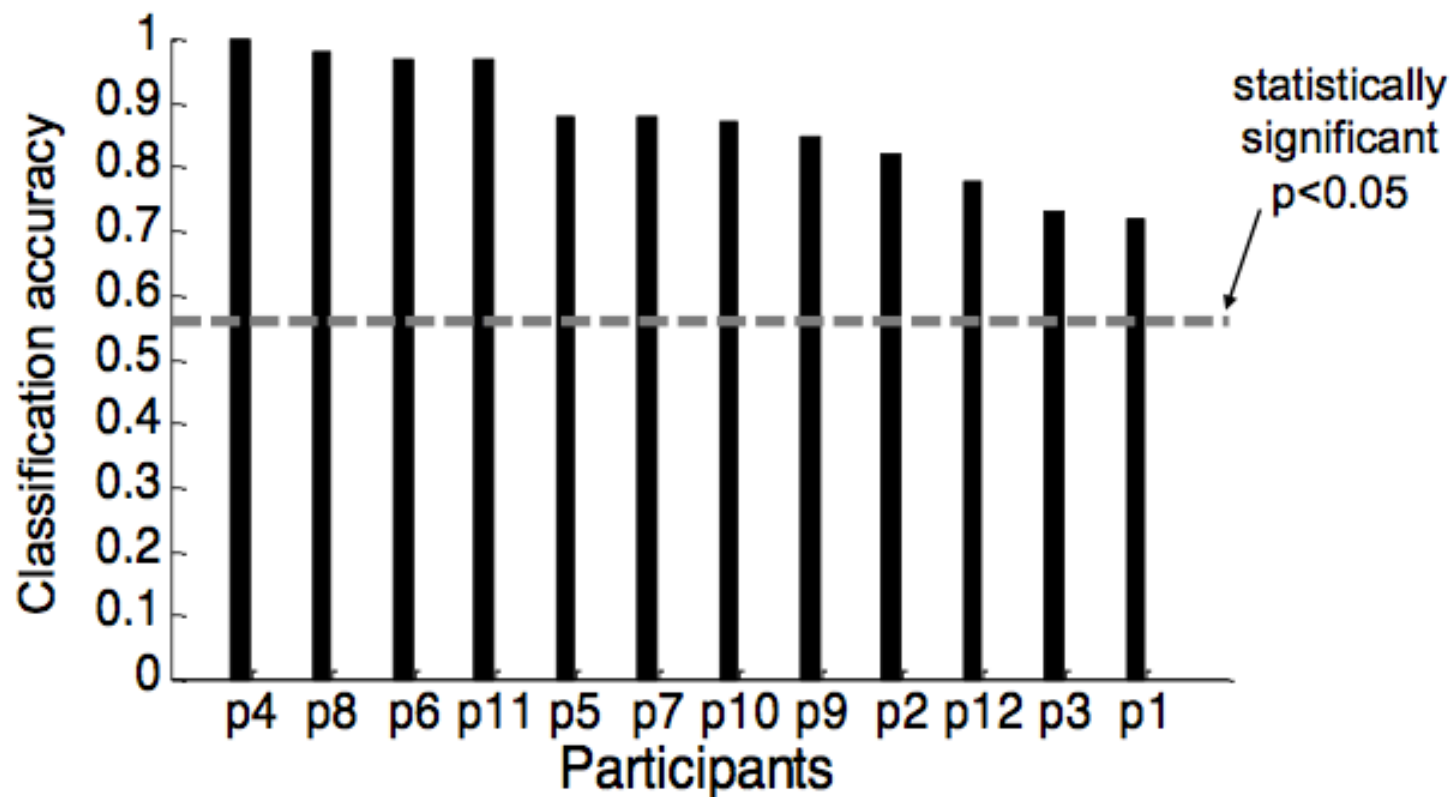
Mean activations over all training examples for  $Y=\text{"bottle"}$



$Y$  is the mental state (reading "house" or "bottle")  
 $X_i$  are the voxel activities,

