

On the affect of the Laplacian in equilibration dynamics of the Spherical Model

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Consider a system of N linearly interacting degrees of freedom. We collect them into a vector $\bar{\mathbf{x}}(t) = (x_1(t), \dots, x_N(t))$ and represent their interactions with random coupling matrix $\mathbf{J}(t)$. We subject them to a global constraint: lying on an N -dimensional sphere of radius N . These degrees of freedom may also experience constant bias $\mathbf{h}(t)$ external noise $\boldsymbol{\xi}(t)$. We write down the Langevin Equation of motion, dropping the explicit time dependence for brevity.

$$\partial_t \bar{\mathbf{x}} = (\mathbf{J} - \mu) \bar{\mathbf{x}} + \mathbf{h} + \boldsymbol{\xi} \quad (1)$$

$$\text{where } \mu = \frac{1}{N} \bar{\mathbf{x}}^\top (\mathbf{J} \bar{\mathbf{x}} + \mathbf{h} + \boldsymbol{\xi}) \quad \text{enforces constraint } |\bar{\mathbf{x}}(t)|^2 = N \quad (2)$$