

Reduction of Logical Regulatory Networks by rewriting logical functions

1 Introduction

2 Model Reduction

- Dynamical Impact

3 Selecting Reduced Components

4 Implementation and Applications

- GINsim: Definition and Analysis of Logical Models
- CoLoMoTo: Improving Interoperability
- Th differentiation

5 Conclusion and Prospects

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Logical Formalism

Regulatory Graph



- Components
- Interactions
- Logical functions

next(A): $A \ \& \ !B$

next(B): $A \ \& \ !B:2$

State Transition Graph

10

11

12

00

01

02

Logical Formalism

Regulatory Graph

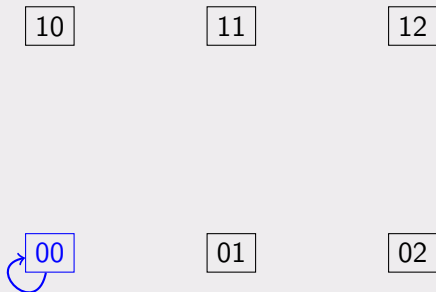


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State Transition Graph



Logical Formalism

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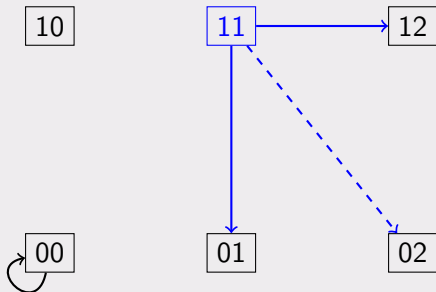


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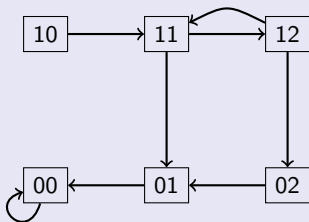
next(B): $A \ \& \ !B:2$

State Transition Graph

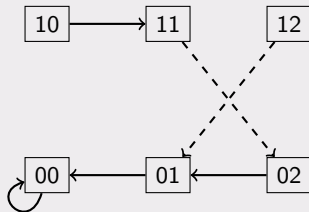


Dynamical Behaviour

Asynchronous



Synchronous



Other updatings

- Sequential
- Block-sequential
- Random walks

Properties

- Attractors
stable states/oscillations
- Reachability

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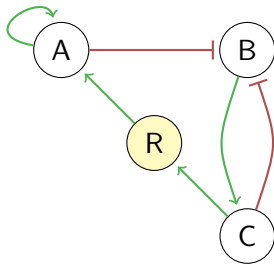
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Aim and properties

- Detailed reference model
- Multiple reductions
- Preserve feedback circuits
- Dynamical impact well understood

Removal of a Single Component

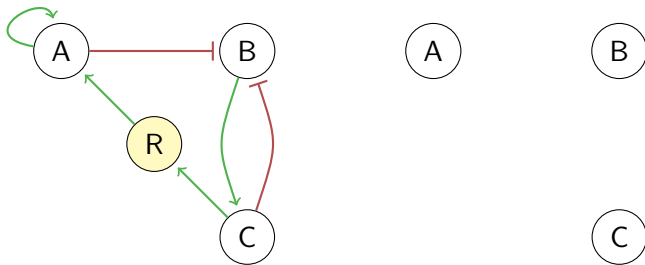
Definition of the reduced model:



Removal of a Single Component

Definition of the reduced model:

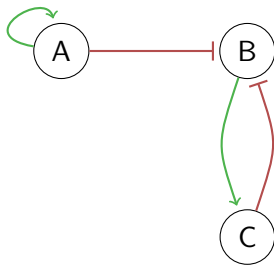
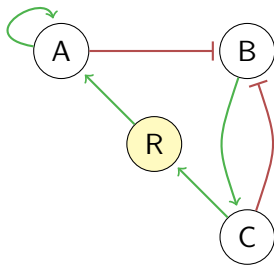
- All components but r



