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Study of Comparator and their Architectures

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ABSTRACT

Comparator is one of the most important analog circuits required in many analog integrated circuits and also in digital design. It is used for the comparison between two different or same electrical signals. Nowadays, the need for ultra low-power, area efficient and high speed analog-to-digital converters is pushing toward the use of dynamic regenerative comparators to maximize speed and power efficiency. In this paper, study of comparators and their architectures is done and analytical expressions are derived. From the analytical expressions, designers can obtain an intuition about the main contributors to the comparator characteristics and fully explore the tradeoffs in comparator design. Based on study few points are derived based on which new comparator can be designed as the design of Comparator becomes an important issue when technology is scaled down.

KEYWORDS: Double Tail comparator, ADCs, Voltage swing.

INTRODUCTION

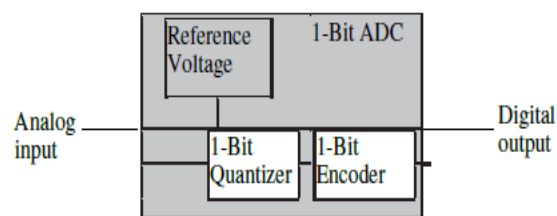
Comparator is a circuit that compares one analog signal with another analog signal or a reference voltage and outputs a binary signal based on the comparison and works on two phases: reset and regeneration phase.

These were developed with the introduction of the first dc-coupled amplifier, at the dawn of the field of electronics. Since then, comparators have remained a very important building block for many types of circuits, including analog-to-digital converters (ADCs), power converters, sensor circuits, and many other types of mixed-signal systems. Over the years, researchers have improved comparator performance in areas such as sensitivity, offset, speed, and power consumption through the use of multistage topologies and other circuit methods[4],[5]. Many of the improvements [3] to comparators have focused on improving the comparator as an isolated circuit rather than as part of a larger system. In many applications, e.g., in ADCs and power converters, knowledge of the signals driving the comparator (for

example, pulse-frequency modulation of power converters) may be used to improve the performance of the comparator.

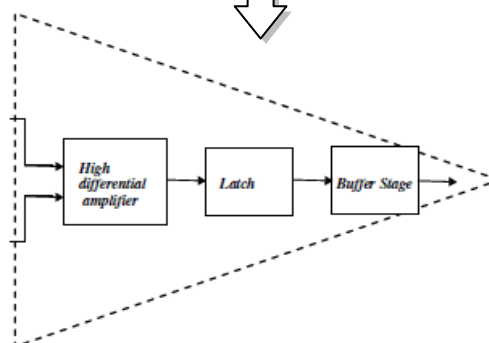
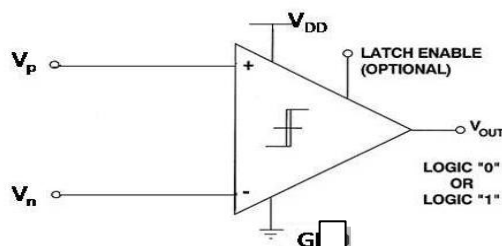
This paper describes basic comparator and their architectures since, designing high-speed comparators is more challenging when the supply voltage is smaller. The schematic symbol and basic operation of a voltage comparator are shown in Figure 1. The comparator can be thought of as a decision-making circuit. If the +, v_+ input of the comparator is at a greater potential than the -, v_- , input, the output of the comparator is a logic 1, whereas if the + input is at a potential less than the - input, the output of the comparator is at a logic 0. Although the basic op- amp can be used as a voltage comparator, in some less demanding low-frequency or speed applications, we will not consider the op-amp as a comparator.

The comparator is basically a 1-bit ADC.



