Scale spaces and Semigroup theory

https://tinyurl.com/scalegroups

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Motivational problems

Enhancing (Deblurring)



(a) Blurry Data



(b) Enhanced Data

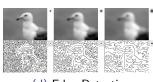
Smoothing (Denoising, Edge detection)



Noisy 1



(c) Gaussian Filter



(d) Edge Detection

Idea: The image we want is a solution of some PDE

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• Smoothing: (Gaussian filter)

$$\partial_t u + \Delta u = 0 \text{ on } \Omega \times (0, T)$$

 $u(\cdot, 0) = u^{\delta} \text{ on } \Omega$

Idea: The image we want is a solution of some PDE

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$$\partial_t u + \Delta u = 0 \text{ on } \Omega \times (0, T)$$

 $u(\cdot, 0) = u^{\delta} \text{ on } \Omega$

Enhancing: (Backward linear diffusion)

$$egin{aligned} \partial_t u + \Delta u &= 0 \ ext{on} \ \Omega imes (0,T) \ u(\cdot,T) &= u^\delta \ ext{on} \ \Omega \end{aligned}$$

Idea: The image we want is a solution of some PDE

Smoothing: (Gaussian filter)

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Why scale spaces

Example problem: Edge detection

Observation: We perceive things in different scales.

Solution: Smooth things to make the different scales pop out.

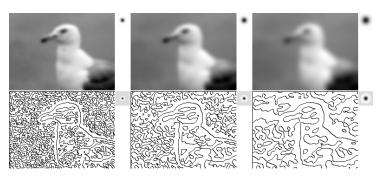


Why scale spaces

Example problem: Edge detection

Observation: We perceive things in different scales.

Solution: Smooth things to make the different scales pop out.



Scale spaces: Definition

Definition

Let U be a space of functions on $\Omega \subseteq \mathbb{R}^n$. A scale space on U is a family of mappings $\{T_t: U \to U\}_{t \geq 0}$. It is called **pyramidal** if there exists a family of operators $\{T_{t+h,t}: U \to U\}_{t,h \geq 0}$ such that:

$$T_{t+h,t}T_t = T_{t+h}, \quad T_0 = \operatorname{Id}$$

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Definition

A pyramidal scale space satisfies the **local comparison principle** if for all $u, v \in U$ the following are true:

- $u \le v$ around $x \in \Omega \Rightarrow T_{t+h,t}u(x) \le T_{t+h,t}v(x) + o(h)$
- $u \le v$ in Ω , then $T_{t+h,t}u \le T_{t+h,t}v, \forall h \ge 0$

Scale spaces and PDEs

Definition

A pyramidal scale space is **regular** if there exists a function $F: \mathbb{R} \times \Omega \times \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^{n \times n} \to \mathbb{R}$ continuous with respect to its last component such that

$$\lim_{h \to 0^+} \frac{T_{t+h,t} u(x) - u(x)}{h} = F(t, x, u(x), \nabla u(x), \nabla^2 u(x)) \tag{R}$$

for all quadratic functions u around x, i.e.

$$u(y) = c + p^{T}(y - x) + \frac{1}{2}(y - x)^{T}A(y - x)$$

for y around x. A regular pyramidal scale space that satisfies the local comparison principle is called **causal**.

Scale Spaces and PDEs

Theorem

If T_t is causal, then (R) holds for all $u \in C^2(\Omega), x \in \Omega, t \geq 0$. Moreover the function F is non-decreasing with respect to its last component in the sense that: $F(t,x,c,p,A) \leq F(t,x,c,p,B)$ when $B-A \geq 0$

Example

Let $U = C_b(\mathbb{R}^n)$ and define $T_t u^\delta = u(t, \cdot)$ is the convolution with the Gaussian with variance t. Then $u(t, x) = T_t u^\delta(x)$ solves

$$\partial_t u = \Delta u, t > 0$$
 $u(0, \cdot) = u^{\delta}$

Then T_t it a causual scale space that satisfies the local comparison principle.

Scale spaces: Invariance

Definition

Let T_t be a causal scale space on U. Then:

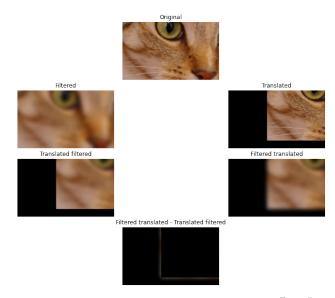
• T_t is translation invariant if

$$T_{t+h,t} \circ \tau_z = \tau_z \circ T_{t+h,t}$$

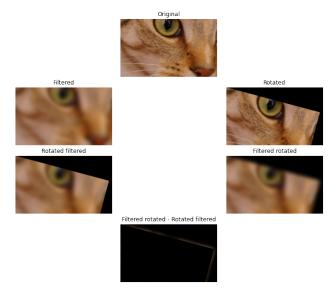
• T_t is **Euclidean invariant** if for every orthogonal matrix O:

$$T_{t+h,t} \circ \rho_O = \rho_O \circ T_{t+h,t}$$

Translation invariance for heat scale space



Euclidean invariance for heat scale space



Scale spaces: Invariance

Definition

- T_t is **scale invariant** if there exists a rescaling function $\theta: (0,\infty) \times [0,\infty) \to [0,\infty)$ satisfying the following conditions:
 - θ is differentiable and $\partial_c \theta(t,1) > 0$ and is continuous for all t > 0.
 - $T_{t+h,t} \circ \sigma_c = \sigma_c \circ T_{\theta(c,t+h),\theta(c,t)}, c > 0$
- A scale invariant T_t is **affine invariant** if there exists $\hat{\theta}: \operatorname{GL}^n \times [0,\infty) \to [0,\infty)$ such that $\theta(c,\cdot) := \hat{\theta}(c\operatorname{Id},\cdot)$ satsfies the conditions above and

$$T_{t+h,t} \circ \rho_A = \rho_A \circ T_{\hat{\theta}(A,t+h),\hat{\theta}(A,t)}, A \in \mathsf{GL}^n$$

where $(\sigma_c u)(x) := u(cx), (\rho_A u)(x) = u(Ax).$



Scale spaces: Invariance

Definition

• T_t is invariant by gray level translations if

$$T_{t+h,t}(0) = 0, \quad T_{t+h,t}(u+C) = T_{t+h,t}(u) + C, C \in \mathbb{R}$$

• T_t is **contrast invariant** if for every non-decreasing continuous function $g : \mathbb{R} \to \mathbb{R}$ and $u \in U$:

$$g(T_{t+h,t}u(x)) = T_{t+h,t}(g \circ u)(x), x \in \mathbb{R}^n$$

Heat scale space is not contrast invariant



Semigroups

Bibliography

- [GMR12] Frédéric Guichard, Jean-Michel Morel, and Robert Ryan. "Contrast invariant image analysis and PDE's (Preprint)". In: (2012).
- [Sch+09] Otmar Scherzer et al. "Variational methods in imaging". In: (2009).