

# In-Class Lab Activity: Image Registration using ITK

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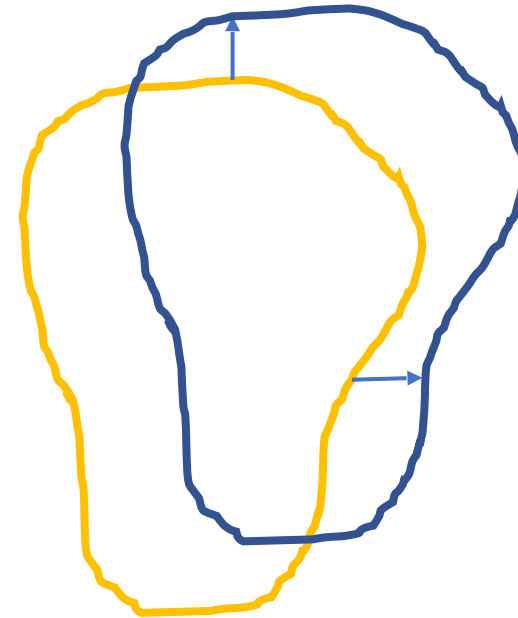
# ITK Image Registration

- `Itk::ImageRegistrationMethodv4`

- `SetFixedImage(ImageType)`: Set fixed input image
- `SetMovingImage(ImageType)`: Set moving input image
- `SetInitialTransform(TransformType)`: Set transform for fixed image (can be identity transform)
- `SetMovingInitialTransform(TransformType)`: Set initial transform for moving image, type of transform determines the type of registration (can be identity transform)
- `SetMetric(MetricType)`: Set the metric for registration
- `SetOptimizer(OptimizerType)`: Select optimizer for registration
- `SetNumberOfLevels(int)`: Number of scale spaces used for registration [1]
- `SetShrinkFactorsPerLevel(Array)`: Size factor for each scale space [1]
- `SetSmoothingSigmasPerLevel(Array)`: Smoothing for each scale space [0]

# 2D Translation Transform

- `Itk::TranslationTransform<double, 2>`  
(allows translation in x- and y-dimension)
  - `GetNumberOfParameters()`: Returns the number of modifiable parameters (2)
  - `SetParameters(double[2])`: Set x-, and y-translation



# Mean Squares Metric

- `itk::MeanSquaresImageToImageMetricv4`
- Calculates similarity between two images using the mean squared error
- Use `SetMetric()` function of registration method object to set this metric

$$\text{MSE} = \frac{1}{N} \sum_{\forall x} \left( I_f(x) - I_m(x) \right)^2$$

# Gradient Descent Optimization

- `itk::RegularStepGradientDescentOptimizerv4<double>`  
(Calculates the gradient of the cost function using local sampling and steps into the direction of the negative gradient)
  - `SetLearningRate(double)`: Determines the initial step size [4]
  - `SetMinimumStepLength(double)`: Stopping criterion [0.001]
  - `SetRelaxationFactor(double)`: Step size reduction after sudden gradient direction change [0.5]
  - `SetNumberOfIterations(int)`: Stopping criterion [200]

# Postprocessing

- `itk::ResampleImageFilter`

- `SetInput(ImageType)`: Original moving image
- `SetTransform(TransformType)`: Estimated transform after registration
- `SetUseReferenceImage(bool)`: Use spatial reference from fixed image [true]
- `SetReferenceImage(ImageType)`: Fixed image
- `SetDefaultPixelValue(PixelType)`: Pixel value for pixels outside the FOV [0]