$V_P < V_N$ then $V_O = V_{SS} = \text{logic 0}$

$V_P > V_N$ then $V_O = V_{DD} = \text{logic 1}$



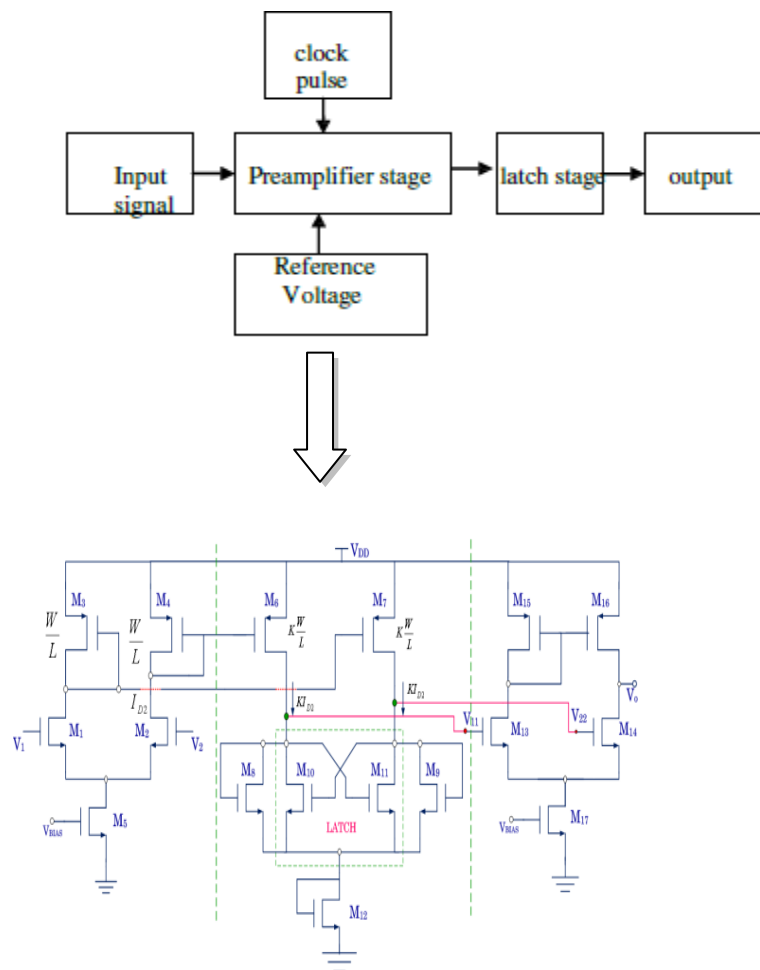


Figure1: Basic comparator diagram and its basic blocks

Voltage transfer characteristics of basic comparator in ideal mode

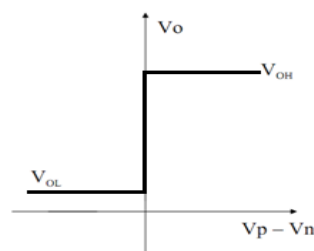


Figure 2: Voltage Transfer Characteristic

Important characteristics of comparator which is to be checked while designing comprises of two parts:

1. Static characteristics

- Gain

$$\text{Gain} = A_v = \lim_{\Delta V \rightarrow 0} \frac{V_{OH} - V_{OL}}{\Delta V} \text{ where } \Delta V \text{ is the input voltage change}$$

- Output high and low states

$$V_{OH} \quad V_{OL} \quad V_{IL} \quad V_{IH}$$

$$\text{The voltage gain is } A_v = \frac{V_{OH} - V_{OL}}{V_{IH} - V_{IL}}$$

- Input resolution

It is the input voltage change which is necessary to make output swing to valid binary states

- Offset
Offset in the comparators generates due to input transistor mismatches.
- Noise
- ICMR

2. Dynamic characteristics

- Propagation delay(t_p)
propagation delay is the delay between output and input
- Slew Rate(SR)

Relation between t_p and SR

$$t_p = \Delta T = \Delta V / SR = (V_{OH} - V_{OL}) / 2 \cdot SR$$

COMPARATOR ARCHITECTURES

High gain amplifiers are often used as comparators since the outputs of most amplifiers naturally clip at high and low levels when overdriven. Some comparators are clocked and only provide an output after the transition of the clock. The value of the input to a clocked comparator is only of concern in a short time interval around the clock transition. The speed of clocked comparators can be very high and the power dissipation of clocked comparators can be very low. Clocked comparators are often called Dynamic Comparators and are widely used in the design of high-speed ADCs. Regenerative feedback is often used in dynamic comparators and occasionally in non-clocked comparators.

