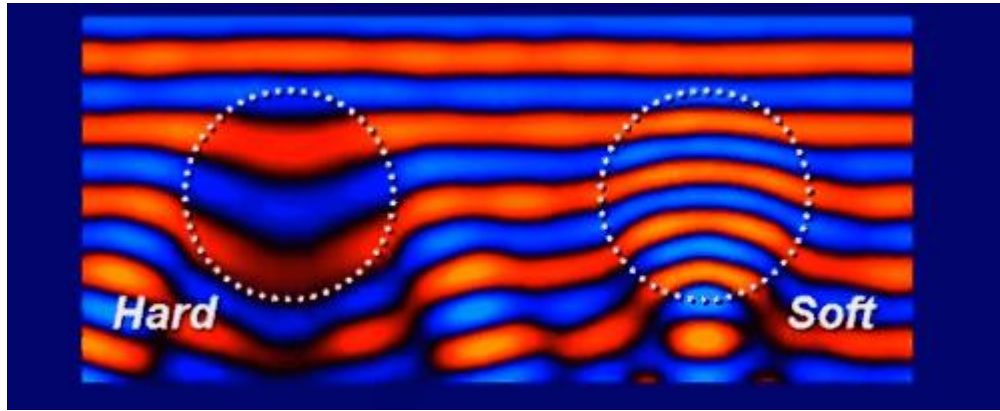


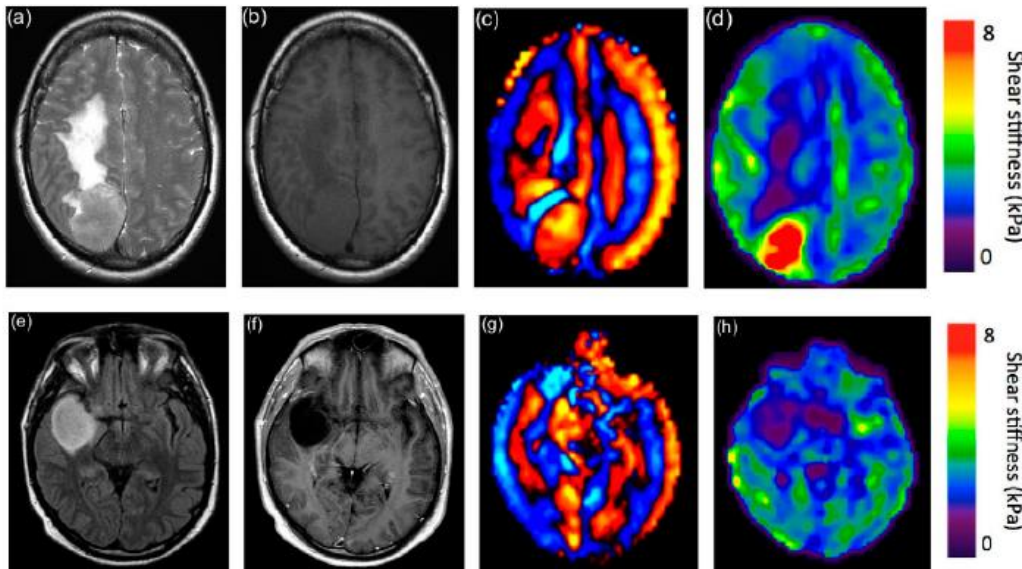
# Brain MR Elastography: *Acquisition and Reconstruction Strategies*



From: [https://www.youtube.com/watch?v=CcmZi0J\\_u3Y](https://www.youtube.com/watch?v=CcmZi0J_u3Y)

## MRI Group Talk

**Grant Roberts**  
March 5<sup>th</sup>, 2020



From: Hiscox. *Phys Med Bio* (2016)