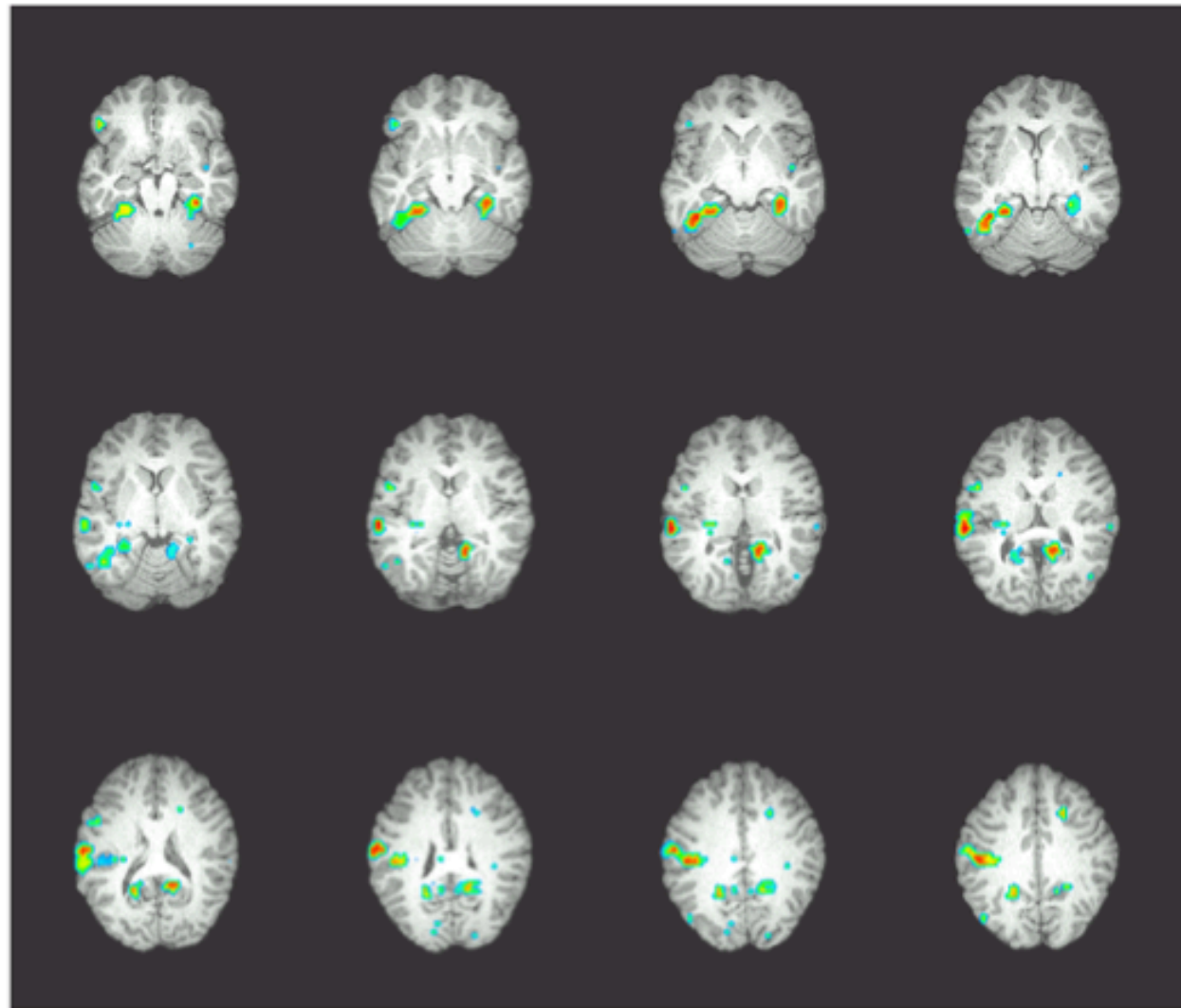
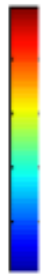
this is a plot of the  $\mu$ 's defining  $P(X_i | Y=\text{"bottle"})$

## Classification task: is person viewing a “tool” or “building”?



# Where is information encoded in the brain?

Accuracies of  
cubical  
27-voxel  
classifiers  
centered at  
each significant  
voxel  
[0.7-0.8]



# Naïve Bayes: What you should know

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- Designing classifiers based on Bayes rule
- Conditional independence
  - What it is
  - Why it's important
- Naïve Bayes assumption and its consequences
  - Which (and how many) parameters must be estimated under different generative models (different forms for  $P(X|Y)$ )
    - and why this matters
- How to train Naïve Bayes classifiers
  - MLE and MAP estimates
  - with discrete and/or continuous inputs  $X_i$