Basically there are various architectures available in modern days which are then summarized into three categories:

- A. Open Loop Comparator
- B. Regenerative
- C. High Speed Comparator

- Open Loop Comparators

These comparators are basically operational amplifier without compensation shown in figure 3 to obtain the largest bandwidth, hence improving its time response. Since the precise gain and linearity are of no interest in comparator design no compensation does not pose a problem. However, due to its limited gain-bandwidth product, open loop comparators are too slow for much application

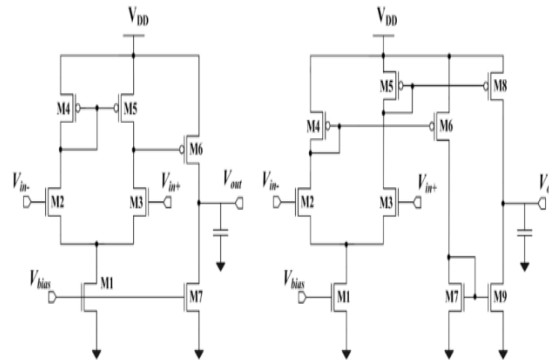


Figure 3: (a) Two-stage open-loop comparator (b) Push-pull output open-loop comparator

- Regenerative Comparator

These comparators use positive feedback like latch to compare signals shown in figure 4, 5, 6.

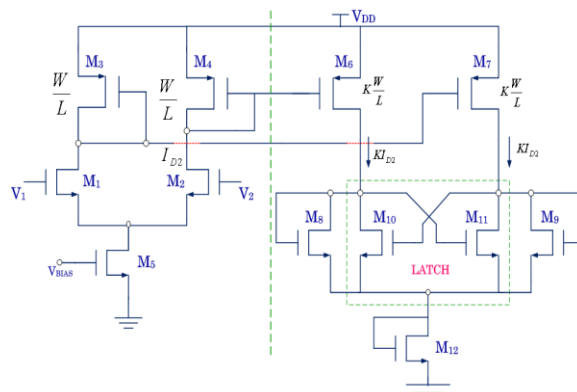


Figure 4: Fully differential amplifier and Latch

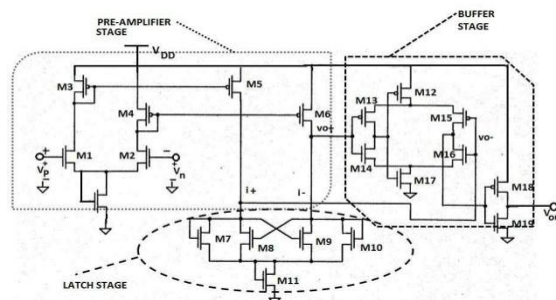


Figure 5: Preamplifier based comparator

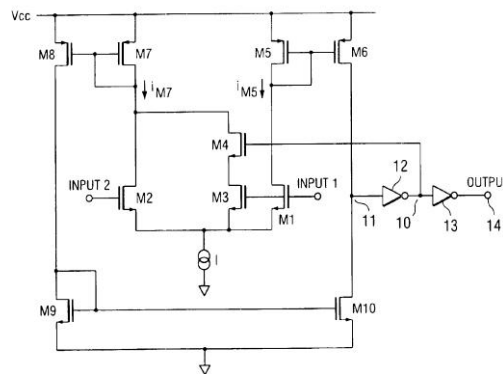


Figure 6: Comparator with hysteresis

A. High Speed Comparator

These comparators are combination of above two types of comparator which leads to faster response