Removal of a Single Component

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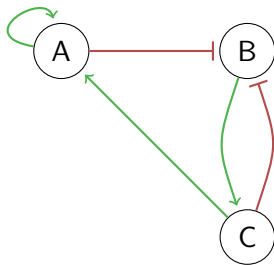
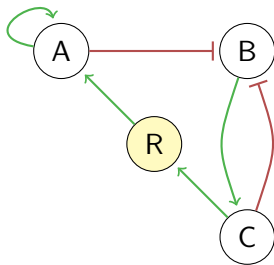
- All components but r
- Interactions between these components



Removal of a Single Component

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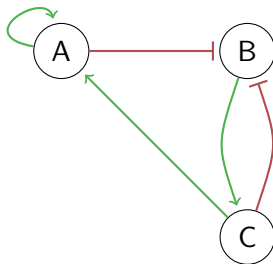
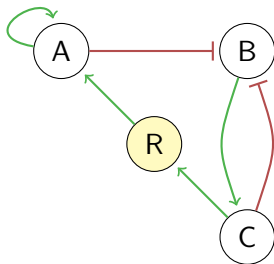
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Removal of a Single Component

Definition of the reduced model:

- All components but r
- Interactions between these components
- Regulators of r become regulators of its targets
- New logical functions for the targets of r



Removal of a Single Component

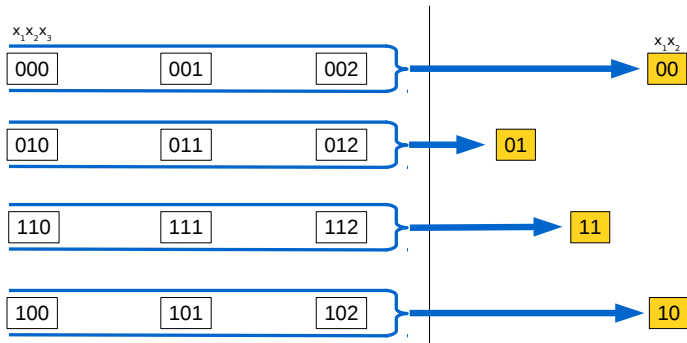
Definition of the reduced model:

- All components but r
- Interactions between these components
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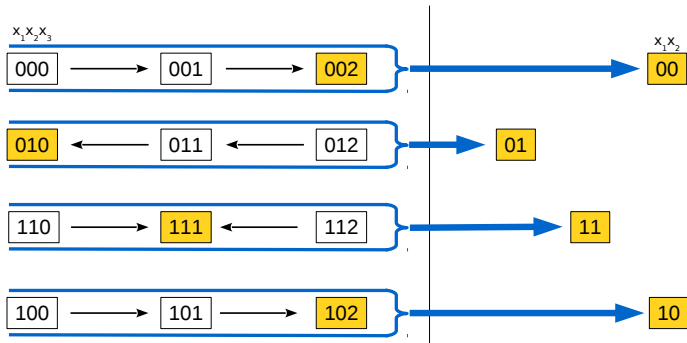
Replace constraints $r == v$ by parts of the function of r

All happens as if r reached its target value:
it can not be self-regulated

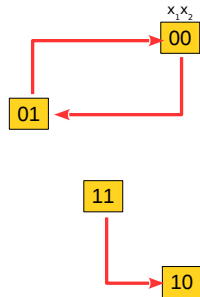
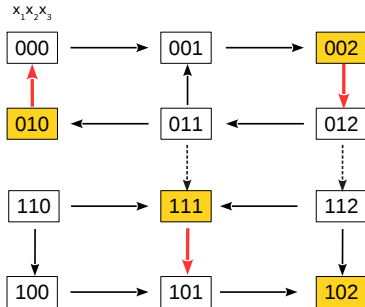
Dynamical Impact



Dynamical Impact



Dynamical Impact



Order of multiple reductions

How to apply a series of reductions?