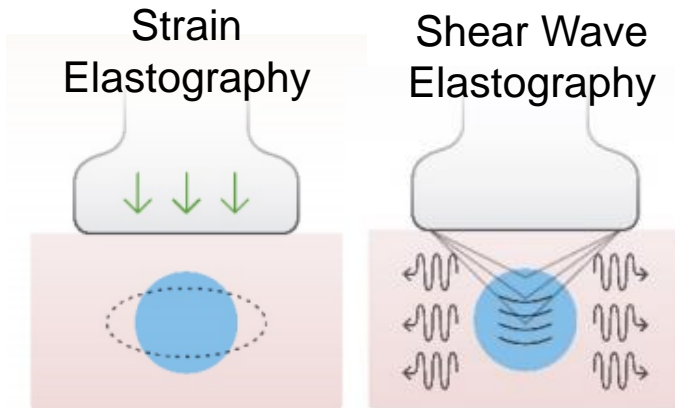


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# Elastography Introduction

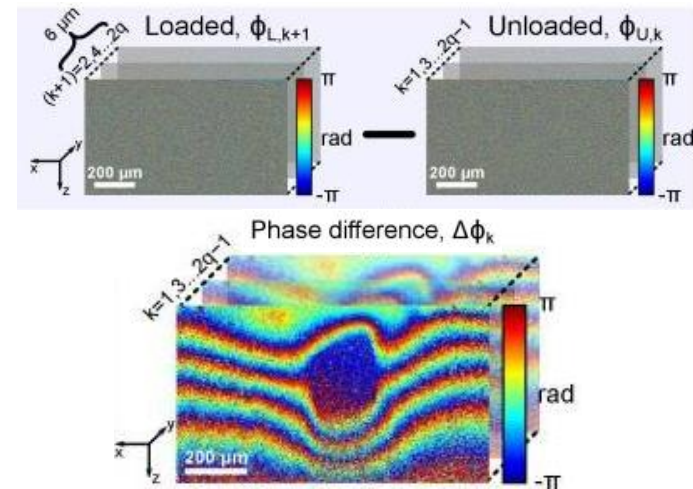
- Ingredients for elastography
  1. Mechanical excitation
  2. Measurement of tissue response
  3. Mechanical parameter estimation

## Ultrasound



From: Sigrist, et al. *Theranostics*. (2017)

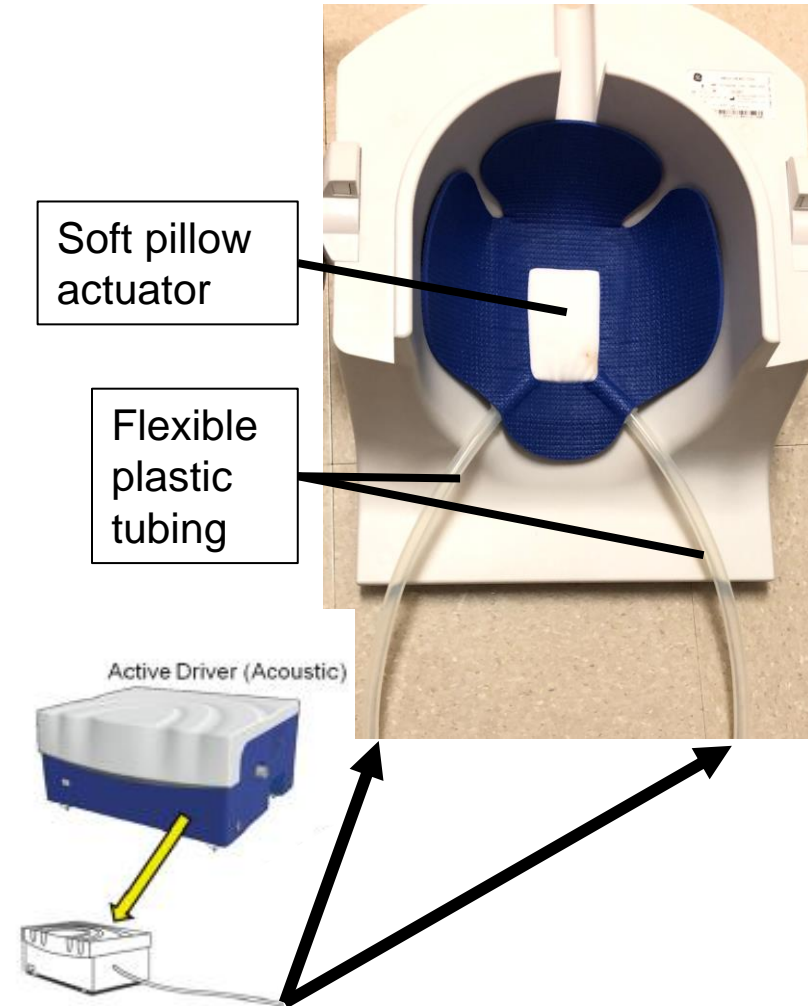
## Optical Imaging



From: Kennedy, et al. *Biomed Opt Express*. (2014)