DYNAMIC COMPARATOR

Among different types of comparators, clocked regenerative comparators (called dynamic comparators) have found wide applications in many high-speed ADCs since they can make fast decisions due to the strong positive feedback in the regenerative latch. Recently, many comprehensive analyses have been presented which investigate the performance of these comparators from different aspects such as noise [6], offset [8], [9], random decision errors [12], delay [1] and kick-back noise [11]. Even the power of the dynamic comparators can also be investigated by the well-known formula, (1), for dynamic power consumption considering leakage current is used to estimate the power.

$$Power = f_{clk} C_L V_{DD} + V_{DD} I_{leakage} \quad (1)$$

This formula would provide the designers with acceptable estimation, but it does not reveal the design parameters which contribute to the power consumption. While a comparator is by definition a nonlinear circuit element that makes a hard decision on the input signal polarity, almost every clocked comparator does so by sampling the input signal and then regeneratively amplifying it, each of which operation can be treated as that of a linear system. Thus, comparator can be treated as a linear periodically time-variant (LPTV) system.

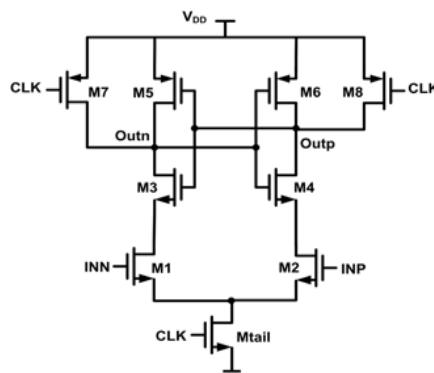


Figure 7: Conventional Dynamic Comparator

A. Conventional Dynamic Comparator

The schematic diagram of the conventional dynamic comparator [1],[2],[13] shown in fig 7 which is widely used in A/D converters, with high input impedance, rail-to-rail output swing, and no static power consumption is shown in fig. The operation of the comparator is as follows.

During the reset phase when CLK = 0 and M_{tail} is off, reset transistors ($M7-M8$) pull both output nodes $Outn$ and $Outp$ to V_{DD} to define a start condition and to have a valid logical level during reset.

In the comparison phase, when CLK = V_{DD} , transistors $M7$ and $M8$ are off, and M_{tail} is on. Output voltages ($Outp$, $Outn$), which had been pre-charged to V_{DD} , start to discharge with different discharging rates depending on the corresponding input voltage (INN/INP). Assuming the case where $V_{INP} > V_{INN}$, $Outp$ discharges faster than $Outn$, the corresponding pMOS transistor ($M5$) will turn on initiating the latch regeneration caused by back-to-back inverters ($M3, M5$ and $M4, M6$). Thus, $Outn$ pulls to V_{DD} and $Outp$ discharges to ground. If $V_{INP} < V_{INN}$, the circuits works vice versa.

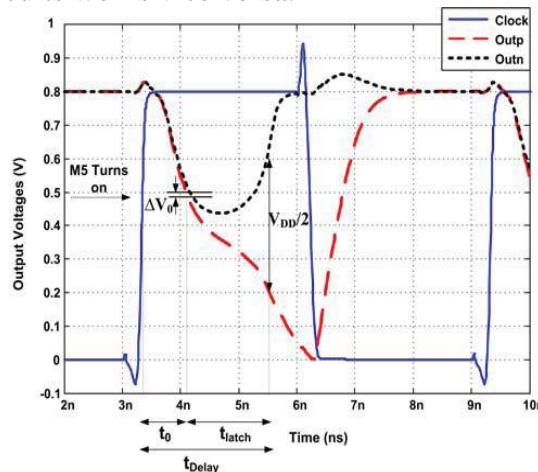


Fig 8. Transient response of the conventional dynamic comparator

As shown in Fig. 8 the delay of this comparator is comprised of two time delays, t_0 and t_{latch} . The delay t_0 represents the capacitive discharge of the load capacitance C_L until the first p-channel transistor ($M5/M6$) turns on. Here the discharge delay(t_0) is given by

$$t_0 = \frac{C_L |V_{thp}|}{I_2} \cong 2 \frac{C_L |V_{thp}|}{I_{tail}} \quad (2)$$

