Basics: ASP and logical modeling of Thomas GRNs Applications Generally true Additivity Constraints and automatic consistency On going works

# Non-Monotonic Logical Modeling for Regulatory Genetic Networks

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#### Motivations

To show the interest of a **declarative** approach based on **Answer Set Programming** (ASP)

- for modeling Thomas' logical discrete Genetic Regulatory Networks (GRNs)
- for inducing GRNs a priori consistent with experiments (reverse engineering).
- for taking into account both automatic inconsistency repairing and gene interaction properties which are only generally true, by using default rules provided by ASP.

## Declarative approach. Personnal wiew

#### Four steps methodology.

- Formalization (network structure, behaviors, ...) with constraints.
- Consistency test (see below).
- Extraction of properties (theorems).
- Choice of experiments / Knowledge addition. Return to step1.

## Content

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# Belief revision with ASP (Answer Set Programming).

ASP is a logic programming technology based on a non monotonic logic with models said **stable** which are minimal. Rules are:

$$a_0: -a_1, \ldots, a_m, not \ a_{m+1}, \ldots, not \ a_n$$

The typical example for introducing to non monotonic logics:

- From the axioms in ordinary (monotonic) logic:  $flies(X) \Leftarrow bird(X)$  bird(tweety) one deduces flies(tweety).
- The problem is with penguins. Taking them into account demands:
  - completing the 1st axiom by  $\neg penguin(X)$  as a premise,
  - qualifying by hand every bird (is it or not a penguin ?).

## Advantages of ASP. Belief revision(cont.)

With ASP, these manual revisions may be avoided by using **defaults**. Unless the contrary is **proved**, a bird is not a penguin.

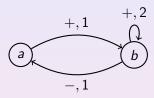
• From:

```
flies(X) :- bird(X), not penguin(X).
bird(tweety).
one deduces flies(tweety).
```

 If by addition of new knowledge (e.g. result of experimentation), penguin(tweety) can been proved then flies(tweety) is no more deducible (non monotony).

Additivity constraints on gene interactions (see later) can be modeled by such defaults.

## Thomas GRNs. Interaction graph



#### Focal equations:

$$\begin{split} \mathbf{X}_{a} &= \begin{cases} K_{a} & \text{if } \mathbf{x}_{b} < \theta_{b}^{1} \\ K_{a}^{b} & \text{if } \mathbf{x}_{b} \geq \theta_{b}^{1} \end{cases} \\ \mathbf{X}_{b} &= \begin{cases} K_{b} & \text{if } \mathbf{x}_{a} < \theta_{a}^{1} \text{ and } \mathbf{x}_{b} < \theta_{b}^{2} \\ K_{b}^{a} & \text{if } \mathbf{x}_{a} \geq \theta_{a}^{1} \text{ and } \mathbf{x}_{b} < \theta_{b}^{2} \\ K_{b}^{b} & \text{if } \mathbf{x}_{a} < \theta_{a}^{1} \text{ and } \mathbf{x}_{b} \geq \theta_{b}^{2} \\ K_{b}^{ab} & \text{if } \mathbf{x}_{a} \geq \theta_{a}^{1} \text{ and } \mathbf{x}_{b} \geq \theta_{b}^{2} \end{cases} \end{split}$$

 $x_a$ : (discrete) concentration of protein a.  $\theta_a^1$ : threshold of a.

# Thomas GRNs. Dynamics

- Focal equations relate a state  $[x_a, x_b]$  and its focal state  $[X_a, X_b]$  indicating in which direction are its neighboring successors, thanks to parameters K.
- Semantics of signs:

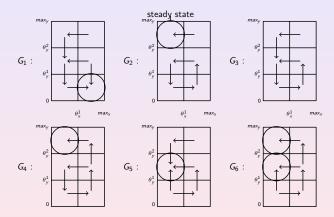
**Observability** constraint (always true) for 
$$a \stackrel{+,1}{\rightarrow} b$$
:  $(K_b < K_b^a) \lor (K_b^b < K_b^{ab})$ 

i.e activation in at least on case.