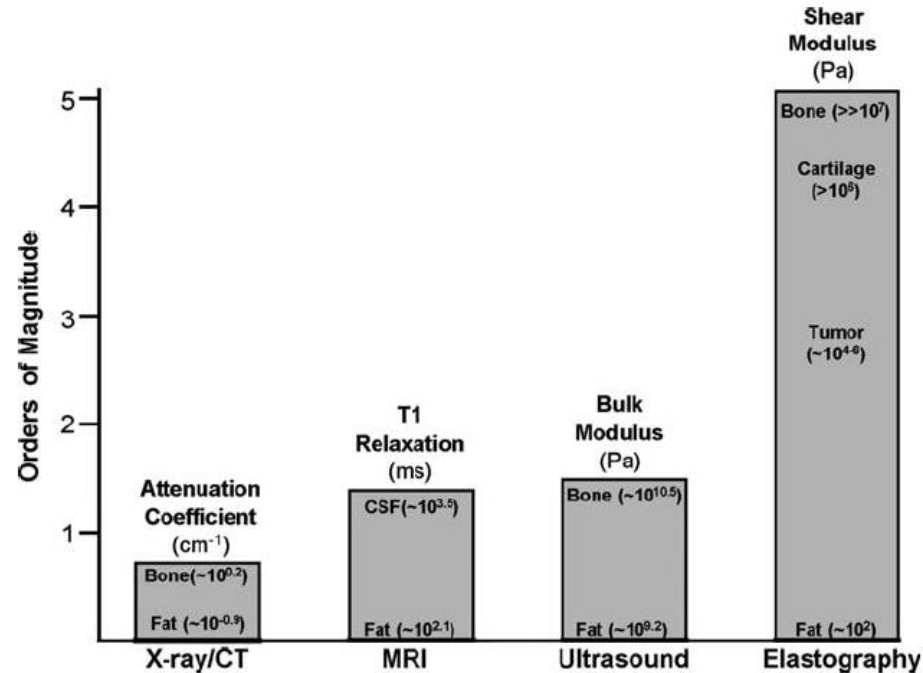
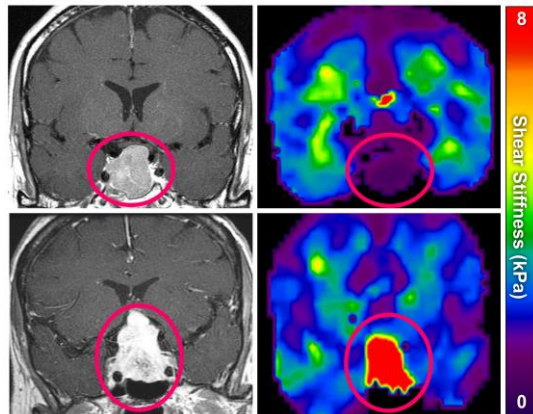
# MR Elastography

- MRE allows quantitative analysis of viscoelastic properties of tissue
  - “Virtual palpation”
- Shear waves are introduced by driver (20-200Hz)
  - Active pneumatic driver placed outside of MR room
  - Passive driver placed under patient's head
- Wavelength dependent on shear modulus
  - Waves propagate rapidly in rigid tissue, slower in softer tissue



# Shear Elastic Modulus

- MRE measures shear modulus (G)
  - $\tilde{G} = G' + iG''$
  - Other elastic moduli:
    - Young's Modulus (E), Bulk Modulus (K), etc.
  - High inherent dynamic range



From: Mariappan, et al. *Clin Anat* (2010)

# MRE Encoding

- Modified phase-contrast sequence
- Sensitized motion to cyclic displacement from shear waves
  - Spins accumulate phase along motion encoding gradients
    - Bipolar or 1<sup>st</sup> order motion compensated gradient
  - Synchronized to driver frequency
- Multiple acquisitions with phase offsets
  - Shows shear wave at different points in cycle
- Goal: Acquire displacement fields in 3D (encode  $x,y,z$ ) at different phase offsets