In equation (2), since $I_2 = I_{tail}/2 + I_{in} = I_{tail}/2 + g_{m1}2\Delta V_{in}$, for small differential input (ΔV_{in}), I_2 can be approximated to be constant and equal to the half of the tail current.

The second term, t_{latch} , is the latching delay of two cross coupled inverters. Here it is assumed that a voltage swing of $\Delta V_{out} = V_{DD}/2$ has to be obtained from an initial output voltage difference ΔV_0 at the falling output (e.g., $Outp$). Half of the supply voltage is considered to be the threshold voltage of the comparator following inverter or SR latch. Hence, the latch delay time is given by,

$$t_{latch} = \frac{C_L}{g_{m,eff}} \cdot \ln \left(\frac{\Delta V_{out}}{\Delta V_0} \right) = \frac{C_L}{g_{m,eff}} \cdot \ln \left(\frac{V_{DD}/2}{\Delta V_0} \right) \quad (3)$$

where $g_{m,eff}$ is the effective transconductance of the back-to back inverters. In fact, this delay depends, in a logarithmic manner, on the initial output voltage difference at the beginning of the regeneration (i.e., at $t = t_0$). Based on (2), ΔV_0 can be calculated from (4)

$$\begin{aligned}\Delta V_0 &= |V_{outp}(t = t_0) - V_{outn}(t = t_0)| \\ &= |V_{thp}| - \frac{I_2 t_0}{C_L} = |V_{thp}| \left(1 - \frac{I_2}{I_1}\right).\end{aligned}\quad (4)$$

The current difference, $\Delta I_{in} = |I_1 - I_2|$, between the branches is much smaller than I_1 and I_2 . Thus, I_1 can be approximated by $I_{tail}/2$ and (4) can be rewritten as

$$\begin{aligned}\Delta V_0 &= |V_{thp}| \frac{\Delta I_{in}}{I_1} \\ &\approx 2 |V_{thp}| \frac{\Delta I_{in}}{I_{tail}} \\ &= 2 |V_{thp}| \frac{\sqrt{\beta_{1,2} I_{tail}}}{I_{tail}} \Delta V_{in} \\ &= 2 |V_{thp}| \sqrt{\frac{\beta_{1,2}}{I_{tail}}} \Delta V_{in}.\end{aligned}\quad (5)$$

In equation (5), $\beta_{1,2}$ is the input transistors' current factor and I_{tail} is a function of input common-mode voltage (V_{cm}) and V_{DD} . Now, substituting ΔV_0 in latch delay expression and considering t_0 , the expression for the delay of the conventional dynamic comparator is obtained as

$$\begin{aligned}t_{delay} &= t_0 + t_{latch} \\ &= 2 \frac{C_L |V_{thp}|}{I_{tail}} + \frac{C_L}{g_{m,eff}} \cdot \ln \left(\frac{V_{DD}}{4 |V_{thp}| \Delta V_{in} \sqrt{\frac{I_{tail}}{\beta_{1,2}}}} \right).\end{aligned}\quad (6)$$

Equation (6) explains the impact of various parameters.

The total delay is inversely proportional to the input difference voltage (ΔV_{in}) and directly proportional to the comparator load capacitance C_L . Besides this the delay also depends indirectly to the input common-mode voltage (V_{cm}).

In principle, this structure has the advantages of high input impedance, rail-to-rail output swing, no static power consumption, and good robustness against noise and mismatch.