The order does not affect the result

"Representative states in Multiple directions" are unique

... but it may affect feasibility

- A self-regulated state can not be reduced
- Reduction of his regulator may kill the loop
- finding a possible order is not trivial

Controlled dynamical impact

- Equivalence classes and representative states
- Preserve attractors
 - Same stable states
 - Stable oscillations in the same regions
 - May add new stable oscillations
- Reachability can be lost, not made up

Picking "good" reduced nodes is crucial

- "Fast" components
- Conservative reductions
 - no change in attractors
 - no change in reachability

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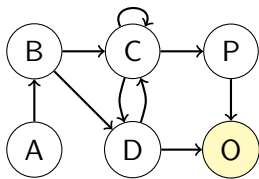
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Reduction of output components

Output reduction

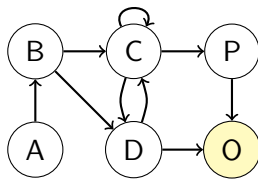
- No computation
- No impact
- Retrieve values



Reduction of output components

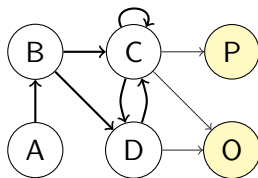
Output reduction

- No computation
- No impact
- Retrieve values



Extend to pseudo-outputs

- No impact
 - Harder retrieval
- ⇒ Rewire the model:
pseudo-outputs become
outputs

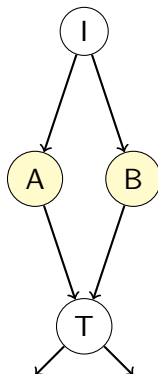


Rewiring: all functions only depend on core components

Reduction of pseudo-inputs

Propagation of pseudo-inputs

- Preserves attractors
- Reachability depends on initial condition

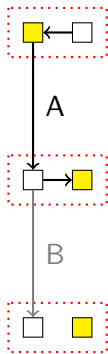
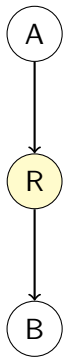


Looking for "safe" reductions



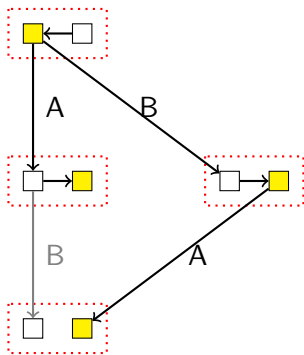
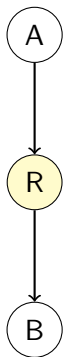
"Local" reachability loss related to targets of R: can't be avoided

Looking for "safe" reductions



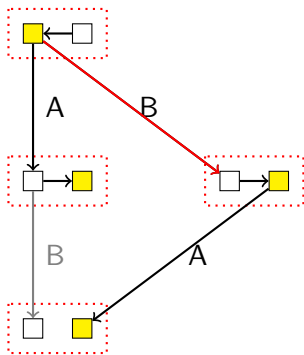
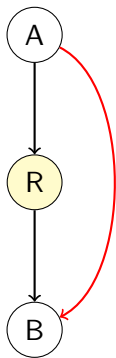
Better approach: look at longer paths with alternatives

Looking for "safe" reductions



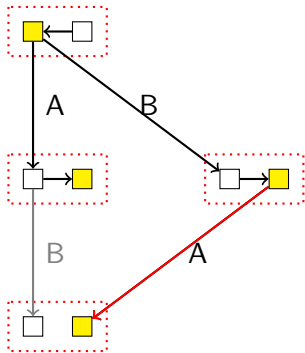
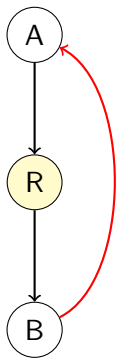
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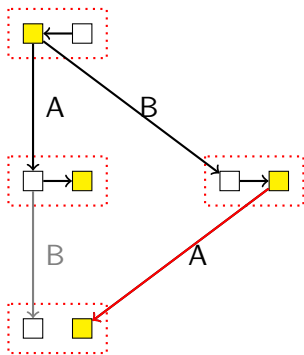
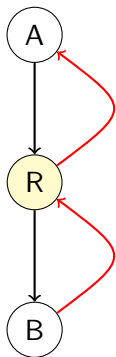
WIP: identification of motifs killing groups of alternative paths