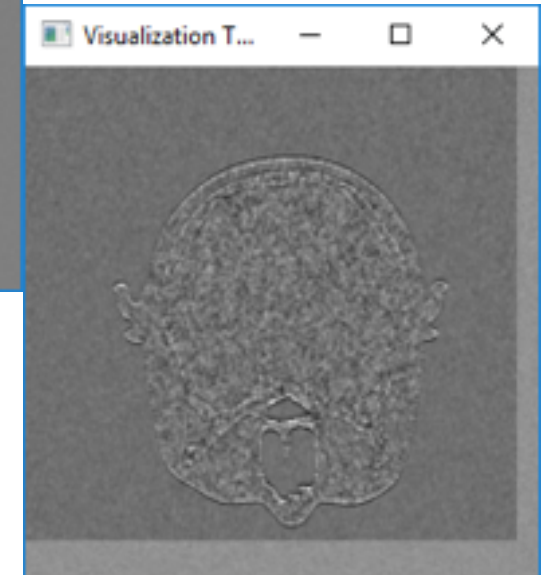
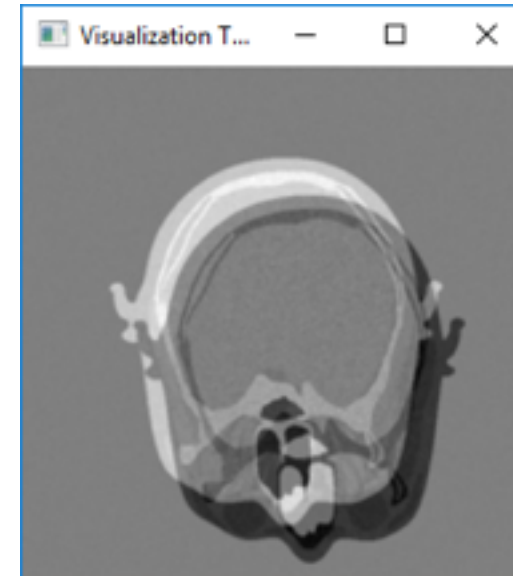
- `itk::SubtractImageFilter`

- `SetInput1(ImageType)`: FixedImage
- `SetInput2(ImageType)`: Output of resample filter

# Exercise 2

## [06\_MSETranslationRegistration]

1. Read moving and fixed image:
  - head\_fix.png
  - head\_mov.png
2. Perform 2D translation registration
3. Display the difference between the original fix and moving images
4. Display the difference after registration



# 2D Affine Transform

- `itk::AffineTransform`
  - Translation in x- and y-direction
  - 2D Rotation
  - Isotropic and anisotropic scaling
  - Shear transformation



# Mutual Information Image Metric

- `itk::MutualInformationImageToImageMetric`
  - Commonly used for multi-modality registration (e.g. MRI / CT)
  - Larger value corresponds to higher similarity between images

# Evolutionary Optimizer

- `itk::OnePlusOneEvolutionaryOptimizer`
  - `SetMaximumIteration(int)`: Set number of iterations [5000]
  - `SetNormalVariateGenerator(RandomGeneratorType)`: Use `itk::Statistics::MersenneTwisterRandomVariateGenerator` as random number generator
  - `SetInitialRadius(double)`: Initial step size [1.0]
  - `MaximizeOn()`: Use this to maximize metric value for mutual information metric

