

Journal Discussion #4: **M Lustig et al.**, MRM 2007, **Sparse MRI: The Application of Compressed Sensing for Rapid MR Imaging**.

Due: October 15th at beginning of class. Please turn in by hand, email, or submission to Learn@UW.

Name:

Question 1 (2 points)

Compressed sensing theory requires 'incoherent sampling' artefacts from undersampling.

- a. How can that be achieved when using a (A) Cartesian 2D and a (B) Cartesian 3D acquisition?
- b. Is one of these sampling schemes (Cartesian 2D vs Cartesian 3D) better suited to fulfill the requirement of incoherent sampling artefacts.

Question 2 (2 points)

Besides sparsity, what are other conditions should be met for a compressed sensing reconstruction according to the CS theory?

Question 3 (2 points)

Which of the following is a true statement about the Constrained Optimization problem used in CS image reconstruction?

- (1) The L2 norm is used to measure the reconstructed image in the sparse transform domain since it penalizes large coefficients.
- (2) The parameter ϵ represents the minimum allowable difference between the Fourier transformed reconstruction and the measured k-space data (under the L2 norm).
- (3) The sparse transform ψ may be any non-linear operator besides the identity matrix.
- (4) The use of the L1 norm in the sparse transform domain is crucial since it often results in a solution comprised of a small number of large coefficients.

(question 4 on next page)

Question 4 (4 points)

Briefly explain how the sparse signal shown in Fig 2a can be properly recovered from pseudo-random k-space undersampling shown in (b), resulting in the signal representation in (d) with a direct reconstruction. Hint: you don't have to explore this with mathematical rigor, an intuitive description is sufficient.