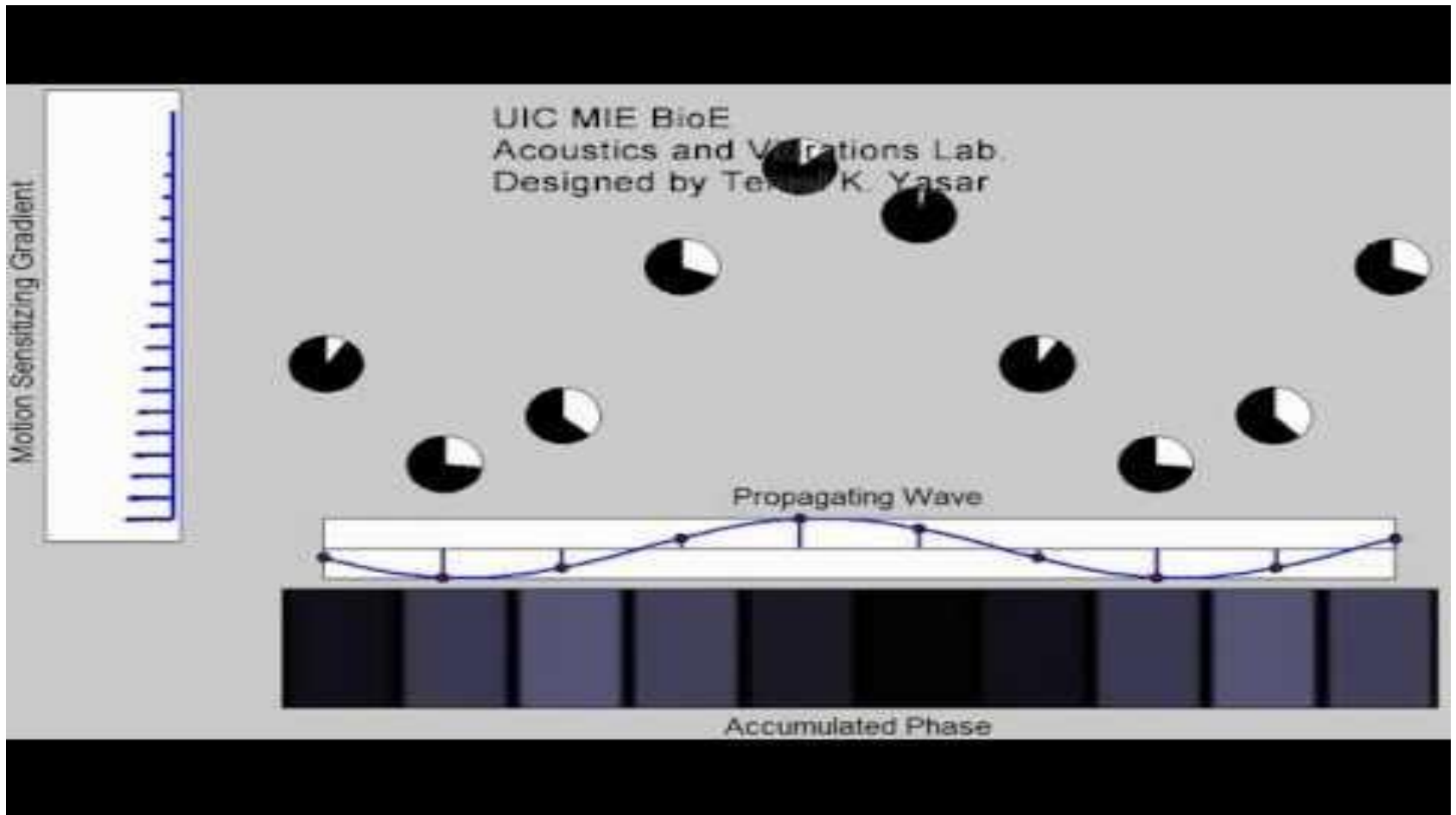
# MRE Encoding

- Phase is described by the following equation

$$- \phi(\vec{r}, \theta) = \frac{\gamma NT(\vec{G} \cdot \xi_0)}{2} \cos(\vec{k} \cdot \vec{r} + \theta)$$

- $\phi$  = displacement induced phase
- $\vec{r}$  = spatial position
- $\theta$  = phase offset
- $\gamma$  = gyromagnetic ratio
- $N$  = number of MEG pairs
- $T$  = period of the MEG
- $\vec{G}$  = gradient strength
- $\xi_0$  = peak amplitude of motion
- $k$  = wave number

# MRE Encoding (Visual)

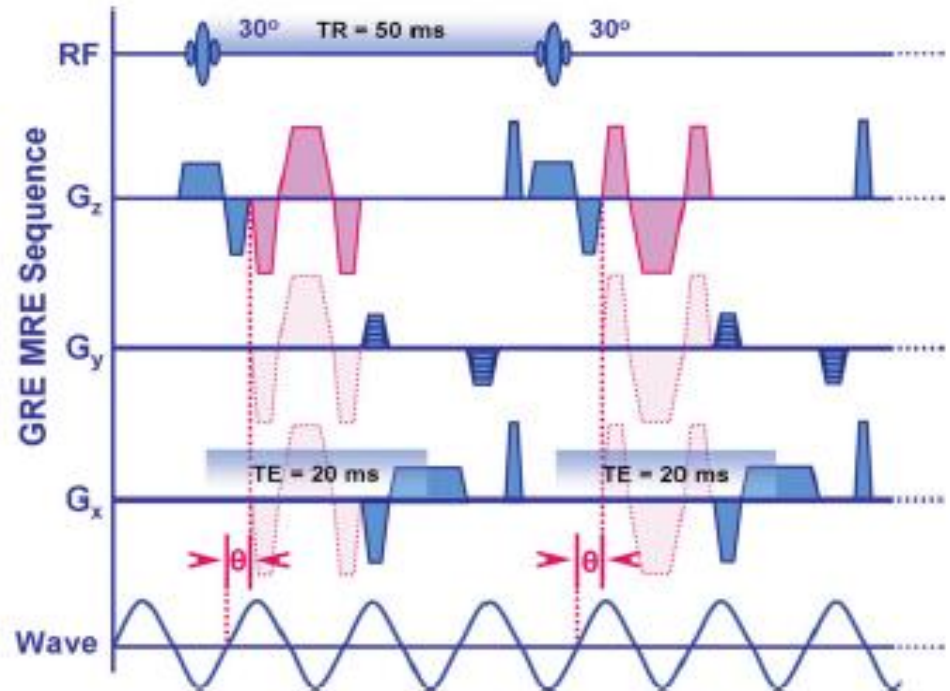




# GRE Acquisition

## 1. Gradient-recalled echo (GRE)

- Oldest method
- Online reconstruction
- Limitations:
  - Relatively slow



From: Venkatesh, et al. *JMRI* (2013)