But the disadvantage on the other hand, is that due to several stacked transistors, the delay time of the latch becomes large due to lower transconductances.

Another important drawback of this structure is that there is only one current path, via tail transistor M_{tail} , which is not favourable for regeneration.

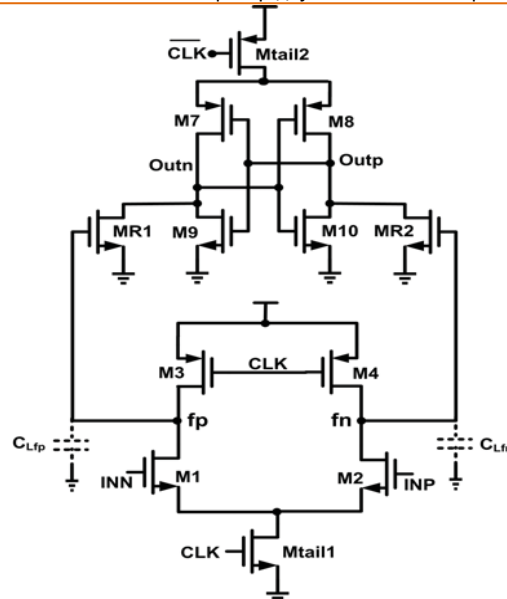


Figure 9: Schematic diagram of the conventional double-tail dynamic comparator.

B. Conventional Double-Tail Dynamic Comparator

As there are some disadvantages in conventional dynamic comparator so here we are going to study a conventional double-tail comparator is shown in Fig.9. [1], [10]. This topology has less stacking and therefore can operate at lower supply voltages. Here the double tail enables both a large current in the latching stage and wider M_{tail2} , for fast latching independent of the input common-mode voltage (V_{cm}), and a small current in the input stage (small M_{tail1}), for low offset.

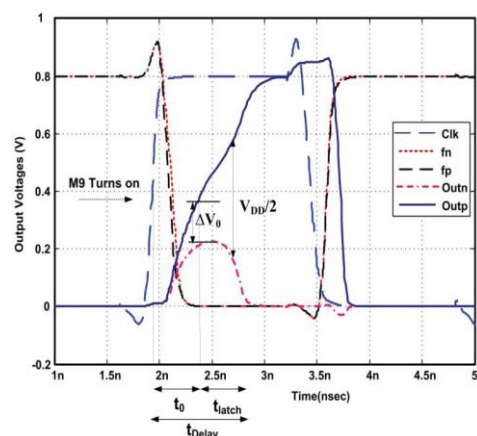


Figure 10: Transient simulations of the conventional double-tail dynamic comparator

Operation of this comparator as follows

During reset phase ($CLK = 0$, M_{tail1} , and M_{tail2} are off), transistors $M3$ - $M4$ pre-charge fn and fp nodes to V_{DD} , which in turn causes transistors $MR1$ and $MR2$ to discharge the output nodes to ground.

During decision-making phase ($CLK = V_{DD}$, M_{tail1} and M_{tail2} turn on), $M3$ - $M4$ turn off and voltages at nodes fn and fp start to drop with the rate defined by $I_{Mtail1}/C_{fn(p)}$ and on top of this, an input-dependent Differential voltage $\Delta V_{fn(p)}$ will build up. The

intermediate stage formed by $MR1$ and $MR2$ passes $V_{fn}(p)$ to the cross coupled inverters and also provides a good shielding between input and output, resulting in reduced value of kickback noise.

Similar to the conventional dynamic comparator, the delay of this comparator comprises two main parts, t_0 and t_{latch} , shown in fig 10.