**Additivity** constraint (**generally** true) for 
$$a \stackrel{+,1}{\rightarrow} b$$
:  $(K_b \leq K_b^a) \wedge (K_b^b \leq K_b^{ab})$  i.e. no inhibition.

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## Transition graph



Transition graphs satisfying observability and additivity constraints. One equilibrium for  $G_1$ ,  $G_3$ ,  $G_5$ . **Mutistationarity** for  $G_2$ ,  $G_4$ ,  $G_6$ .

There are  $2^2 * 3^4 = 332$  possible set of parameters.

## Experiments (behaviors) represented as paths

#### Examples:

- Enforcing the existence of a path of two successive identical states (steady state) gives all transition graphs except  $G_3$ .
- Enforcing the existence of a path beginning with the state [0,0] and reaching the state w [0,2] leads to the models  $G_4$  and  $G_6$ .

## Other facilities

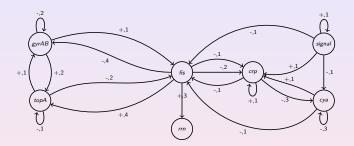
#### Include

- automatic inconsistency repairing.
- mutant specification.
- minimization (interactions and thresholds values): the ASP software provides para-logical operators like
   #minimize{f\_1,...,f\_n} that produces only models with the lowest number of literals f\_i true.
- deduction of properties on domains specified by biologists : for example,  $(K_b < K_b^a) \lor \neg (K_b < K_b^{ab})$  true in all models.

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# Carbon Starvation in E. Coli [Ropers et al., Biosyst., 2006]



Two **steady states**: 1) with a high concentration of Fis and a high supercoiling (e.g. high ratio GyrAB / TopA), 2) after carbon deprivation, with a high concentration of Crp and a weaker supercoiling.

Two **response paths** to the two stresses: carbon deprivation, carbon-source availability.

## Inconsistency repairing. [Corbin et al., Biosyst., 2009]

**Automatic repairing**, by relaxing as few as possible additivity constraints, offers two possibilities:

- Rejecting  $K_{gyrAB} \ge K_{gyrAB}^{fis}$ : means that Fis does not inhibit GyrAB when the bacteria are not stressed. **Disagrees** experimental data from [Schneider et al., Mol. Microbiol., 1999].
- Rejecting  $K_{topA}^{fis} \ge K_{topA}$ : would imply that TopA synthesis is possible even if the concentration of Fis is low. **Supported** by [Westein Fischer et al., Mol. Microbiol., 2007] for a stress due to hydrogen.
- By relaxing this last constraint, we get only 3 different instantiated models (on the 279,936 possible instantiated models due to the possible values of the 22 logical parameters).

# Drosophila embryo gap genes net. [Corblin et al. IPCAT 2012]

- Three maternal genes (cad, bcd, ter) and four gap genes (kr, hb, kni, gt). Well-established or **potential** interactions.
- Spatio-temporal expression profile of the main genes along the antero-posterior axis, giving seven regions (stable states).
- Expressions of genes also available from the seven mutants.

Objective: networks with the number of potential interactions and the number of thresholds **minimized**.

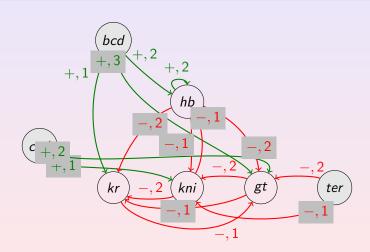
Potential interactions are represented by dotted red arrows.

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## Mutants and minimization. Results

- The set of constraints is found consistent (3338 s., on a PC, 2 proc. 2.4 GHz, 2.9GB memory).
- A unique minimal regulatory graph is then obtained (1016 s.) which includes only two potential interactions. Finally we get a unique minimal instantiation of the thresholds (368 s.).
- Deduced properties on parameters: 52 fixed parameters(over 72), 48 inequalities on the remaining ones: 12 between one parameter and one threshold, 36 between two parameters.
- The story is not finished... Enforcing CTL AF-like formulas is now required.