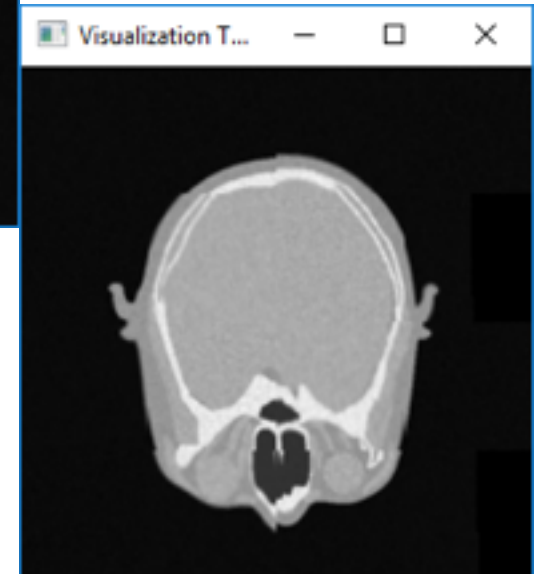
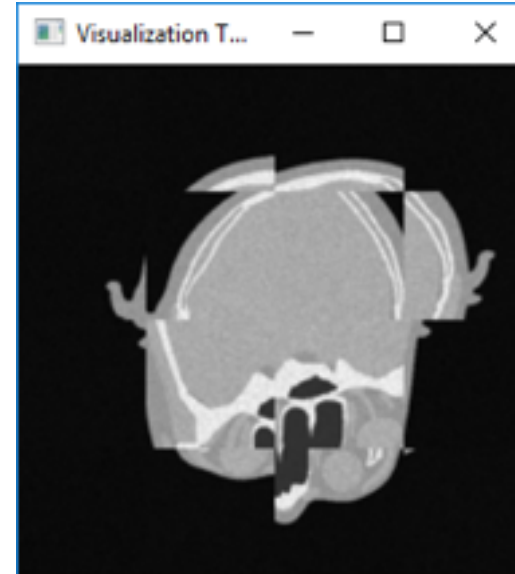
# Postprocessing

- `itk::CheckerBoardImageFilter`
  - Combines moving and fixed image by alternately displaying blocks of each image in a checkerboard pattern
  - `SetInput1(ImageType): FixedImage`
  - `SetInput2(ImageType): MovingImage`

# Exercise 3

## [07\_MIAffineRegistration]

1. Read moving and fixed image:
  - head\_affine\_fix.png
  - head\_affine\_mov.png
2. Perform 2D affine registration using mutual information and evolutionary optimizer
3. Display pre- and post registration results using the checkerboard filter



# Deformable Registration

- `itkDemonsRegistrationFilter`

- `AddObserver(itk::IterationEvent(), ObserverType)`: Allows tracking of the registration progress
- `SetFixedImage(ImageType)`: Fixed image
- `SetMovingImage(ImageType)`: Moving image
- `SetSmoothUpdateField(bool)`: Activate displacement field smoothing [true]
- `SetNumberOfIterations(int)`: Number of iterations [500]
- `SetStandardDeviations(double)`: Controls amount of smoothing [1.0]

# Preprocessing: Histogram Matching

- `itk::HistogramMatchingImageFilter`
  - `SetInput(ImageType)`: Original moving image
  - `SetReferenceImage(ImageType)`: Original fixed image
  - `SetNumberOfHistogramLevels(int)`: Number of histogram bins [1024]
  - `SetNumberOfMatchPoints(int)`: Number of match points [7]
  - `ThresholdAtMeanIntensityOn()`

```

class CommandIterationUpdate : public itk::Command
{
public:
    using Self = CommandIterationUpdate;
    using Superclass = itk::Command;
    using Pointer = itk::SmartPointer<Self>;
    itkNewMacro(Self);

protected:
    CommandIterationUpdate() {};

public:
    using OptimizerType = itk::OnePlusOneEvolutionaryOptimizer;
    using OptimizerPointer = const OptimizerType    *;

    void Execute(itk::Object *caller, const itk::EventObject & event) override
    {
        Execute((const itk::Object *)caller, event);
    }

    void Execute(const itk::Object * object, const itk::EventObject & event) override
    {
        auto optimizer = dynamic_cast< OptimizerPointer >(object);
        if (!itk::IterationEvent().CheckEvent(&event)) return;
        std::cout << optimizer->GetCurrentIteration() << optimizer->GetValue() <<
            optimizer->GetCurrentPosition() << std::endl;
    }
};

```

# Exercise 4

## [08\_DeformableRegistration]

1. Read moving and fixed image:
  - liver\_exp.png
  - liver\_insp.png
2. Perform histogram matching
3. Perform deformable registration and display status in each iteration
4. Display pre- and post registration results using difference filter
5. Display intermittent results during registration using the difference filter and VTK