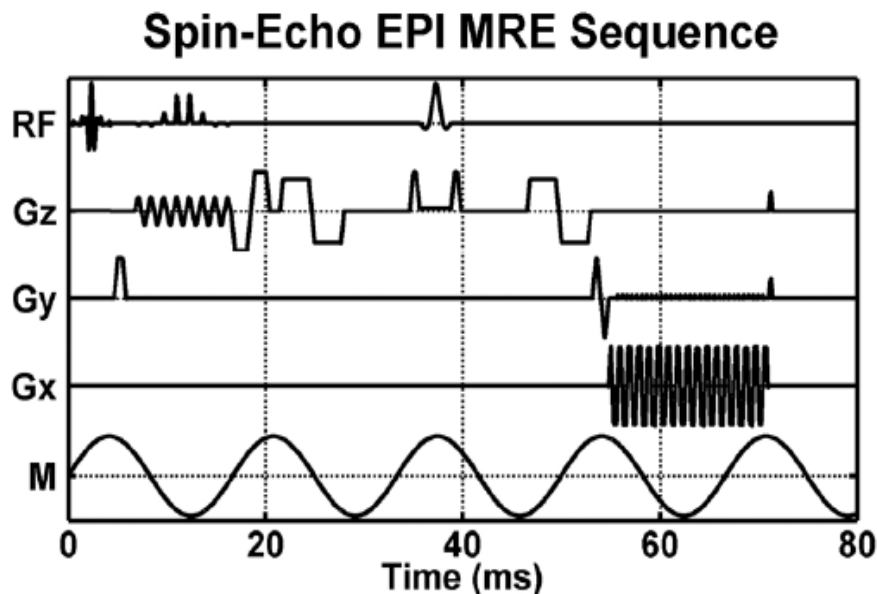
# SE-EPI Acquisition

## 2. Single-shot echo planar imaging (SE-EPI)

- Most common
  - What we use here
- Much faster than GRE
- Online reconstruction

- Limitations:

- Long readouts
  - Distortion
  - Reduced SNR



From: Glaser, et al. *JMRI* (2012)

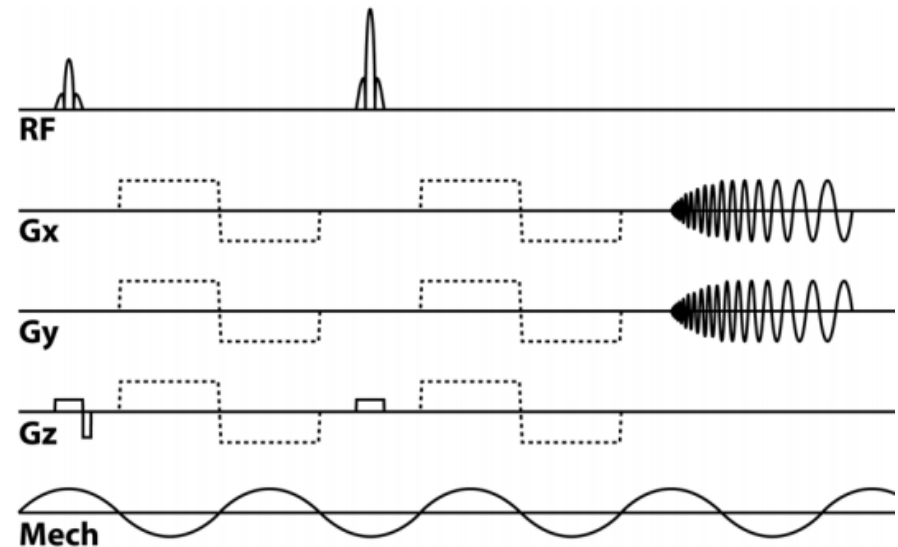
# Multi-Shot Spiral Acquisition

## 3. Multi-shot, variable density spiral

- Relatively new
- Increased resolution
- Increased SNR
- Flexible Tradeoffs

### • Limitations:

- Phase error between shots from bulk motion
- Offline Recon
- Increased complexity