## Minimized network, with only two potential interactions



# IRMA network, from [G. Batt et al., Bioinformatics, 2010]

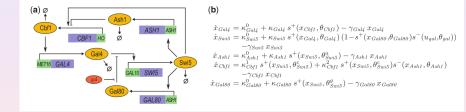
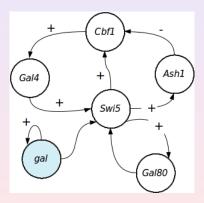


Figure: (a) The IRMA (In vivo benchmarking of Reverse-engineering and Modeling Approaches) network [I.Cantone et al., Cell., 2009], (b) the corresponding piecewise affine differential equations.

## IRMA interaction network



## Temporal profiles

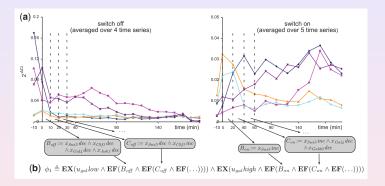


Figure : (a)Temporal profiles encoding of averaged gene expression. "switch-on" ("swith-off") refers to the activation(inhibition) of Swi5 during growth of galactose (glucose). (b) Temporal encoding of the switch-on and switch-off behaviors. Only changes greater than  $5\times 10^{-3}$  units are considered significant

## Two approaches

- Batt's approach (with singular states): a new modeling with more regular states, such that each species has a unique derivative sign in them + the model checking tool NuSMV. He claims, when comparing its work, that it applies to "incompletely instantiated models" and provides "more precise results" and "efficient coding".
- Our approach for replying: Thomas initial model (no singular states), with adequate constraints expressing that a path satisfies a temporal series.
- Programming experiments for inferring parameters and thresholds: which models satisfy formulas  $\varphi 1$  (2 large EF formulas representing averaged "switch-off" and switch-on" experiments) and  $\varphi 2$  (9 large EF formulas representing all time series).

#### Results

- After discovering mistakes in Batt's work (and Batt in both our works...), we found the <u>same</u> results: 64 models for  $\varphi 1$  and 4 for  $\varphi 2$  (on 4860). No more precise results with singular states...
- Better or equivalent performances: 139 s. vs 885 s. for  $\varphi$ 1, 2002 s. vs 2021 s. for  $\varphi$ 2, with a regular ASP solver (no incremental solving).

## Constraints vs model checking

- Model checking is based on CTL with a weak expression power compared to Prolog like ASP language, e.g. enforcing the existence of at least two steady states is not possible.
- Model checking is oriented toward verification of transition systems, Logic programming toward programming with logic, e.g. Batt performs out of NuSMV by using a counter-example delivery facility and a para-logic help for producing models by extension (not appropriate to deduce properties).

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## Two modeling issues

- Escaping inconsistency if some additivity constraints cannot not be satisfied because contraindications due to behaviors.
- Accepting only models with as many as "possible" additivity constraints.

#### A first solution

- Enumerating all models, i.e. all possible atoms kparam(K, Ik) where K is the value of the parameter named Ik. **Costly**.
- Maximizing, with a para-logical process (Max-SAT like), the number of satisfied additivity constraints. Costly too.
   And debatable: logical minimization provided by stable models vs para-logic global criterion.

## New solution (main lines)

**Firm** production of kparam atoms restricted to:

- rules specifying the paths.
- rules specifying the observability constraints. **Important**: these constraints are disjunctions, like  $(K_b < K_b^a) \lor (K_b^b < K_b^{ab})$ . Non minimal models of them should be rejected (unless a contraindication due to a behavior), e.g. the rules must reject  $(K_b < K_b^a) \land (K_b^b < K_b^{ab})$  if possible. Naturally expressible in ASP.

## New solution. Efficient inconsistency repairing

Conditional production of kparam atoms due to the additivity constraints, by **default** rules like:

addit(+, a, b) :- obs(+, a, b), not obs(-, a, b). where addit(+, a, b) implies kparam atoms satisfying  $(K_b \leq K_b^a) \wedge (K_b^b \leq K_b^{ab})$ .