Looking for "safe" reductions



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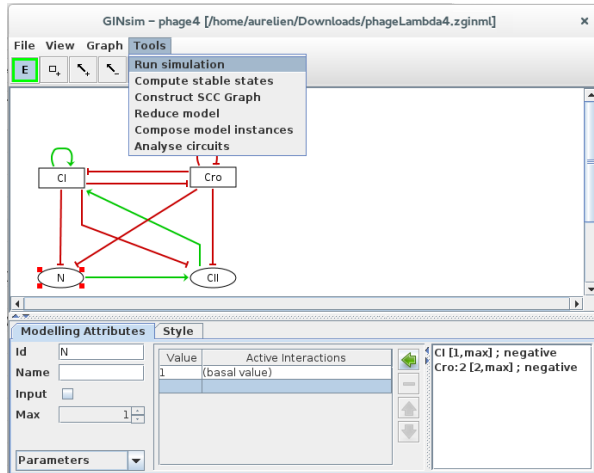
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GINsim: Definition and Analysis of Logical Models



<http://www.ginsim.org>

A Naldi et al. *Bio Systems* (2009)

GINsim features

Model definition

- Interaction Graph & Logical functions
- Annotations
- Perturbations

Simulation

- Updating modes
- STG and HTG

Static Analysis

- Circuit Analysis
- Stable states

Import / Export

- Other modelling tools
- Documentation & Images

Miscellaneous

- Scripting with Jython
- Open Source

Using Multiple Tools for Logical Model Analysis

"Many" logical modelling tools available

Complete each other, but have no interoperability

Consortium for Logical Models Tools (CoLoMoTo)

- Exchanging models: SBML qual format
- Toolbox/converter: LogicalModel
- Take advantage of multiple tools



<http://www.colomoto.org>

<https://github.com/colomoto>

Related Tools

Formal: Attractor Identification

- Stable Motifs (J Zanudo & R Albert)
- Symbolic Steady States (H Klarner & H Siebert)

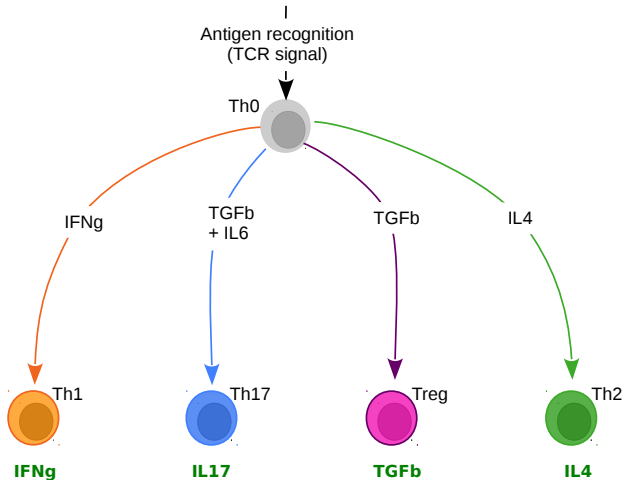
Simulation

- Model checking with NuSMV (P Monteiro)
- Reachability analysis with Pint (L Paulevé)
- Stochastic simulations with MaBoSS (G Stoll)
- Time delays with boolnet (C Müssel & H Kestler)
- Continuous simulations with SQUAD (L Mendoza & I Xenarios)

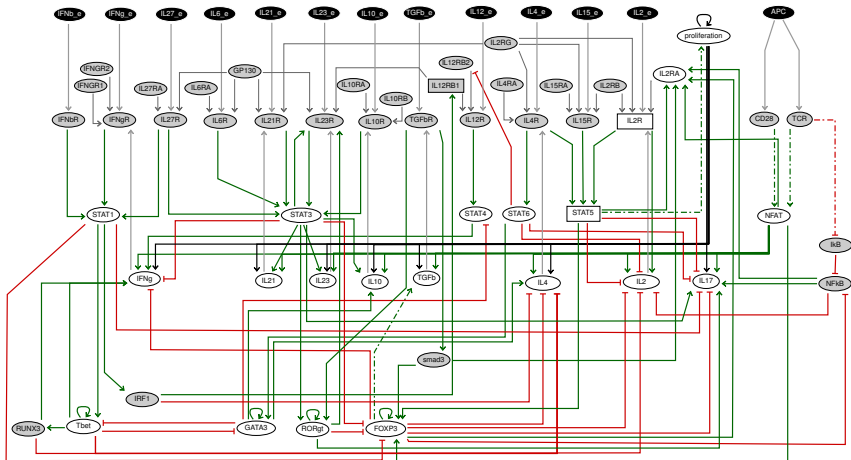
Model Optimization

- CellNopt (J Saez-Rodriguez)

