

# Using LSTMs with Variational Autoencoders to Model Time Series Data

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# AutoEncoder (AE): A type of unsupervised neural networks

- The **encoder** network transforms the input data from a high-dimensional space into codes in a low-dimensional space.
- The **decoder** network reconstructs the inputs from the corresponding codes.

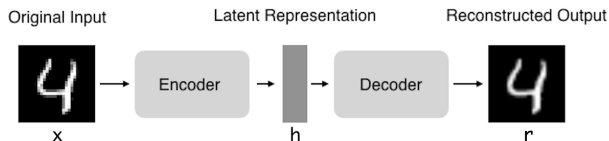


Figure 1: Representation of a simple autoencoder. *Credit:* <http://i-systems.github.io>

# AutoEncoder (AE): Loss function

- Reconstruction error:  $||x - \tilde{x}||$

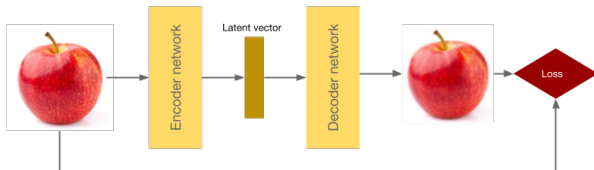


Figure 2: Basic principle of an AutoEncoder. *Credit:* Dehaene's blog, 2018.

# AutoEncoder (AE): Applications

- Image compression
- Image denoising

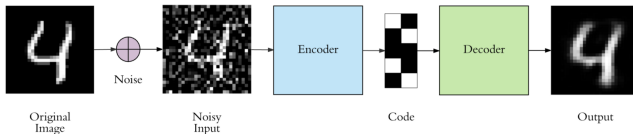


Figure 3: Basic principle of an AutoEncoder. *Credit:* Dehaene's blog, 2018.

# Variational AutoEncoder (VAE):

Consider

- Observable Data:  $\mathbf{X} = \{x_1, x_2, x_3, \dots, x_m\}$
- Hidden Variable:  $\mathbf{z} = \{z_1, z_2, z_3, \dots, z_n\}$

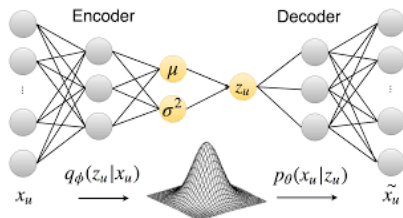


Figure 4: Architecture graph of a variational autoencoder. *Credit:* Karamanolakis et al., 2018.

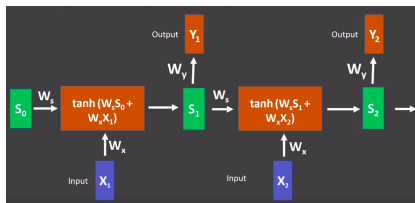
Training a VAE, the loss function becomes:

$$\mathcal{L}(\theta, \phi; \mathbf{x}, \mathbf{z}) = \mathbb{E}_{\mathbf{z}}[\log p_{\theta}(\mathbf{x}|\mathbf{z})] - \frac{\mathbb{E}_{\mathbf{z}}[\log q_{\phi}(\mathbf{z}|\mathbf{x})]}{p_{\theta}(\mathbf{z})} \quad (1a)$$

$$= \mathbb{E}_{\mathbf{z}}[\log p_{\theta}(\mathbf{x}|\mathbf{z})] - D_{KL}(q_{\phi}(\mathbf{z}|\mathbf{x})||p_{\theta}(\mathbf{z})) \quad (1b)$$

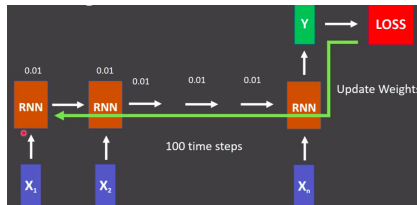
- ① Periodic formula:  $S_t = R_w(S_{t-1}, X_t)$ 
  - $X_t$  – Input at time  $t$
  - $S_t$  – Current state at time  $t$
  - $S_{t-1}$  – Initial state at time  $t - 1$
  - $R_w$  – Periodic function
  
- ② Simple case:  $S_t = \tanh(W_s S_{t-1} + W_x X_t)$

# How RNNs works



**Figure 5:** Basic RNN (unfolded).

*Credit:* The Semicolon RNN lecture, 2018.



**Figure 6:** Problem of vanishing gradient.

*Credit:* The Semicolon RNN lecture, 2018.



- Input Gate:  

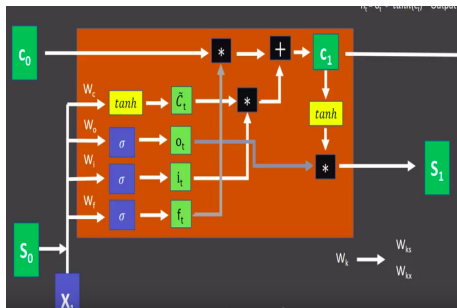
$$i_t = \sigma(W_i S_{t-1} + W_i X_i)$$
- Forget Gate:  

$$f_t = \sigma(W_f S_{t-1} + W_f X_f)$$
- Output Gate:  

$$o_t = \sigma(W_o S_{t-1} + W_o X_o)$$
- Cell State:  

$$c_t = (i_t * \tilde{C}_t) + (f_t * c_{t-1})$$
  - Intermediate cell state:  

$$\tilde{C}_t = \tanh(W_c S_{t-1} + W_c X_c)$$



Architecture graph of LSTM. *Credit: The Semicolon RNN lecture, 2018.*

# LSTM-VAE

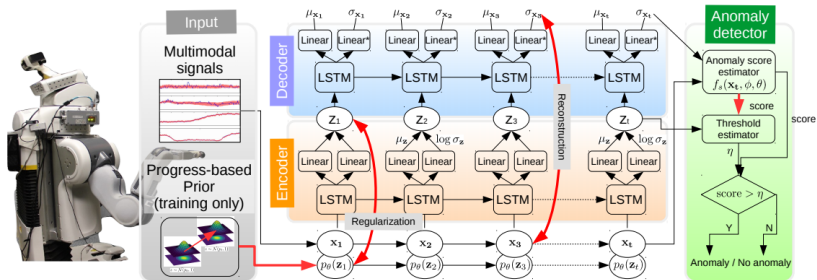
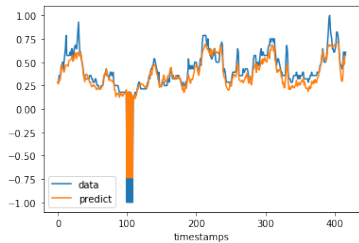
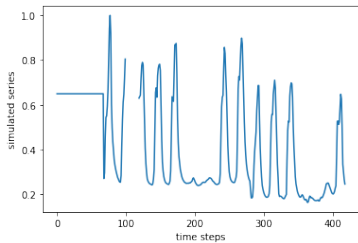
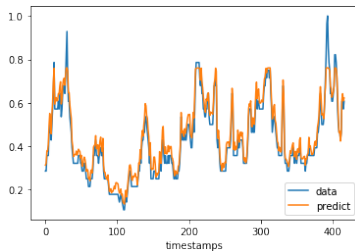


Figure 7: Architecture graph of an LSTM-VAE. Credit: Park et al., 2017.

# Simulation Test



# Simulation Test



- Run an RNN on the imputed inputs (i.e. mean, median, fill nans)
- Use weighted average approach to interpolate missing values
- Gaussian processes to interpolate missing values



*That's all Folks!*