Here

$$t_0 = \frac{V_{Thn} C_{Lout}}{I_{B1}} \approx 2 \frac{V_{Thn} C_{Lout}}{I_{tail2}} \quad (7)$$

$$\begin{aligned} \Delta V_0 &= |V_{outp}(t = t_0) - V_{outn}(t = t_0)| = V_{Thn} - \frac{I_{B2} t_0}{C_{Lout}} \\ &= V_{Thn} \left(1 - \frac{I_{B2}}{I_{B1}} \right) \end{aligned} \quad (8)$$

where I_{B1} and I_{B2} are the currents of the latch left- and right side branches of the second stage, respectively.

Considering $\Delta I_{latch} = |I_{B1} - I_{B2}| = g_{mR1} \Delta V_{fn/fp}$, (8) can be rewritten as

$$\Delta V_0 = V_{Thn} \frac{\Delta I_{latch}}{I_{B1}} \approx 2 V_{Thn} \frac{\Delta I_{latch}}{I_{tail2}} = 2 V_{Thn} \frac{g_{mR1,2}}{I_{tail2}} \Delta V_{fn/fp} \quad (9)$$

where $g_{mR1,2}$ is the transconductance of the intermediate stage transistors ($MR1$ and $MR2$) and $\Delta V_{fn/fp}$ is the voltage difference at the first stage outputs (fn and fp) at time t_0 . In fact, here intermediate stage transistors amplify the voltage difference of $\Delta V_{fn/fp}$ causing the latch to be imbalanced. So

$$\begin{aligned} \Delta V_{fn/fp} &= |V_{fn}(t = t_0) - V_{fp}(t = t_0)| \\ &= t_0 \cdot \frac{I_{N1} - I_{N2}}{C_{L,fn(p)}} \\ &= t_0 \cdot \frac{g_{m1,2} \Delta V_{in}}{C_{L,fn(p)}} \end{aligned} \quad (10)$$

Where $I_{N1}-I_{N2}$ refer to discharging currents of input transistors ($M1$ and $M2$) which are dependent on the input differential voltage ΔV_{in} . So from (10) & (9) we have ΔV_0 as

$$\begin{aligned} \Delta V_0 &= 2 V_{Thn} \frac{g_{mR1,2}}{I_{tail2}} \Delta V_{fn/fp} \\ &= \left(\frac{2 V_{Thn}}{I_{tail2}} \right)^2 \cdot \frac{C_{Lout}}{C_{L,fn(p)}} \cdot g_{mR1,2} g_{m1,2} \Delta V_{in} \end{aligned} \quad (11)$$

This equation((11) shows that ΔV_0 depends strongly on the transconductance of input and intermediate stage transistors, input voltage difference (ΔV_{in}), latch tail current, and the capacitive ratio of C_{Lout} to $C_{L,fn(p)}$. Here the total delay of this comparator is achieved as follows:

$$\begin{aligned}
 t_{\text{delay}} &= t_0 + t_{\text{latch}} = 2 \frac{V_{\text{Thn}} C_{\text{Lout}}}{I_{\text{tail2}}} + \frac{C_{\text{Lout}}}{g_{m,\text{eff}}} \cdot \ln \left(\frac{V_{\text{DD}}/2}{\Delta V_0} \right) \\
 &= 2 \frac{V_{\text{Thn}} C_{\text{Lout}}}{I_{\text{tail2}}} + \frac{C_{\text{Lout}}}{g_{m,\text{eff}}} \\
 &\quad \cdot \ln \left(\frac{V_{\text{DD}} \cdot I_{\text{tail2}}^2 \cdot C_{\text{L},\text{fn(p)}}}{8 V_{\text{Thn}}^2 \cdot C_{\text{Lout}} g_{m\text{R1},2} g_{m\text{L},2} \Delta V_{\text{in}}} \right). \quad (12)
 \end{aligned}$$

So comparing both architecture we found that delay get reduced and even power is consumed low which is to seen while designing.

CONCLUSION

Hence in this paper only explanation about the Comparator their characteristics, architecture and various parameters such as delay, offset voltage, output impedance and voltage gain is done which are further needed to be considered in any design. But, the selection of any topology is based on the application and the requirements.

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