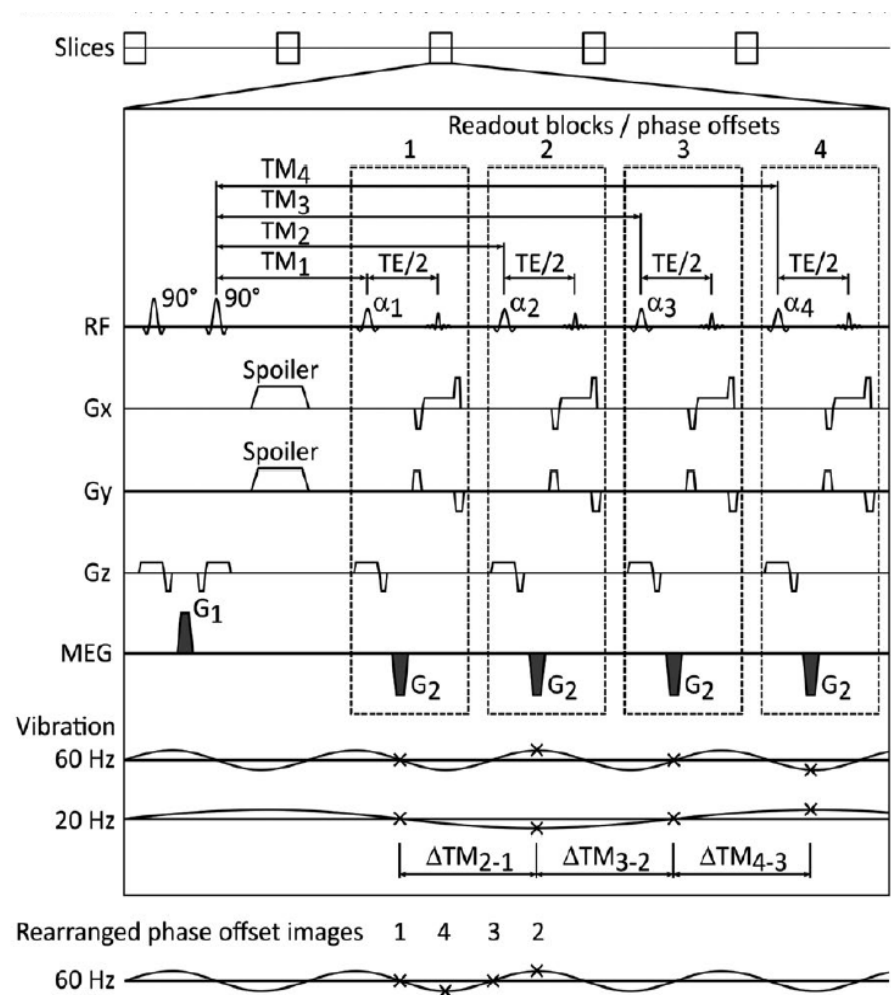


From: Johnson, et al. *MRM* (2013)

# DENSE Acquisition

## 4. Displacement Encoding Using a Stimulated Echo (DENSE)

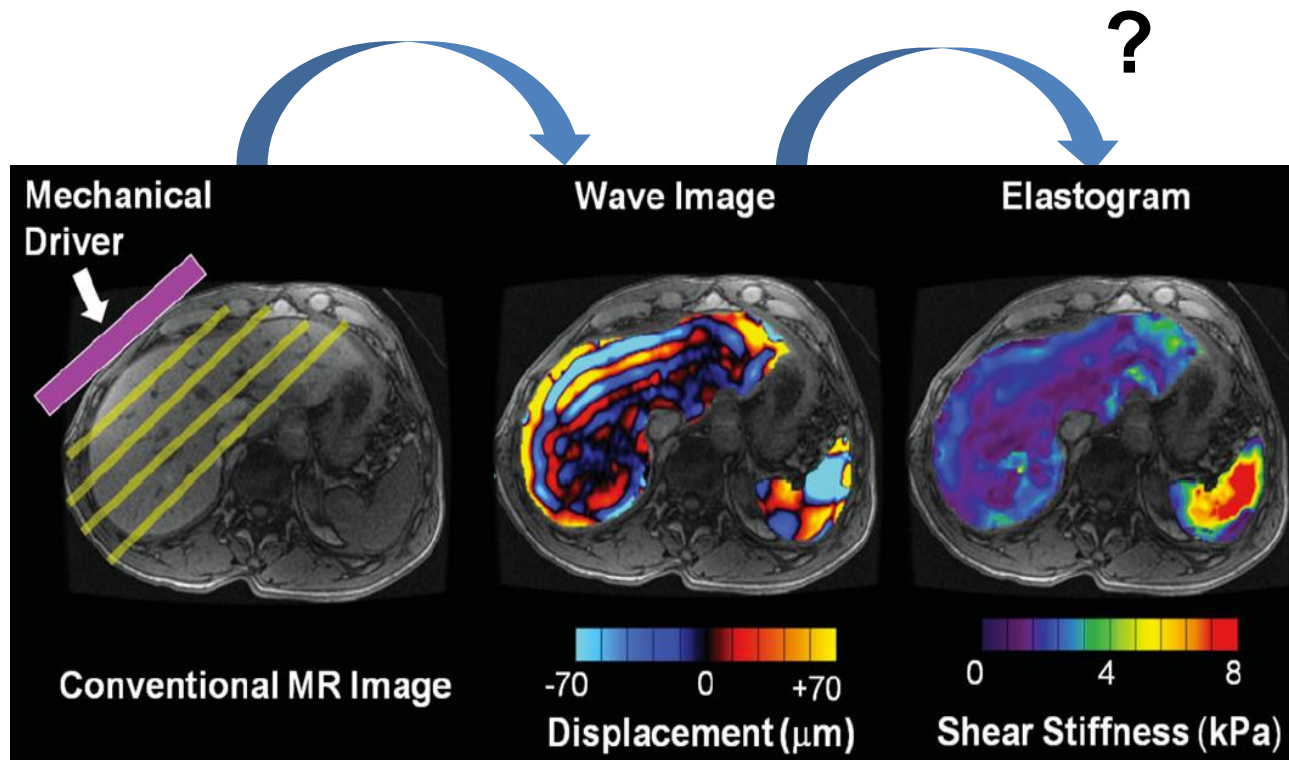
- Relatively new
- Allows for imaging with lower driver frequency
- Fast/Efficient
- Limitations:
  - Offline Recon
  - Increased Complexity