In case of a negative observability due to some behavior, no inconsistency appears since the rule is not applicable.

## New solution. Retaining only appropriate models

- Aim: retaining logically models with maximum allowed additivity constraints.
- Issue: avoiding that additivity on one edge infers non additivity on another one (i.e. inappropriate influence between defaults).
- The following rules mimic such influences with op\_ad1 interpreted as "additivity impossible for the interaction 1" (| stands for minimal disjunction):

```
op_ad2 | ad1 :- not op_ad1.
op_ad1 | ad2 :- not op_ad2.
Three Anwer Sets (ASs) : {ad1,ad2}, {op_ad1} and {op_ad2}.
```

**Challenge**: transform these rules to obtain a conjunction of defaults, i.e. with the only AS {ad1,ad2}.

## Construction of conjunction of defaults

#### Two steps:

Defining the literal c by :

```
c :- op_ad1.
c :- op_ad2.
so that not c means that both op_ad1 and op_ad2 are
unknown or false,
```

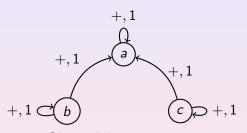
 Adding to each rule a new and "curious" (ASP) tautological term serving as a guard:

```
op_ad2 | ad1 :- not op_ad1, 1{c, not c}1.
op_ad1 | ad2 :- not op_ad2, 1{c, not c}1.
```

Then we get only the AS {ad1,ad2}.
 If we add the rule: 1{op\_ad1}1., we get both {ad1,ad2}
 and {op\_ad1}. Then a para-logical maximization could be applied if wished.

## Possible inconsistency. Example

Unfortunately, asserting all guards may lead to inconsistency.



#### Observability constraints

$$\begin{split} \left(\mathcal{K}_{a} < \mathcal{K}_{a}^{a} \wedge \mathcal{K}_{a}^{a} \geq 1\right) \vee \left(\mathcal{K}_{a}^{b} < \mathcal{K}_{a}^{ab} \wedge \mathcal{K}_{a}^{ab} \geq 1\right) \\ & \vee \left(\mathcal{K}_{a}^{c} < \mathcal{K}_{a}^{ac} \wedge \mathcal{K}_{a}^{ac} \geq 1\right) \vee \left(\mathcal{K}_{a}^{bc} < \mathcal{K}_{a}^{abc} \wedge \mathcal{K}_{a}^{abc} \geq 1\right) \\ \left(\mathcal{K}_{a} < \mathcal{K}_{a}^{b}\right) \vee \left(\mathcal{K}_{a}^{a} < \mathcal{K}_{a}^{ab}\right) \vee \left(\mathcal{K}_{a}^{c} < \mathcal{K}_{a}^{bc}\right) \vee \left(\mathcal{K}_{a}^{ac} < \mathcal{K}_{a}^{abc}\right) \\ \left(\mathcal{K}_{a} < \mathcal{K}_{a}^{c}\right) \vee \left(\mathcal{K}_{a}^{a} < \mathcal{K}_{a}^{ac}\right) \vee \left(\mathcal{K}_{a}^{b} < \mathcal{K}_{a}^{bc}\right) \vee \left(\mathcal{K}_{a}^{abc} < \mathcal{K}_{a}^{abc}\right) \end{split}$$

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## Possible inconsistency (cont.)

The instantiations  $K_a=1$ ,  $K_a^b=0$ ,  $K_a^{ab}=0$ ,  $K_a^{ac}=0$ ,  $K_a^{bc}=0$  and  $K_a^{abc}=1$  ensure the observability constraints, but forbid both additivity constraints related to the edges  $a\to a$  and  $c\to a$ :  $K_a^a$  and  $K_a^c$ , not a priori known, should be higher (resp. lower) than or equal to  $K_a=1$  (resp.  $K_a^{ac}=0$ ). See the lattice:

$$K_a^{ac} = 0$$

$$K_a^{c} = ? K_a^{a} = ?$$

$$K_{a=1}$$

## Inconsistency prevention

#### Briefly

- For each couple of edges targeting a species N, constructing a guard guarantying the conjunction of their additivities only in case of absence of lattices like above (in a generalized form).
- Expressing the conjunction of all additivies on N as the logical conjunction of the above guards devoted to each couple of edges.