Application: Th cell differentiation

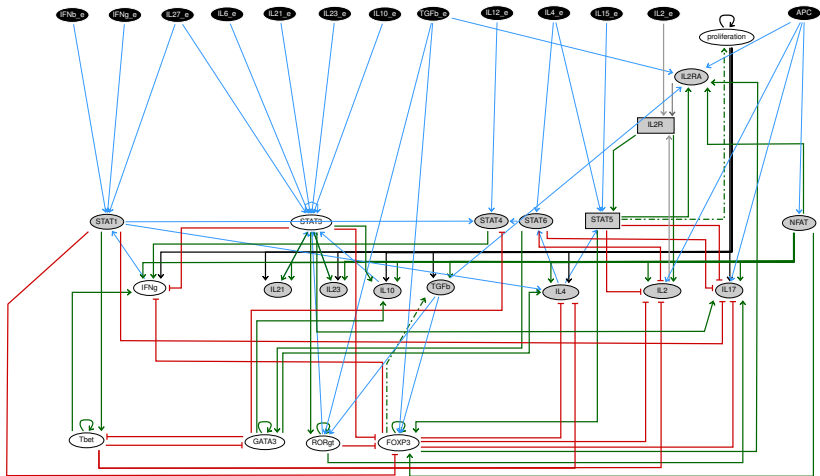


Application: Th cell differentiation

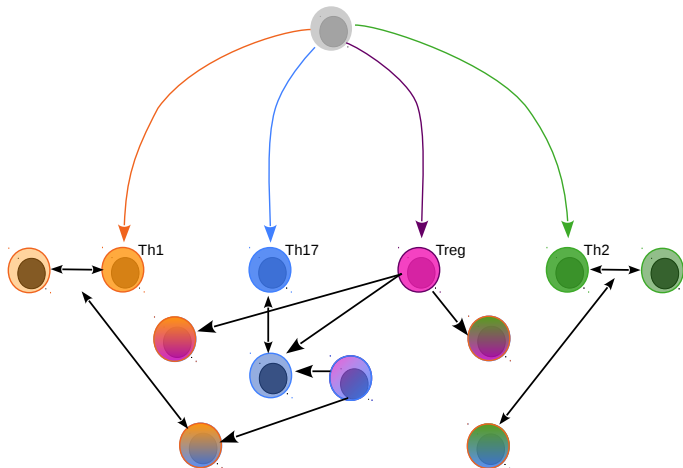


A Naldi et al. *PLoS Comput Biol* (2010)

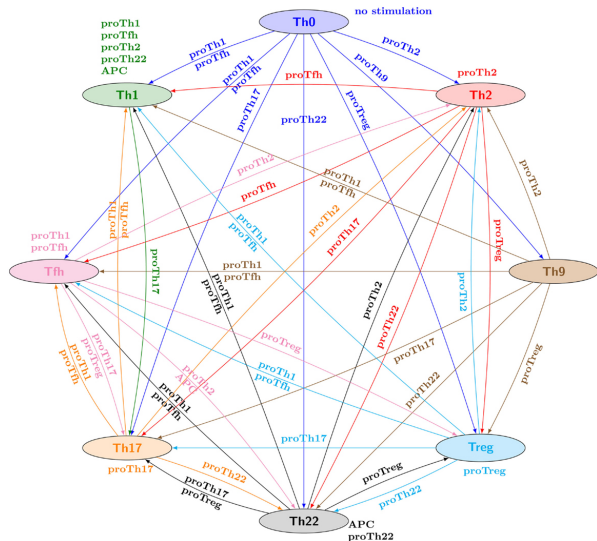
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Conclusion and prospects

An efficient reduction method

- Automated reduction
- Preserved attractors
- Well defined dynamical impact
- Implementation available
- Applied in some published models

... with some low-hanging fruits

- Automated "safe reductions"
Extend to longer paths
- Reduction for static analysis:
do NOT generate complex functions
- Find possible orders

Acknowledgements & Collaborations

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