From: Strasser, et al. *MRM* (2018)

# Reconstruction

- How can we go from wave images to stiffness maps?

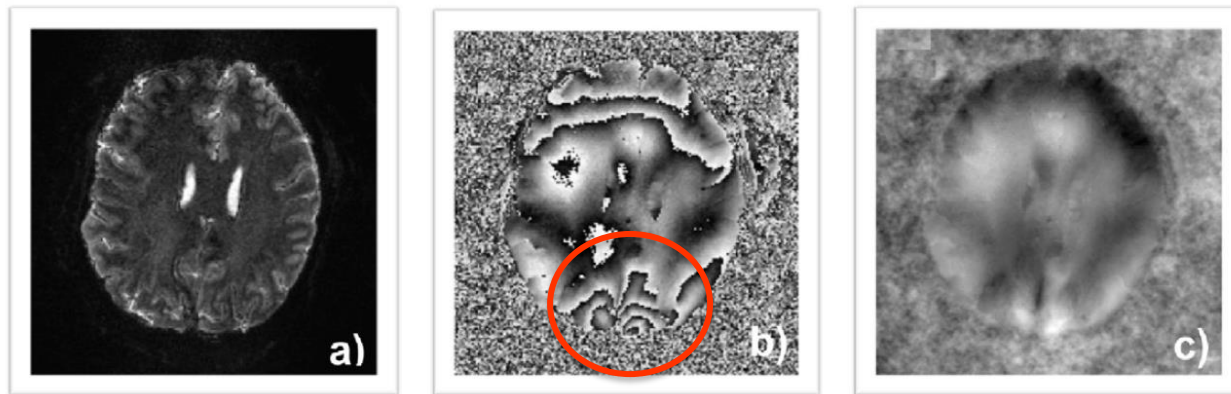


From: Venkatesh, et al. *JMRI* (2013)

# Pre-Processing

## 1) Phase Unwrapping

- Higher amplitude of shear waves allows deeper penetration
- However, this leads to phase-wrapping near brain edges.
- Phase unwrapping algorithms need to be applied before stiffness reconstruction
  - 4D Laplacian-based algorithm

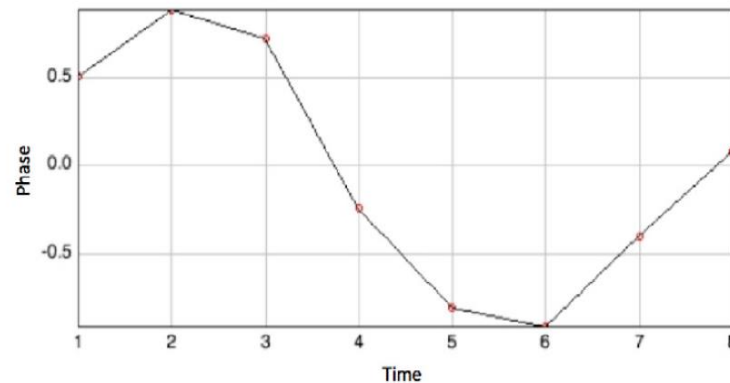
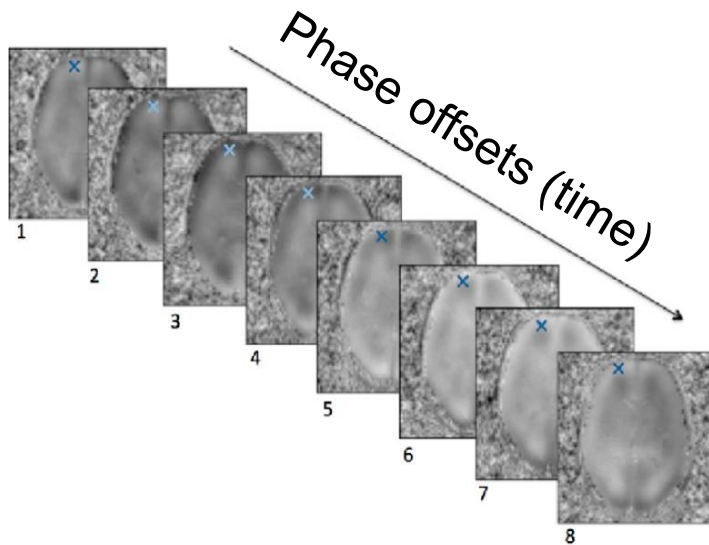