#### Some results

#### For the example above:

- In case no added extra-behavior: 101 ASs respecting only the observability constraints. With additivity constraints, reduction to 51 ASs with unitary defaults and to 9 ASs with the global guard defined above.
- With the extra-behavior  $K_a = 0$ ,  $K_a^a = 0$ ,  $K_a^b = 0$ ,  $K_a^c = 1$ ,  $K_a^{ab} = 1$ , still allowing models with all additivity constraints: 8 ASs with only observability constraints. With additivity constraints, reduction to 6 ASs with unitary defaults and to 1 AS with the global guard defined above.
- If adding K<sub>a</sub><sup>ac</sup> = 0, that forbids the conjunction of defaults involving a → a, one AS is (fortunately) obtained (non monotonic effect).

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## On going work. Ensuring CTL formulas in ASP

EF formulas, already available, for analysis purpose.

AF formulas necessary for **synthesis** purpose.

Trivial definitions (apparently):

aF(Prop,Sp): transition(S,Sp).

## Ensuring CTL formulas in ASP. Issues

- Checking loops, like:
   eF(Prop,s1):-transition(s1,s2), eF(Prop,s2).
   eF(Prop,s2):-transition(s2,s1), eF(Prop,s1).
   Given for free, thanks to the minimality of stable models!
- Actual work: implementation considering a limitation on the number of states instead of a limitation on the length of paths (adequate for EF formulas but not for AF formulas).

## On going work. Multiplexes

When working with a Phd student (lab. IRcyn, Nantes) for comparison with another approach, we had to implement networks where multiplexes were present: ERBB receptor-regulated G1/S transition network (Sahin *et al.*, 18 species), tail resorption during the metamorphosis of tadpole (Khalis *et al.*, 8 species) and the T-cell Signaling network (Klamt *et al.*, 40 species)
Actual work: for efficiency and learning purpose, implementation of multiplexes similar to R. Thomas' SOP (Sum Of Products, disjunctive normal form) with a definition in terms of kinetic parameters.

# Multiplexes. Specification

Syntax of the language of the interactions targeting a species
 x:

```
I ::= Mul \mid Mul \text{ or } I
Mul ::= Iu \mid Iu \text{ and } Mul
Iu ::= Gene\_id \mid Sig Gene\_id
Sig ::= + \mid -
```

• **Semantics**: the value of oc(I), a logical function of the parameters, constructed following the *composition principle*. Examples:

$$oc(+a) = K_{x}^{a} > K_{x}.$$

$$oc(+a \text{ and } + b) = (K_{x}^{ab} > K_{x}) \land (K_{x}^{a} = K_{x}^{b} = K_{x})$$

$$oc(+a \text{ or } + b) = (K_{x}^{ab} > K_{x}^{b} \lor K_{x}^{a} > K_{x}) \land (K_{x}^{ab} > K_{x}^{a} \lor K_{x}^{b} > K_{x})$$

$$oc(-c \text{ and } + a \text{ and } + b) = (K_{x}^{ab} > K_{x}^{c})$$

$$\land (K_{x}^{abc} = K_{x}^{ac} = K_{x}^{bc} = K_{x}^{a} = K_{x}^{b} = K_{x} = K_{x}^{c})$$

## On going work. Mamalian circadian cycle

Knowing the existence of three such cycles (equinox, winter, summer), find models and delays. With a very reduced network (3 species including light). Delay modeling is rather simple, but demands at least large integers for expressing ratios of clocks. Actual work: implementation with **linear equations** on integers, provided by the ASP solver clingo.

#### **Thanks**

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And to Delphine, Emna, Claudine, ... Denis, Gilles, Gregory, Hans, Jean-Paul,...

## Thank you for your attention

# **QUESTIONS?**

Declarative approach ... Non monotonicity ... Composition of defaults...