From: Hiscox. *Phys Med Biol* (2016)

# Pre-Processing

## 2) Filtering

- Low frequency bulk waves
  - Occur because brain is not incompressible
- High frequency noise
  - Prevent parameter overestimation



From: Hiscox. *Phys Med Biol* (2016)

# LFE Reconstruction

## 1) Local frequency estimation (LFE)

- Simplest, most-intuitive method
- Uses multiscale filters to estimate spatial wavelengths of shear waves in image.
- $G' = \rho V_s^2 = \rho (\lambda_{sp} f)^2$ 
  - $\rho$  = tissue density ( $\sim 1000 \text{ kg/m}^3$ )
  - $V_s$  = shear wave speed
  - $f$  = driver frequency
  - $\lambda_{sp}$  = spatial frequency of shear wave
- Limitations:
  - Get only real part of shear modulus
  - Effected by boundary reflections and dilatational waves



# DI Reconstruction

## 2) Single Frequency Direction Inversion (DI)

- Mechanical properties calculated *directly* through the wave equation.
- Complex inversion problem
  - Requires rank 4 tensor with 21 independent complex quantities to relate applied shear stress to resulting shear strain.
- If we assume tissue isotropy, we can greatly simplify problem.
  - $\tilde{G} = -\rho(2\pi f)^2 \cdot \vec{u}(f) / \nabla^2 \vec{u}(f)$ 
    - $\tilde{G}$  = complex shear modulus
    - $f$  = driver frequency
    - $\rho$  = tissue density ( $\sim 1000 \text{ kg/m}^3$ )
    - $\vec{u}(f)$  = frequency-dependent vector displacement field

# DI Reconstruction

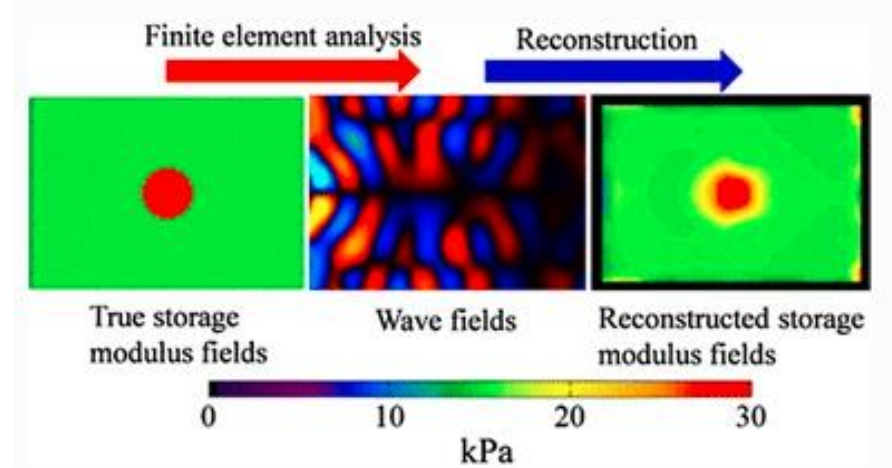
## 2) Single Frequency Direction Inversion (DI)

- Allows for a very quick calculation
  - Really only need to calculate  $\nabla^2 \vec{u}(f)$
- UW scanners use DI
- Limitations:
  - Making many assumptions about material
    - Brain tissue is heterogenous and anisotropic
  - High noise sensitivity
    - Due to second derivative (Laplacian)
  - Susceptible to wave nodes
    - Imaging at single frequency

# NLI Reconstruction

## 3) Non-Linear Inversion with Finite Element Models (NLI)

- Partial differential equations
- Forward problem utilizing prior knowledge
  - Boundary conditions
  - Tissue geometry
  - Mechanical properties



From: Tomita, et al. *J Visual-Japan* (2017)

- Iteratively update heterogenous tissue distribution until difference between experiment and theoretically derived data is minimized.
- Incorporates full equations of motion, nonlinearity, and anisotropy
- Limitations:
  - Speed of processing is on the order of hours

# Conclusion

- MRE is a modified phase contrast sequence to encode displacement into image phase.
- Creates shear modulus maps
  - Must mechanically excite tissue
  - Measure/image tissue stress/strain
- Shear modulus has high dynamic range
- Acquisition Strategies:
  - GRE, Spin-echo EPI, Multi-shot spiral, DENSE
- Reconstruction Strategies:
  - Local frequency estimation (LFE), direct inversion (DI), non-linear finite element modelling (NLI)

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